

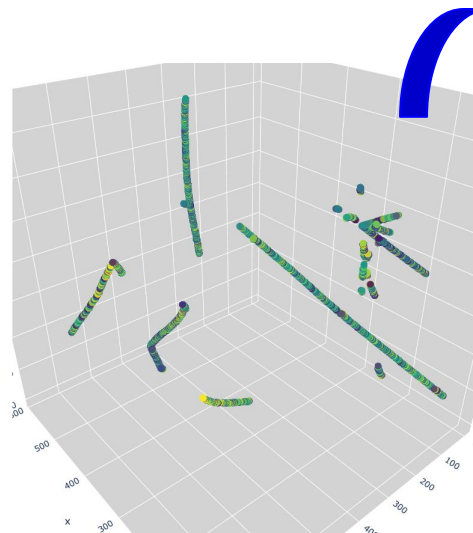
Interaction clustering in Liquid Argon Time Projection Chamber using Graph Neural Network

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on behalf of DeepLearnPhysics collaboration

June 19th

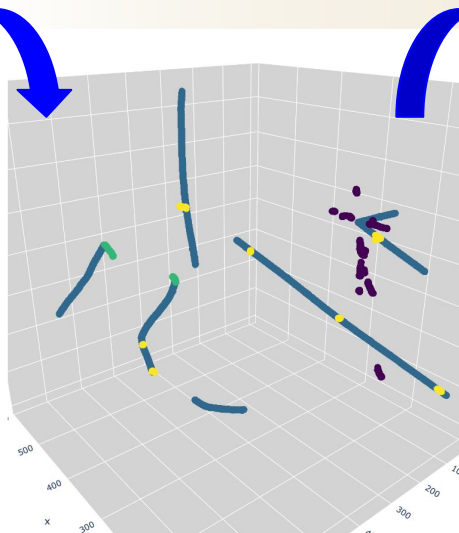
Recap on Recon. Framework (Simplified)



Input:

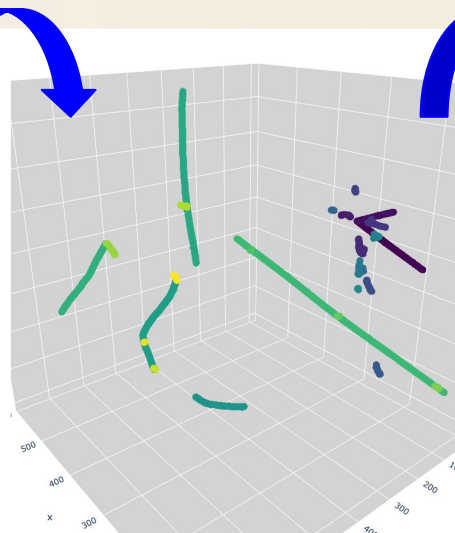
3D image with depth of 1 (energy dep. or charge)

[arXiv: 1903.05663](https://arxiv.org/abs/1903.05663)
doi.org/10.5281/zenodo.1300713



Step 1:

Semantic Segmentation & Point Proposal

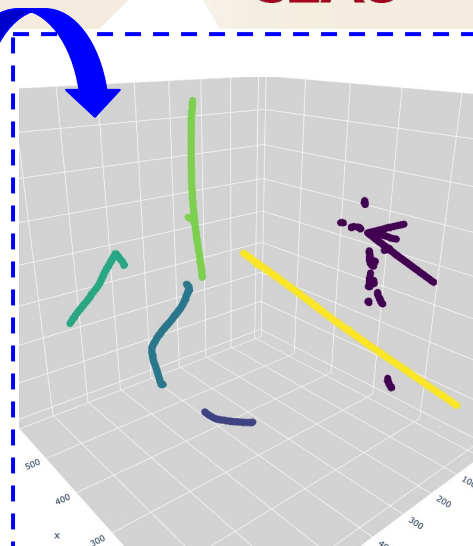


Step 2:

Cluster fragments into particle groups

Step 1.5:

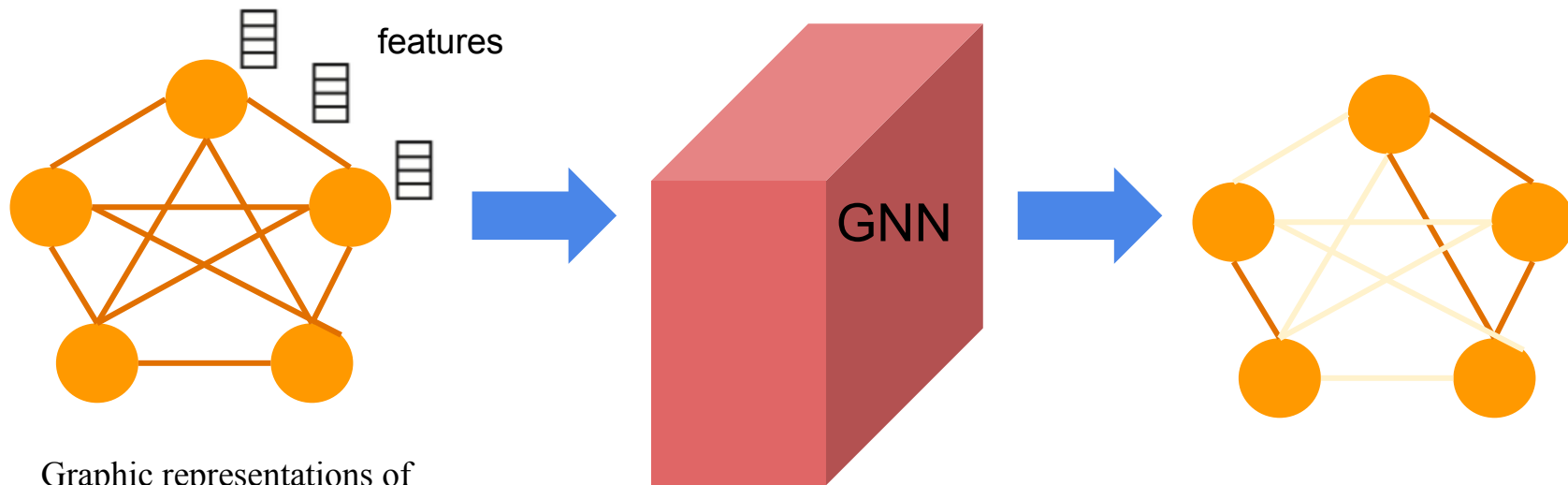
Dense clustering



Step 3:

Cluster particle groups into interaction groups (this presentation)

Interaction clustering



- Graphic representations of particle groups.
- **Node** presents each particle group, and **edge** (connection between two nodes) represents two particle correlation.
- Use Graph Neural Network (GNN) available on market for predicting the edge on/off.
- Currently used GNN is kernel-based convolution operator (`torch.geometric.nn.NNConv`).
- Based on edge prediction, the interaction clustering can be interpreted.

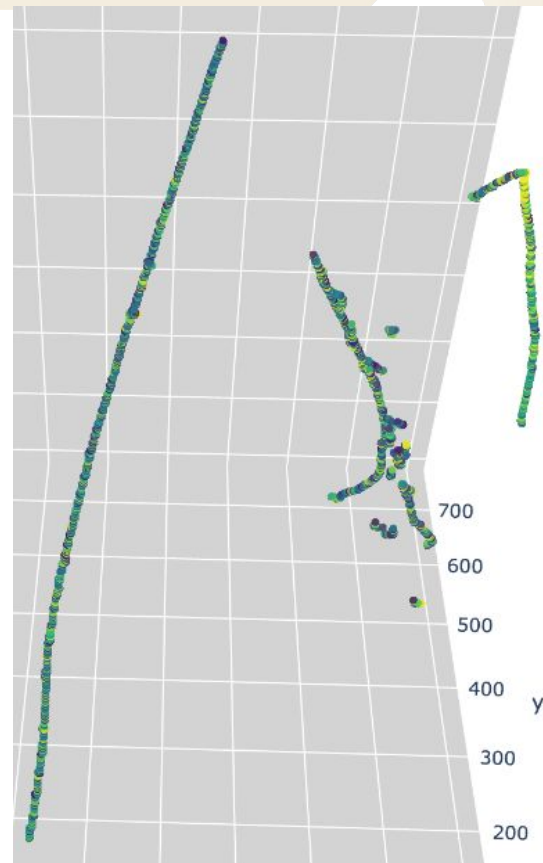
Node & Edge Features (baseline model)

Basic node features (28):

- (1) Size (number of voxels)
- (9) Covariance matrix
- (3) Principle axis
- (3) Particle group centroid
- (2) Energy dep. mean & std
- (1) Largest-fraction semantic type of particle group
- (6) Start & end point
- (3) Direction

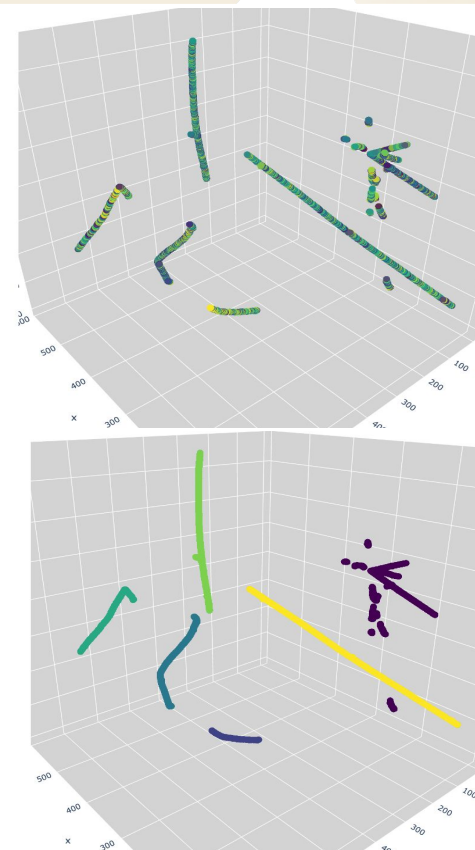
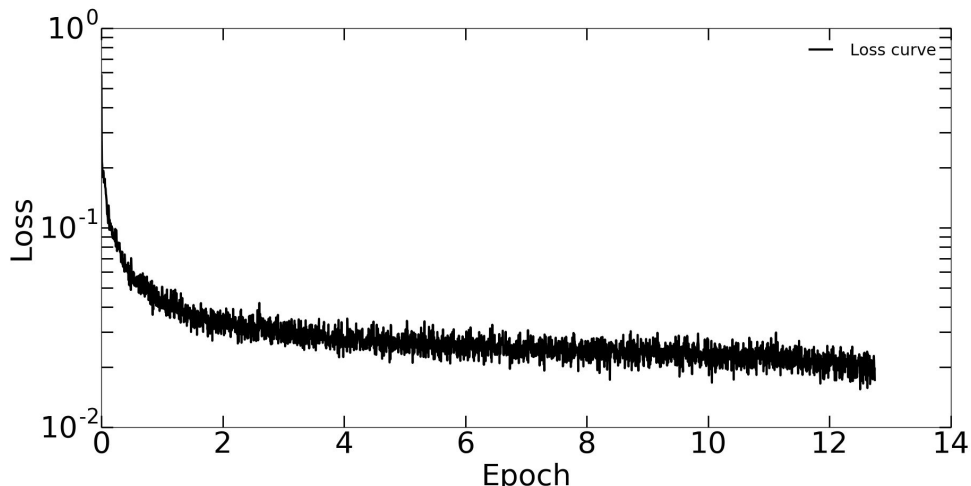
Basic edge features (19):

- (3) Closest point in particle 1
- (3) Closest point in particle 2
- (3) Displacement of two closest points
- (1) Length of displacement
- (9) Outer product of displacement



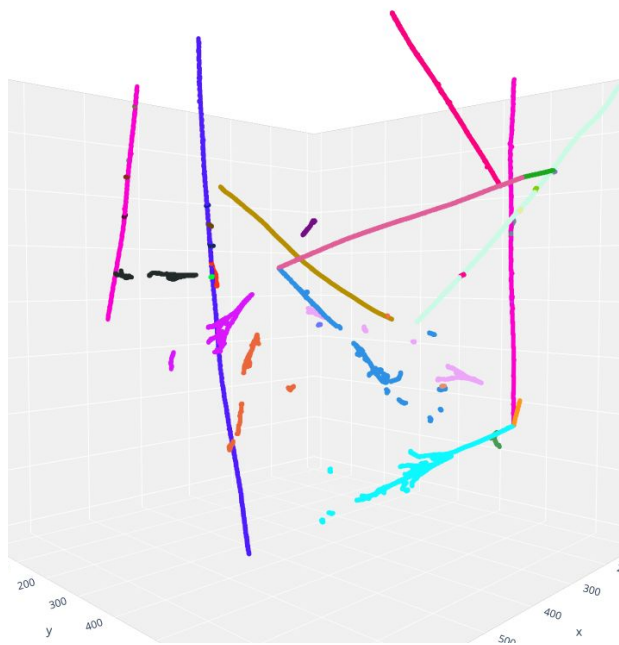
Training

- Image size: 768 px (~ 2.3 m) on each dimension
- 125k training samples and 22k test samples.
- Sample contain nu-like and cosmic-like
- Cosmic-like includes track and gamma showers
- Angular distributions of “nu daughters” and “cosmics” are isotropical.
- Number of nu-like follows Poissonian with mean of 2

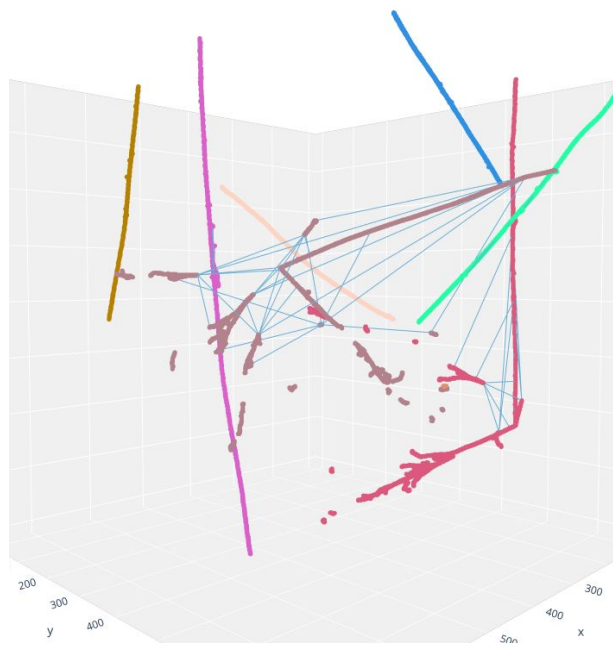


Performance (2 nu)

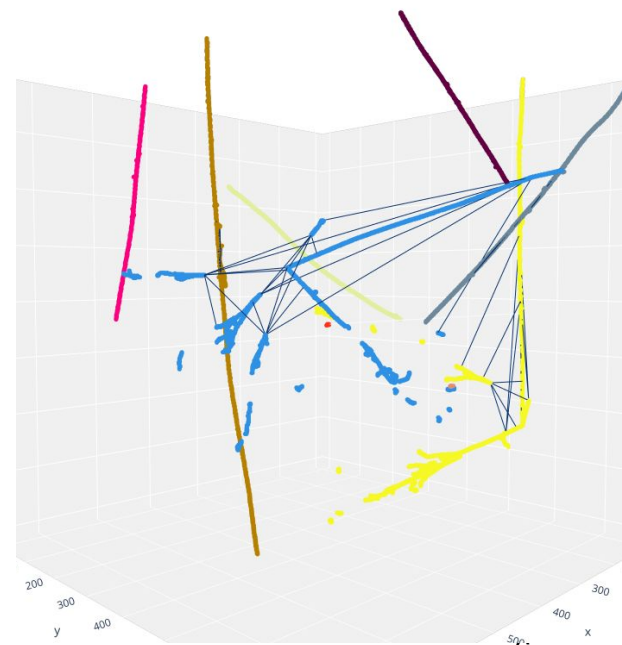
Particle groups



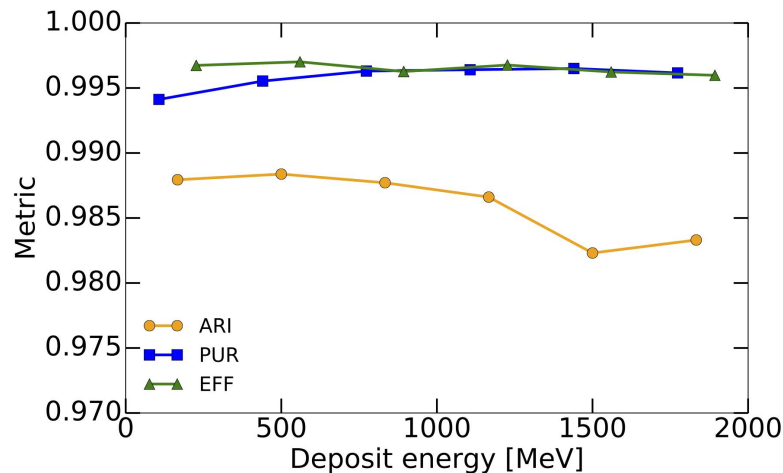
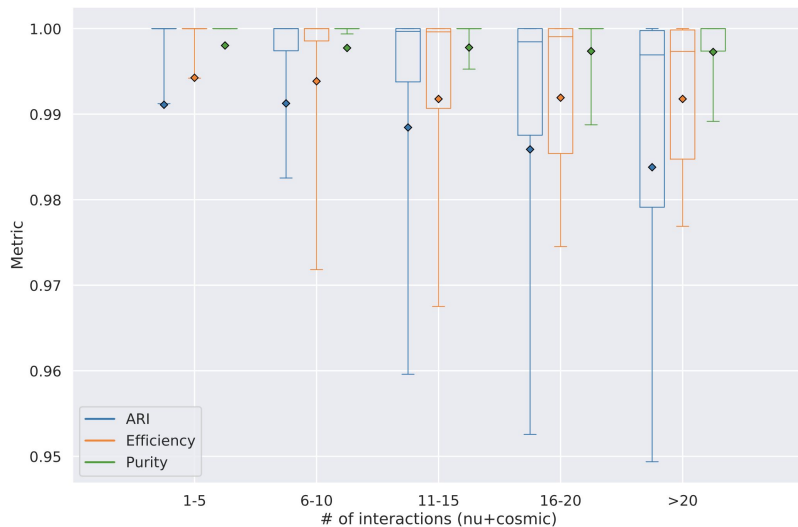
Interaction ground truth



Prediction; ARI = 1.0



Performance:

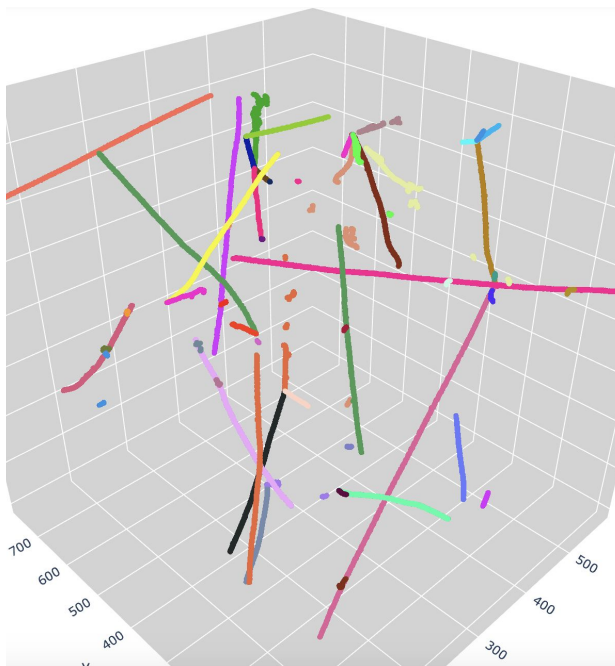


Nv	ARI	PUR	EFF
1	0.986	0.996	0.997
2	0.987	0.996	0.994
4	0.980	0.996	0.989

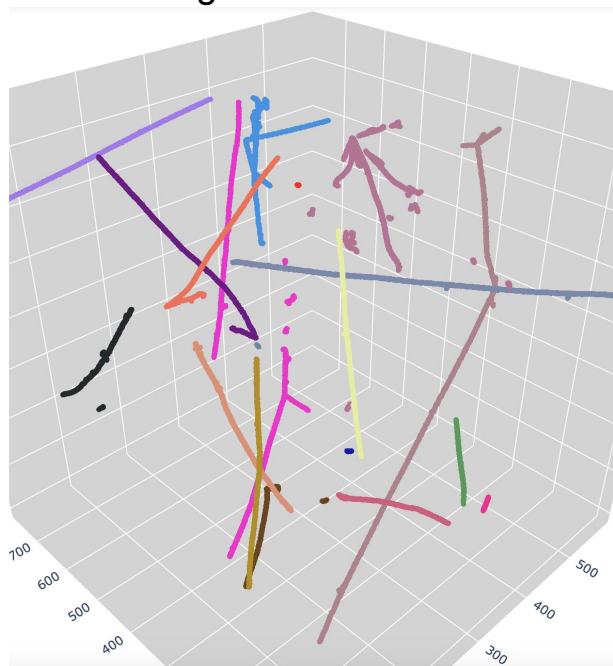
- ARI (adjusted rand index) is used for measuring goodness of clustering.
- Purity and efficiency for checking over- and under-clustering

Performance (4 nu)

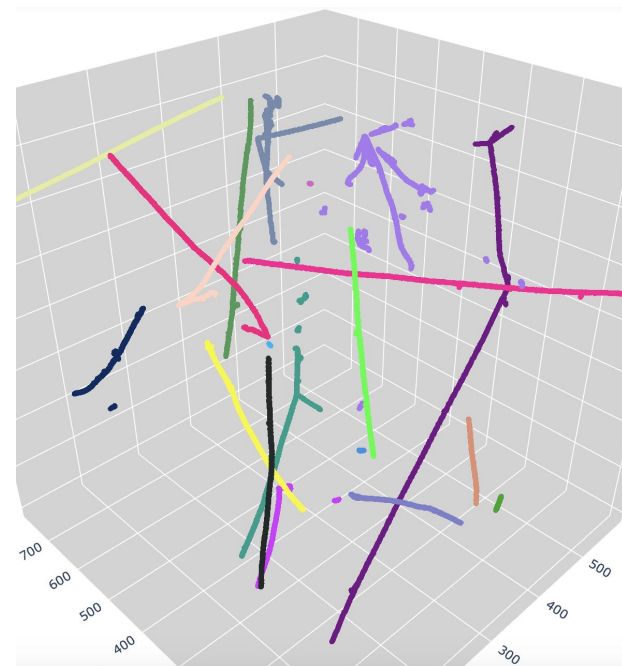
Particle groups



Interaction ground truth



Prediction; ARI = 1.0



- **Baseline model of particle clustering in recon. chain is more or less finished. Input with human-supervised features, GNN is able to achieve ARI of >0.98 @ 4-nu per image**
- **We are also exploring ways to improve performance of particle clustering, such as feeding CNN encoder extracted features into GNN.**

At SLAC, research supported by DoE ML grants (**K. Terao**):

- **Deep-learning-based data reconstruction chain for liquid argon time-projection chambers**
- μ BOONE, pDUNE, ICARUS, ArgonCube 2x2, DUNE



Group consists of three **scientists**, three **postdocs**, three **grad students**



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