Differentiable Ray Tracing Simulator

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- Written in JAX (<u>Autograd</u> & <u>XLA</u>).
 - <u>Autograd</u>:
 - Automatically differentiates native Python and Numpy code.
 - Main purpose: gradient-based optimization.
 - <u>XLA</u>:
 - Compiles and runs programs on CPUs, GPUs and TPUs (fused operations).
- Functional programming paradigm.
- Numpy (Python library) like syntax.
- Automatic parallelization & vectorization.
- Differentiability could also be used for design optimization.

Preliminary results

- Imaging a cloud with a Gaussian density.
 - Tracing one ray at a time takes a few hours (1e6 rays).
 - It takes a few seconds after automatic vectorization.



Next steps

- Short-term goals:
 - Replace the gaussian density with a reallistic interference pattern.

$$N \times f_{\gamma} \times \left[1 + Cos\left(\frac{2\pi}{\lambda}x + \phi\right)\right] \times \frac{1}{\sigma} e^{-\frac{1}{2}\left[\frac{x-\mu}{\sigma}\right]^2}$$

- Prepare the simulator for inference & 3D reconstruction.
 - Make sure that the gradients flow correctly.
 - Optimize the system so that images can be produced in a few seconds.

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