



From ground characterization of the 16 H2RGs to the in-flight commissioning of the NISP* Instrument of Euclid**



SLAC, ISPA24



Rémi Barbier

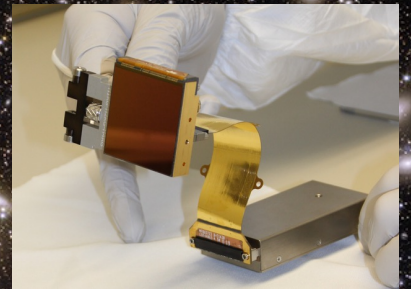
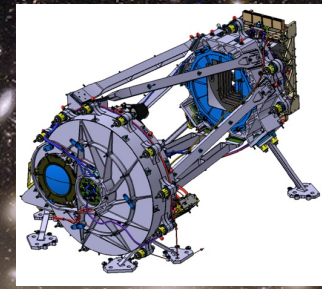
NISP Detector Scientist

*Near Infrared Spectrometer and Photometer

On behalf of NISP

Instrument Development Team

Euclid Consortium



Detector Characterization Laboratory

GSFC



** Disclaimer : every thing you will see in this presentation is obtained by the IDT and are not the results of the Euclid pipeline.

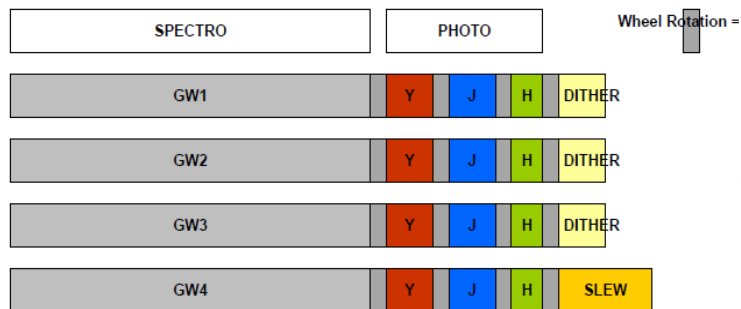


Near Infrared Spectrometer and Photometer



NISP Reference Observation Sequence [ROS]

➤ Two RO modes



➤ 4 dithers

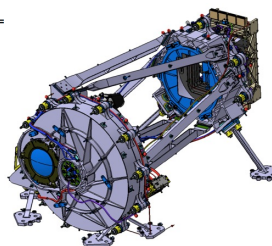
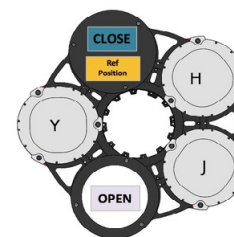
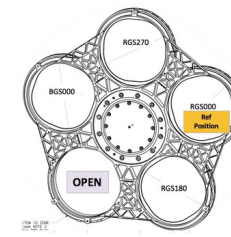


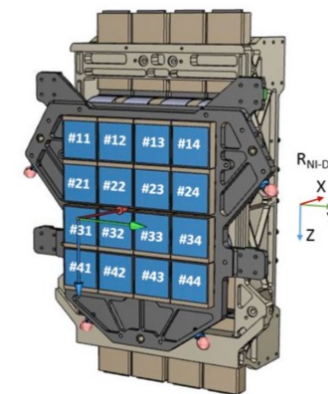
PHOTO mode
Filter Wheel



SPECTRO mode
Grism Wheel



4x4 H2RGs
mosaic



The nominal MACC(G,F,D)

- MACC(15,16,11) = Spectro Exp. Time ~576s
- MACC(4,16,4) = Photo Exp. Time ~116s

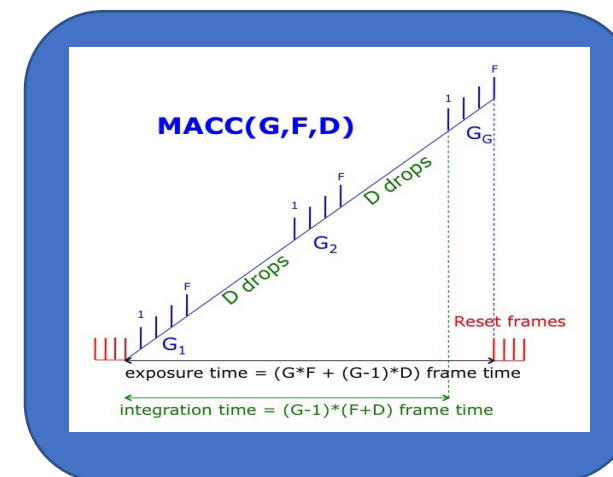
On Board Data Reduction:

- 1 ramp to one slope = flux = ADU/fr

Conclusion :

- Accurate calibration of the pixel response only based on slope of the ramp is challenging

Multi-Accumulation

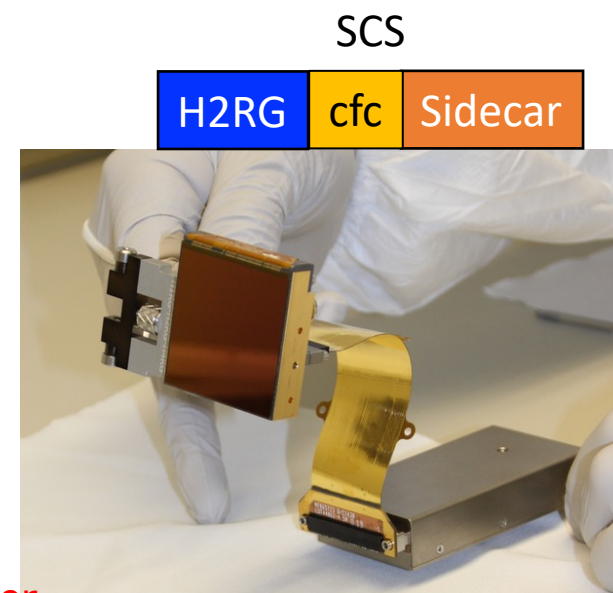


Configurations

- **SCA: H2RG @ OT(L2) = 92K**
 - Cut-off: 2.3 μ m
 - Pixel clock: 100 kHz – slow readout mode
 - 32 channels in //
 - Frame time \sim 1.4548s
 - Buffered mode
 - Bias \sim 500mV, Diode FWC \sim 120ke

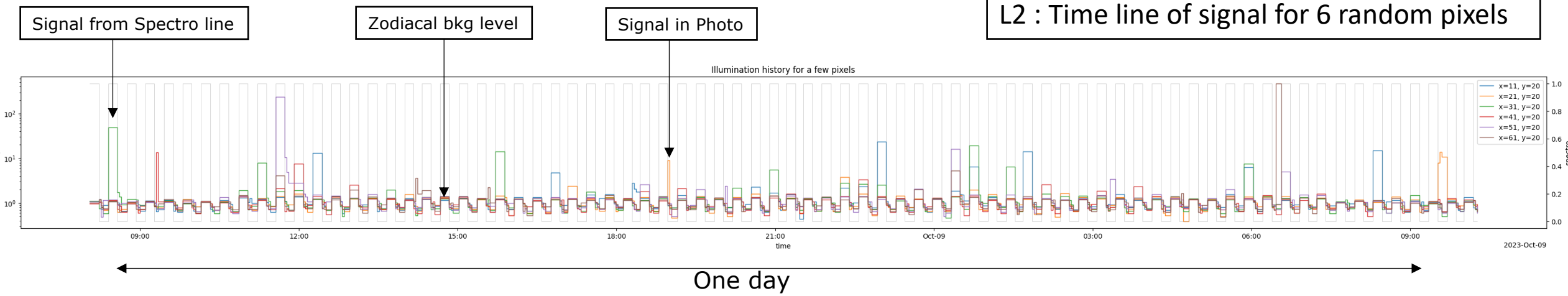
- **SCE : Sidecar @ OT = 136K**
 - Single ended => baseline adjustment with tunable voltage register
 - Preamp Gain: 15dB (x \sim 5)
 - SAR ADC: Sat. \sim 85 ke- before the FW of the diode
 - Reference pixel subtraction : Mean of Top & Bottom + LR Sliding Window (5)Med – computed in the DCU
 - Euclid Firmware : SUTR and Single Pixel Reset (for IPC) Readout modes

- Downlink 5 raw pixel lines : all frames of MACC groups



Test as in flight !

Reference Observation Sequence [ROS]
L2 : Time line of signal for 6 random pixels



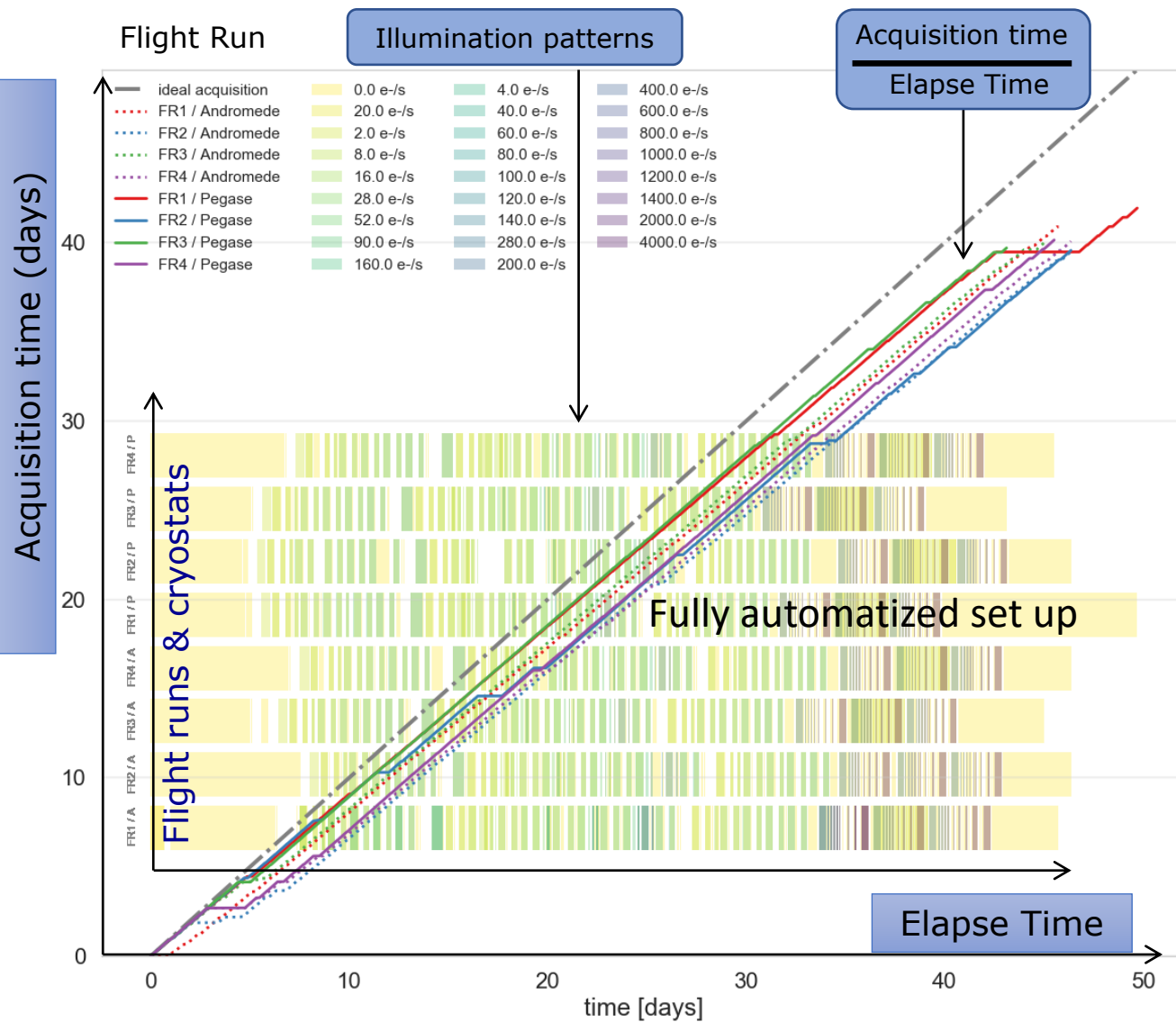
- Most of the time the pixel “see” the zodiacal bkg
- What is the best test flow for this type of ROS ?



Test as in Flight ? complexity and efficiency



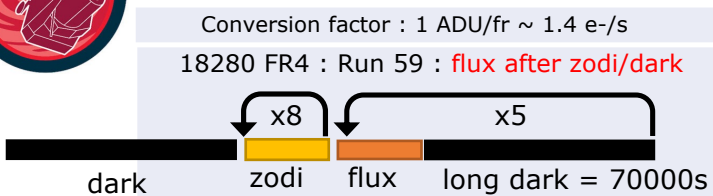
CPPM/IP2I Test flow



Test objective	Test configuration																																								
IPC - SPR	<table border="1"> <tr> <td>Array</td> <td>16</td> <td>Grid 8x8</td> <td>16</td> <td>-- x64 grids</td> </tr> <tr> <td>Rst</td> <td>dark</td> <td>Rst</td> <td>dark</td> <td></td> </tr> </table>	Array	16	Grid 8x8	16	-- x64 grids	Rst	dark	Rst	dark																															
Array	16	Grid 8x8	16	-- x64 grids																																					
Rst	dark	Rst	dark																																						
Baseline, Rst Noise	16 dark -- 1000 ramps																																								
Dark & Noise	396 (spe) or 76 (pho) darks -- 100 ramps																																								
NL Calibration	396 or 76 flux flux -- flux 30-50 ramps																																								
NL /w zodiacal bkg	396 or 76 flux Zodi bkg 2e-/s flux -- 30 seq. of 2 ramps																																								
Persistence short NL w/ dark	396 or 76 800 (~20') flux dark flux -- 30 seq of 2 ramps																																								
Persistence long NL /w dark	396 or 76 8000 (~2h) flux dark flux -- 20 seq. of..																																								
ROS /w zodiacal bkg & /w flux in one seq.	<table border="1"> <tr> <td>GW1</td> <td>Y</td> <td>J</td> <td>H</td> <td>DITHER</td> <td>GW1</td> <td>Y</td> <td>J</td> <td>H</td> <td>DITHER</td> </tr> <tr> <td>GW2</td> <td>Y</td> <td>J</td> <td>H</td> <td>DITHER</td> <td>GW2</td> <td>Y</td> <td>J</td> <td>H</td> <td>DITHER</td> </tr> <tr> <td>GW3</td> <td>Y</td> <td>J</td> <td>H</td> <td>DITHER</td> <td>GW3</td> <td>Y</td> <td>J</td> <td>H</td> <td>DITHER</td> </tr> <tr> <td>GW4</td> <td>Y</td> <td>J</td> <td>H</td> <td>SLEW</td> <td>GW4</td> <td>Y</td> <td>J</td> <td>H</td> <td>SLEW</td> </tr> </table> <p>-- 5 seq.</p>	GW1	Y	J	H	DITHER	GW1	Y	J	H	DITHER	GW2	Y	J	H	DITHER	GW2	Y	J	H	DITHER	GW3	Y	J	H	DITHER	GW3	Y	J	H	DITHER	GW4	Y	J	H	SLEW	GW4	Y	J	H	SLEW
GW1	Y	J	H	DITHER	GW1	Y	J	H	DITHER																																
GW2	Y	J	H	DITHER	GW2	Y	J	H	DITHER																																
GW3	Y	J	H	DITHER	GW3	Y	J	H	DITHER																																
GW4	Y	J	H	SLEW	GW4	Y	J	H	SLEW																																



Gnd test: dark or zodiacal level before illumination



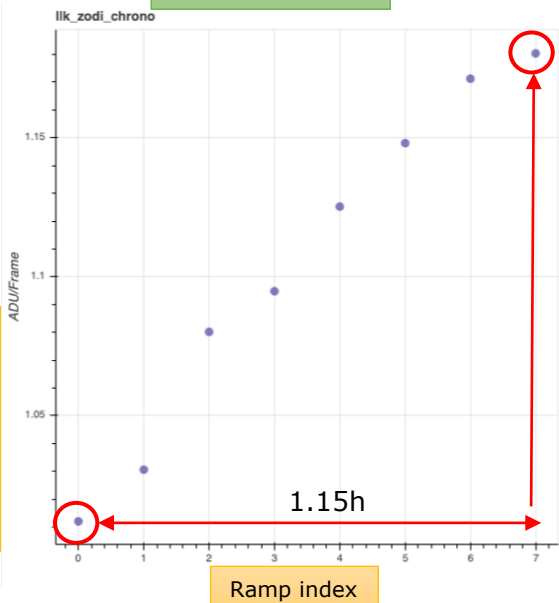
Workflow	Duration acq.+qc	Disk (GB)	Cycle	Iteration	Sequence	# Ramps	# Frames	flux (e/s)	
latency_90	15h00	290.7GiB	cycle_1	1	seq_1	1	5000	0	dark
					seq_2	8	400	2	Zodiacal emulation
			cycle_2	5	seq_1	1	400	90	flux
					seq_2	1	5000	0	dark

zodiacal emulation

Zodi
c_1_seq_2

+20% => persistence accum.
settling time > 1h

<zodi> \sim 1.75 e-/s



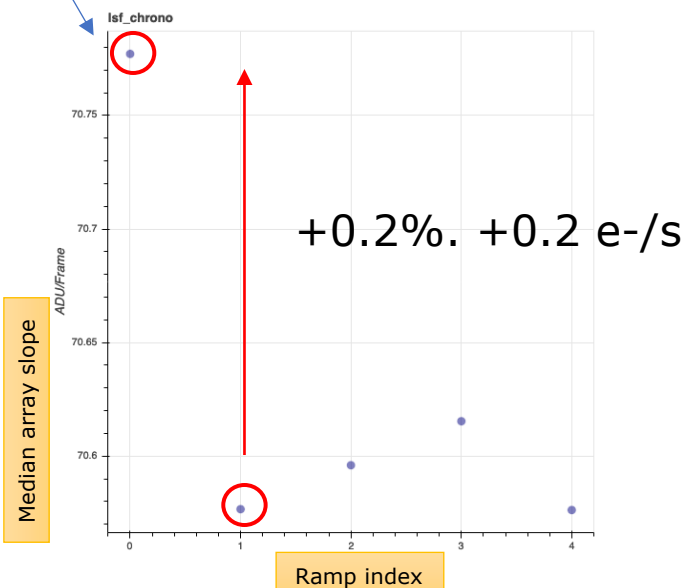
High flux

flux after zodi
c_2_seq_1_r=0

flux after dark
c_2_seq_1_r>0

+0.2% => persistence from zodiacal bkg

<flux> \sim 98 e-/s



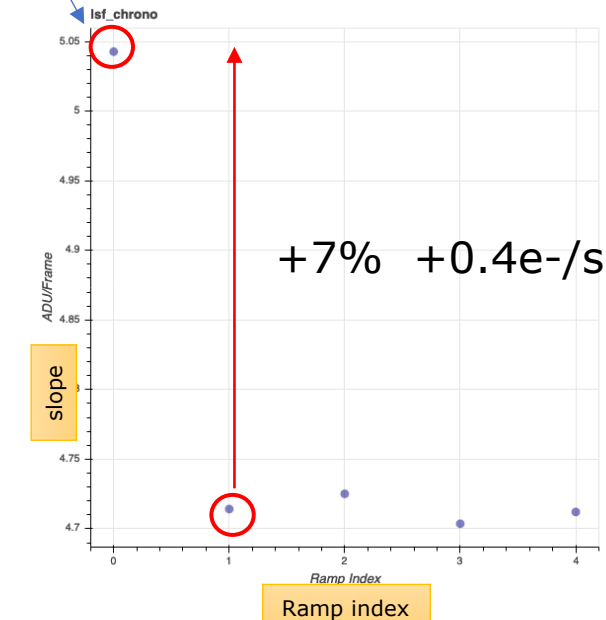
Low flux

Flux after Zodi
c_2_seq_1_r=0

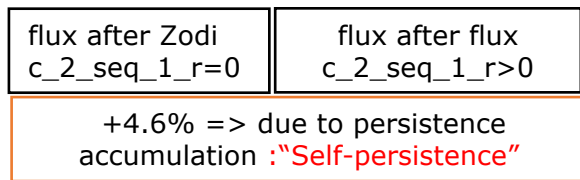
flux after dark
c_2_seq_1_r>0

+7% => persistence from Zodiacal

<flux> \sim 6.6 e-/s



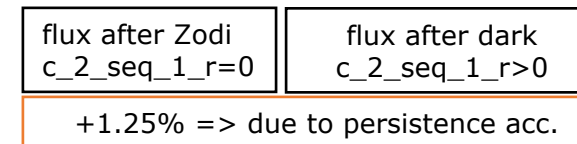
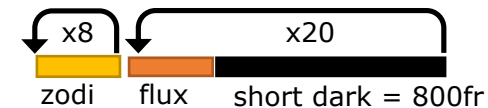
➤ Zodiacal persistence contribution to the signal is negligible for high flux – not negligible to low flux



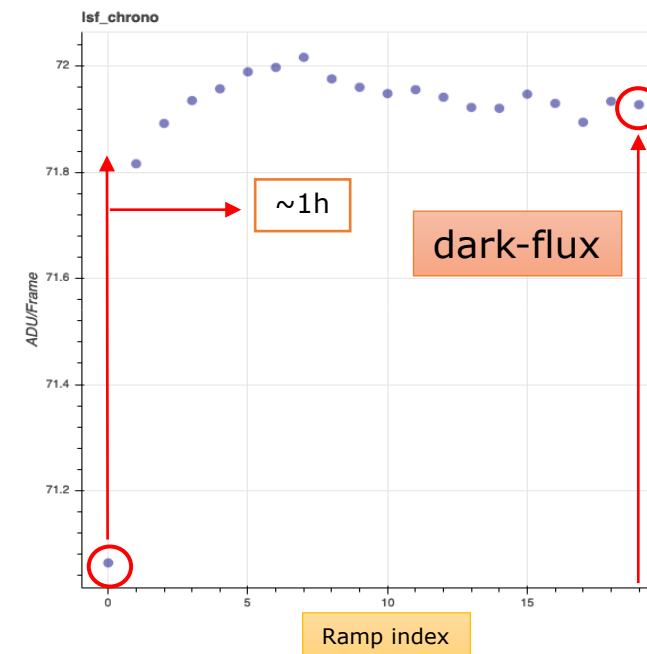
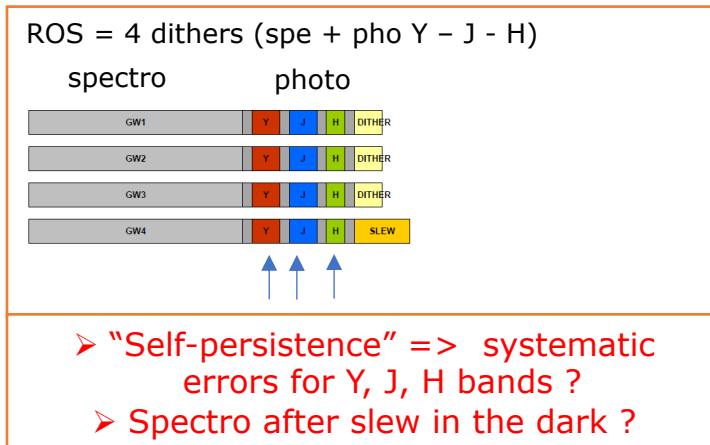
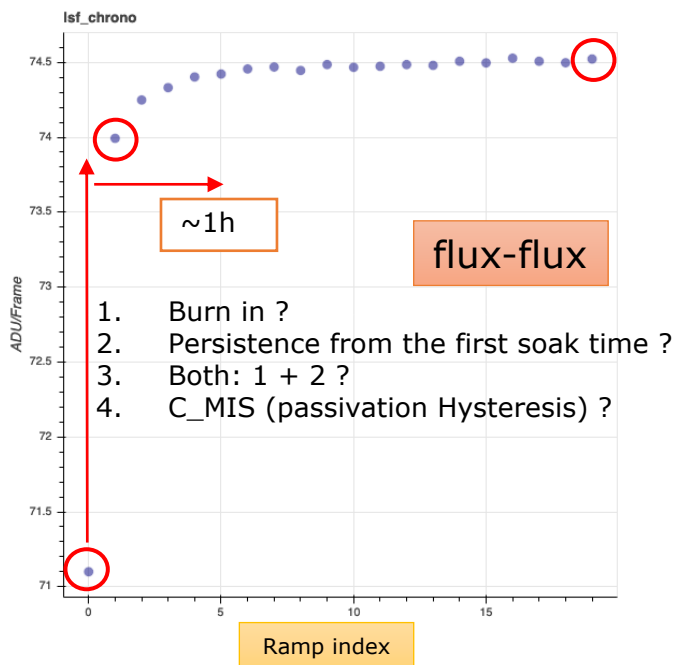
<flux> ~ 105 e-/s

Same illumination level

Delta ~7 e-/s => 7 %



<flux> ~ 98 e-/s





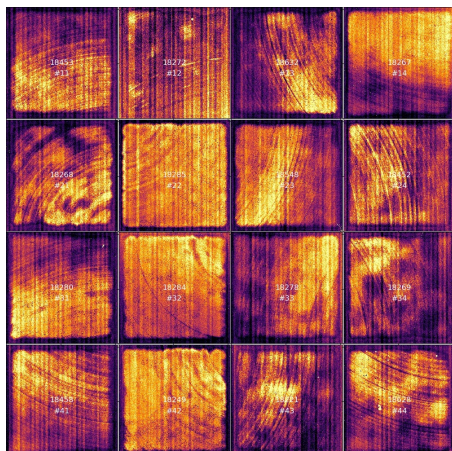
L2* vs Gnd

* Data from Commissioning and PV but not from the SGS pipeline

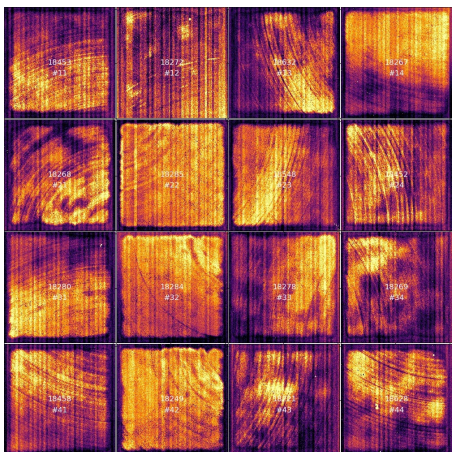
L2 : Baseline = first group (G1) after reset

- Different OT => baseline adjustment @ L2
- Verification on per pixel baseline shift => Gnd-L2 shows some features on 4 detectors
- => Same feature on the Flat Field

Baseline in L2

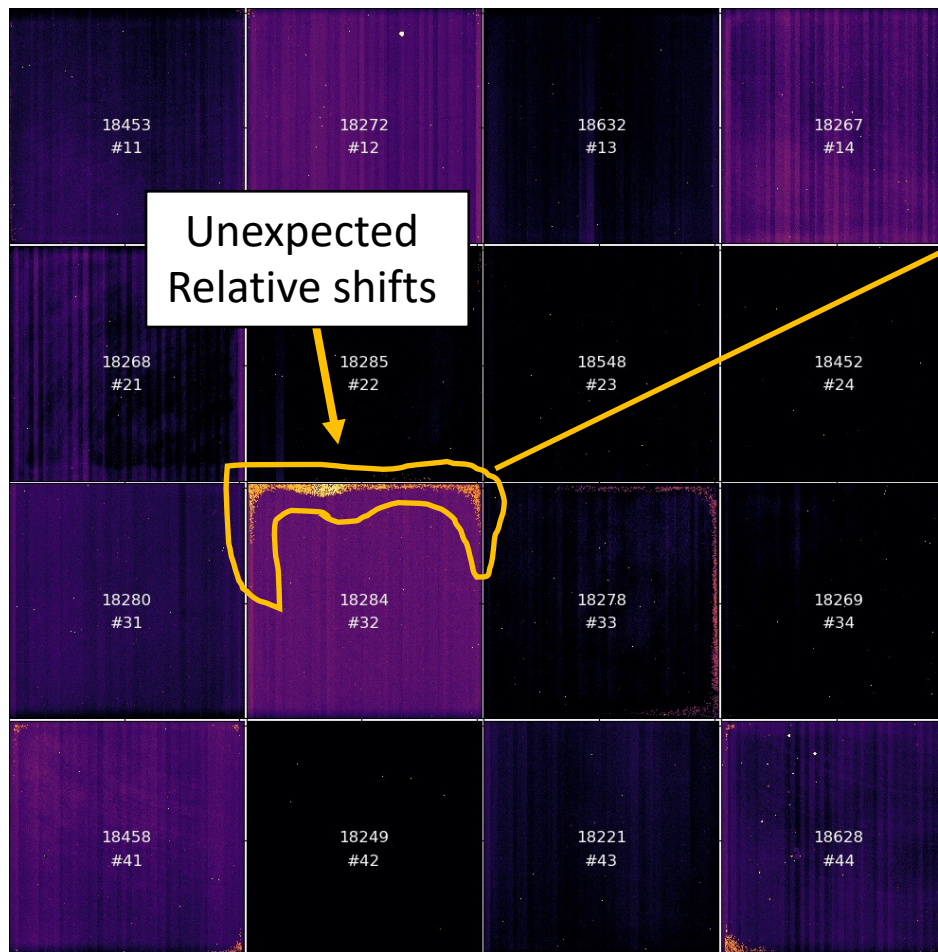


Baseline Gnd



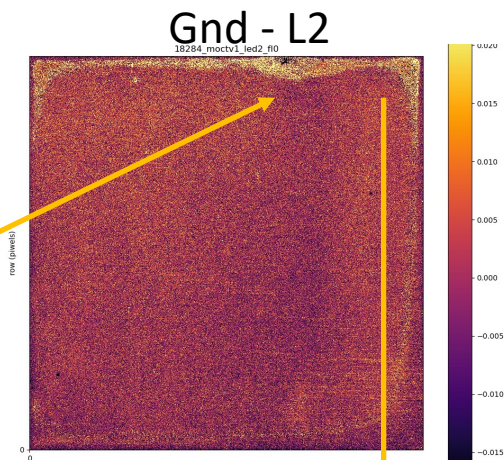
Per pixel difference => sanity check in L2

Baseline difference: Gnd - L2

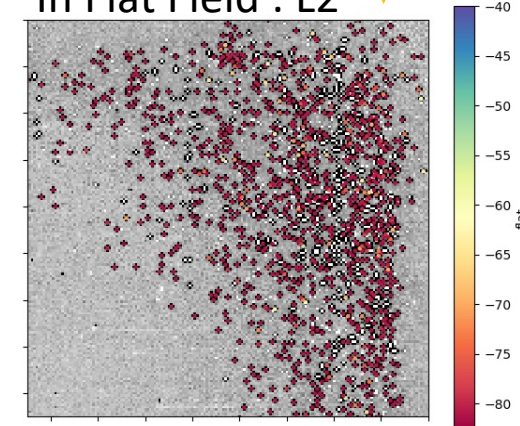


Unexpected Relative shifts

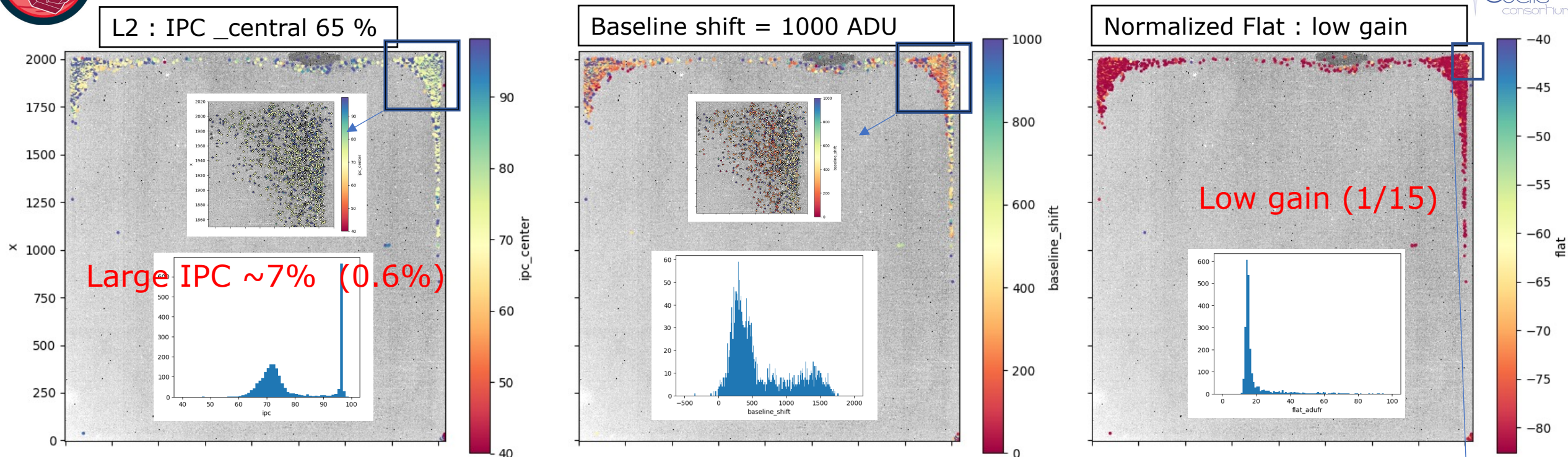
Normalized FF difference During CU commissioning



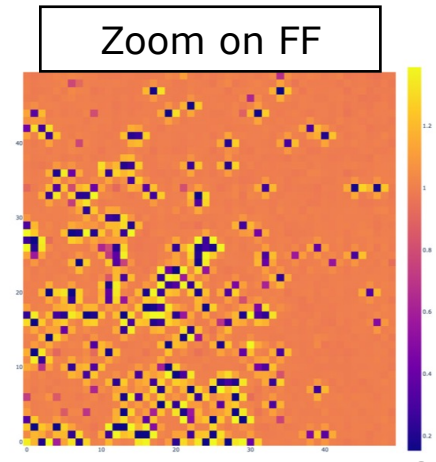
Selected features In Flat Field : L2



18284 Baseline shift & Flat field & IPC correlations



Curtosy of Simon Conseil



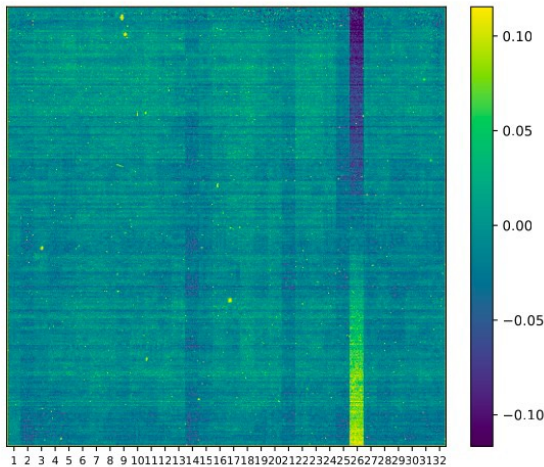
- **no** major impact on the Euclid survey (if the number of features remains as it is today)
- But the root cause is still unknown



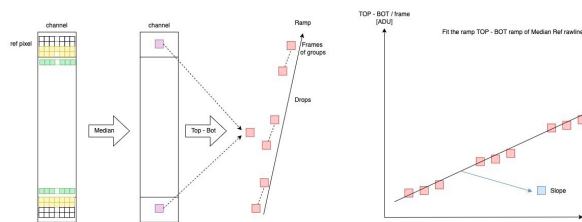
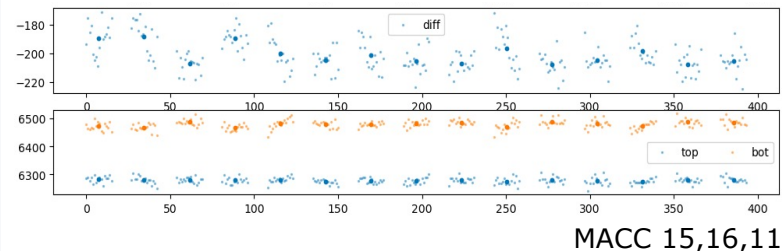
L2 : "unstable" channels



One noisy ramp image

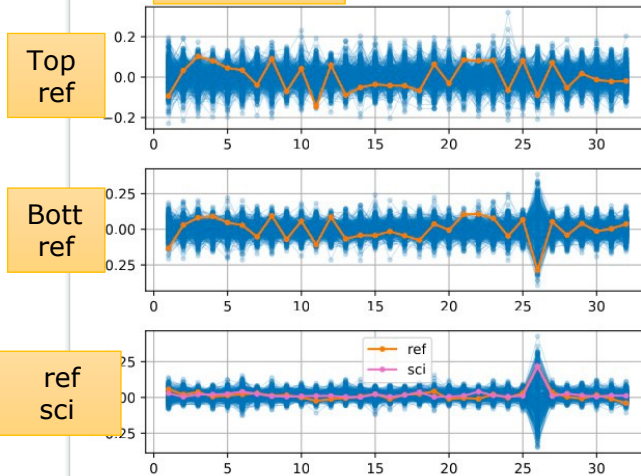


Raw lines on reference pixels (2 Top- 2 Bottom)

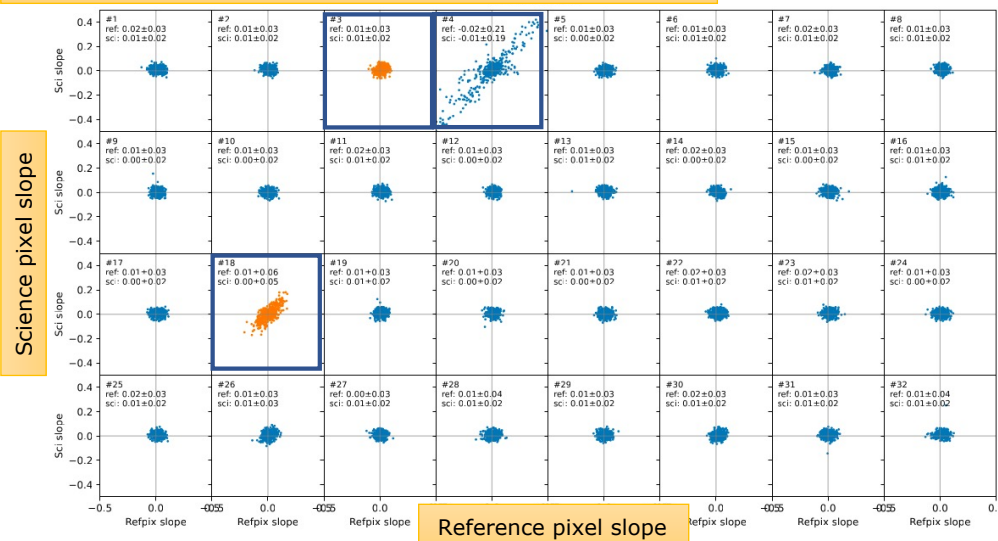


Ref pix :
Ramp of the
Top - Bot

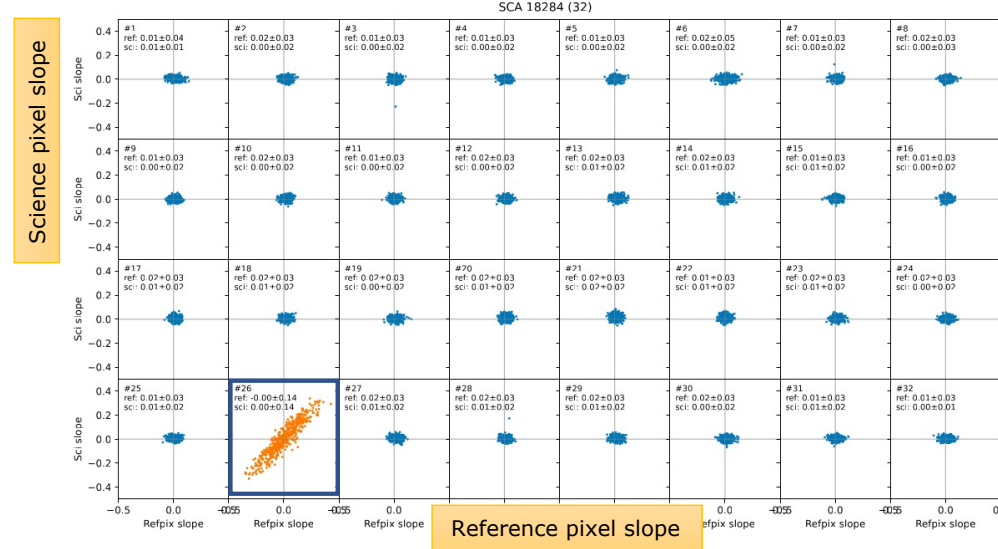
100 ramps



100 dark ramps in photo mode / 32 channels



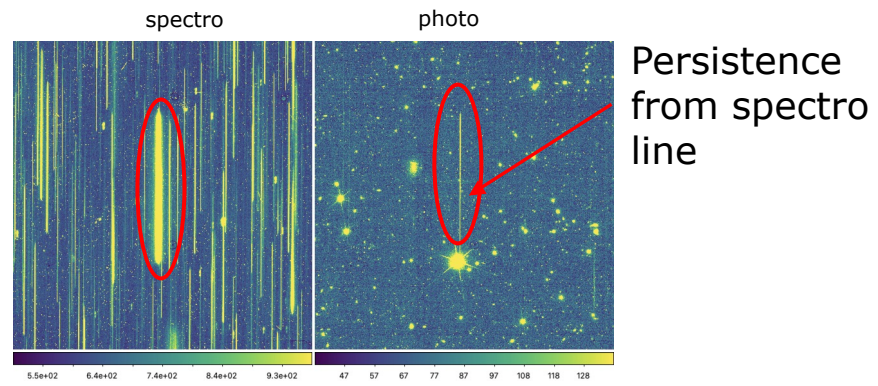
● seen as unstable on Gnd



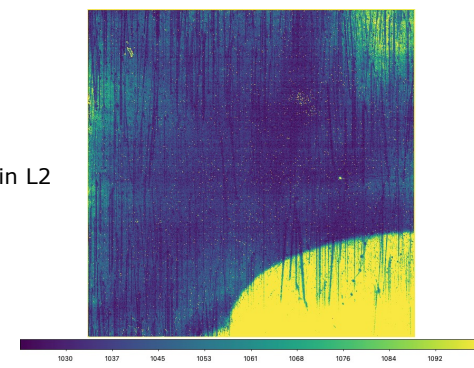
- SGS correction implemented : thanks to the RAW lines on Ref pixels
- Channel instabilities can be thermal cycling dependent

Courtesy of Simon Conseil

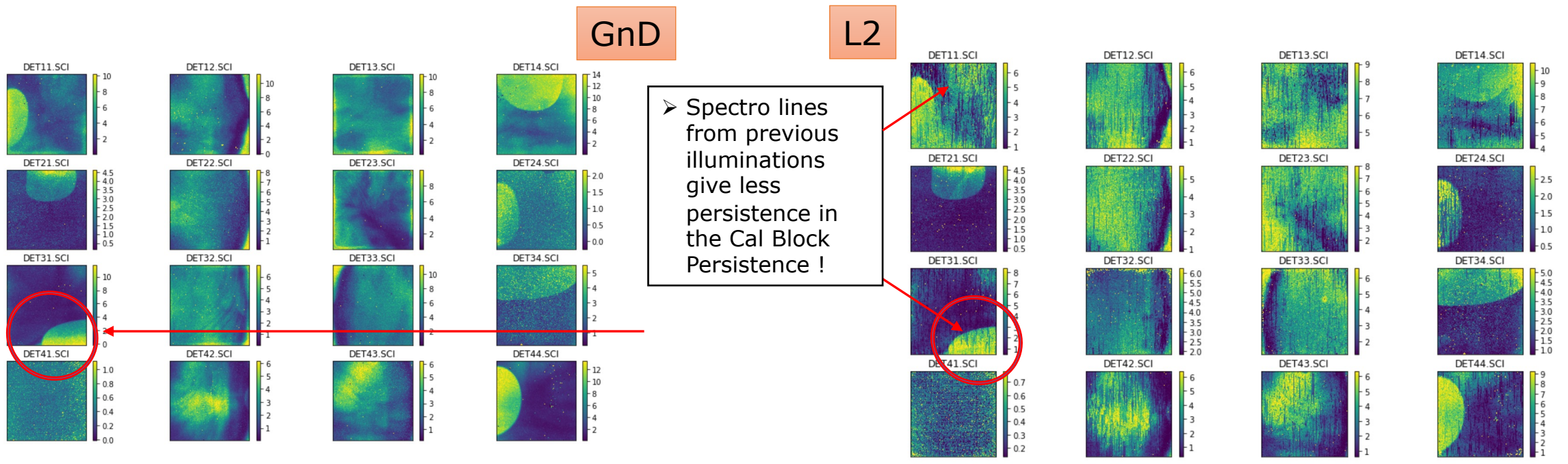
L2 Persistence is as expected : L2 vs Gnd



Persistence image after illumination in L2



Persistence images in the dark after illumination



Courtesy of Bogna Kubiak

- L2 Persistence level and time constants are similar to Gnd values
- Today Euclid SGS applies mask on pixels with high persistence but persistence correction is planned



Non linearity correction

Systematics ?



Non Linearity polynomial correction Method



- $y(x_i)$ signal ramp in ADU from MACC
- $x_i = G_i \Rightarrow 15$ or 4 (spe or pho)

- $P(x_i)$ Orthogonal polynomials computed for each basis
- Alpha = $Y(x)$ projected on $P(x)$

➤ beta_1 as the "linear" flux

$$\blacksquare y(x) = \beta_0 + \beta_1 x + \dots + \beta_N x^N = \sum_{i=0}^N \beta_i x^i$$

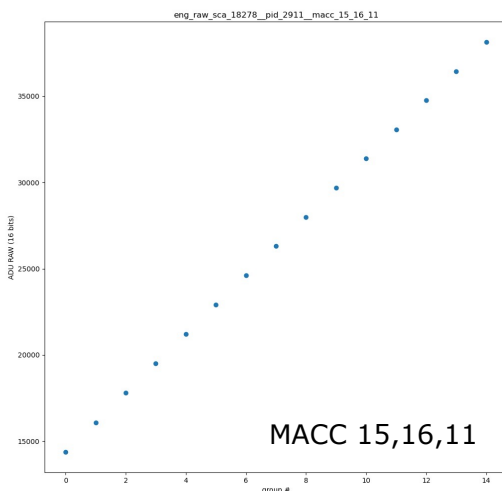
$$\blacksquare P_i(x) = a_{i0} + a_{i1}x + \dots + a_{ii}x^i = \sum_{i=0}^i a_{ij}x^j$$

$$\blacksquare y(x) = \alpha_0 P_0(x) + \alpha_1 P_1(x) + \dots + \alpha_N P_N(x) = \sum_{i=0}^N \alpha_i P_i(x)$$

$$\blacksquare \alpha_m = \langle y, P_m \rangle = \sum_{i=1}^D y_i P_m(x_i) = \sum_{i=1}^D y_i \sum_{j=0}^m a_{mj} x_i^j$$

$$\blacksquare \beta_j = \sum_{i=j}^N \alpha_i a_{ij}$$

15 groups of the spectro ramp MACC(15,16,11)



Raw Eng Mode
=> 15 groups sent to GnD

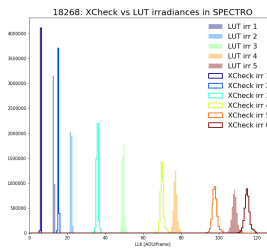
❖ beta_1 : "linear" reference flux

❖ Phi = On board flux

NL correction

polynomial Fit (deg 3 or 4)

beta_1 = P_4(Phi)



- The non linearity on sequences of fluxes in a row : no dark no zodi interleaved
- Polynomial correction is valid only **inside** the range of the tested flux available during calibration => issues when extrapolated

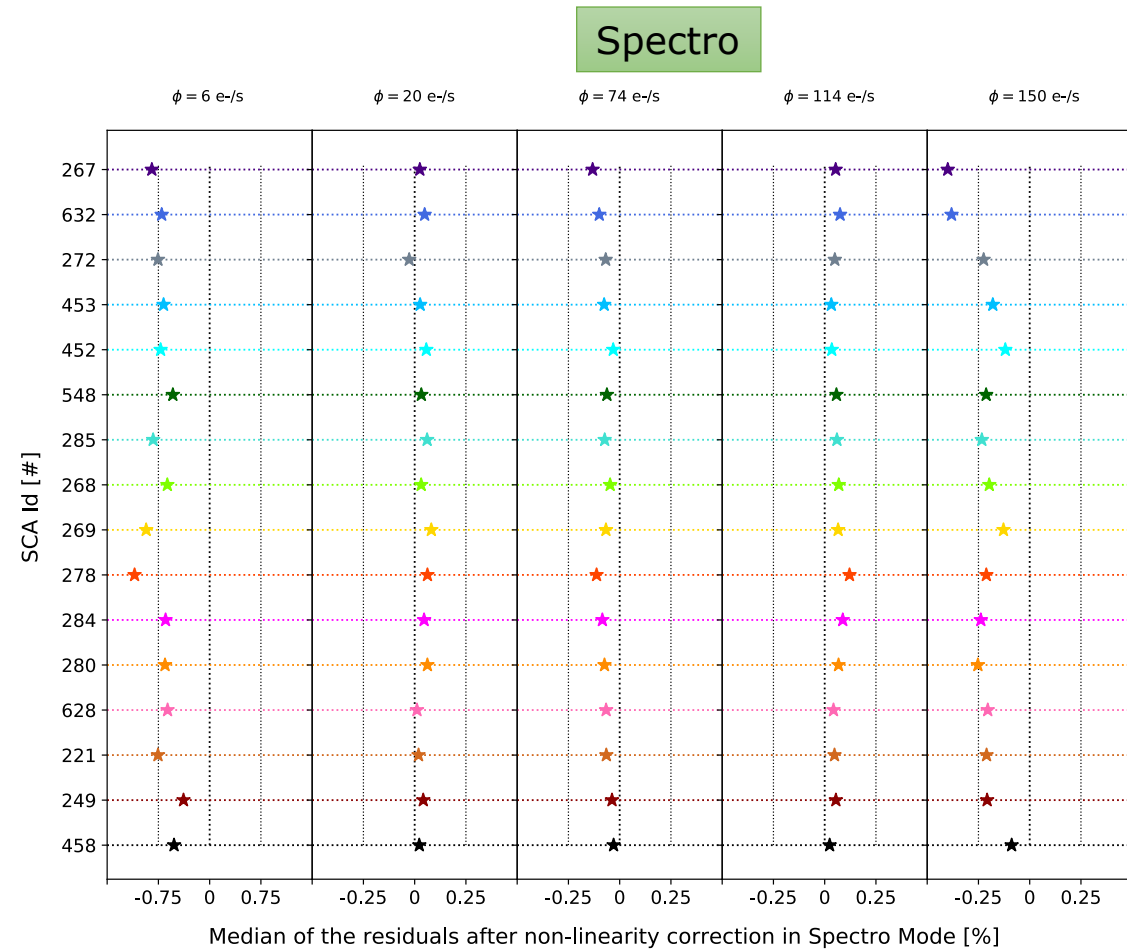
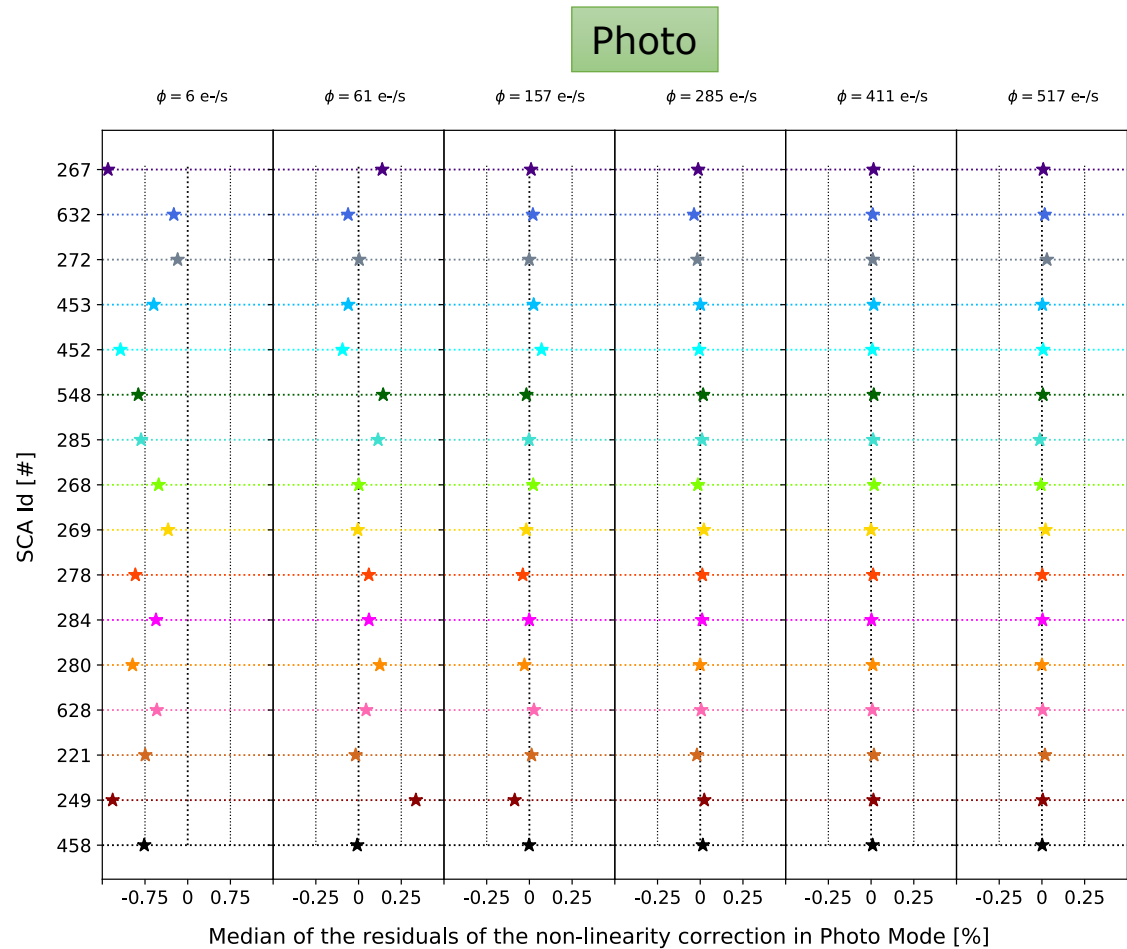


Non Linearity Performances : Gnd residuals 16 flight

NL Spec +/- 1%



Systematic error on NL correction : Residual [%] = (beta_1 - P₄(Phi)) / beta_1 x 100

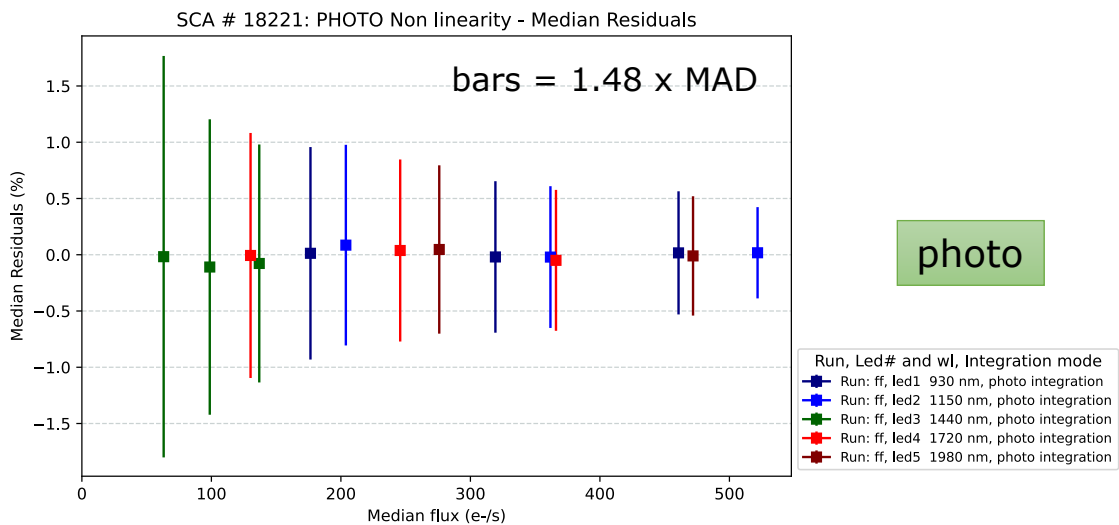




Non linearity corrections: residuals



Median Residual + scaled MAD



photo

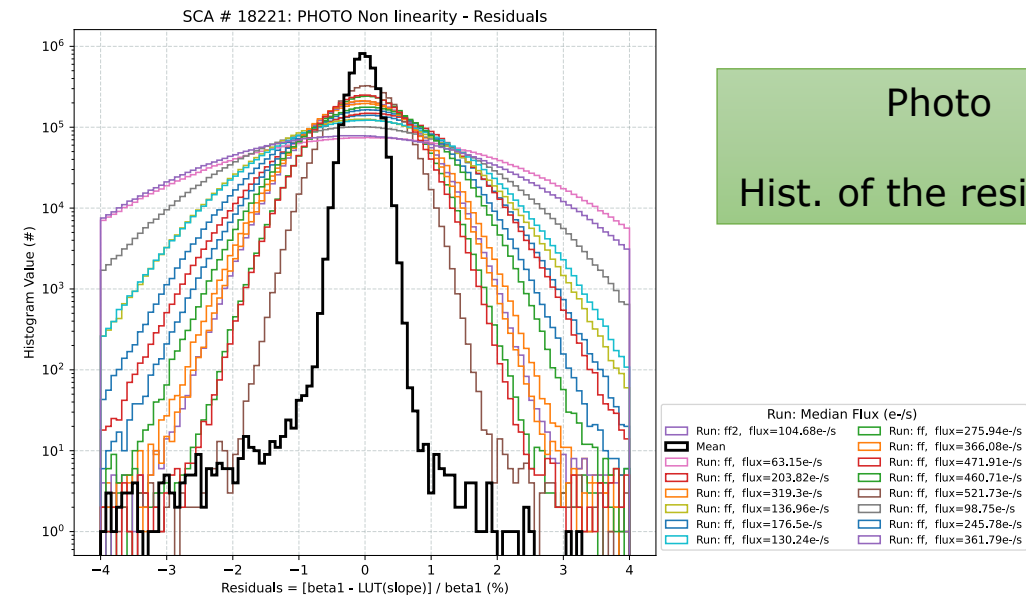
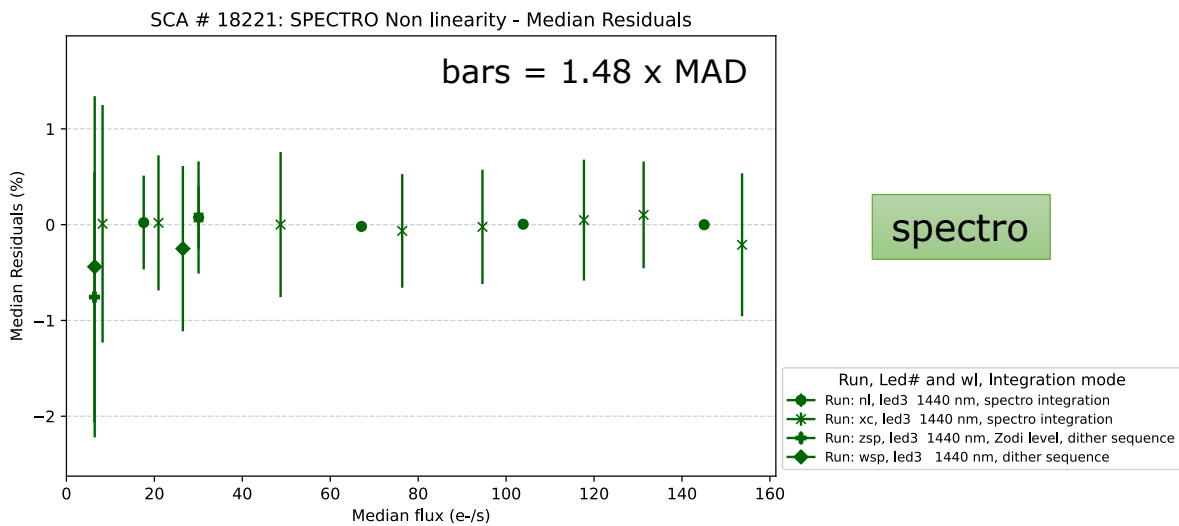


Photo
Hist. of the residuals

bars = 1.48 x MAD



spectro

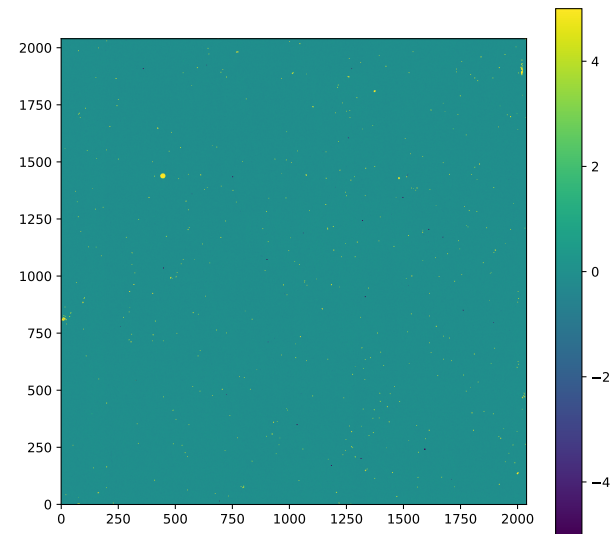
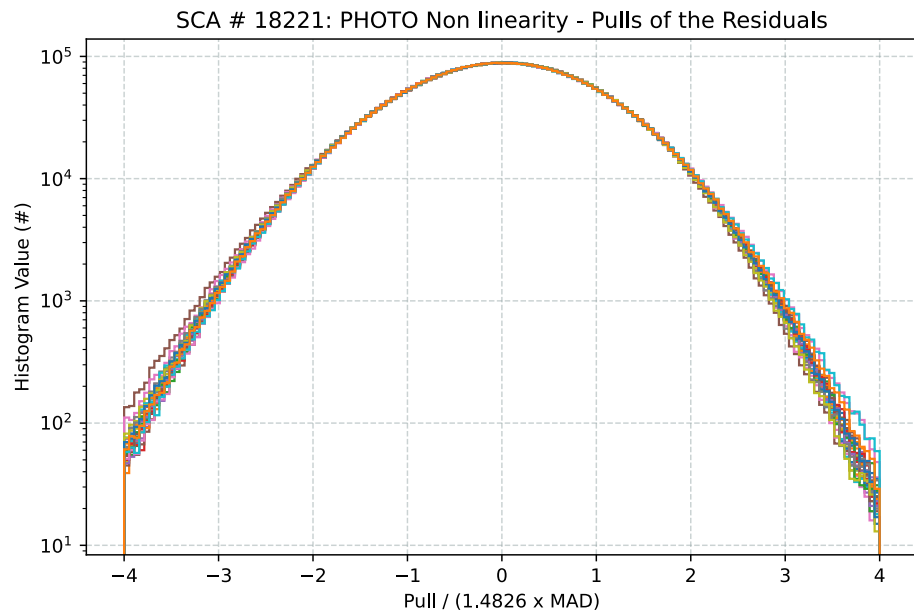


Photo
Image of the Mean residual over fluxes
No spatial features

photo

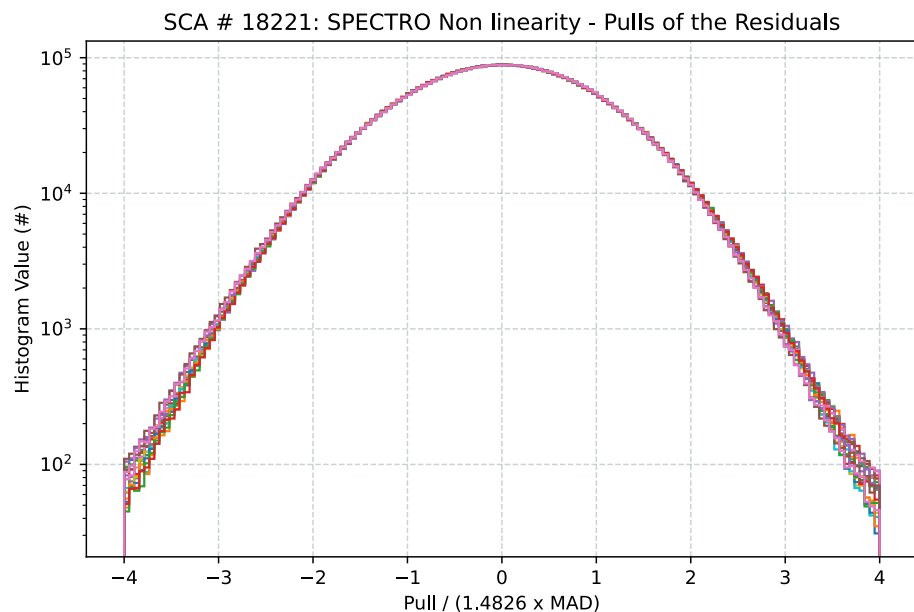


➤ sigma of the pull ~ 1

Run: flux & Pull mean, sigma

Run: la, flux=156 e-/s, mean=0.11 sigma=0.96	Run: la, flux=86 e-/s, mean=-0.02 sigma=1.0
Run: la, flux=432 e-/s, mean=0.07 sigma=0.99	Run: ff, flux=137 e-/s, mean=0.02 sigma=0.99
Run: la, flux=48 e-/s, mean=0.16 sigma=0.99	Run: ff, flux=276 e-/s, mean=0.09 sigma=0.98
Run: ff, flux=472 e-/s, mean=0.04 sigma=1.06	Run: nl, flux=30 e-/s, mean=0.03 sigma=0.98
Run: ff, flux=176 e-/s, mean=0.09 sigma=1.05	Run: nl, flux=18 e-/s, mean=0.06 sigma=0.99
Run: la, flux=313 e-/s, mean=0.13 sigma=0.95	Run: la, flux=853 e-/s, mean=0.0 sigma=1.04
Run: la, flux=607 e-/s, mean=0.19 sigma=0.92	Run: la, flux=665 e-/s, mean=0.11 sigma=1.01
Run: ff, flux=461 e-/s, mean=-0.0 sigma=0.93	Run: nl, flux=106 e-/s, mean=-0.17 sigma=0.97
Run: ff, flux=130 e-/s, mean=-0.11 sigma=1.03	Run: ff, flux=204 e-/s, mean=0.02 sigma=0.99
Run: ff, flux=362 e-/s, mean=-0.06 sigma=0.97	Run: ff, flux=99 e-/s, mean=-0.09 sigma=1.0
Run: ff, flux=246 e-/s, mean=0.08 sigma=0.96	Run: la, flux=209 e-/s, mean=0.2 sigma=0.97
Run: la, flux=550 e-/s, mean=0.14 sigma=0.98	Run: ff, flux=63 e-/s, mean=-0.0 sigma=1.0
Run: nl, flux=149 e-/s, mean=-0.29 sigma=0.92	Run: ff, flux=366 e-/s, mean=-0.04 sigma=1.02
Run: nl, flux=68 e-/s, mean=-0.02 sigma=0.98	Run: ff, flux=522 e-/s, mean=0.02 sigma=1.0
Run: ff, flux=319 e-/s, mean=-0.1 sigma=0.97	Run: ff2, flux=105 e-/s, mean=-0.03 sigma=0.95
Run: zph, flux=6 e-/s, mean=0.21 sigma=0.97	Run: la, flux=104 e-/s, mean=0.0 sigma=0.97

spectro



➤ No systematics observed with flux in a row runs
➤ Traps in steady state

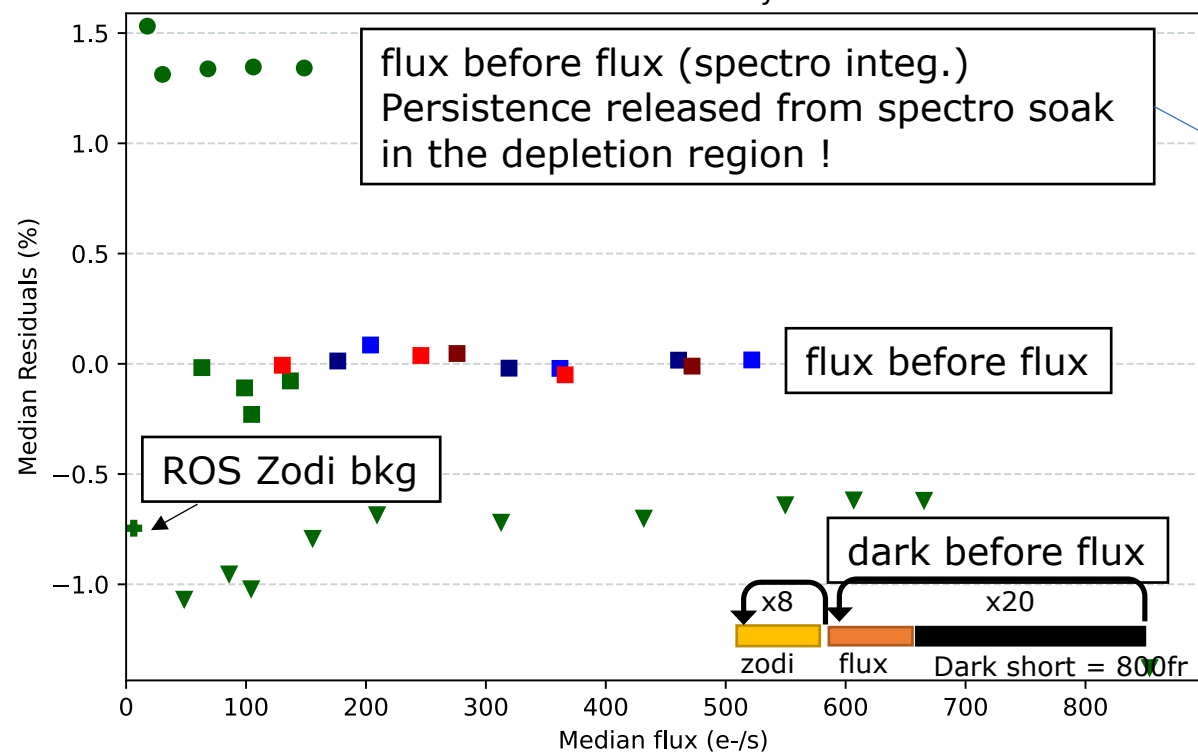
➤ sigma of the pull ~ 1

Run: flux & Pull mean, sigma

Run: nl, flux=18 e-/s, mean=-0.06 sigma=1.01	Run: xc, flux=154 e-/s, mean=0.01 sigma=0.97
Run: wsp, flux=6 e-/s, mean=0.07 sigma=0.94	Run: xc, flux=131 e-/s, mean=-0.03 sigma=0.94
Run: xc, flux=95 e-/s, mean=0.04 sigma=0.98	Run: xc, flux=8 e-/s, mean=-0.0 sigma=1.0
Run: nl, flux=145 e-/s, mean=0.02 sigma=1.06	Run: nl, flux=30 e-/s, mean=0.03 sigma=1.02
Run: xc, flux=49 e-/s, mean=0.07 sigma=0.99	Run: nl, flux=104 e-/s, mean=-0.02 sigma=1.04
Run: xc, flux=118 e-/s, mean=-0.02 sigma=0.97	Run: xc, flux=30 e-/s, mean=-0.06 sigma=0.94
Run: wsp, flux=26 e-/s, mean=0.35 sigma=0.96	Run: nl, flux=67 e-/s, mean=0.02 sigma=1.04
Run: zsp, flux=6 e-/s, mean=0.15 sigma=1.01	Run: xc, flux=76 e-/s, mean=0.07 sigma=0.96
Run: xc, flux=21 e-/s, mean=-0.07 sigma=1.0	

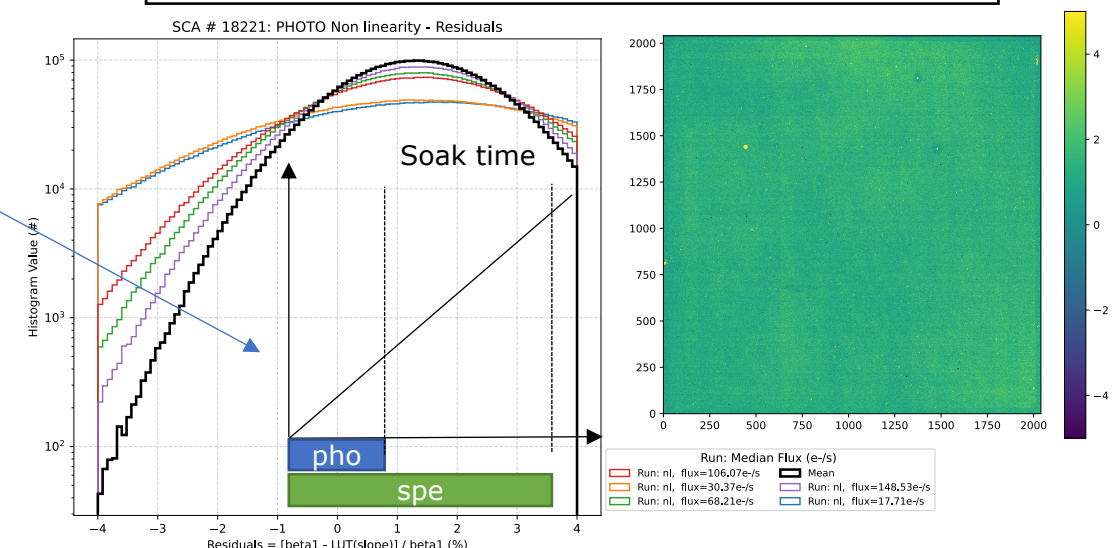
18221 : LUT applied on flux+dark sequences a low persistence SCA 18221

SCA # 18221: PHOTO Non linearity - Median Residuals

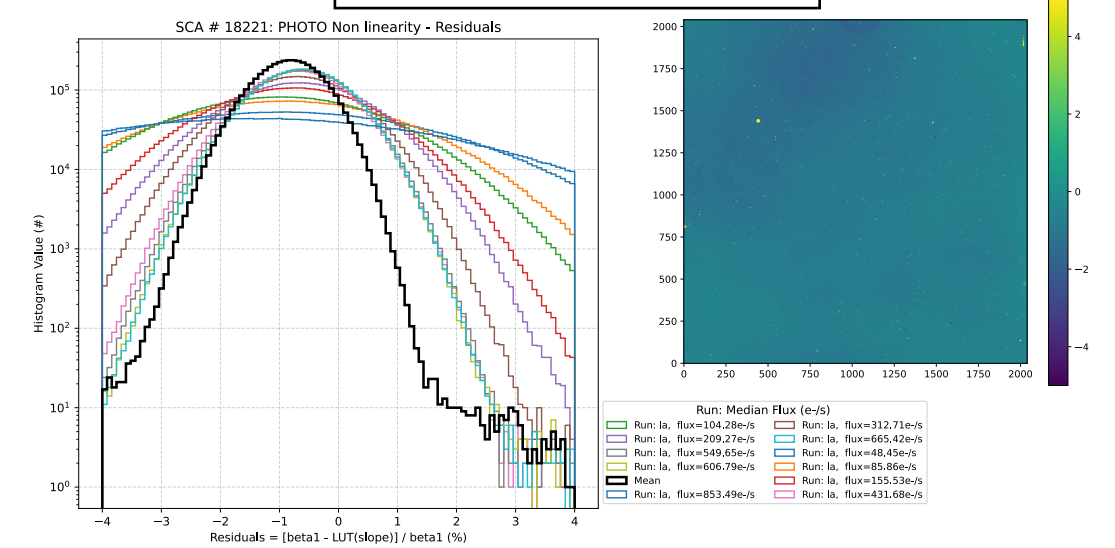


- Run, Led# and wl, Integration mode
- Run: ff, led1 930 nm, photo integration
 - Run: ff, led2 1150 nm, photo integration
 - Run: ff, led3 1440 nm, photo integration
 - Run: ff, led4 1720 nm, photo integration
 - Run: ff, led5 1980 nm, photo integration
 - Run: ff2, led3 1440 nm, photo integration
 - Run: zph, led3 1440 nm, Zodi level, dither sequence
 - ▼ Run: la, led3 1440 nm, with dark before
 - Run: nl, led3 1440 nm, spectro integration

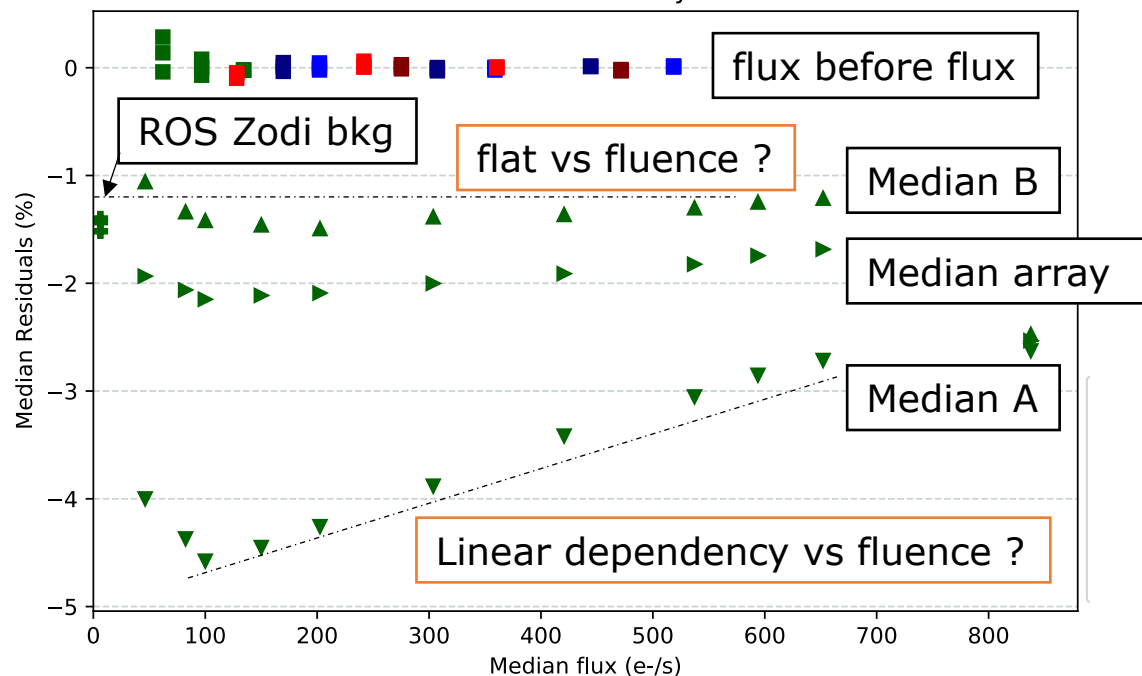
Spectro ramp used with photo LUT. +1.4%



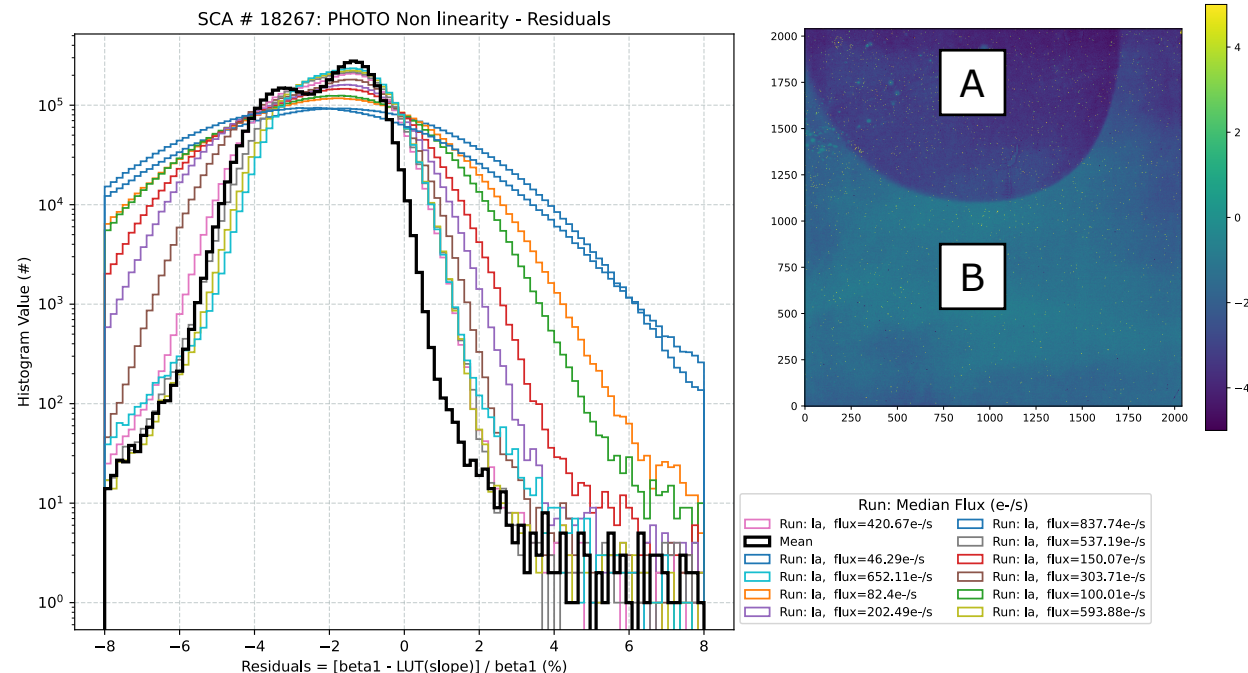
Flux + Dark => - 0.5%



SCA # 18267: PHOTO Non linearity - Median Residuals



Bimodal distribution



Run, Led# and wl, Integration mode
Run: ff, led1 930 nm, photo integration
Run: ff, led2 1150 nm, photo integration
Run: ff, led3 1440 nm, photo integration
Run: ff, led4 1720 nm, photo integration
Run: ff, led5 1980 nm, photo integration
Run: zph, led3 1440 nm, Zodi level, dither sequence
Run: la, led3 1440 nm, with dark before

Systematic error with dark before flux:

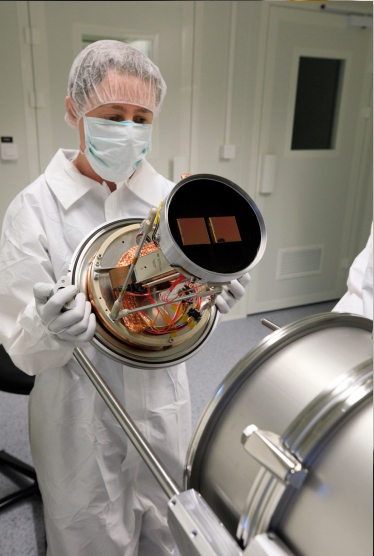
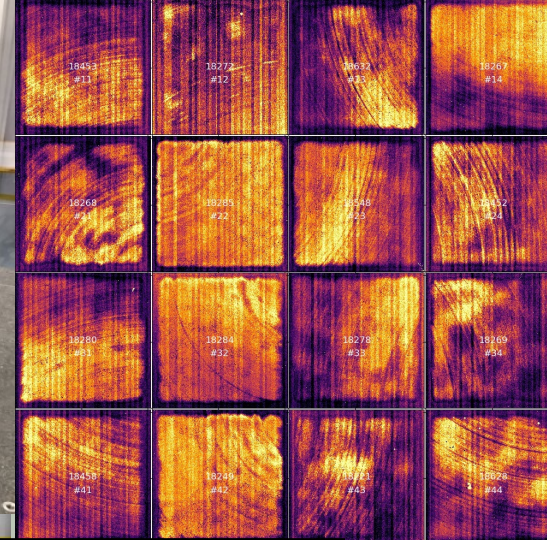
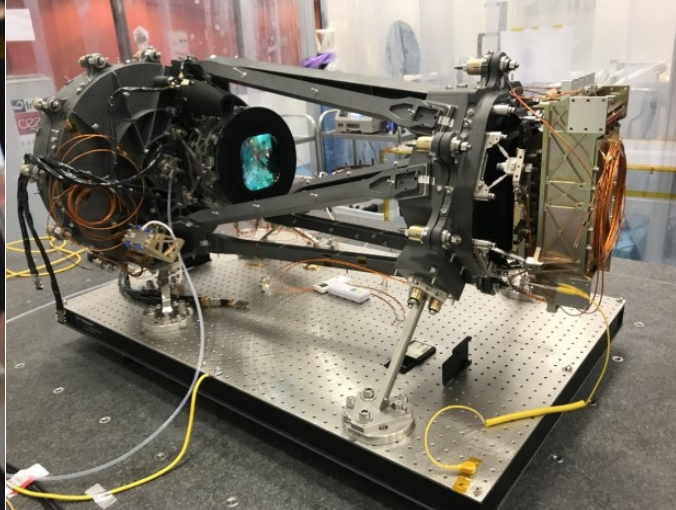
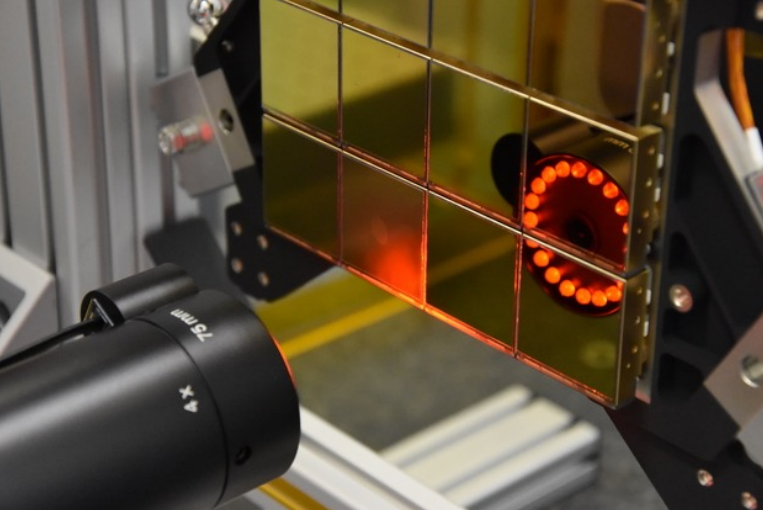
- -4% for high persistence region A /w positive slope vs flux ?
- -1% for regular persistence region B /w flat offset vs flux ?



Lesson Learned



- The 16 Euclid H2RGs work as expected in-flight
- Better to optimize the MACC mode on NL and Persistence correction than on Single SNR foM
- Test as in flight is a very challenging task for the Test flow with 2 possible strategies
 - Emulate the ROS with a all possible combination of illumination scenario and learn the response with a Big Data approach
 - Generate the "good" Cal blocks for pixel response modelling with V/V, e/V NL and Persistence ?
- Even with a low persistence H2RG, to reduce systematics below 1% can be challenging
 - The effect is not negligible but the effect is "clean"



Thank you

