

# Simulation of the multi-view imaging system with differentiable ray tracing

Maxime Vandegar, Michael Kagan

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# Photon mapping (rays from cloud to sensor)



- A high-level API is available.

## API

```
from magis.main_helpers import make_scene, make_image, show_views
scene = make_scene(object_x_pos=0.31, f=0.05, m=0.15, nb_mirror=500)
image = make_image(scene, object_x_pos=0.31, device='cuda:0', nb_rays=int(1e9), batch_size=int(50e6))
show_views(image.data.cpu(), scene, nb_img_per_row=10, nb_img_per_column=10, save_path=None, do_show=True)
```

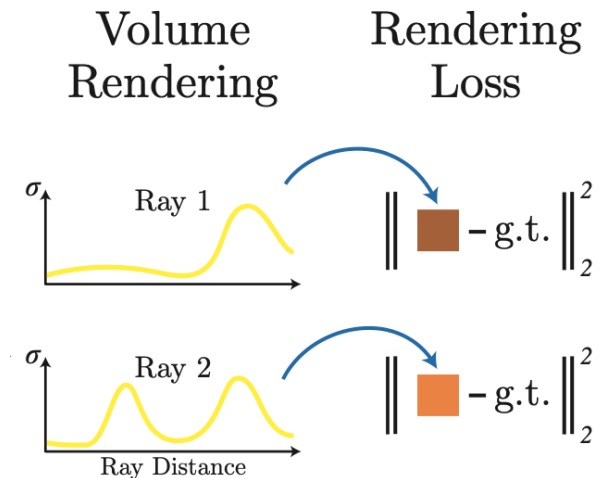
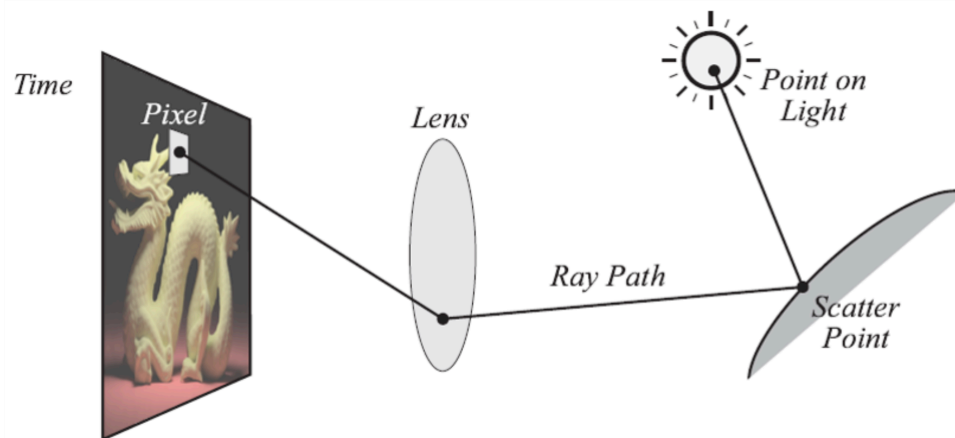
- Generating an image takes ~10minutes on a single GPU.
  - Can be reduced to ~1minute with simple optimization.
- The code is stored on a private GitHub repository.
  - Shall we think about storing it elsewhere?

# Photon mapping (rays from cloud to sensor)

-  Simulation & simulation-based inference.
  - Useful to simulate realistic images.
  - Can be used with simulation-based inference algorithms to learn  $p(\phi|d)$ .
  - Can be used to generate a dataset of pairs  $\{\phi_i, d_i\}$ .
-  3d reconstruction.
  - Some operations are not naturally differentiable.
    - E.g `img[int(hit_position / pixel_size )] += 1`.
  - $A(\cdot)$  is a mapping from a batch of rays to an image.
    - Many rays are required for the image to be statistically significant  $\rightarrow$  large memory footprint.

# Ray marching (rays from sensor to cloud)

- Naturally differentiable.
- Allows to query the value of a single pixel.
- In general, more efficient.
  - Approach used in computer graphics.



- Photon mapping:
  - Spacial-based optimization:
    - A first attempt at solving  $\|A(x) - b\|^2$  did not work.
    - Many things can go wrong.
    - Dozens of diagnostics can be run.
    - → Putting aside, not a priority at the moment.
  - Density-based optimization:
    - Optimizing the ray luminosities is better defined in terms of gradients.
    - → Under progress.
- Ray marching:
  - → Under progress.