Faithful Pulse Shape Analysis for Germanium Detectors using Feature Importance Supervision

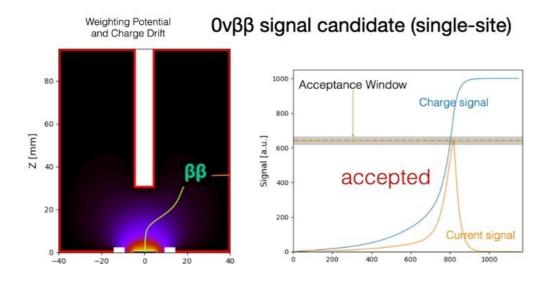
Katharina Kilgus 08/25/23 NPML 2023, Boston Large Enriched Germanium Experiment for Neutrinoless ββ Decay



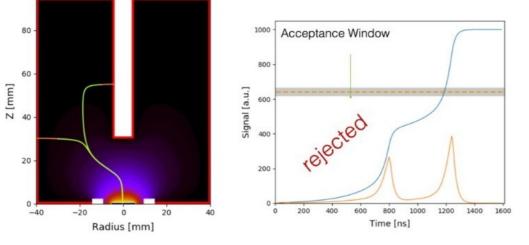


- Short about HPGe Detectors
- Pulse Shape Analysis (PSA)
- Feature Importance Supervision (FIS)
- Application to Germanium Signals
- Further possibilities by FIS

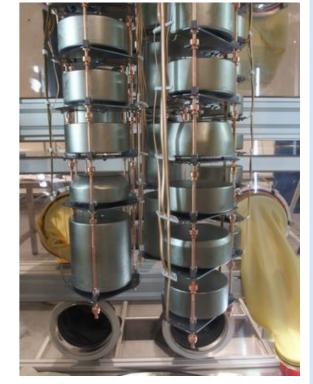
Short about HPGe Detectors



γ-background (multi-site)



- Good requirements for Pulse Shape Analysis
- Classic analysis is done by A/E



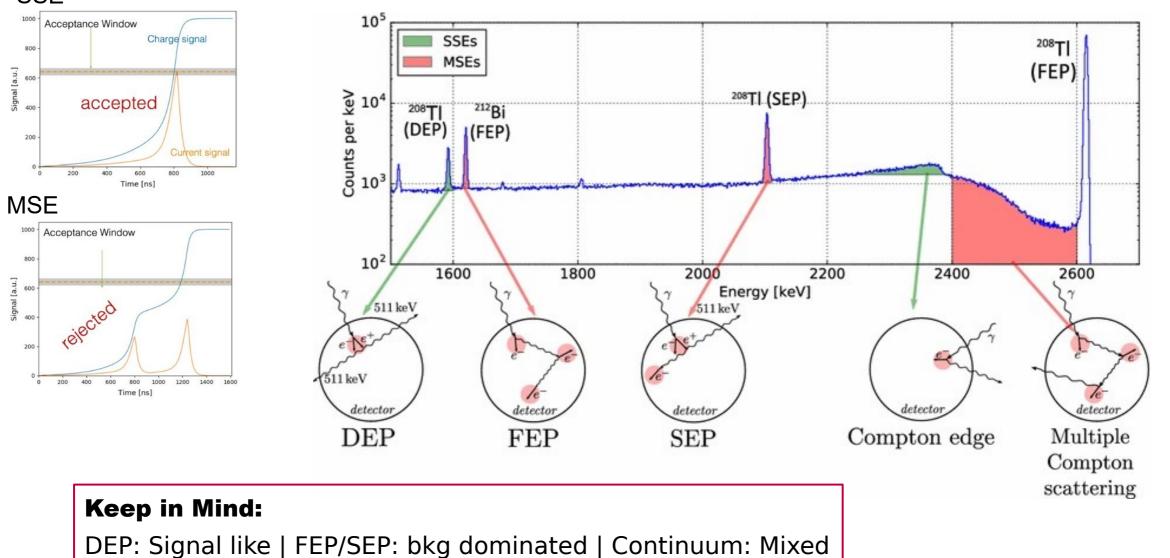
Main Task to keep in Mind:

Discriminate MSE (one backgroundtype) from SSE (signal-like)

Pulse Shape Analysis



SSE



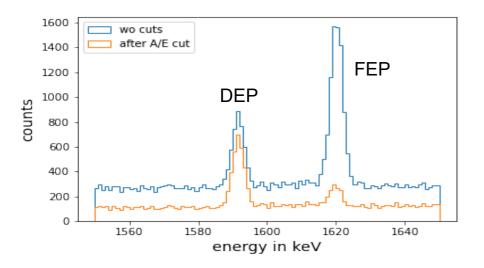
All peaks at different energies



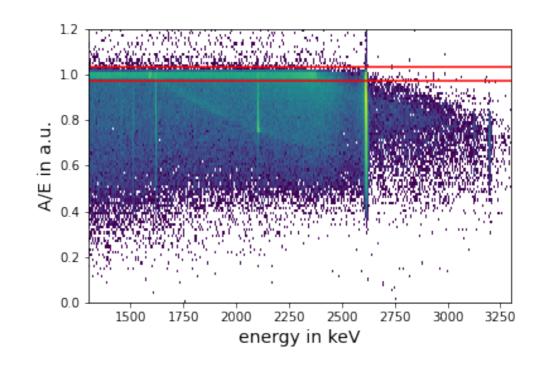
In General:

1. Determine some kind of classifier

2. Set cut on classifier at 90% survival fraction in DEP



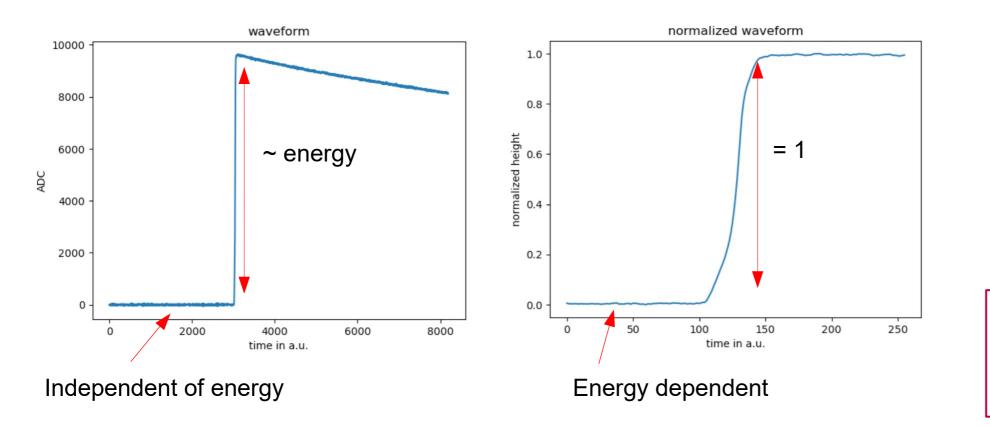
Classic A/E Analysis:



But does it work with Machine Learning too?

Waveform Energy Dependence





Keep in Mind: Baseline & tail contain energy information

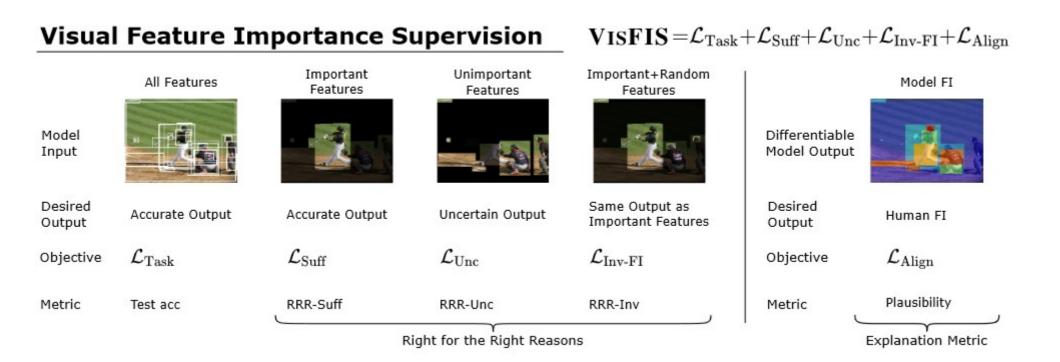
- Model can classify by using energy, not pulse shape
- Result shall be right for the right reasons

What's the idea behind Feature Importance Supervision (FIS?)

- Using human knowledge about important and unimportant features
- Lead the model to take right decisions

Visual Feature Importance Supervision





- VisFIS used for Visual Question Answering
- Use different variations of the input image
- Calculate a loss function for every variation
- Train with a combined loss function

https://arxiv.org/pdf/2206.11212.pdf

Zhuofan Ying, Peter Hase, and Mohit Bansal Department of Computer Science University of North Carolina at Chapel Hill

Visua	Feature In	portance Su	$\mathbf{VISFIS} \!=\!\! \mathcal{L}_{\mathrm{Task}} \!+\! \mathcal{L}_{\mathrm{Suff}} \!+\! \mathcal{L}_{\mathrm{Unc}} \!+\! \mathcal{L}_{\mathrm{Inv-FI}} \!+\! \mathcal{L}_{\mathrm{Align}}$			
	All Features	Important Features	Unimportant Features	Important+Random Features		Model FI
Model Input			😵		Differentiable Model Output	
Desired Output	Accurate Output	Accurate Output	Uncertain Output	Same Output as Important Features	Desired Output	Human FI
Objective	$\mathcal{L}_{\mathrm{Task}}$	$\mathcal{L}_{ ext{Suff}}$	$\mathcal{L}_{ ext{Unc}}$	$\mathcal{L}_{ ext{Inv-FI}}$	Objective	$\mathcal{L}_{ ext{Align}}$
Metric	Test acc	RRR-Suff	RRR-Unc	RRR-Inv	Metric	Plausibility
			TO REAL REAL COMMONSTRATION			1 (C) (C)

Right for the Right Reasons

50

100

150

200

Explanation Metric

250

All Features 1.0 0.8 Adaption to Ge Signals 0.6 0.4 0.2 0.0

Goal: Given the full task input, the model shall return an accurate output.

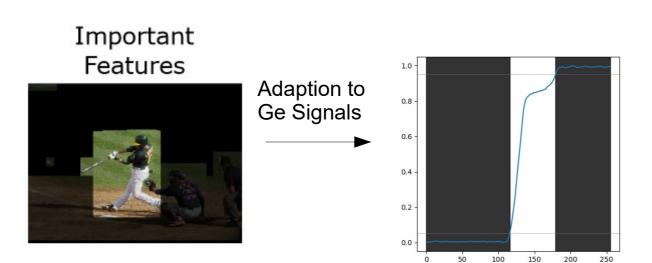
Method: Feed into model and train model by using known label y.

 $\mathcal{L}_{\mathrm{Task}}$

Accurate Output

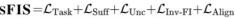


Visua	l Feature Ir	nportance Si	pervision	$VISFIS = \mathcal{L}_{Task}$	$+\mathcal{L}_{ ext{Suff}}+\mathcal{L}_{ ext{Unc}}$
	All Features	Important Features	Unimportant Features	Important+Random Features	Ĩ
Model Input					Differentiable Model Output
Desired Output	Accurate Output	Accurate Output	Uncertain Output	Same Output as Important Features	Desired Output
Objective	$\mathcal{L}_{\mathrm{Task}}$	$\mathcal{L}_{ ext{Suff}}$	$\mathcal{L}_{ ext{Unc}}$	$\mathcal{L}_{ ext{Inv-FI}}$	Objective
Metric	Test acc	RRR-Suff	RRR-Unc	RRR-Inv	Metric
		R	ight for the Right Reaso	ons	



Accurate Output

$\mathcal{L}_{ ext{Suff}}$



Model FI

Human FI

 $\mathcal{L}_{\mathrm{Align}}$

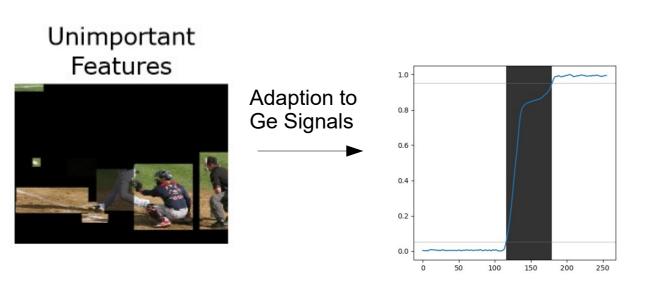
Plausibility Explanation Metric

Goal: Subset of input containing the important features shall be sufficient to produce accurate output.

Method: Feed into model and train model by using known label y (as with the original input)

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Visual	Feature In	nportance Su	$\mathbf{VISFIS}\!=\!\!\mathcal{L}_{\mathrm{Task}}\!+\!\mathcal{L}_{\mathrm{Suff}}\!+\!\mathcal{L}_{\mathrm{Unc}}\!+\!\mathcal{L}_{\mathrm{Inv-FI}}\!+\!\mathcal{L}_{\mathrm{Align}}$			
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Metric	Test acc	RRR-Suff	RRR-Unc	RRR-Inv	Metric	Plausibility
Right for the Right Reasons						r Explanation Metric



Uncertain Output

 $\mathcal{L}_{ ext{Unc}}$

just unimportant features shall result in total uncertainty.

Method: Feed into model and train model by using a random number as label.

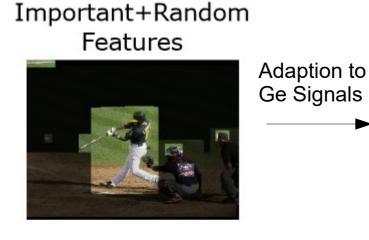
 $\mathcal{L}_{\text{Unc}}(\theta, x, e) = \text{KL}\big(\text{Unif}(|\mathcal{Y}|), f_{\theta}(x_u)\big)$



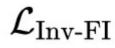
Goal: Subset of input containing

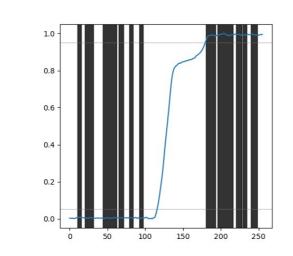
08/25/23

Visual Feature Importance Supervision				$\underline{\mathbf{VISFIS}} \!=\!\! \mathcal{L}_{\mathrm{Task}} \!+\! \mathcal{L}_{\mathrm{Suff}} \!+\! \mathcal{L}_{\mathrm{Unc}} \!+\! \mathcal{L}_{\mathrm{Inv-FI}} \!+\! \mathcal{L}_{\mathrm{Align}}$			
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		R	ight for the Right Reas	ons		Explanation Metric	



Same Output as **Important Features**





Goal: Model shall be invariant under important features + random sampling of unimportant features.

Method: Using input with important and unimportant features, train to same result as just with important input.

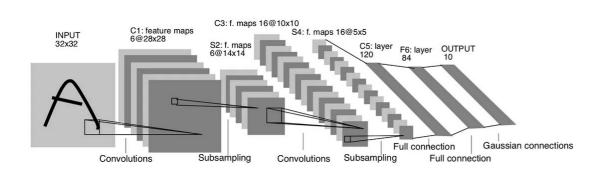
 $\mathcal{L}_{\text{Inv-DA}}(\theta, x, e, \mathcal{D}_u) =$ $\mathbb{E}_{u \sim \mathcal{D}_u} \operatorname{KL}(f_{\theta}(x_e), f_{\theta}(x_{e \cup u}))$



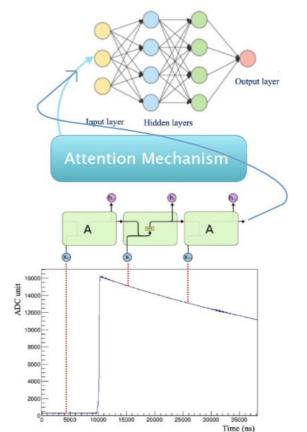
CNN & RNN+attention model



- CNN:
 - Necessary to calculate vanilla gradient as explanation metric

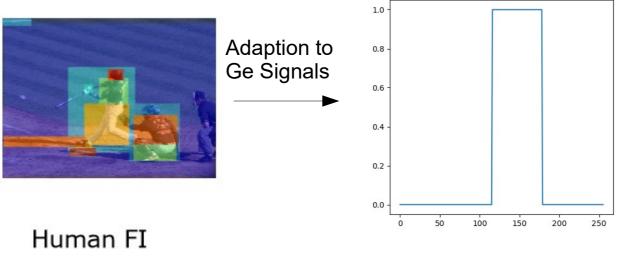


- RNN+attention:
 - Attention score intrinsic to model, leads direct to explanation metric



Visua	Feature I	mportance S	upervision	$VISFIS = \mathcal{L}_{Task}$	$+\mathcal{L}_{ ext{Suff}}+\mathcal{L}_{ ext{Unc}}$	$+\mathcal{L}_{ ext{Inv-FI}}+\mathcal{L}_{ ext{Align}}$
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Metric	Test acc	RRR-Suff	RRR-Unc	RRR-Inv	Metric	Plausibility
		Ri	r ight for the Right Reas		۲ Explanation Metric	

Model FI



 $\mathcal{L}_{\mathrm{Align}}$

Goal: Want an alignment between human and model feature importance.

Method: Train model to result explanation metric e of the model having the same shape as human explanation \bar{e} .

Explanation Metric:

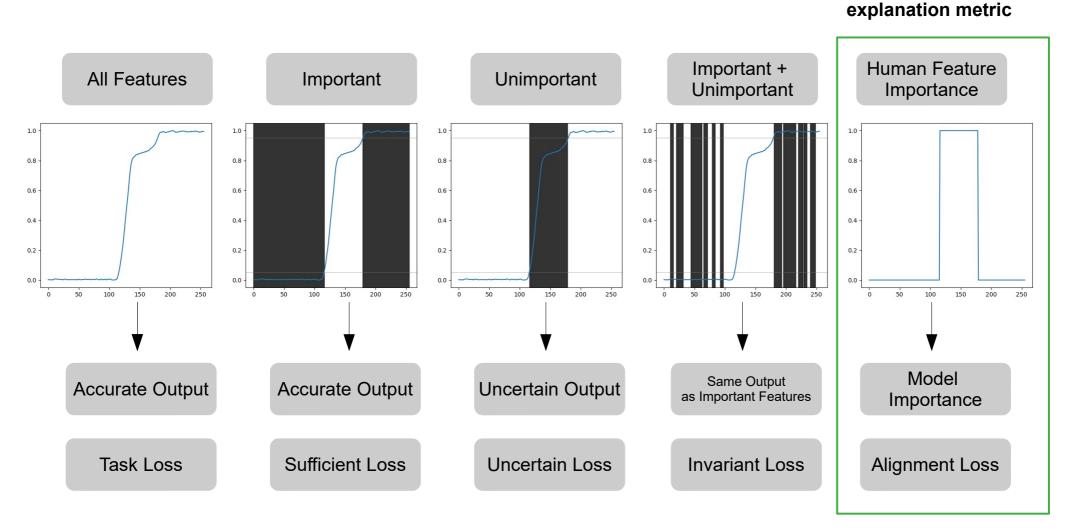
 Vanilla Gradient for CNN
Attention score for RNN+attention

 $\mathcal{L}_{align}(\theta, x, e, \tilde{e}) = cos-sim(e, \tilde{e})$

Overview about FIS model



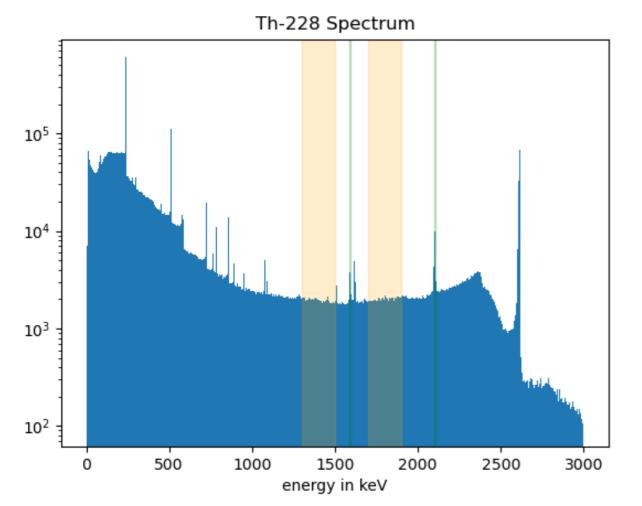
About the



Add all together

►





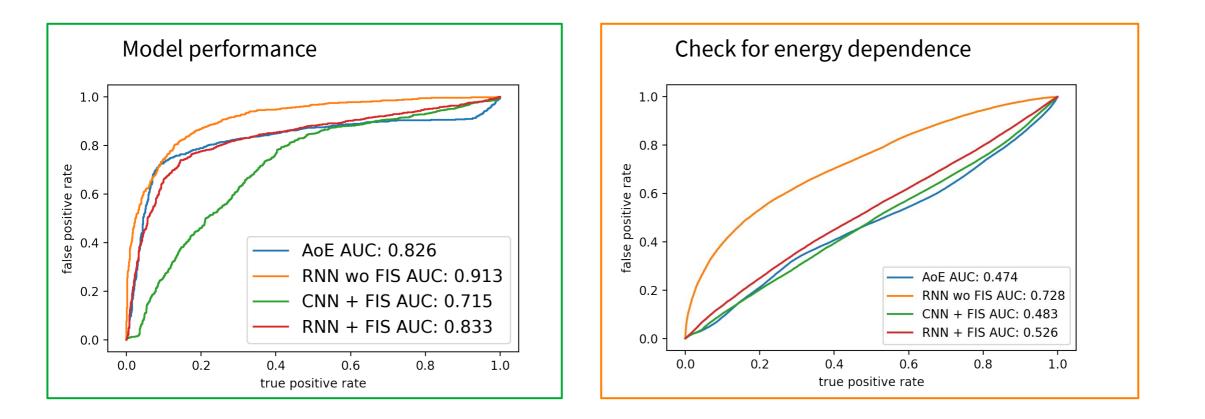
- Using characterization measurements
- Compare 4 Versions:
 - A/E as non-ML analysis
 - RNN wo FIS
 - CNN as a basic model
 - RNN+attention as an advanced model

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a) training peaks (DEP as signal type, SEP as bkg type)b) check for energy dependence

Classification power



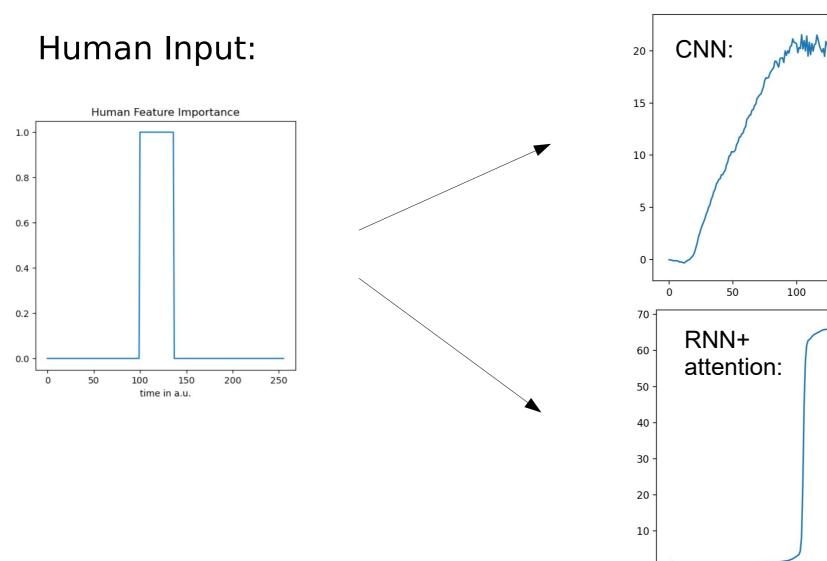


 \rightarrow models with FIS are energy independent

 \rightarrow RNN + FIS seem to perform very well

Training results of FIS



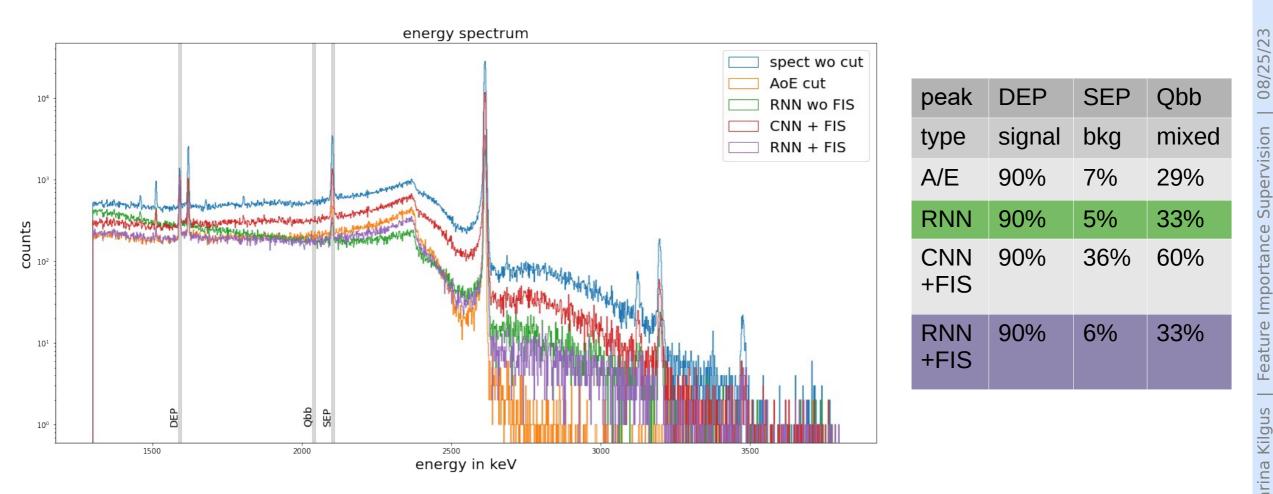


Machine Output:



Spectrum after cuts

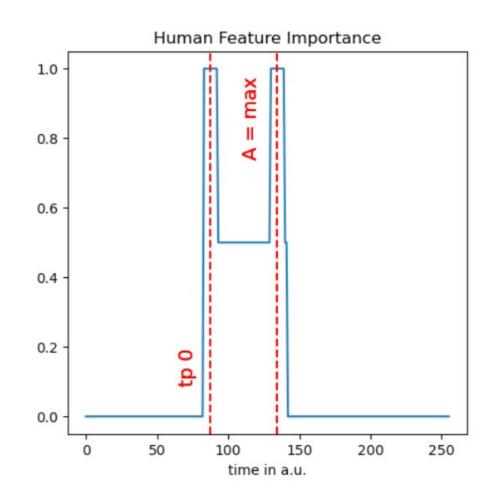




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Further possibilities by FIS

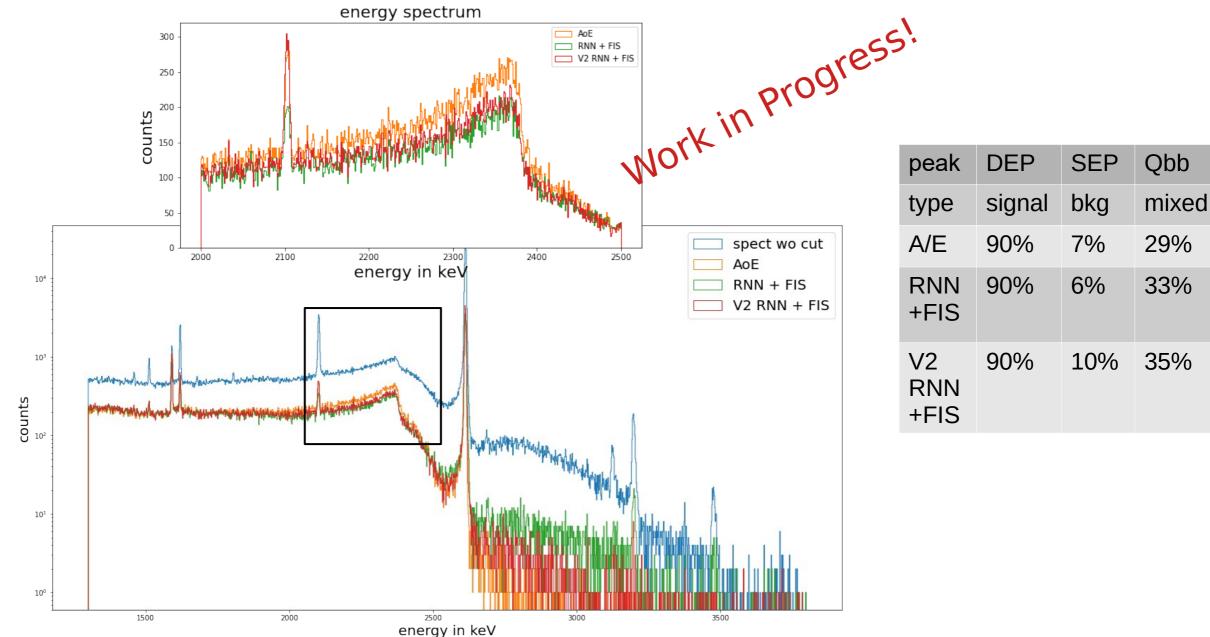
- Adding more physical knowledge
 - Starting point
 - Point of maximal A
 - ...?
- 2nd version of Human FI
- Other versions possibles





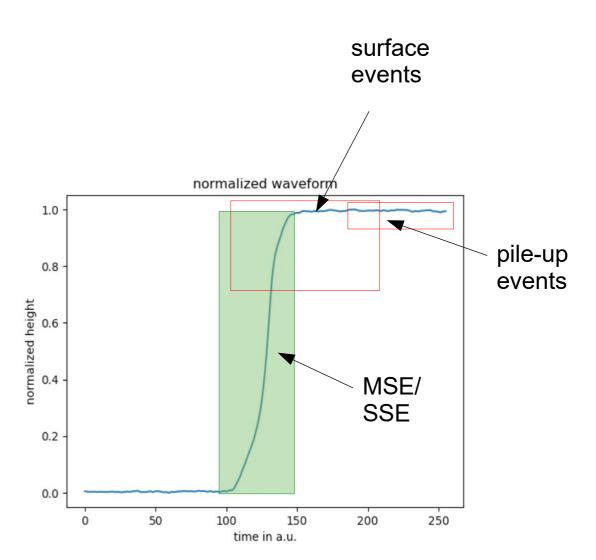
Further possibilities by FIS





Further possibilities by FIS

- Use FIS for other PSA tasks
- Focussing on different part of the waveform, depending on the task
 - Surface events (alphas, betas)
 - Pile-up events
 - Position reconstruction





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23

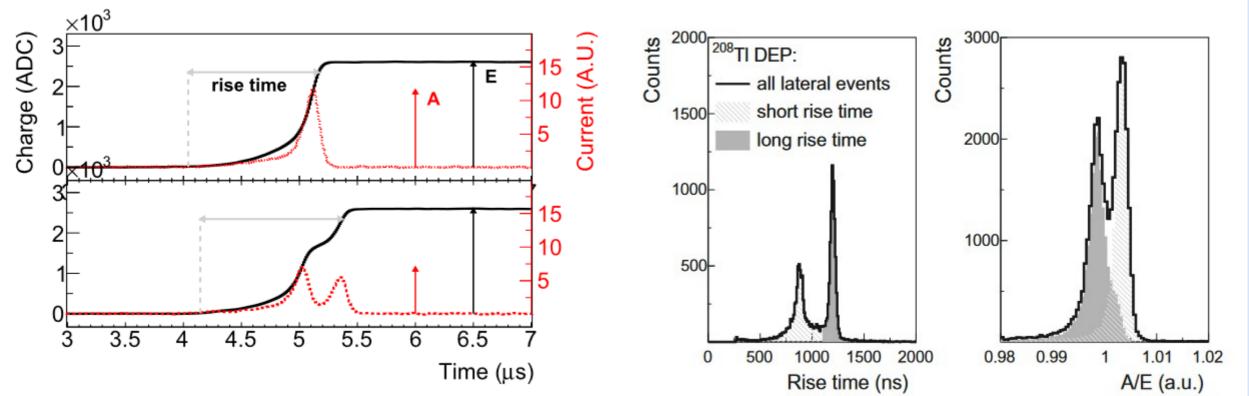
Summary

- Possible to remove energy dependence
- RNN better than CNN
- RNN+FIS close to A/E
- Still some differences to investigate
- Further steps:
 - Check behaviour in compton shoulder
 - Investigate model performance on low-background physics data
 - FIS for other classes of events



Rise time

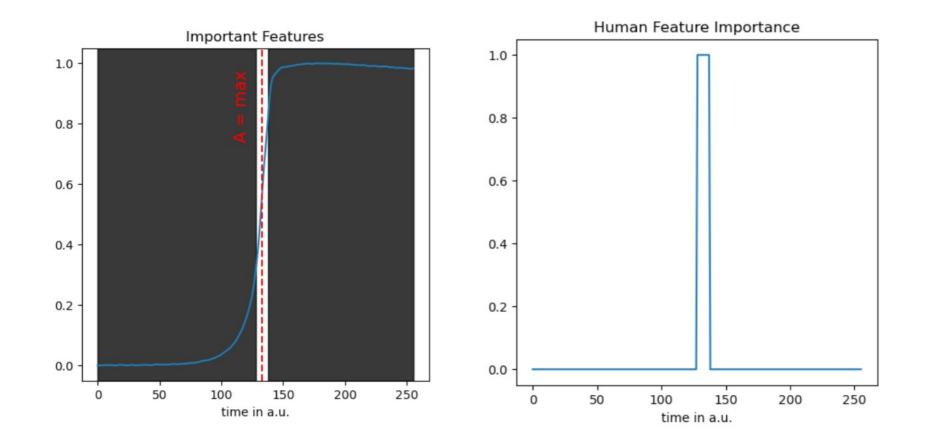




- https://doi.org/10.1140/epjc/s10052-021-09184-8
- Depends on position inside detector (short RT close to p+ contact)

Backup





Backup

10

8

4 -

2 -

0

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50

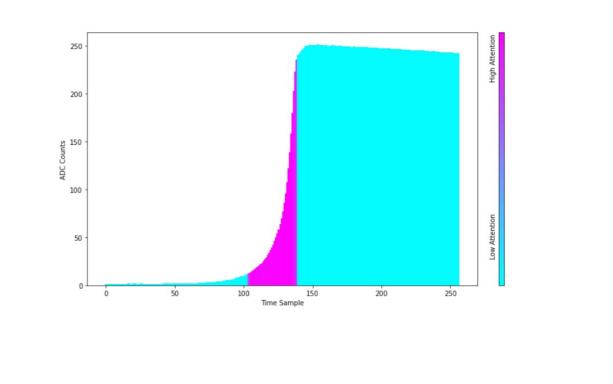
100

150

Time Sample

ADC Counts





High Attention

Low Attention

250

200