



Software Update

Online HPS Collaboration Meeting.

May 14, 2020

Outline

- ❖ Current status.
- ❖ Priorities
- ❖ Recent decision that impact software use.
- ❖ Lowering barriers: Docker

Status of the software

❖ The entire software chain works well for 2015 & 2016 analysis.

❖ Yes, there are always more improvements possible / desirable...

❖ Development cycle has been fairly smooth.

❖ Most “pull requests” are merged fairly quickly.

❖ reviewers have generally given good feedback.

❖ Many current issues are actively resolved.

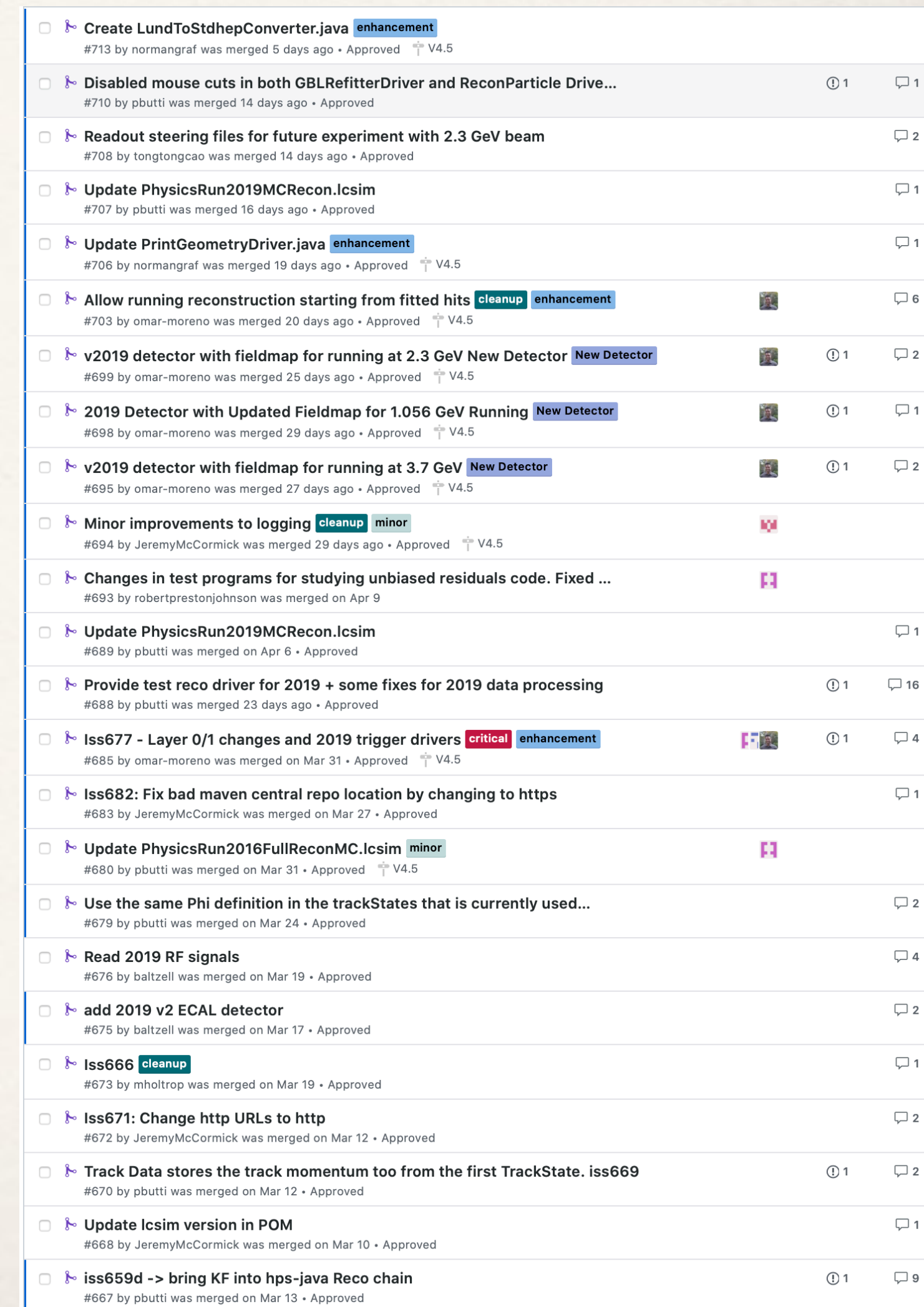
❖ but there is a big old list of old ones we should address.

❖ Recent updates

❖ Some larger changes.

❖ Many small changes.

❖ Probably time for a release soon.



A screenshot of a GitHub pull request list. The list contains 20 entries, each with a title, author, merge date, and status. The entries are as follows:

Issue Title	Author	Merge Date	Status
Create LundToStdhepConverter.java	normangraf	5 days ago	Approved
Disabled mouse cuts in both GBLRefitterDriver and ReconParticle Drive...	pbutti	14 days ago	Approved
Readout steering files for future experiment with 2.3 GeV beam	tongtongcao	14 days ago	Approved
Update PhysicsRun2019MCRecon.lcsim	pbutti	16 days ago	Approved
Update PrintGeometryDriver.java	normangraf	19 days ago	Approved
Allow running reconstruction starting from fitted hits	omar-moreno	20 days ago	Approved
v2019 detector with fieldmap for running at 2.3 GeV New Detector	omar-moreno	25 days ago	Approved
2019 Detector with Updated Fieldmap for 1.056 GeV Running New Detector	omar-moreno	29 days ago	Approved
v2019 detector with fieldmap for running at 3.7 GeV New Detector	omar-moreno	27 days ago	Approved
Minor improvements to logging	JeremyMcCormick	29 days ago	Approved
Changes in test programs for studying unbiased residuals code. Fixed ...	robertprestonjohnson	merged on Apr 9	Approved
Update PhysicsRun2019MCRecon.lcsim	pbutti	merged on Apr 6	Approved
Provide test reco driver for 2019 + some fixes for 2019 data processing	pbutti	merged 23 days ago	Approved
Iss677 - Layer 0/1 changes and 2019 trigger drivers	omar-moreno	merged on Mar 31	Approved
Iss682: Fix bad maven central repo location by changing to https	JeremyMcCormick	merged on Mar 27	Approved
Update PhysicsRun2016FullReconMC.lcsim	pbutti	merged on Mar 31	Approved
Use the same Phi definition in the trackStates that is currently used...	pbutti	merged on Mar 24	Approved
Read 2019 RF signals	baltzell	merged on Mar 19	Approved
add 2019 v2 ECAL detector	baltzell	merged on Mar 17	Approved
Iss666	mholthrop	merged on Mar 19	Approved
Iss671: Change http URLs to http	JeremyMcCormick	merged on Mar 12	Approved
Track Data stores the track momentum too from the first TrackState. iss669	pbutti	merged on Mar 12	Approved
Update lcsim version in POM	JeremyMcCormick	merged on Mar 10	Approved
iss659d -> bring KF into hps-java Reco chain	pbutti	merged on Mar 13	Approved

Status of the software

- ❖ For 2019 data, some critical updates were needed.
 - ❖ Implement code for MC readout of L0 & L1 SVT layers. ✓ (Omar)
 - ❖ Create 2019 versions of detector. ✓
 - ❖ Evio readers for Hodoscope and RF ✓
 - ❖ Trigger simulation & analysis - ★ **Not finished.** (Tongtong)
 - ❖ + all the things that were done before the run ✓✓✓!
- ❖ Lots of bugs fixed in this process.
- ❖ Big leaps forward:
 - ❖ Kalman Filter + seed finder (Robert + PF)
 - ❖ Still needs finishing touches and further testing but looks very promising.
 - ❖ Improvement in analysis tools, “hpstr” (Cameron + PF)
 - ❖ This will be ongoing, see presentation 2nd after this one.

Priorities

❖ **Top Priorities:**

- ❖ Finish 2019 calibrations.
 - ❖ Code changes, bug fixes, needed for 2019 calibration, alignment, production reconstruction.
 - ❖ Eg - immediately fix the $(-x,-y)$ missing ECal hits.
- ❖ Get started on 2019 MC production. Next presentation. (Tongtong)
 - ❖ Code changes, bug fixes, needed for 2019 MC production.
 - ❖ Convert MC production chain into clear recipes.
- ❖ Trigger simulation & analysis code. (Tongtong)
- ❖ Beam background merging. (Cameron? + Kyle?)
- ❖ WAB biassing in MC (Omar)
- ❖ Finish Kalman Filter + seed finder (Robert + PF)
 - ❖ Plus all the tracking studies associated with this: tracking efficiency, etc.

Priorities

❖ Other Priorities:

- ❖ Improve MC - Data agreement accuracy.
- ❖ Optimizations for code speedup:
 - ❖ Early cutting of bad events.
 - ❖ Pulse fitting improvements.
 - ❖ Other code optimization.
- ❖ Run MC chain on OSG.
- ❖ Documentation:
 - ❖ We need to keep improving the docs!

C++17 and ldmx-sw

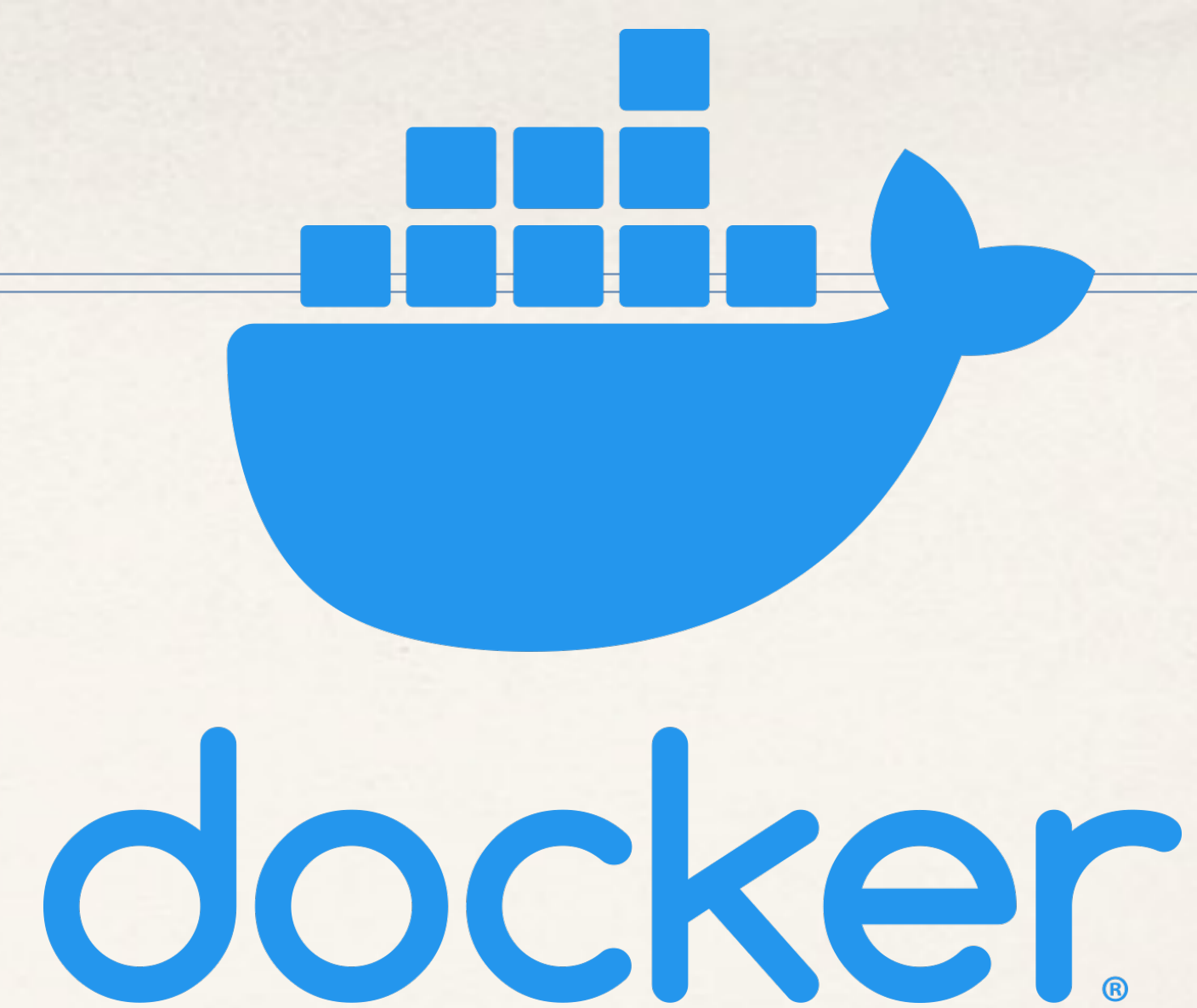


❖ Move MC detector simulation to ldmx-sw

- ❖ To accommodate Omar implementing the WAB biasing code, a decision was made to go from SLIC to ldmx-sw (instead of hps-sim).
- ❖ Many of the other required changes to ldmx-sw to become HPS compatible were already implanted (Cameron and Omar).
- ❖ This will require some validation (but no more than for hps-sim).

❖ The “hpstr” development moves to C++17 level compilers.

- ❖ Ubuntu 18.04 (gcc 7) and 20.04 (gcc 9), Centos 8 (gcc 8 or 9) and MacOS (clang) are already c++17 compatible.
- ❖ ldmx-sw also requires C++17, so we need it there anyhow.
- ❖ For Centos 7 (gcc 4.8): We will need to make use of a newer compiler, compile root, lcio, hpstr with it.
 - ❖ We may need / want to update the LCIO headers.



❖ What is Docker?

- ❖ Not quite a Virtual Machine, not quite an application: Containerization.
- ❖ Containerization: Wrap your application with a very much reduced operating system into a single purpose image that can now run anywhere.
- ❖ Benefits: Easy to ship!
- ❖ Using a Docker images makes it very easy to run HPS software on your local machine (laptop, desktop, server).
 - ❖ Everything you need comes in a single downloaded container.
 - ❖ All your computer resources (cpu's, memory, disk) are accessible to the container.
 - ❖ The image is much smaller than a virtual machine "disk".
 - ❖ When running, the image does not load your computer as much as a virtual machine.
 - ❖ Images can easily be deployed on "the cloud" (Azure, AWS, OSG, ...)

Docker and hpstr

Simplistic example of using docker locally.

Start a docker container (run)
Translate port 22 (ssh) to 2222

Bind my home directory to
that of the “hps” user: the home
directory on my system is now
mounted at /home/hps in Docker.

Get the image: maurik/ubuntu_hps_hpstr
If it is not already on my system, it will download.
Run it in the background (-d instead of -i)
Cleanup when I am done (--rm)

```
> docker run -p 2222:22 -v /Users/maurik:/home/hps --rm -d maurik/ubuntu_hps_hpstr
```

```
> ssh -Y hps@localhost -p 2222  
password: hps
```

Connect to docker with ssh -Y, so X11 is forwarded, to
port 2222 as user “hps” (password is also “hps”)

```
hps@09d9b0108889 ~$ pwd  
/home/hps  
hps@09d9b0108889 ~$ root
```

My home directory is now at “/home/hps”.
File permissions are translated automatically.

gcc/g++, ROOT, LCIO and hpstr are pre-installed
(but nothing else!)

From here you can do analysis as if you were
running an app on your machine.
(Entire home directory tree visible to app)

```
-----  
| Welcome to ROOT 6.20/05                               https://root.cern |  
| (c) 1995-2020, The ROOT Team; conception: R. Brun, F. Rademakers |  
| Built for linuxx8664gcc on May 09 2020, 10:59:00      |  
| From heads/v6-20-00-patches@v6-20-04-49-gc916bee956  |  
| Try '.help', '.demo', '.license', '.credits', '.quit'/'.'q' |  
-----
```

```
root [0] R__LOAD_LIBRARY(libevent)  
root [1] auto *evt = new EventHeader()  
(EventHeader *) 0x558a82e89290  
root [2]
```

No changes to the operating system are persisted!

Docker

- ❖ **Current available container: maurik/ubuntu_hps_hpstr**
 - ❖ Based on Ubuntu 20.04, with gcc 9
 - ❖ All development library for building root, lcio and hpstr.
 - ❖ root v6.20, lcio and hpstr (current master) pre-installed in /usr/local
- ❖ **Work in progress.**
 - ❖ I need testers!
 - ❖ Because the container cannot be modified, it cannot be corrupted.
 - ❖ BUT, if you want to add/subtract something, you make a new image.
 - ❖ You would want to try to keep the image as small as reasonable, rather than add everything you might possibly need.
- ❖ **Next:**
 - ❖ Adapt the MC chain to Docker containers for off site running (OSG).
 - ❖ Put recipes up on GitHub and write documentation.
 - ❖ Include documentation on how you can customize your containers.

Conclusions

- ❖ A lot got done
 - ❖ A lot of critical tasks have been completed.
- ❖ A lot more needs doing
 - ❖ Some larger tasks have been talked about for long time.
 - ❖ Many smaller tasks, ongoing.