

A new era for fundamental physics with deep learning and quantum computing

Benjamin Nachman

Lawrence Berkeley National Laboratory

cern.ch/bnachman

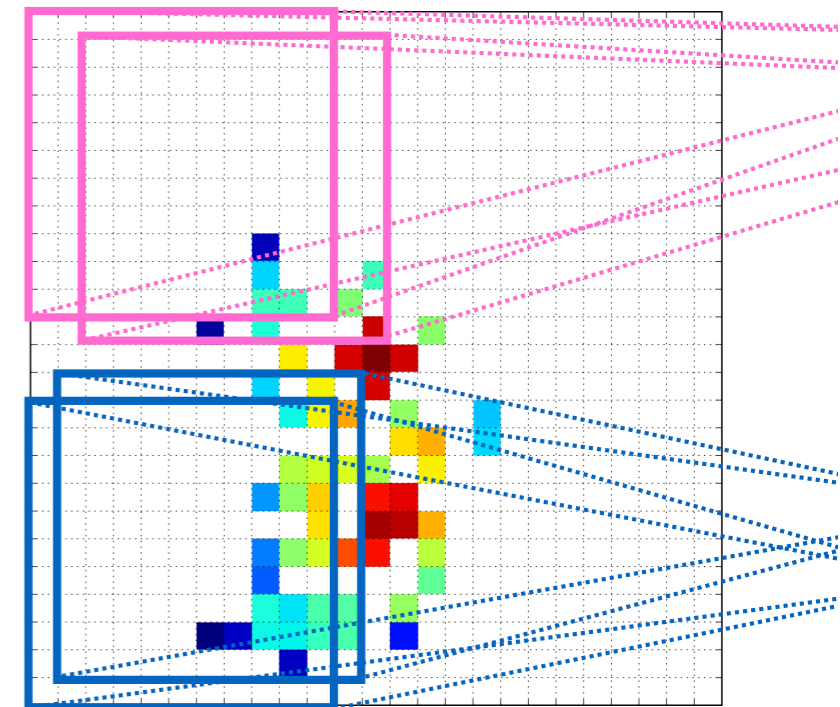
bnachman@lbl.gov



@bpnachman



bnachman



**BERKELEY
EXPERIMENTAL
PARTICLE
PHYSICS**

SLAC National Lab.
Panofsky Seminar
March 2, 2020



NESAP for Learning



QuantISED HEP initiative



Outline for today



Theoretical and experimental questions motivate a deep exploration **of the fundamental structure of nature**

Outline for today



Theoretical and experimental questions motivate a deep exploration **of the fundamental structure of nature**

Key **challenge** and **opportunity**: *hypervariate phase space*
& *hyper spectral data*

Outline for today

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**Deep learning
& Quantum
computing for
fundamental
physics**

Outline for today

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**Likelihood-Free
inference**

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Outline for today

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[Deconvolution/Unfolding]

[Generative models]

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Questions in fundamental physics

10

Theoretical and experimental questions motivate a deep exploration **of the fundamental structure of nature**

Why is the Higgs boson so light?

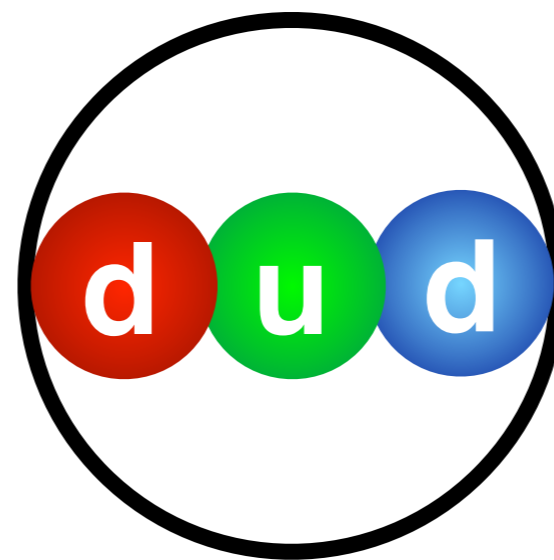
Hierarchy problem



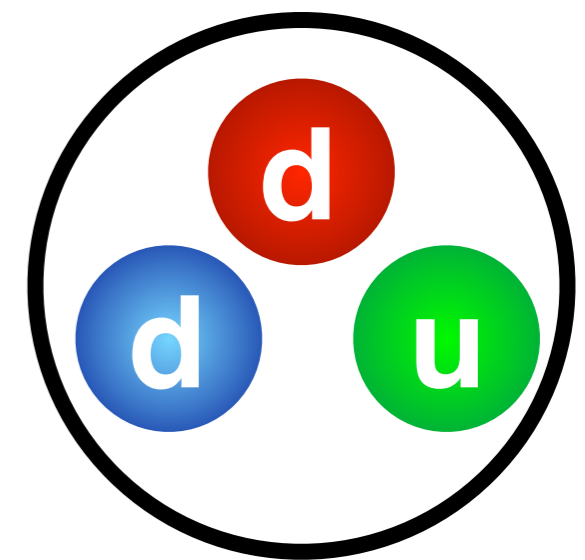
See also: quantum gravity

Why do neutrons have no dipole moment?

Strong CP



Reality



>99% of pictures on the internet

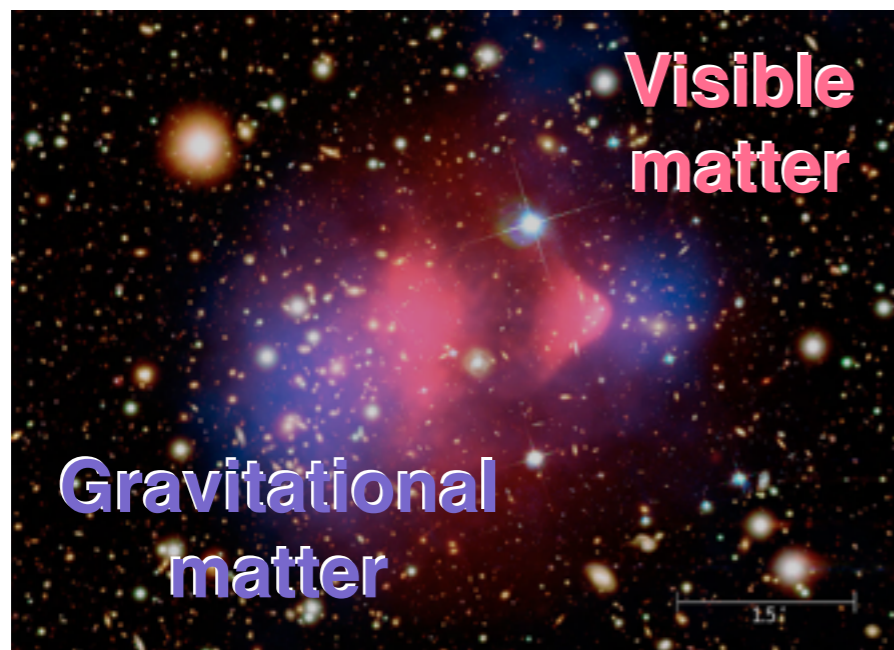
Questions in fundamental physics

11

Theoretical and **experimental** questions motivate a deep exploration **of the fundamental structure of nature**

What is the extra gravitational matter?

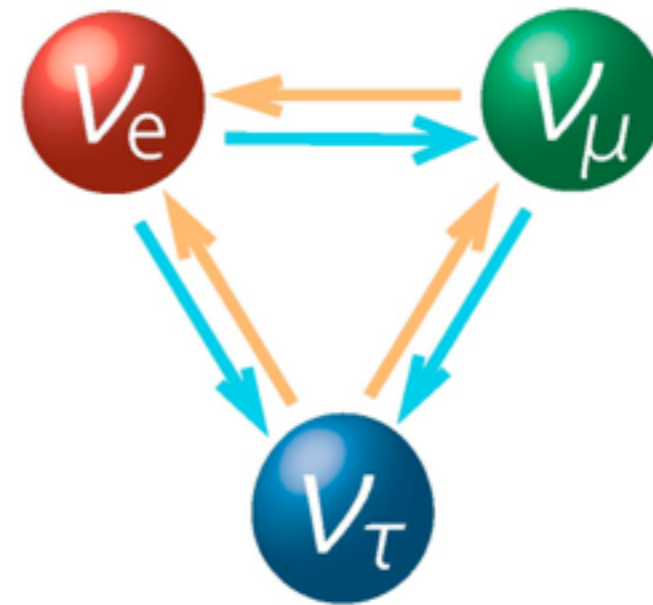
Dark Matter



See also: dark energy

Why do neutrinos have a mass?

Flavor puzzles



See also: Where did all the anti-particles go? (Baryogenesis)

Questions in fundamental physics

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Theoretical and **experimental** questions motivate a deep exploration **of the fundamental structure of nature**

Dark matter

Hierarchy problem

Strong CP

Flavor puzzles

Baryogenesis

Dark energy

We have performed thousands of hypothesis tests and have never rejected the null (the Standard Model(s))

Three possibilities



Theoretical and **experimental** questions motivate a deep exploration **of the fundamental structure of nature**

Dark matter

Hierarchy problem

Strong CP

Flavor puzzles

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Three possibilities

(1) There is nothing new

Theoretical and **experimental** questions motivate a deep exploration **of the fundamental structure of nature**

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Hierarchy problem

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(1) There is nothing new

(2) Patience! (new physics is rare)

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Three possibilities

(1) There is nothing new

(2) Patience! (new physics is rare)

(3) Our search methods are not sensitive

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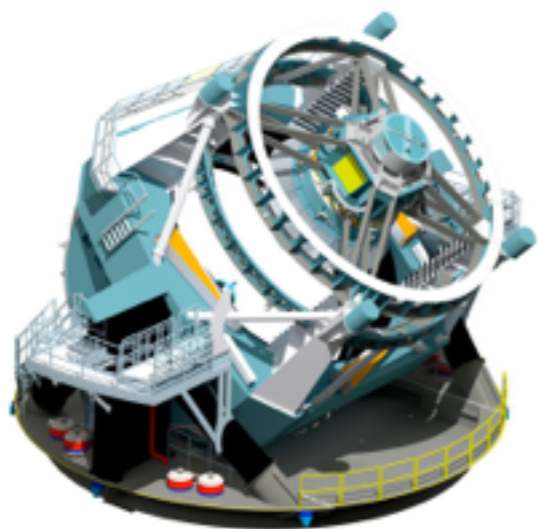
This is what keeps me up at night !

(3) Our search methods are not sensitive

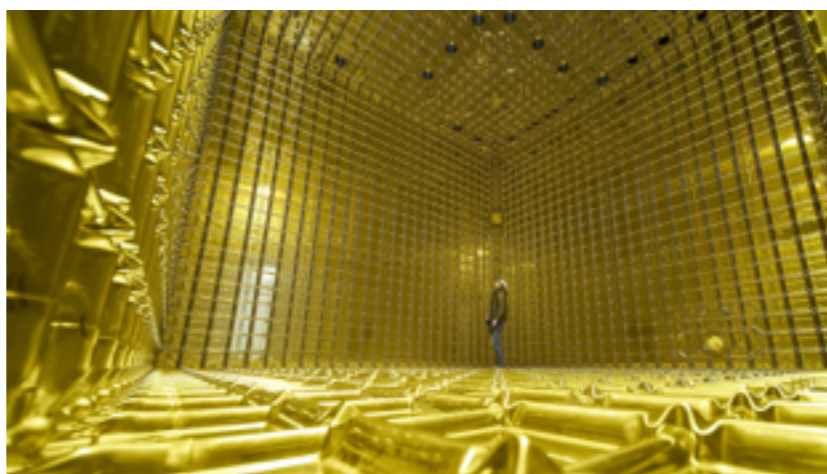
Addressing the questions

17

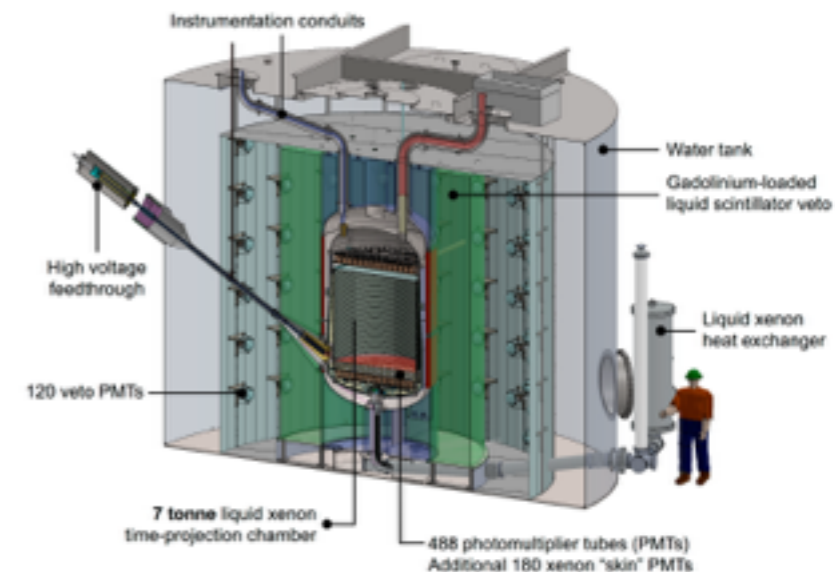
Dark matter/energy
with LSST



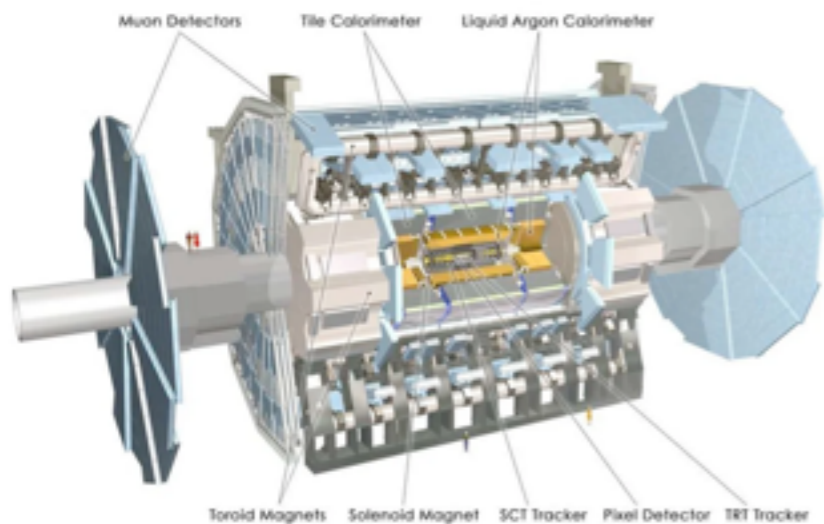
Fermilab neutrino experiments



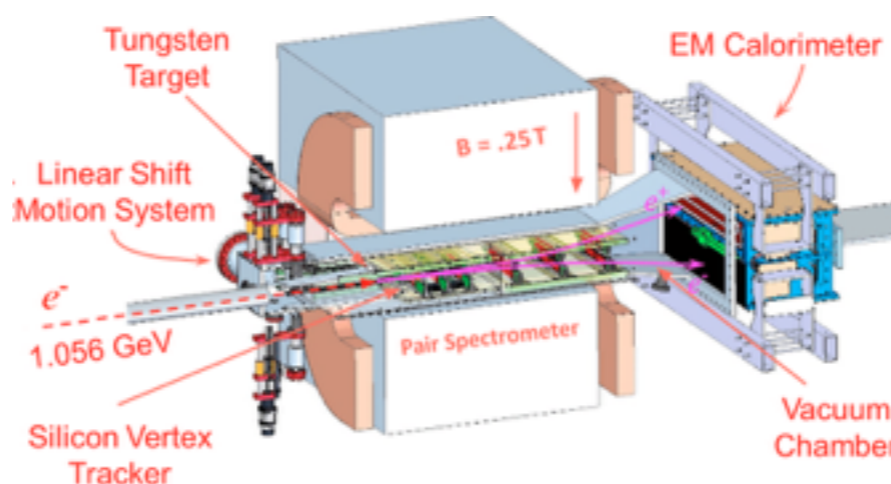
Dark Matter
with LZ



Large Hadron Collider



Heavy Photon Search



+ others !

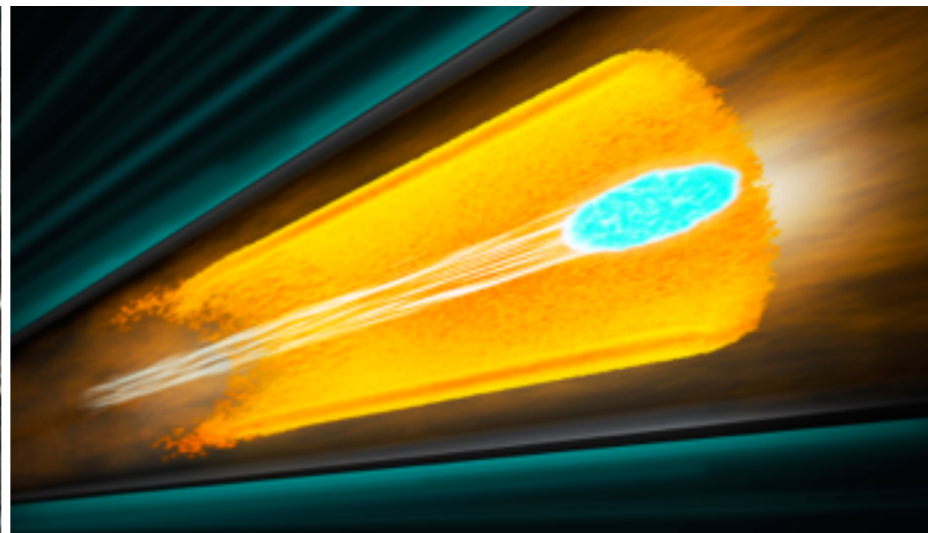
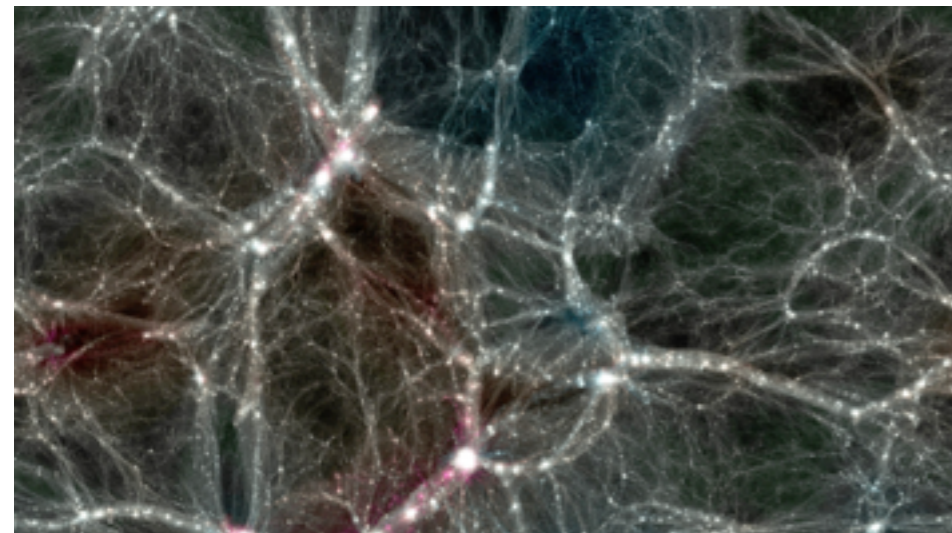
Addressing the questions

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N-body simulations

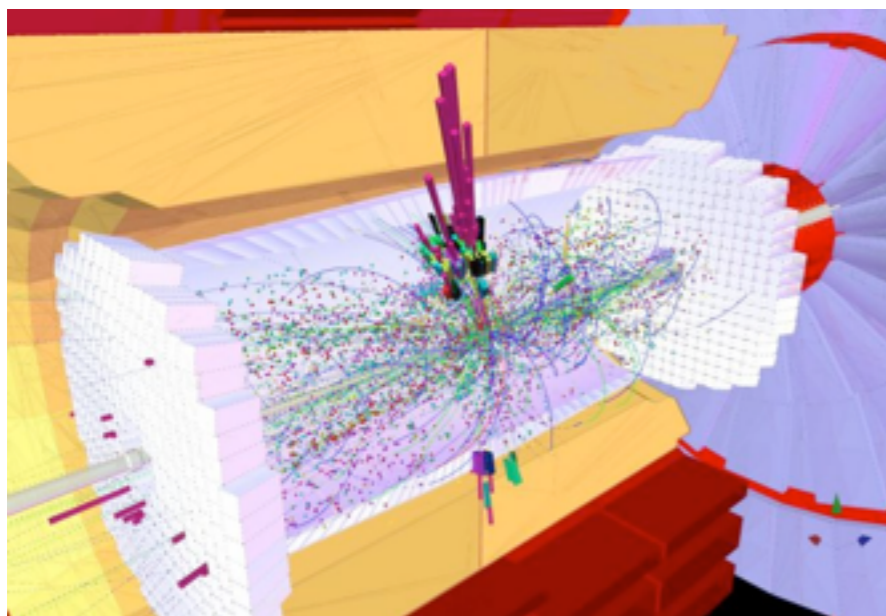
Advanced accelerators

Supercomputers



Material interactions
with Geant4

Theory Calculations



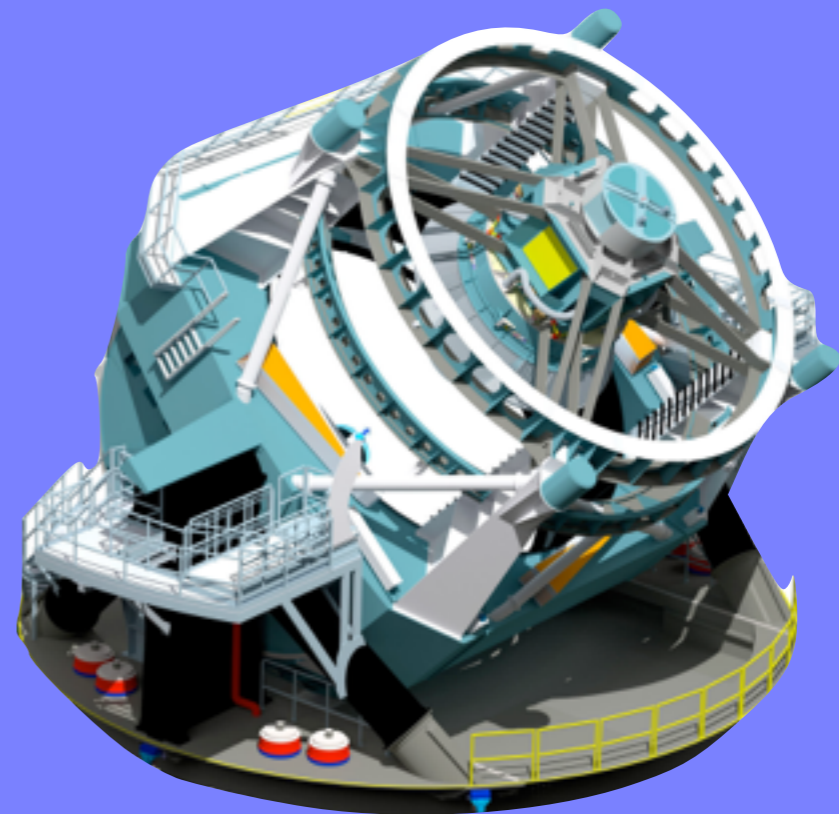
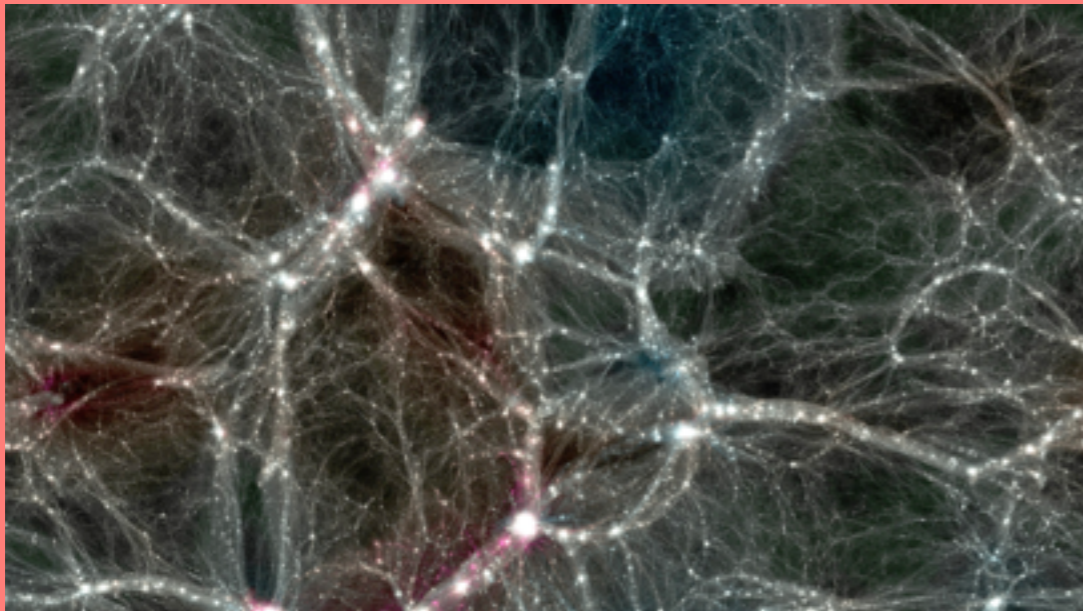
$$2\text{Im} \left(\text{Diagram with wavy line and dashed line} \right) = \int d\Pi \left| \text{Diagram with wavy line} \right|^2$$

+ others !

A *hyper* challenge

19

Key **challenge** and **opportunity**: *hypervariate phase space*
& *hyper spectral data*



A *hyper* challenge

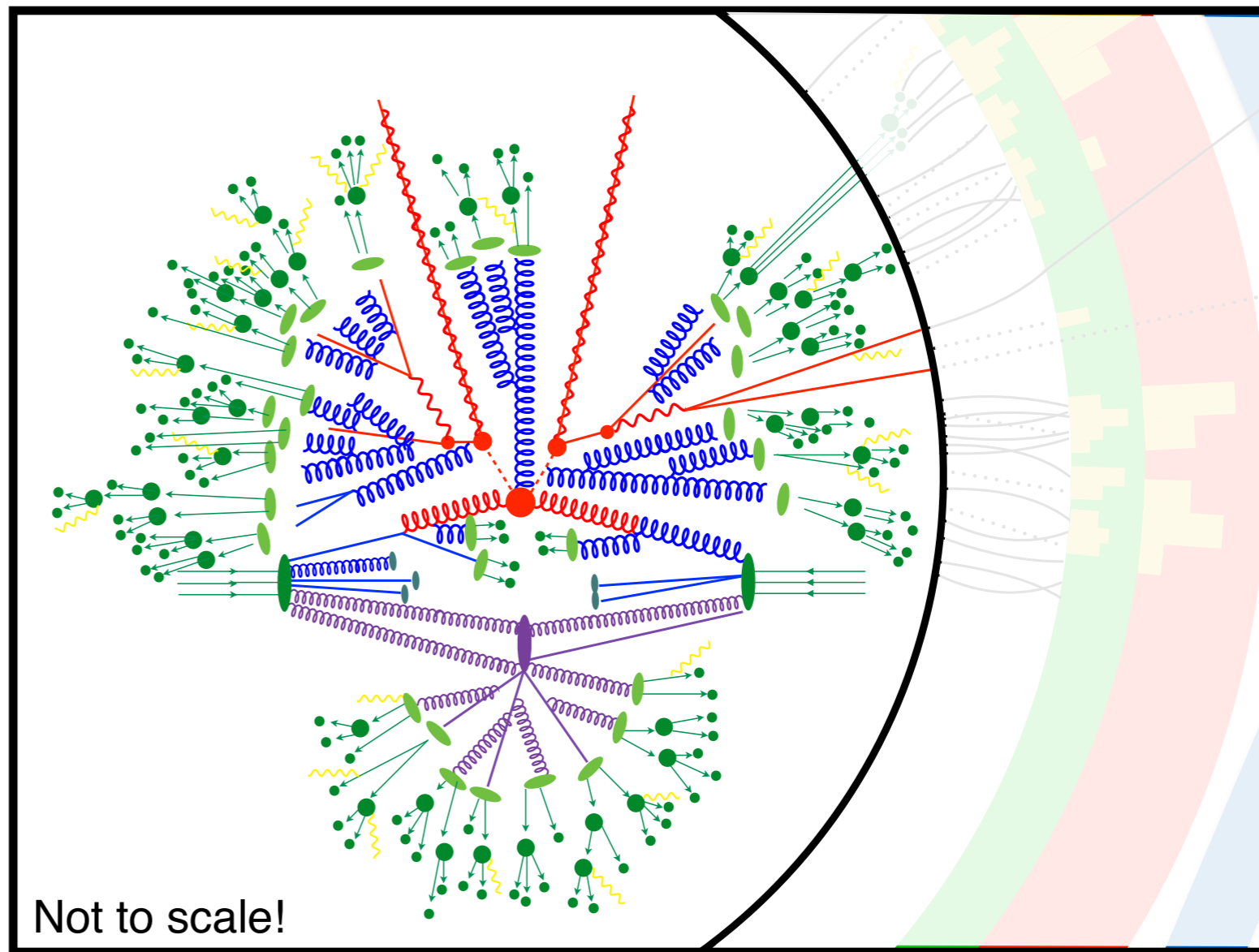
20

Key **challenge** and **opportunity**: *hypervariate phase space*
& *hyper spectral data*

Typical collision events
at the LHC produce
O(1000+) particles

We detect these
particles with
O(100 M)
readout channels

Image inspired by JHEP 02 (2009) 007



Not to scale!

A *hyper* challenge

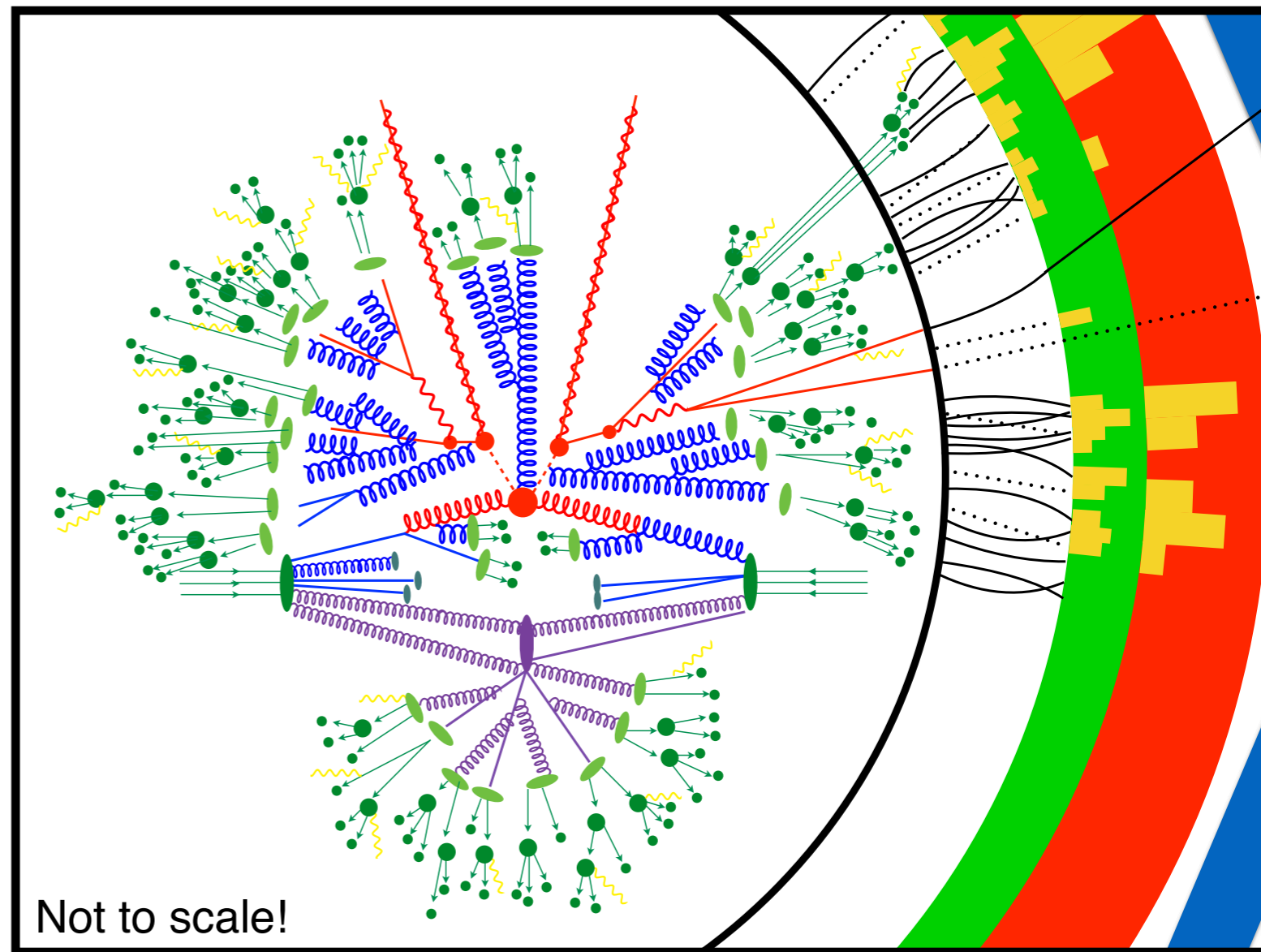
21

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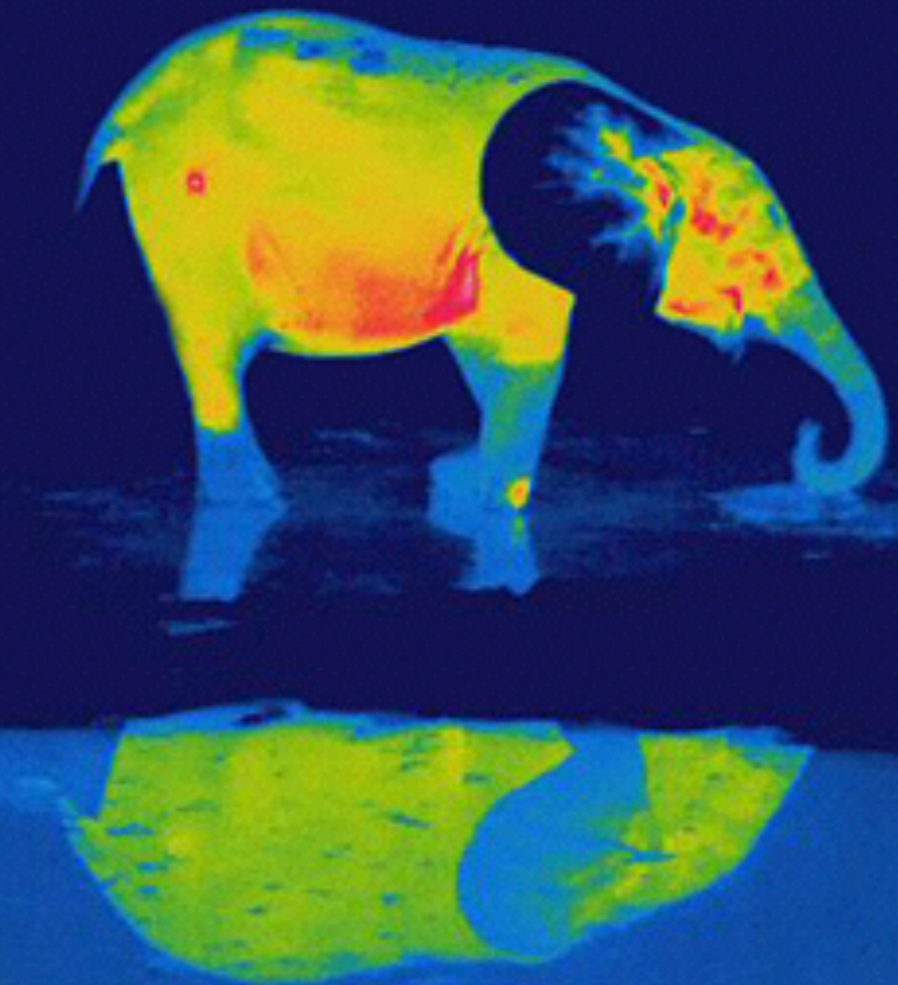
Hypervariate vision with deep learning

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We have been conducting “multivariate” analysis of collision events for many years

However, recent advances have opened up a **new way** of looking at our data. This **hypervariate vision** will lead to a deeper understanding of nature and perhaps surprises along the way...

Everyone is aware that there must be new physics, but maybe we need hypervariate vision to see it?



Theory of everything



Physics simulators



Detector-level observables



Pattern recognition



Nature



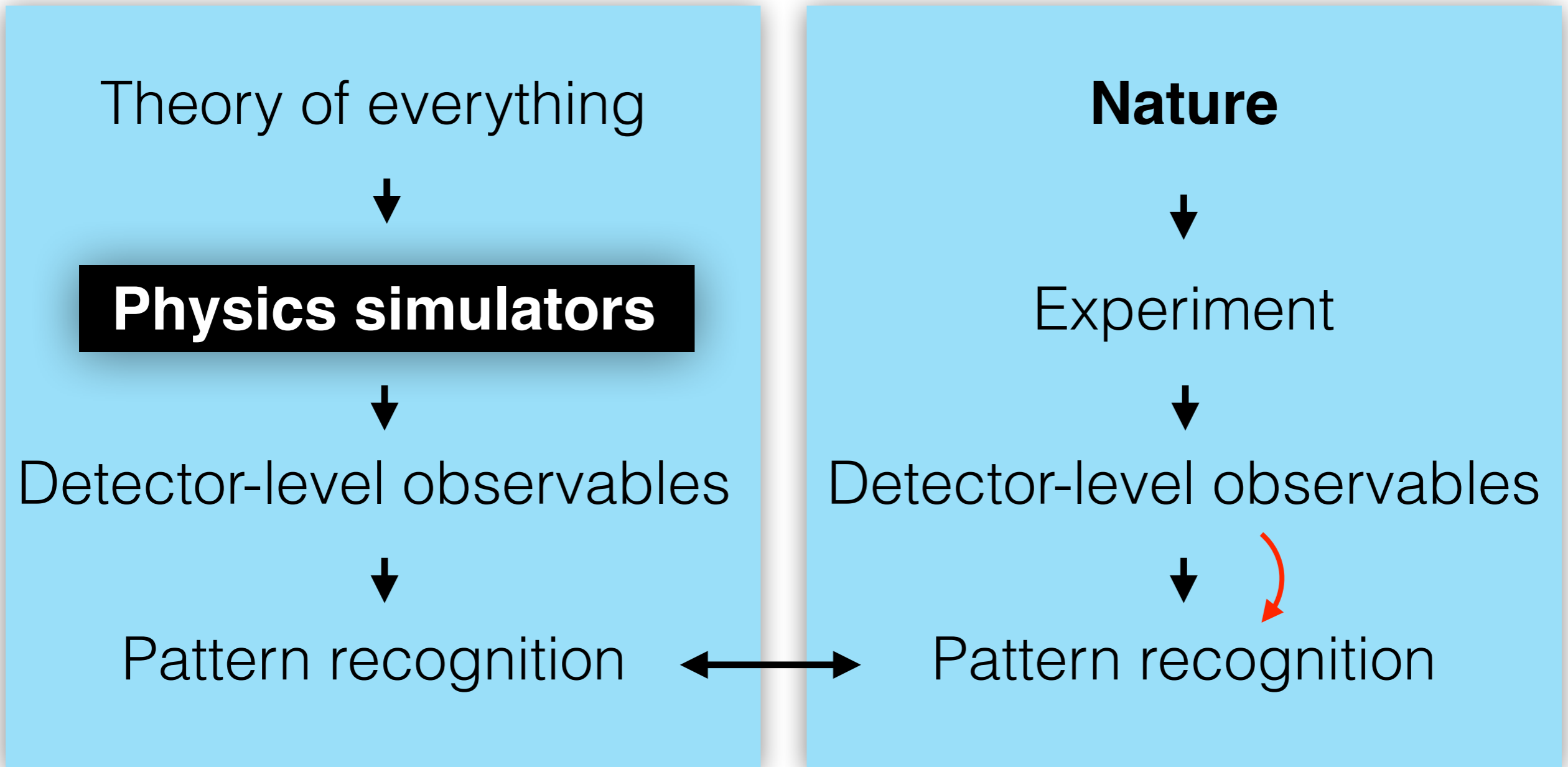
Experiment



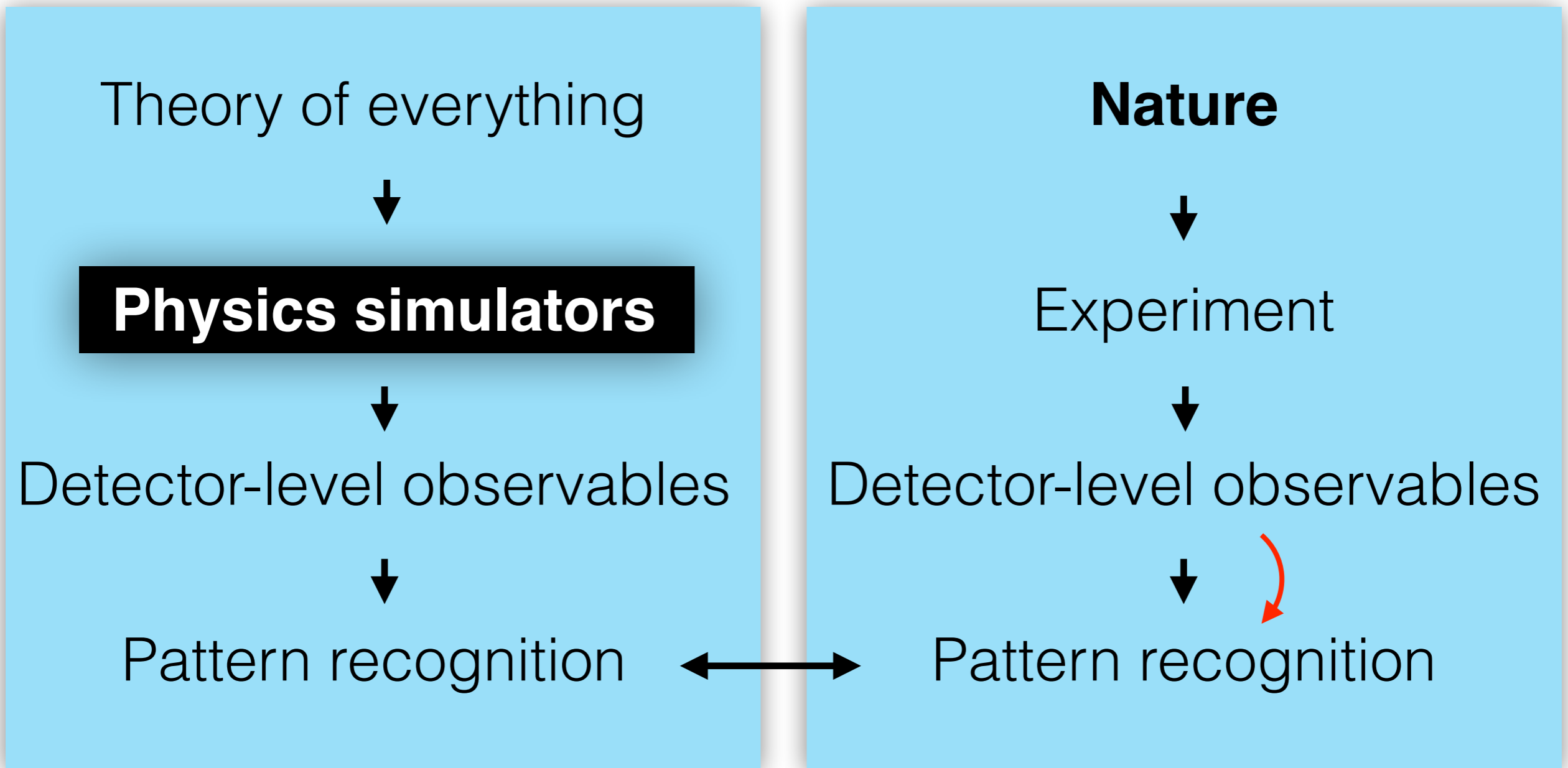
Detector-level observables



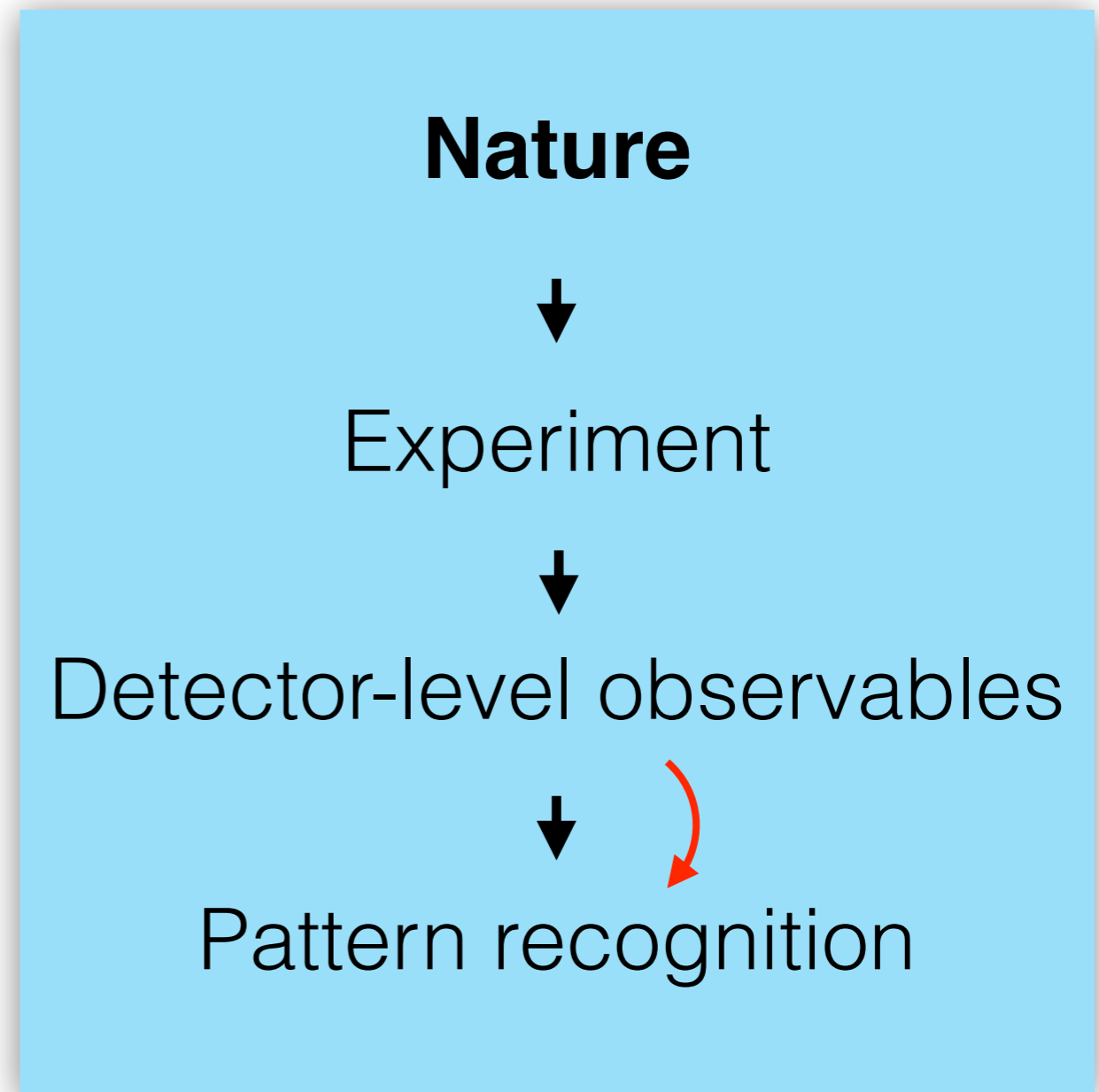
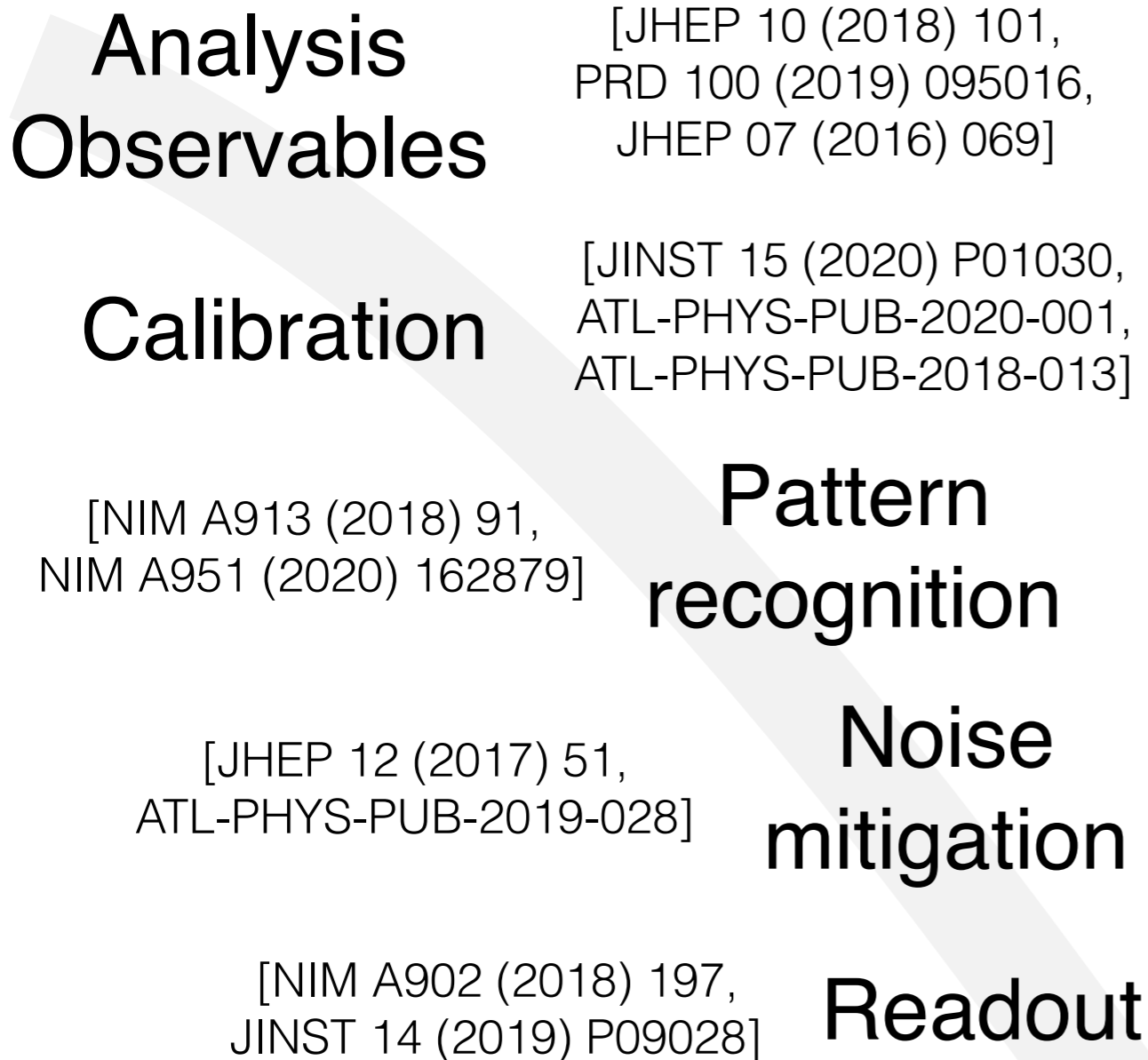
Pattern recognition



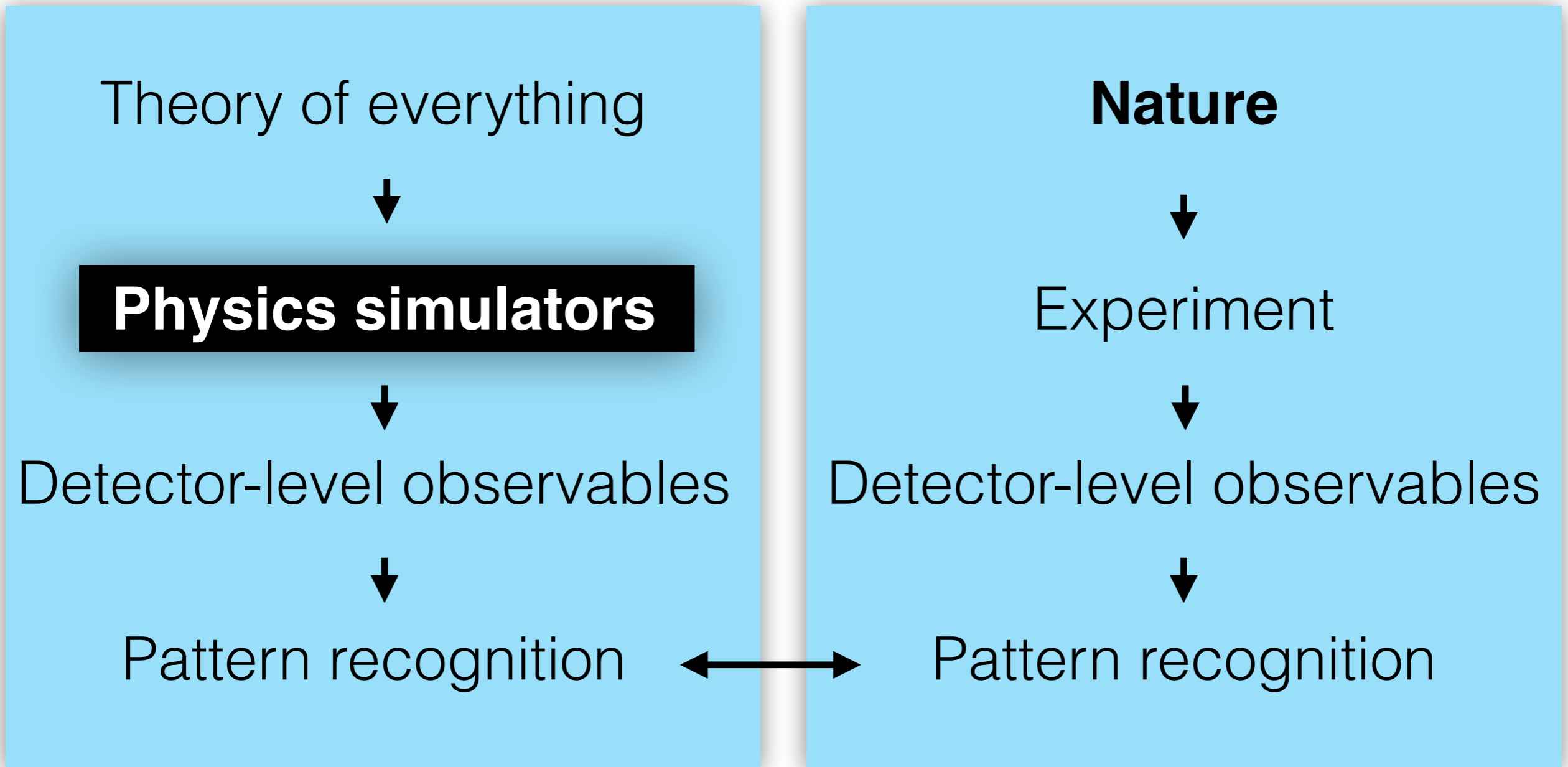
This is where most machine learning is being applied.

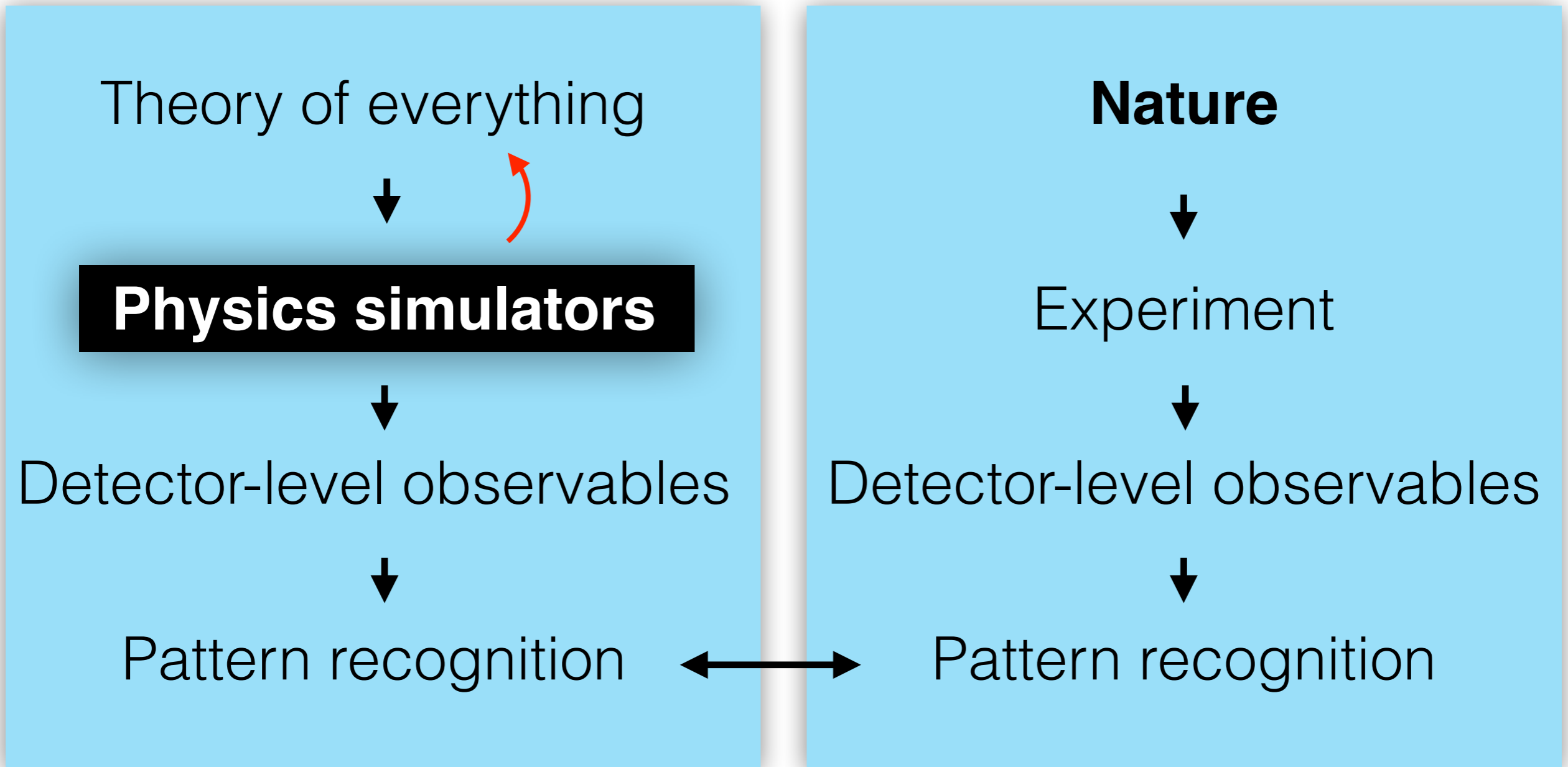


This is where most machine learning is being applied.
Most of that machine learning is “straightforward”.

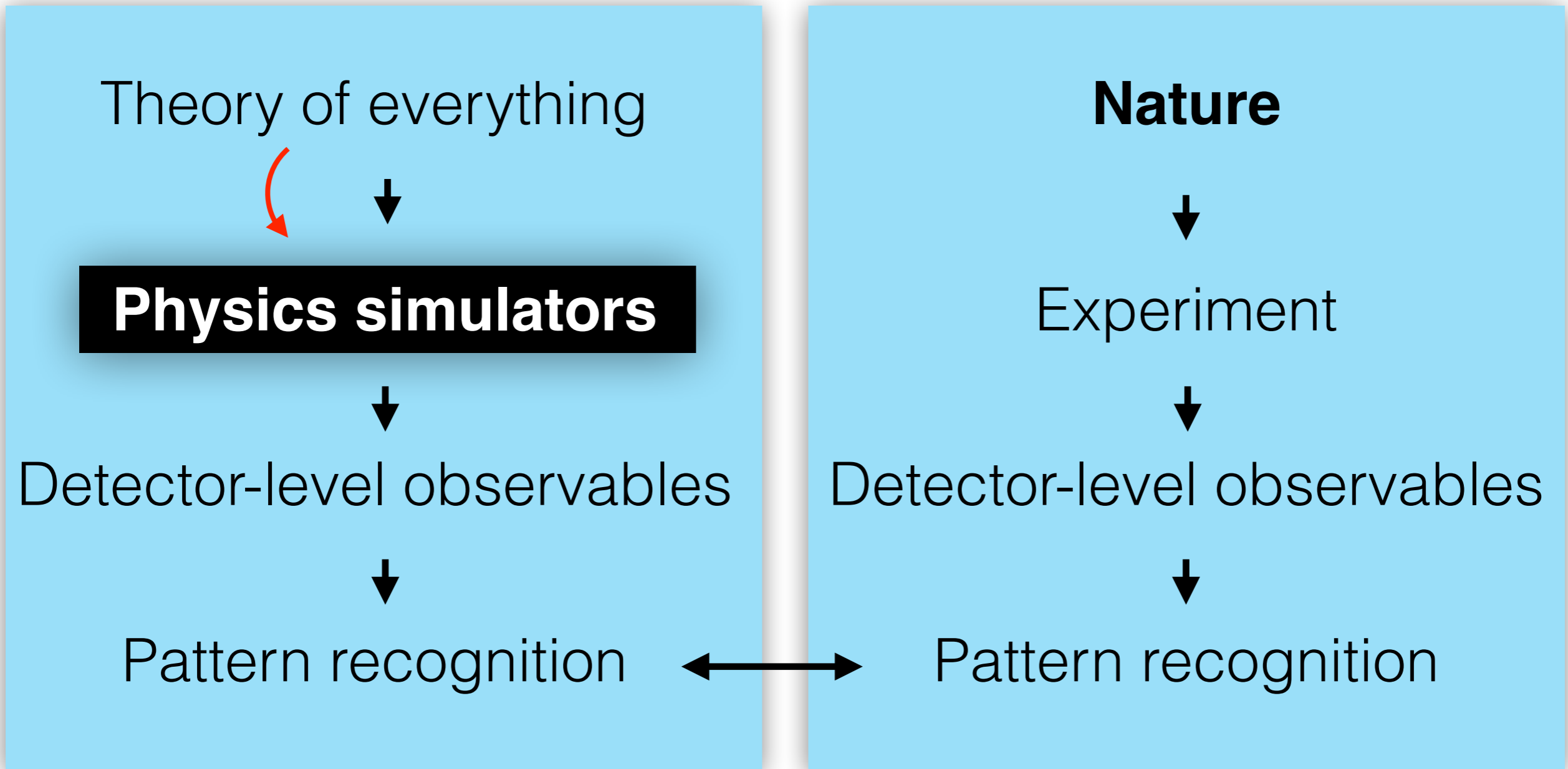


I won't discuss this area at all, but I am happy to talk later about the potential gains from deep learning on many fronts.

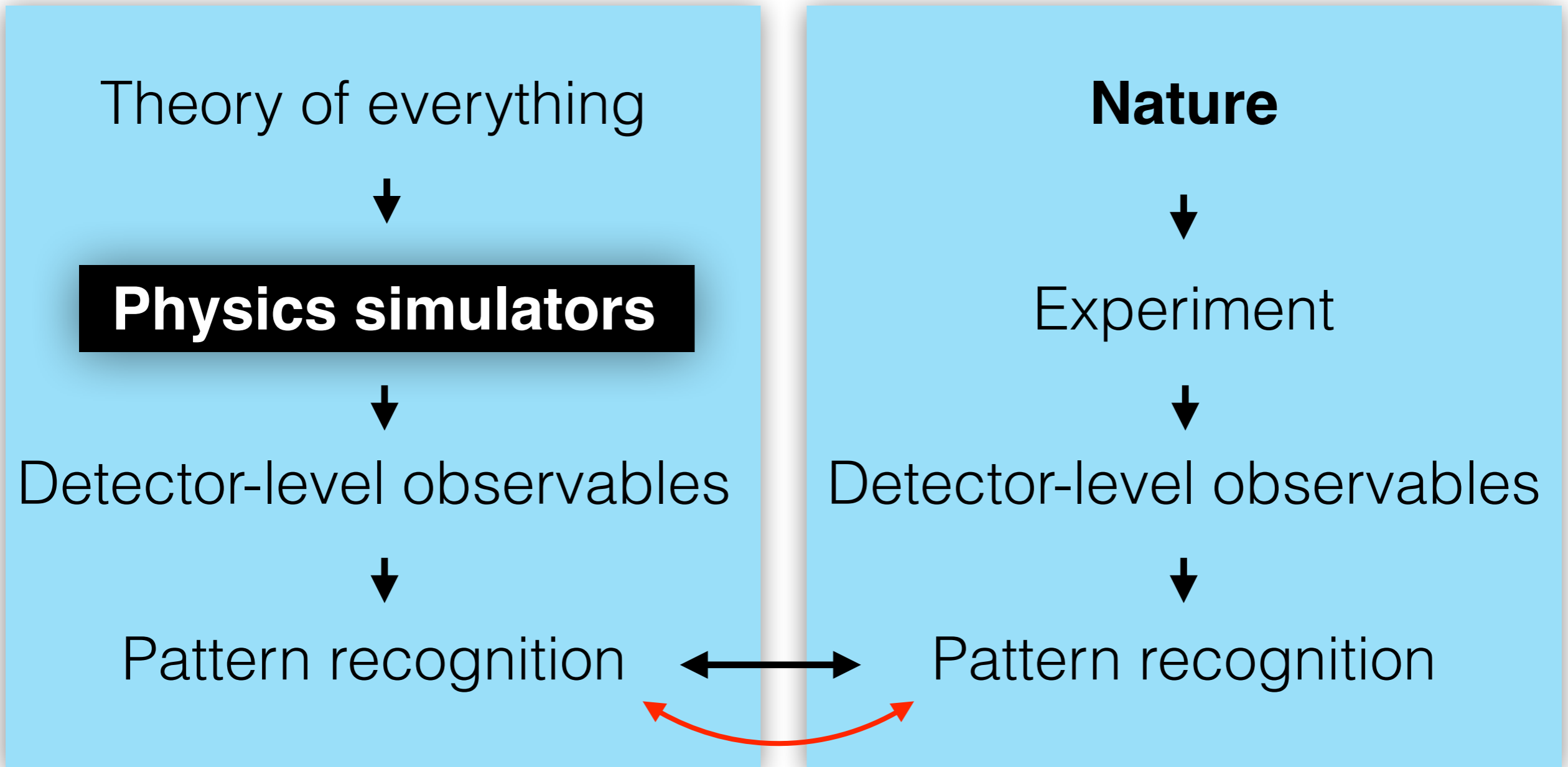




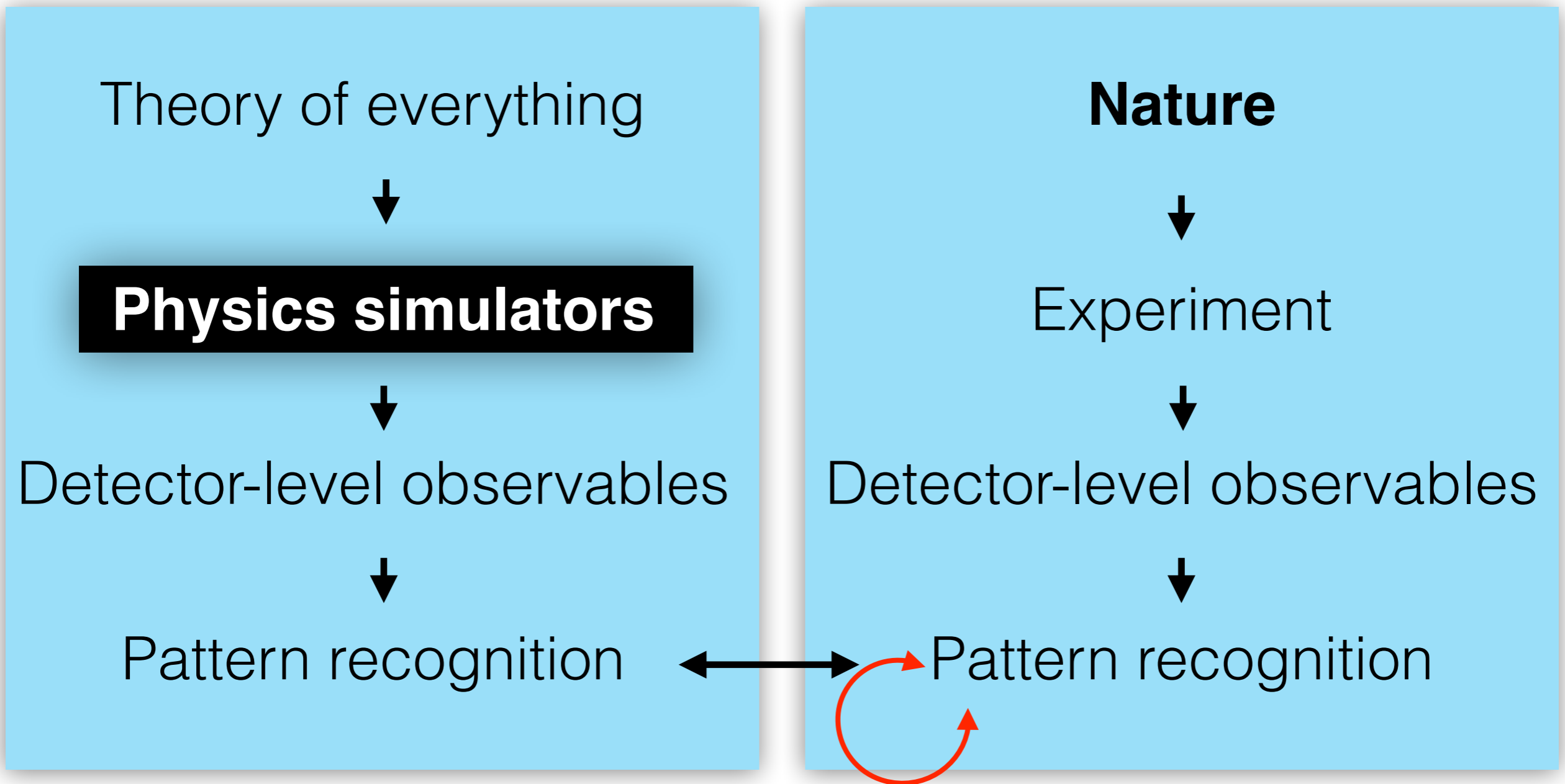
Goal of likelihood-free inference is to extract physical information about nature using only the “forward model”.



A growing toolkit called “generative models” are being developed to accelerate or augment simulations.

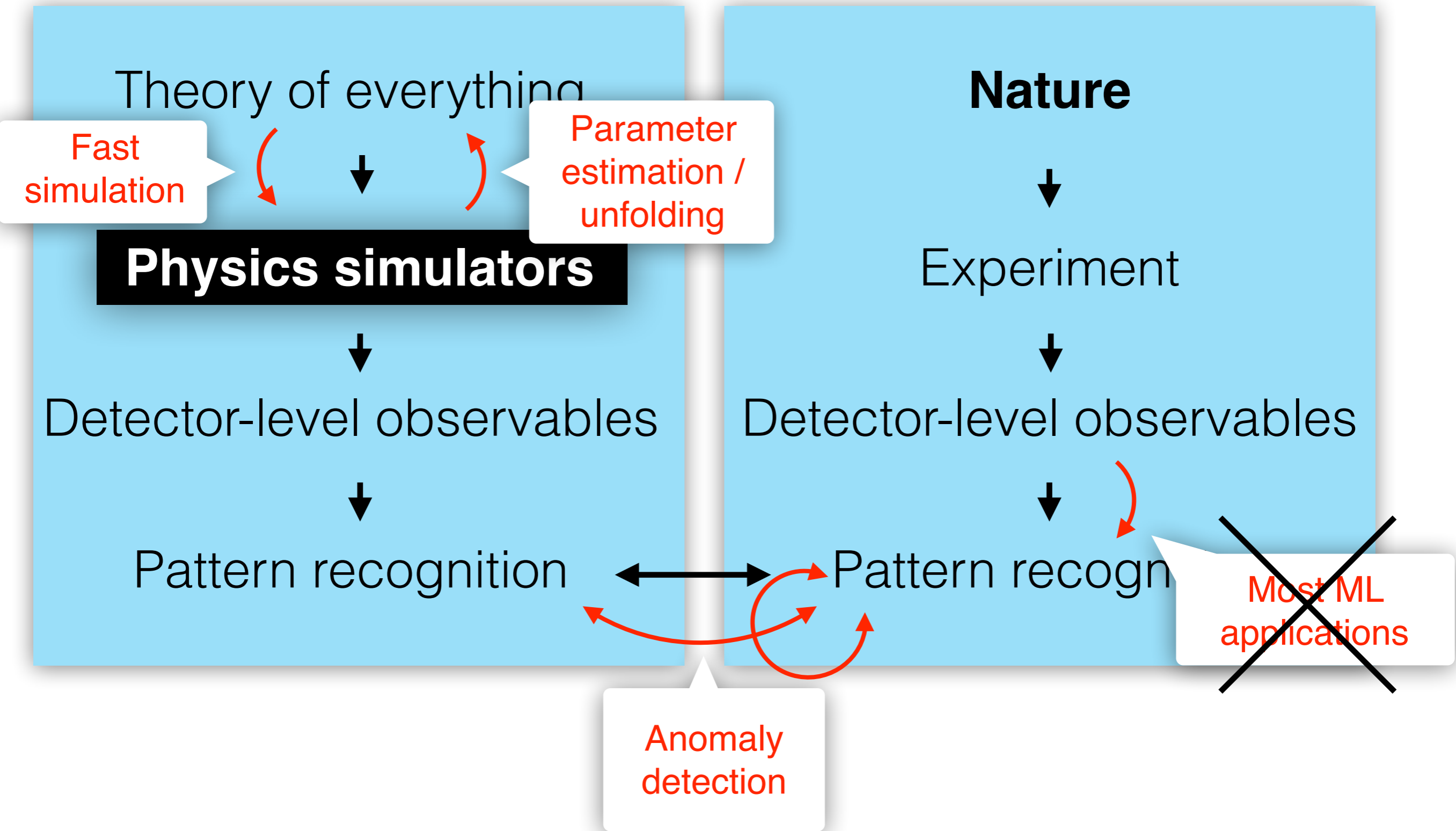


Anomaly detection



Anomaly detection

Roadmap for rest of this talk



CAUTION



LHC Area

No RWP required for entry

I will use examples from **collider physics**, but the techniques are **much broader**.

Colliders offer a complex environment for developing methods, but I am actively investigating applications **across fundamental physics domains**.

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**Likelihood-Free
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**Deep learning
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Label-Free
learning

[Deconvolution/Unfolding]

[Generative models]

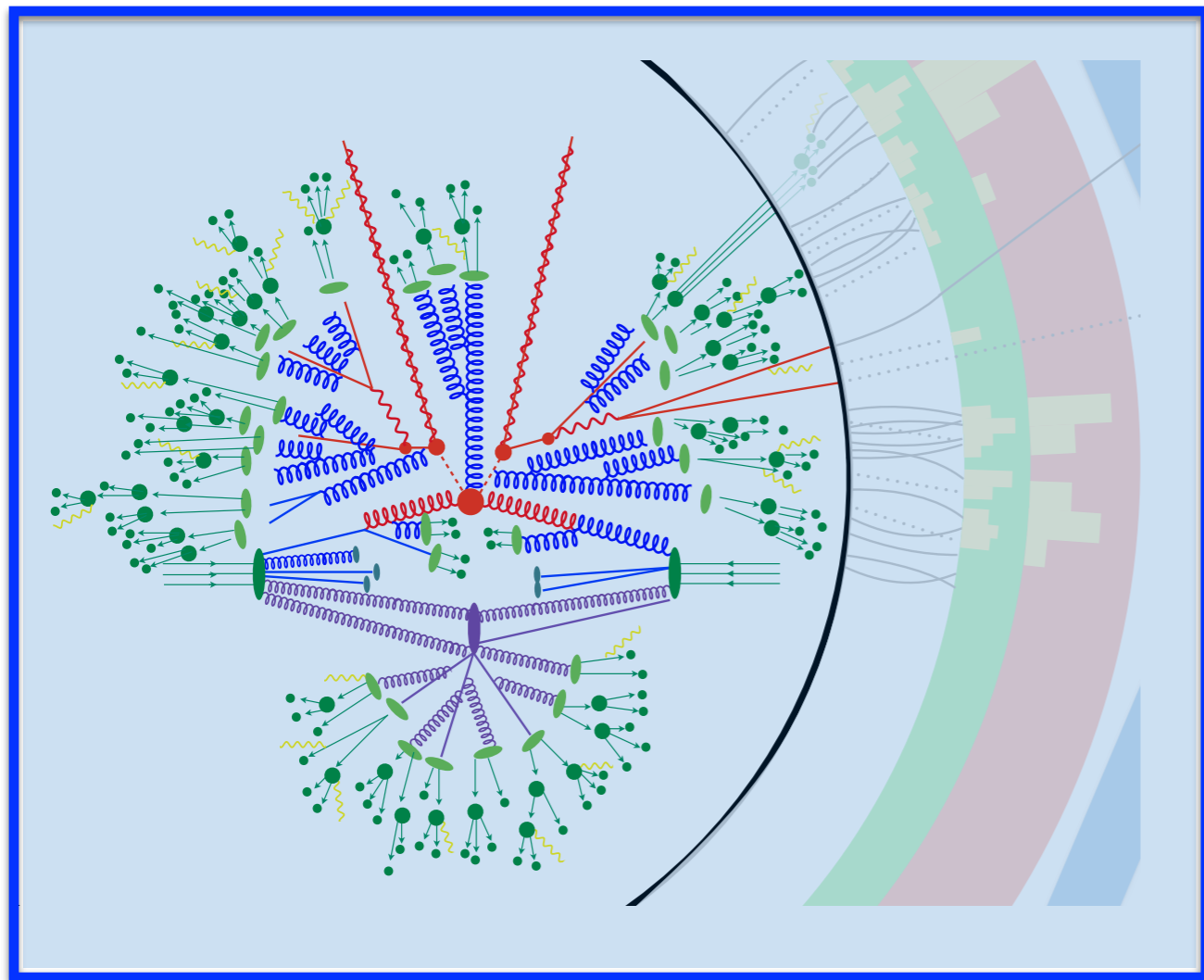
[Weak supervision]

[Anomaly detection]

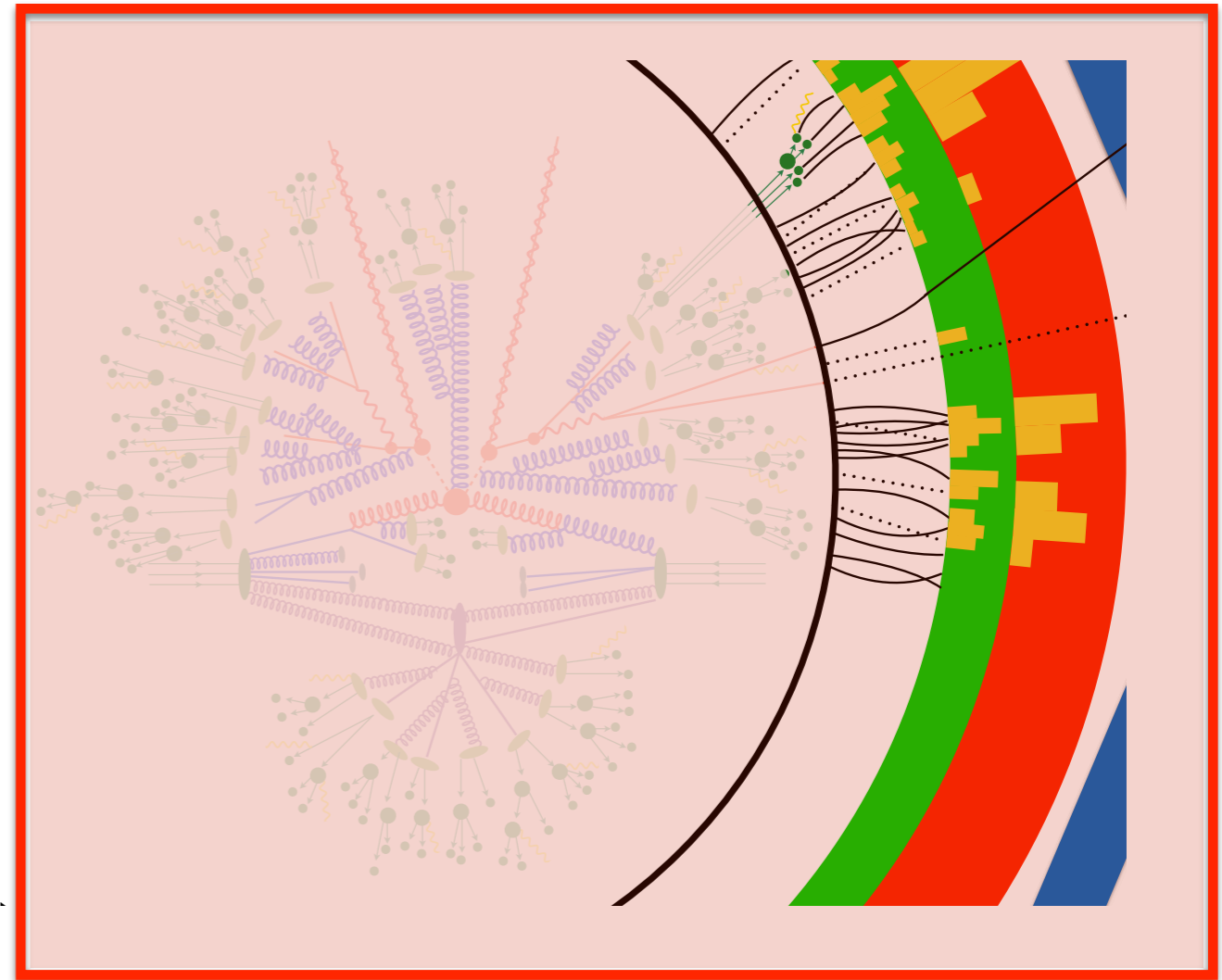
Deconvolution/Unfolding

35

Want this



Measure this

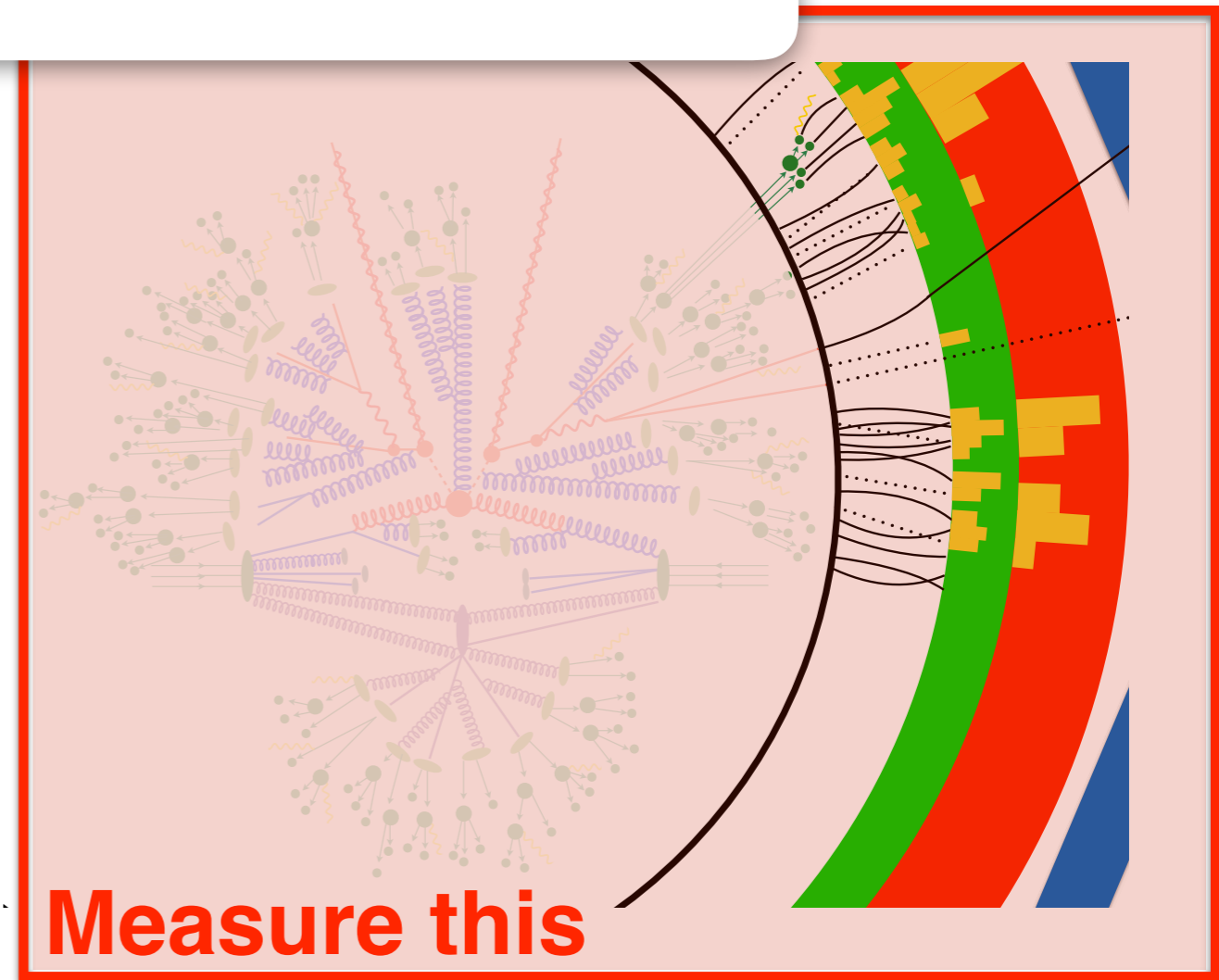
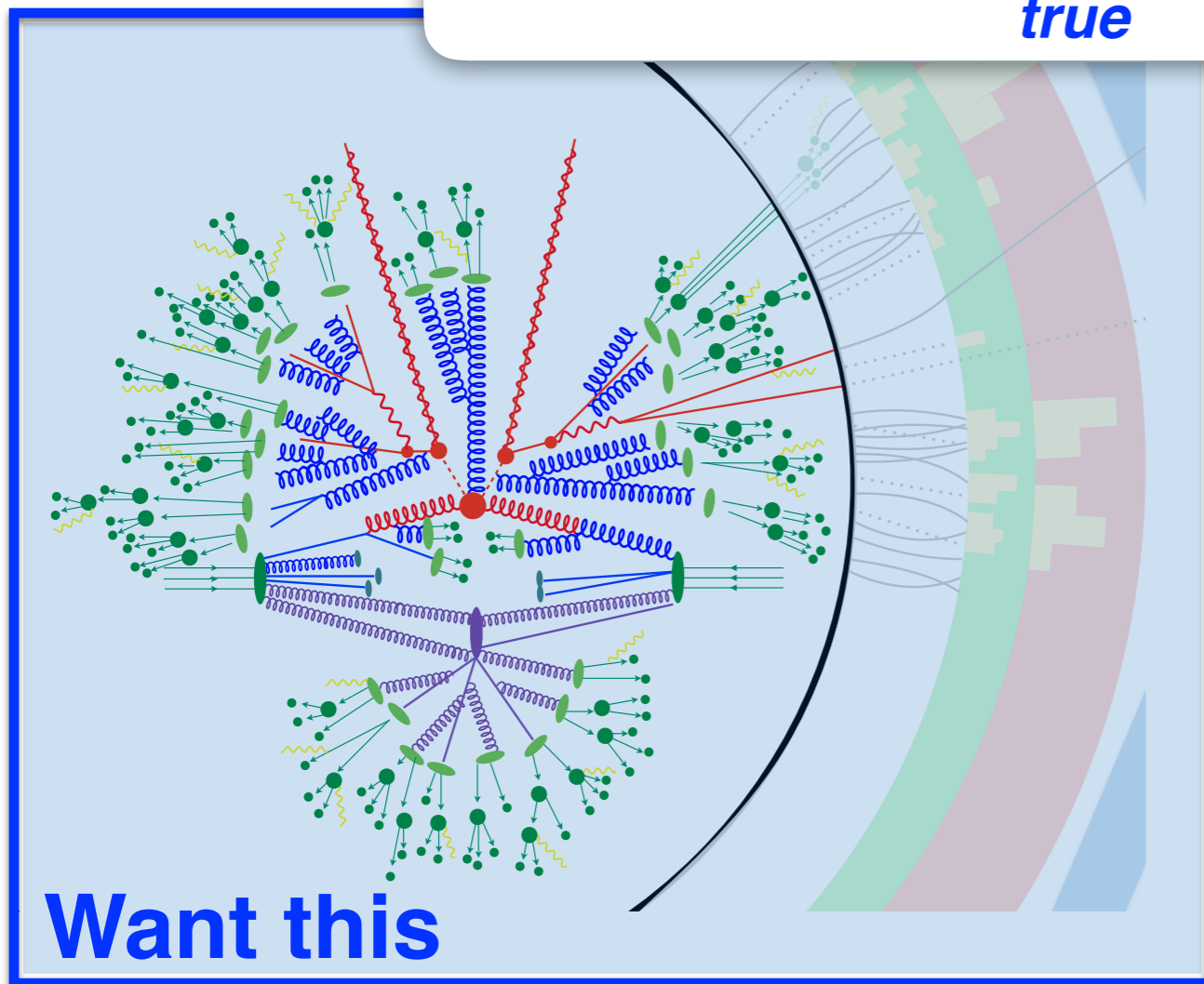


i.e. remove detector distortions

Deconvolution/Unfolding

If you know $p(\textit{meas.} / \textit{true})$, could do maximum likelihood, i.e.

$$\textit{unfolded} = \underset{\textit{true}}{\operatorname{argmax}} p(\textit{measured} / \textit{true})$$



$p(\textit{meas.} / \textit{true})$ = “response matrix” or “point spread function”

Deconvolution/Unfolding

37

If you know $p(\textit{meas.} \mid \textit{true})$, could do maximum likelihood, i.e.

$$\textit{unfolded} = \underset{\textit{true}}{\operatorname{argmax}} p(\textit{measured} \mid \textit{true})$$



Challenge: **measured** is hyperspectral and **true** is hypervariate ... $p(\textit{meas.} \mid \textit{true})$ is **intractable** !

$p(\textit{meas.} \mid \textit{true})$ = “response matrix” or “point spread function”

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Challenge: **measured** is hyperspectral and **true** is hypervariate ... $p(\textit{meas.} \mid \textit{true})$ is **intractable** !

However: we have **simulators** that we can use to sample from $p(\textit{meas.} \mid \textit{true})$

→ **Likelihood-free inference**

$p(\textit{meas.} \mid \textit{true})$ = “response matrix” or “point spread function”

I'll briefly show you one solution to give you a sense of the power of likelihood-free inference.

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The solution will be built on ***reweighting***

dataset 1: sampled from $p(x)$

dataset 2: sampled from $q(x)$

Create weights $w(x) = q(x)/p(x)$ so that when dataset 1 is weighted by w , it is statistically identical to dataset 2.

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Create weights $w(x) = q(x)/p(x)$ so that when dataset 1 is weighted by w , it is statistically identical to dataset 2.

What if we don't (and can't easily) know q and p ?

Fact: Neural networks learn to approximate the likelihood ratio = $q(x)/p(x)$

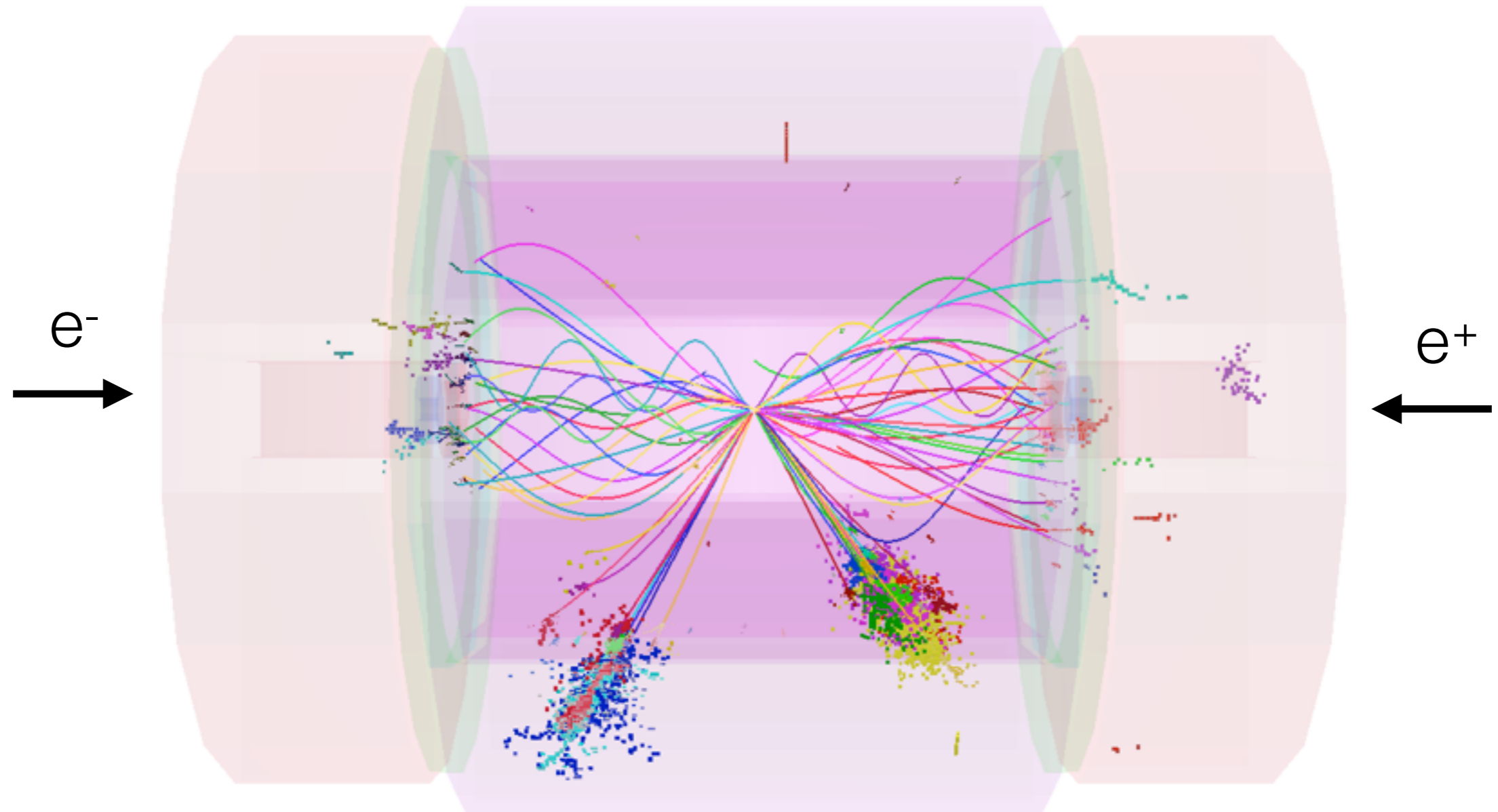
Solution: train a neural network to distinguish the two datasets!

This turns the problem of **density estimation** (**hard**) into a problem of **classification** (**easy**)

Classification for reweighting

43

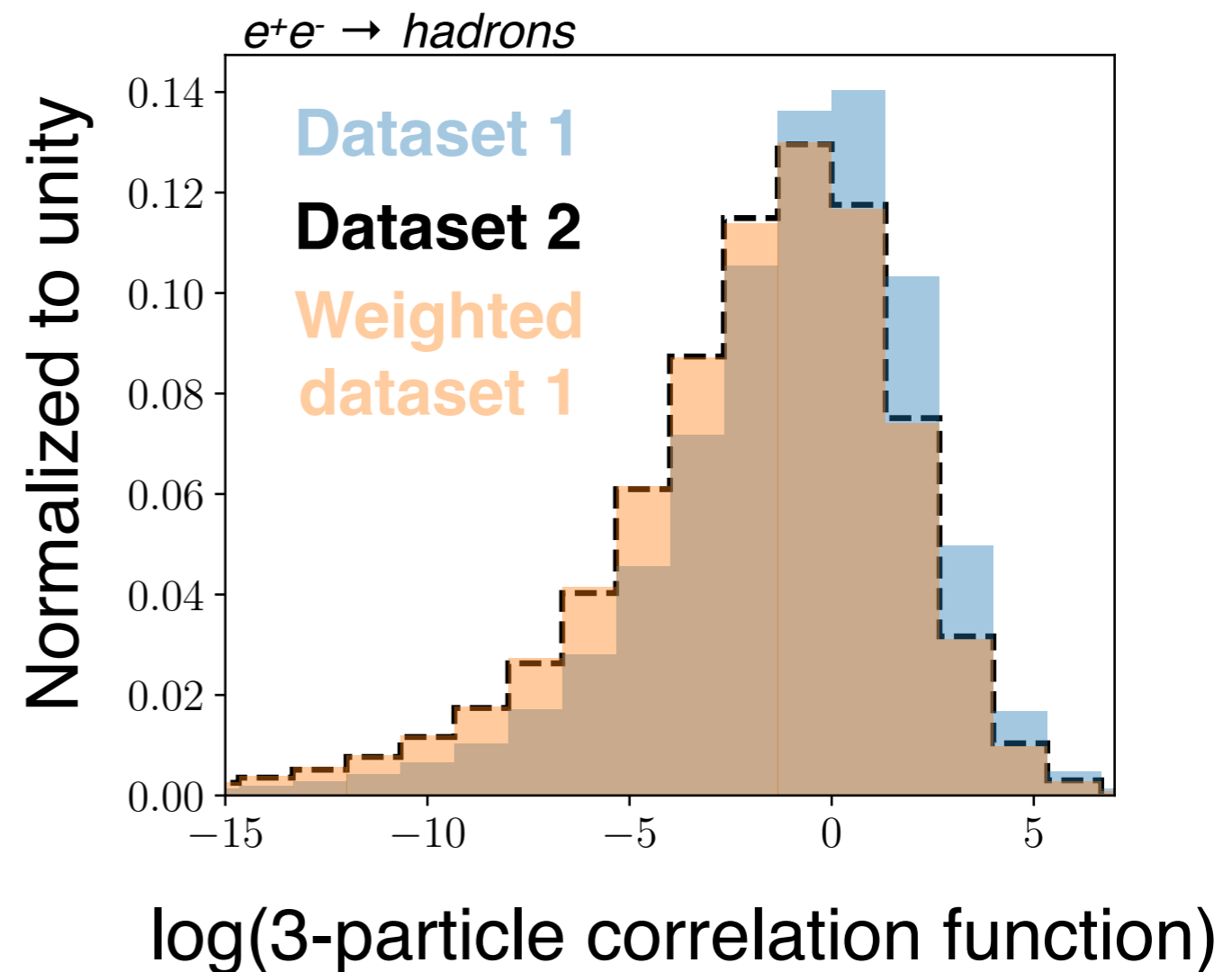
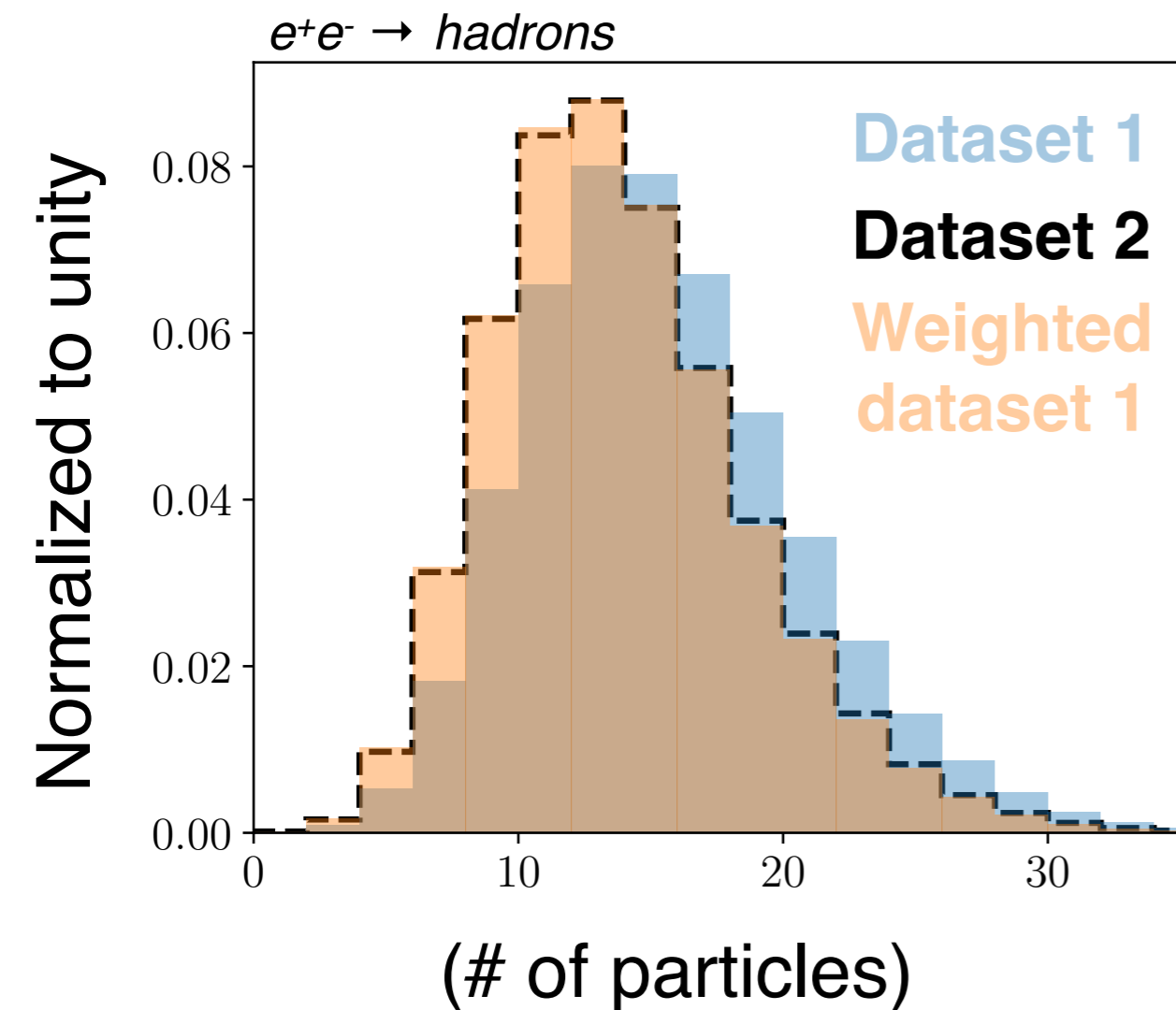
Particularly useful for particle physics, where collisions may produce a variable # of particles which are interchangeable



Classification for reweighting

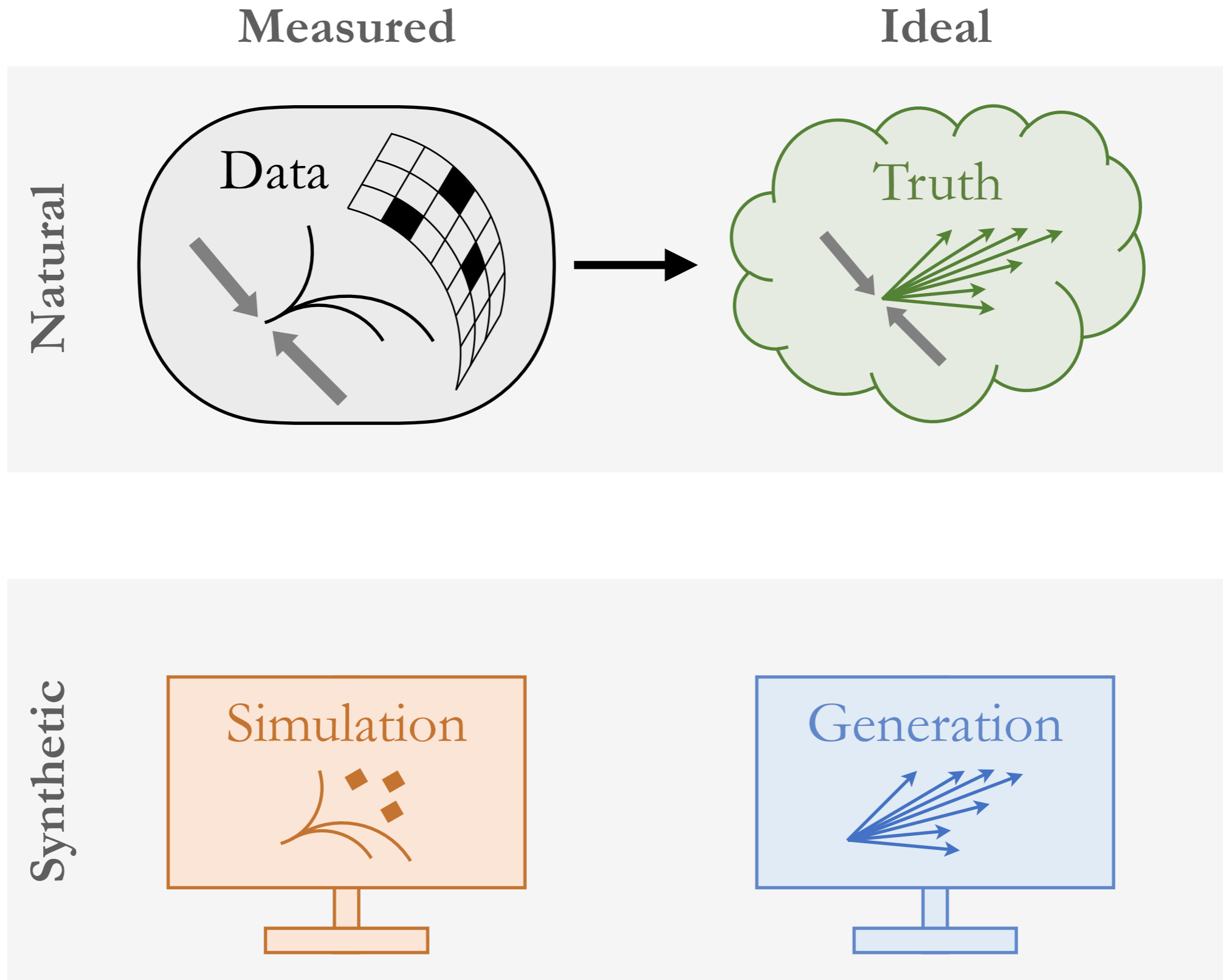
44

Reweight the **full phase space** and then check for various binned 1D observables.



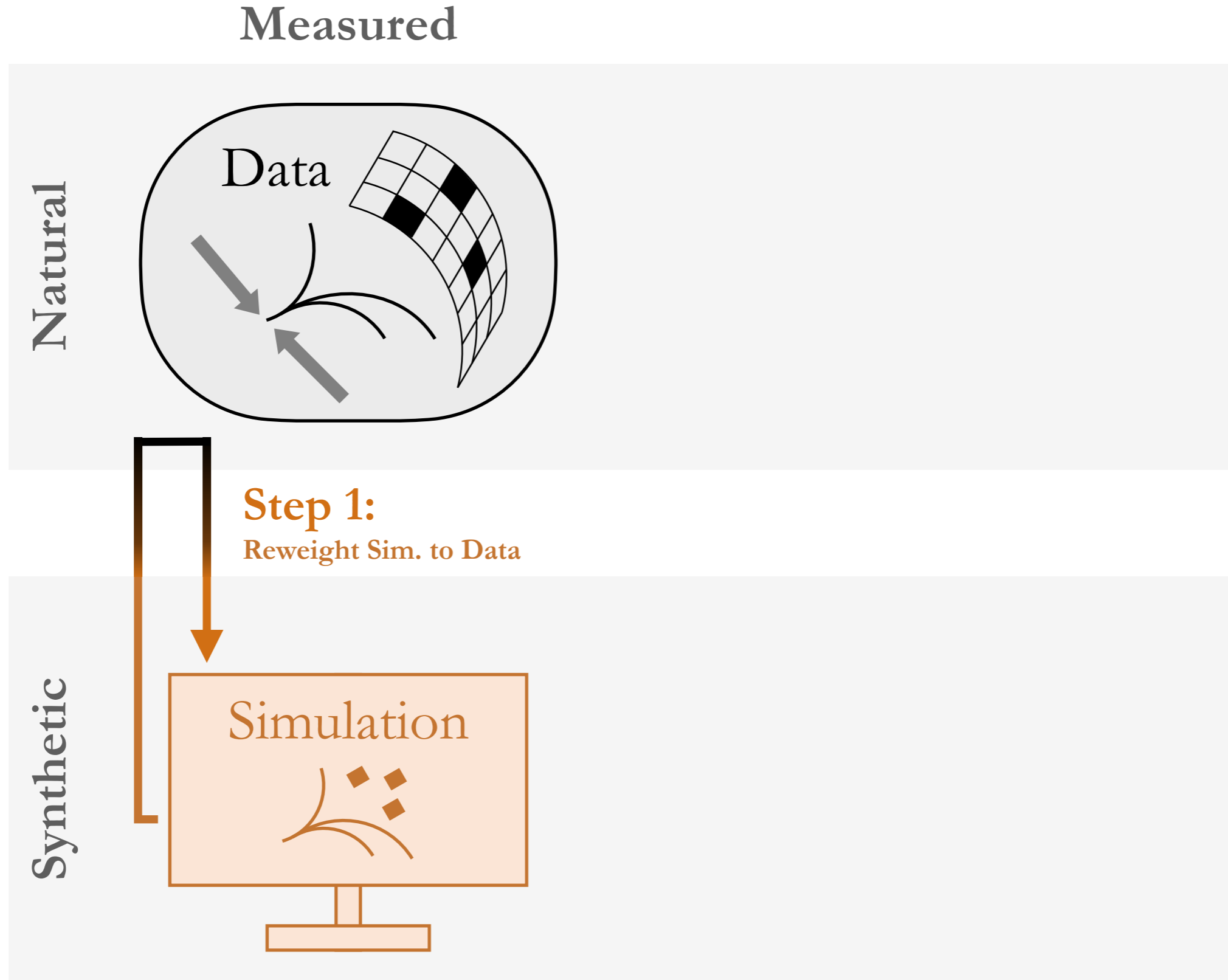
Unfold by iterating: OmniFold

45

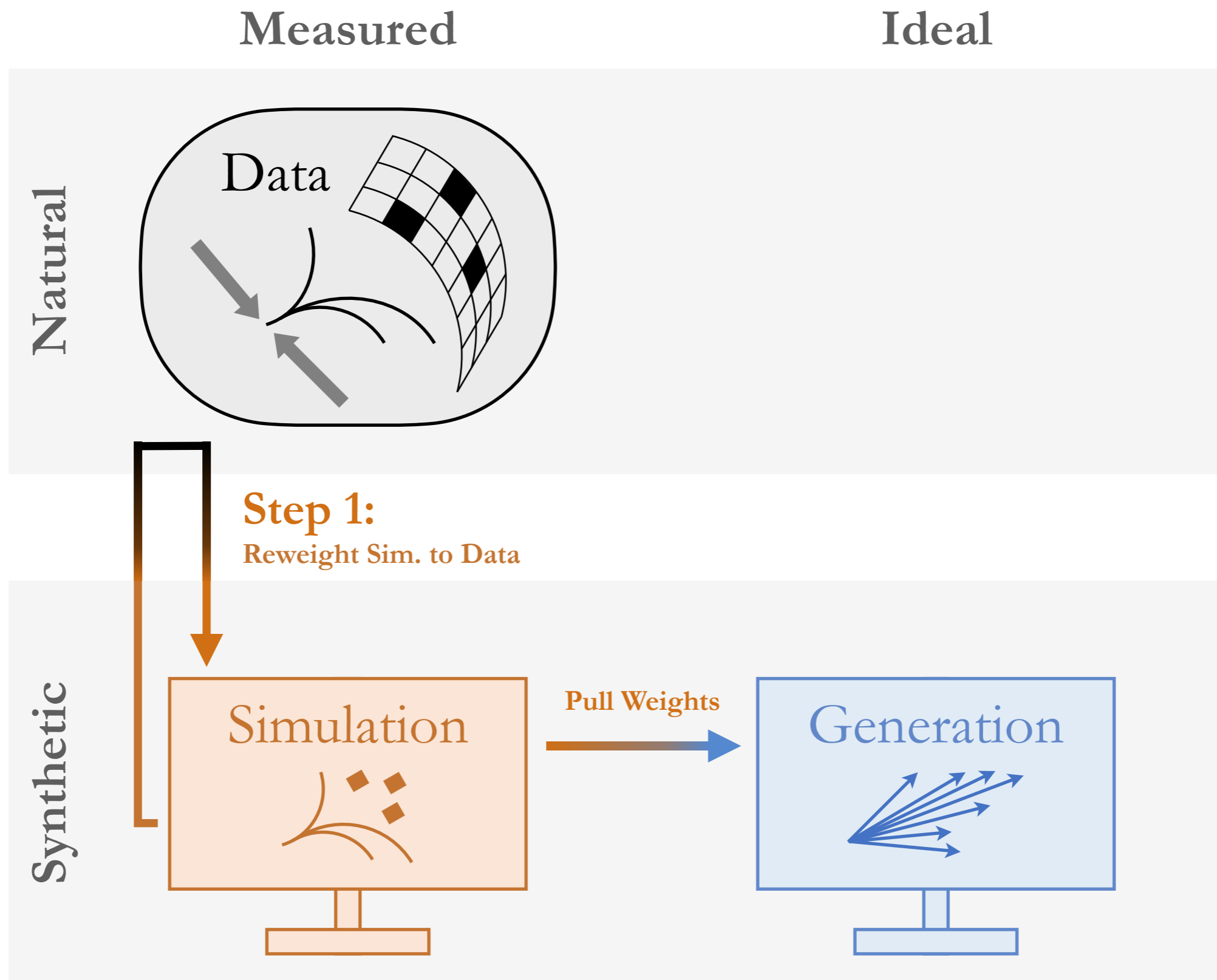


Unfold by iterating: OmniFold

46

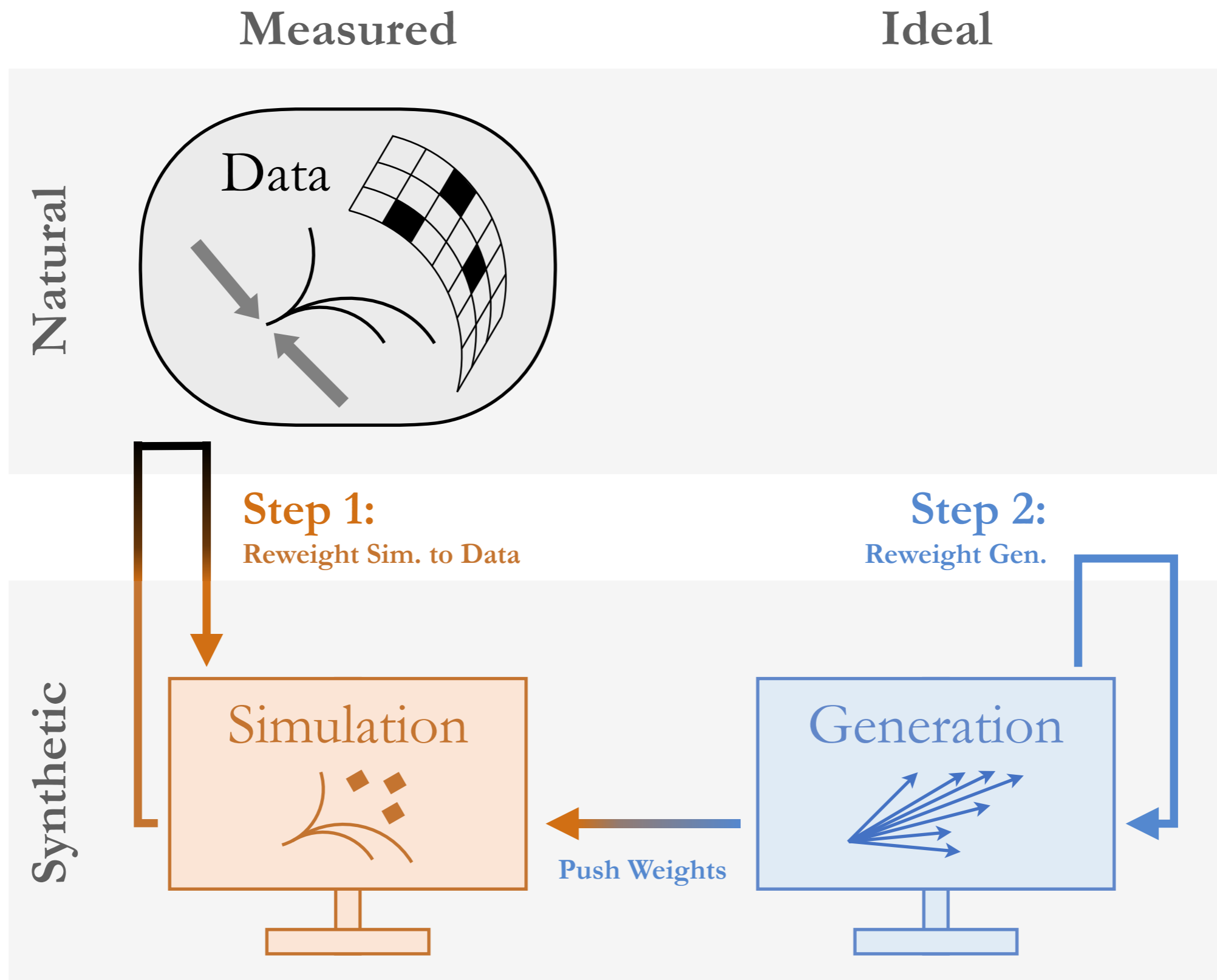


Unfold by iterating: OmniFold

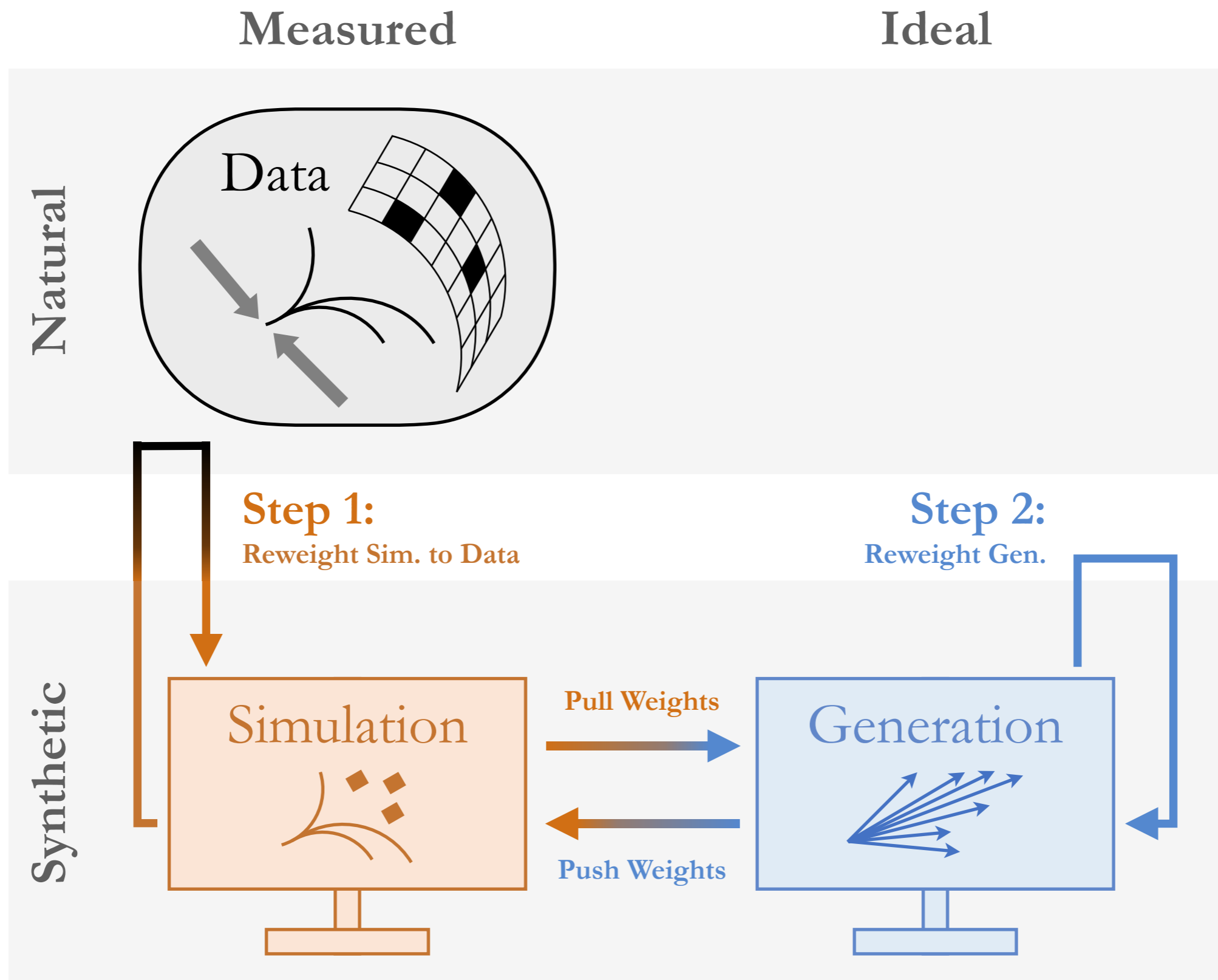


Unfold by iterating: OmniFold

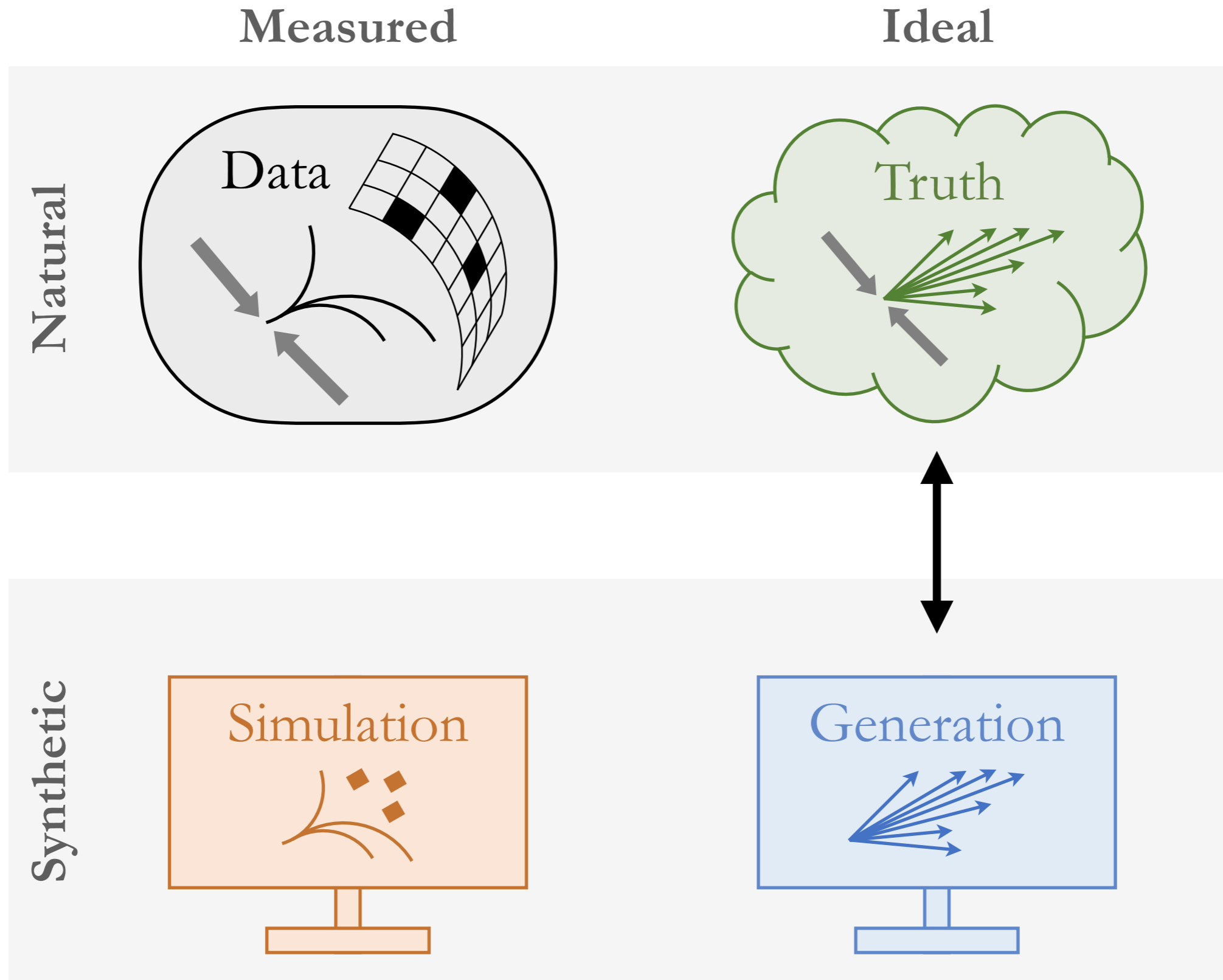
48



Unfold by iterating: OmniFold

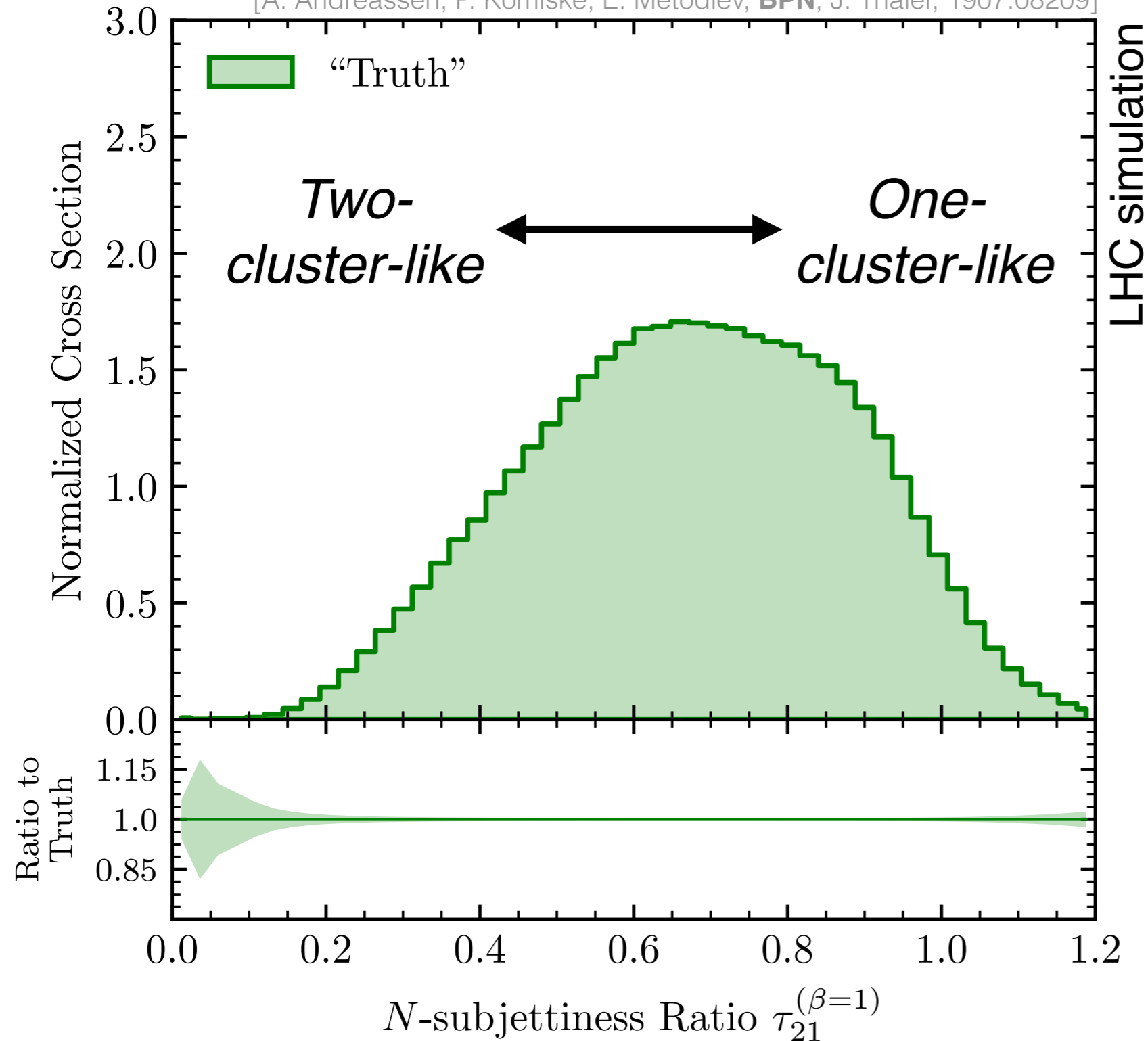


Unfold by iterating: OmniFold



Results

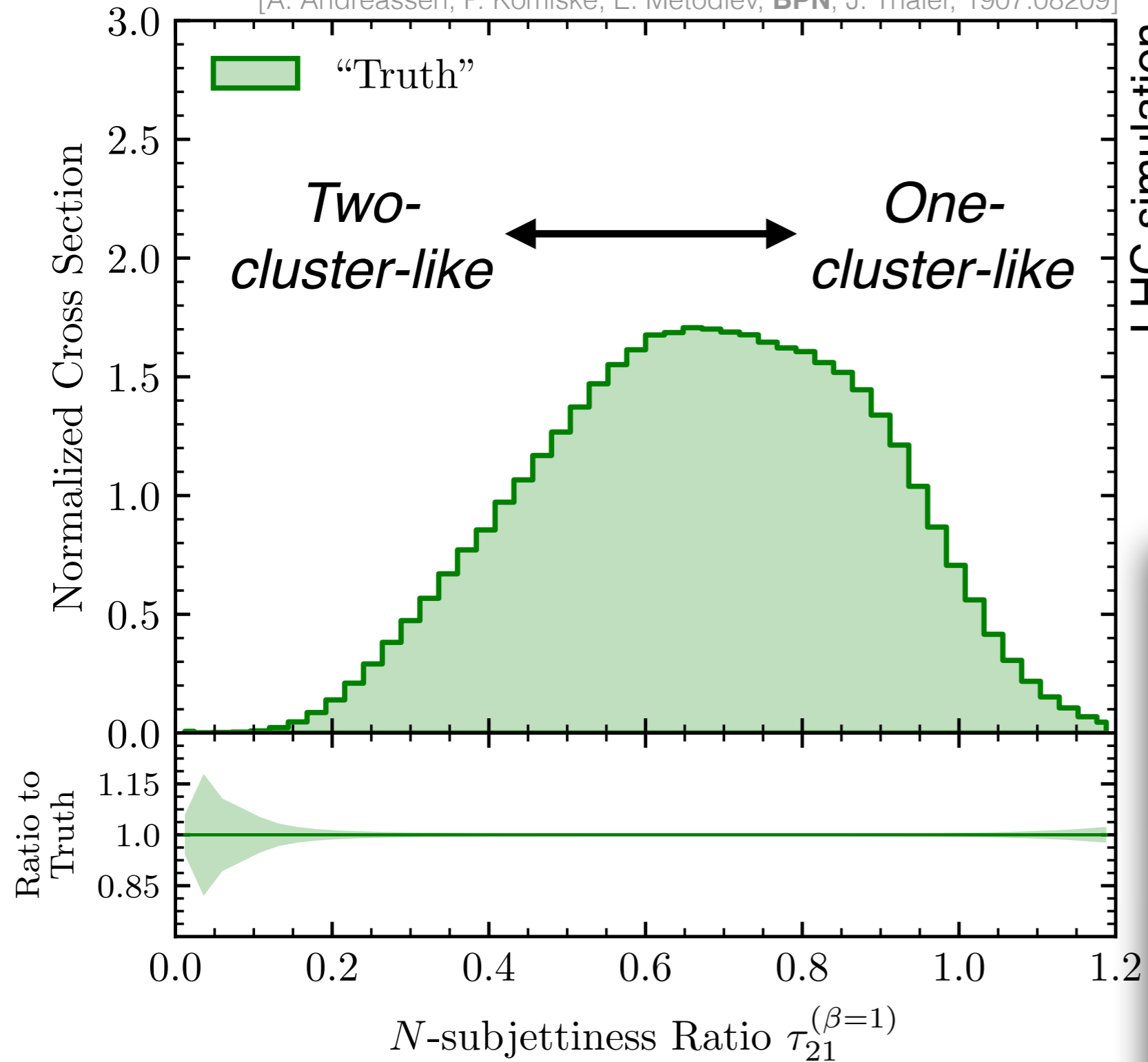
[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]



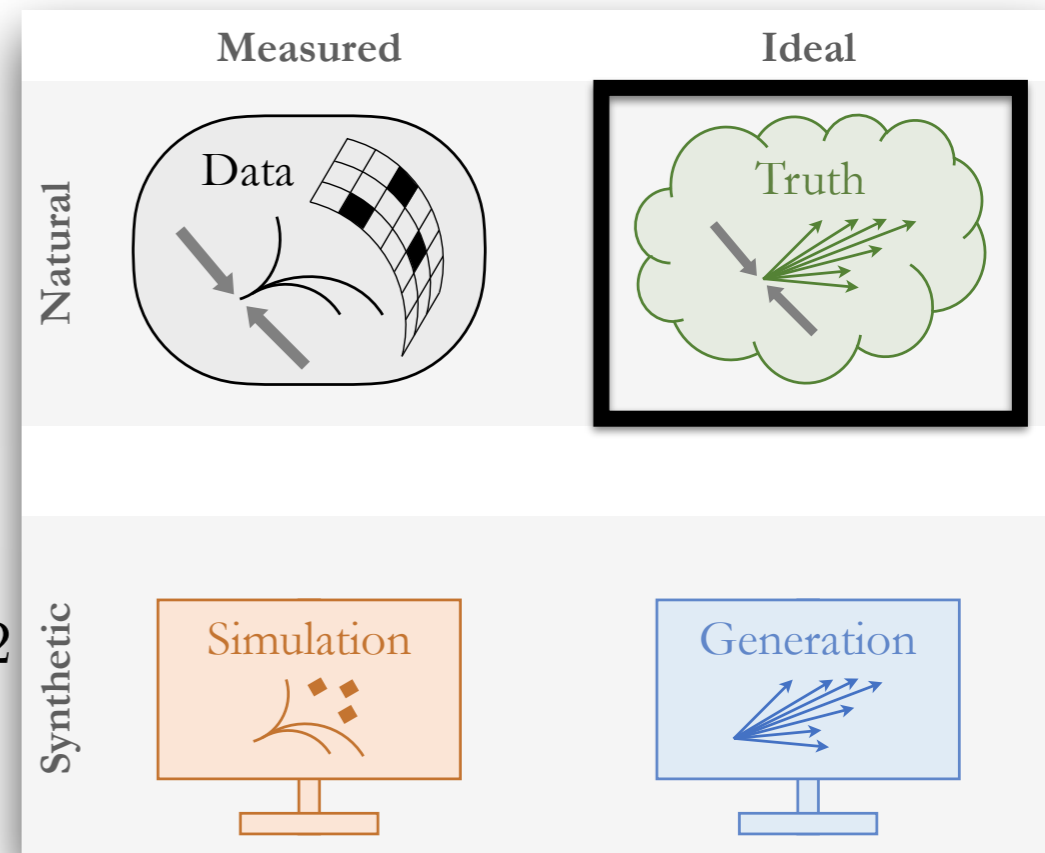
Consider this observable, which characterizes the substructure

Results

[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]

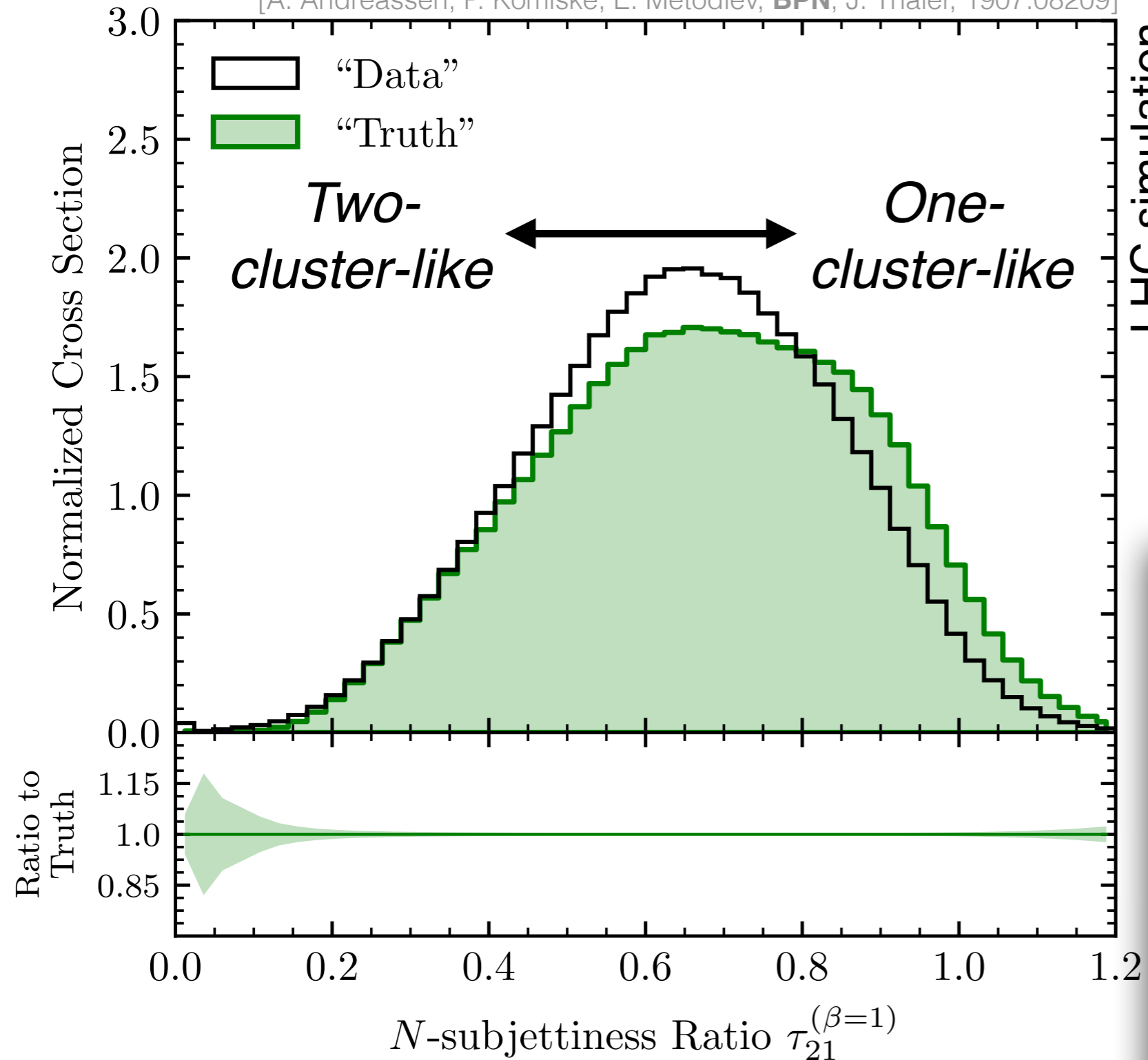


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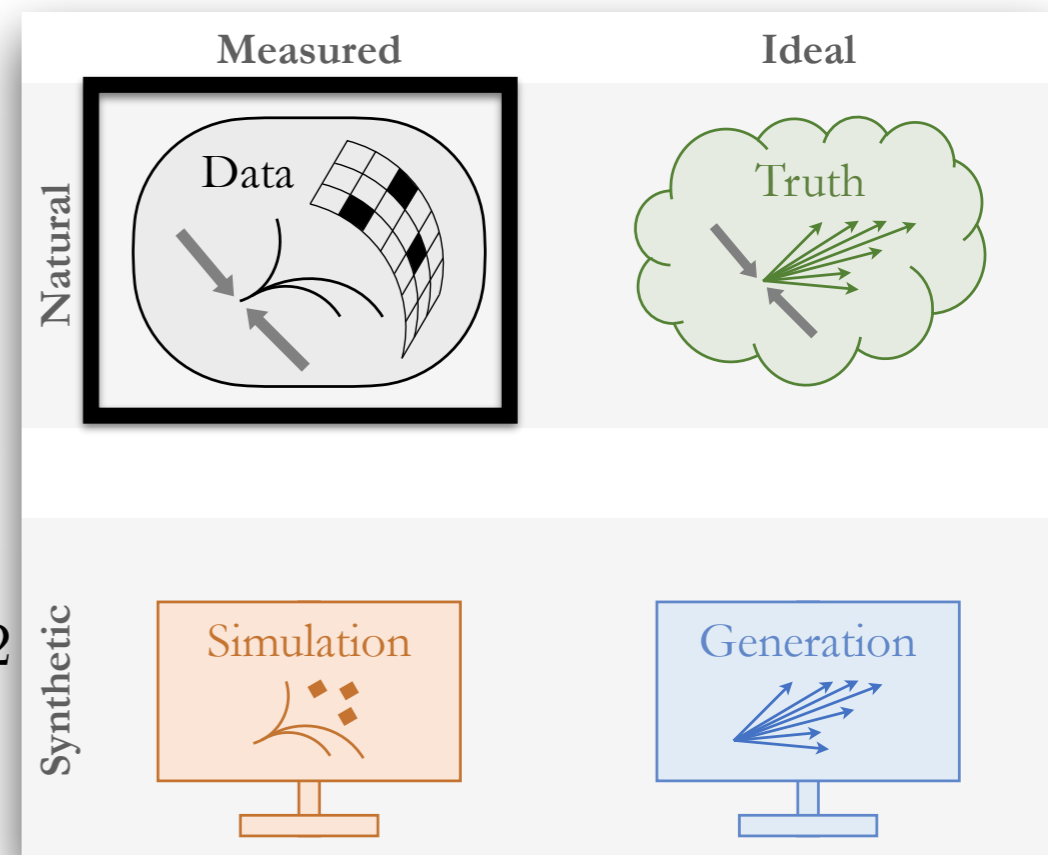


Results

[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]

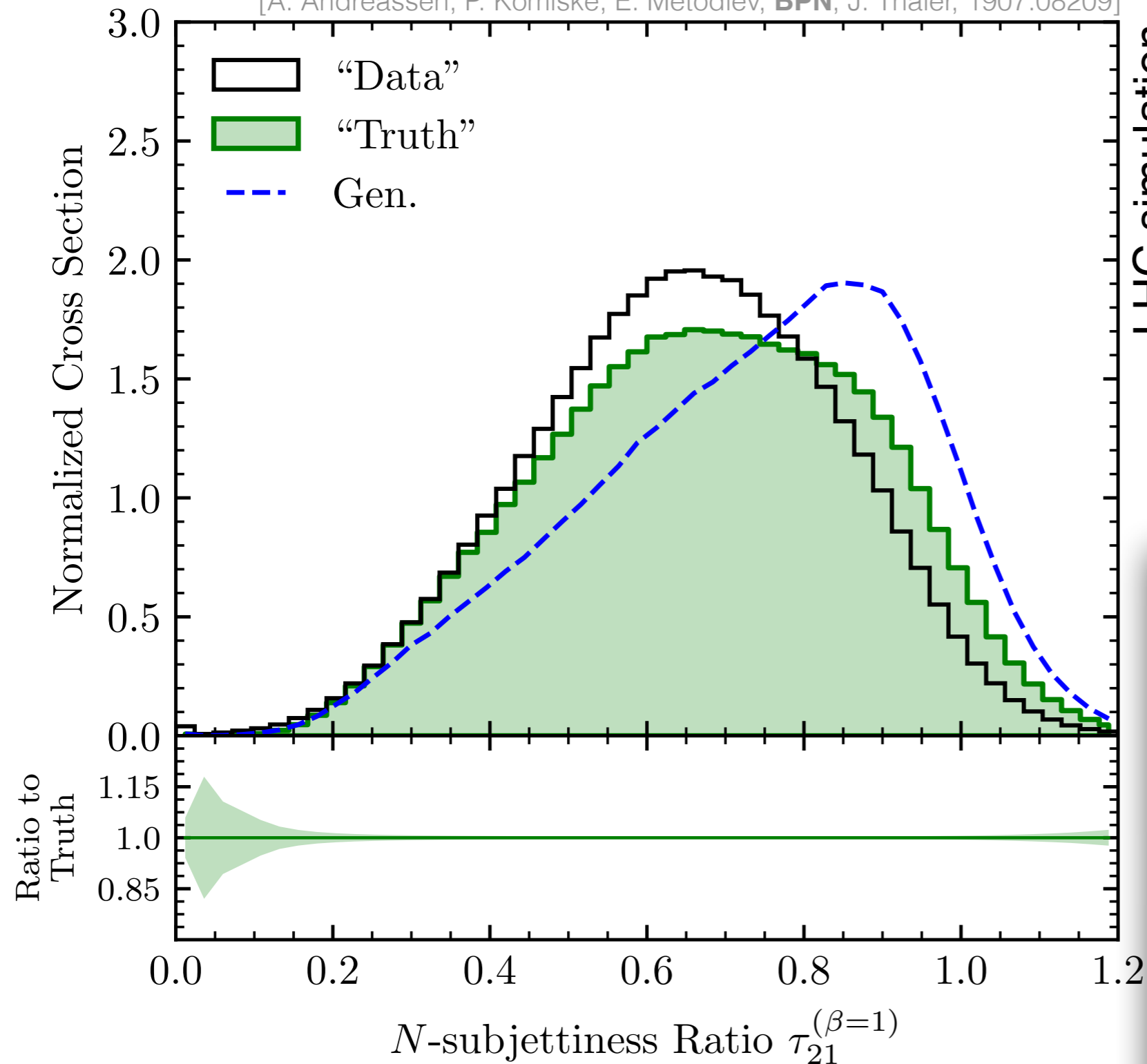


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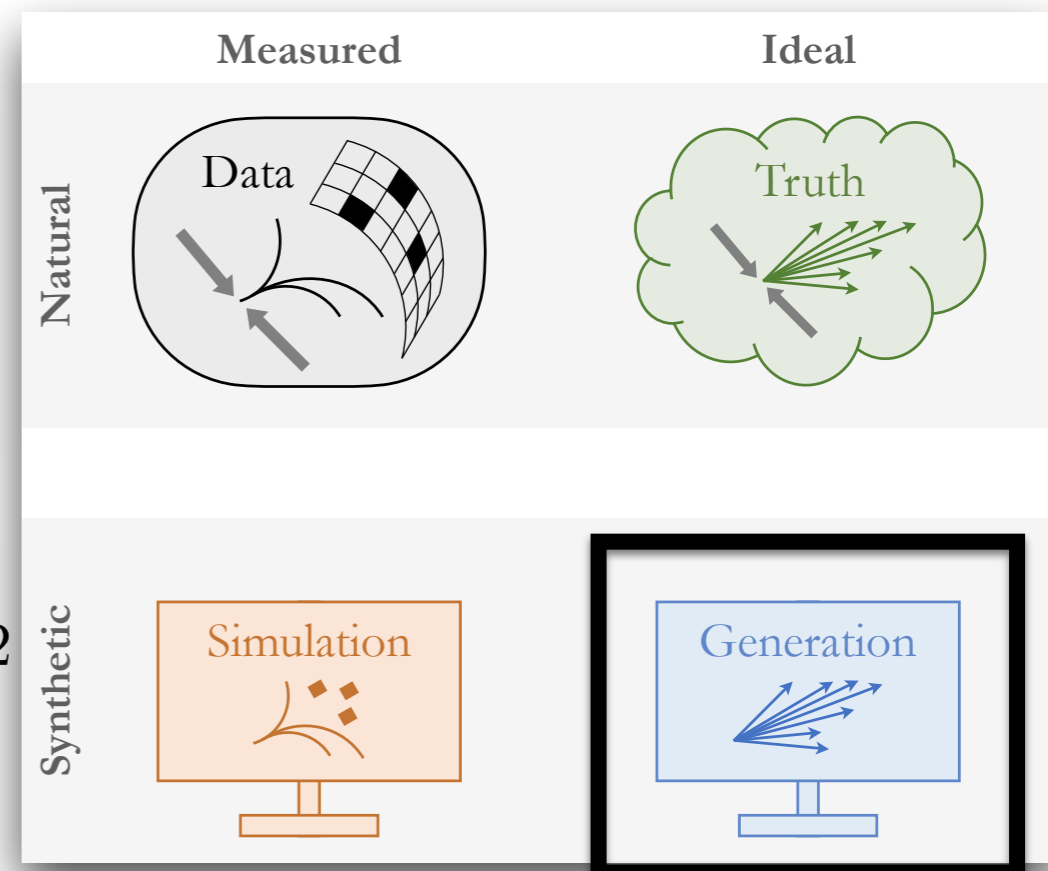
Results

[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]



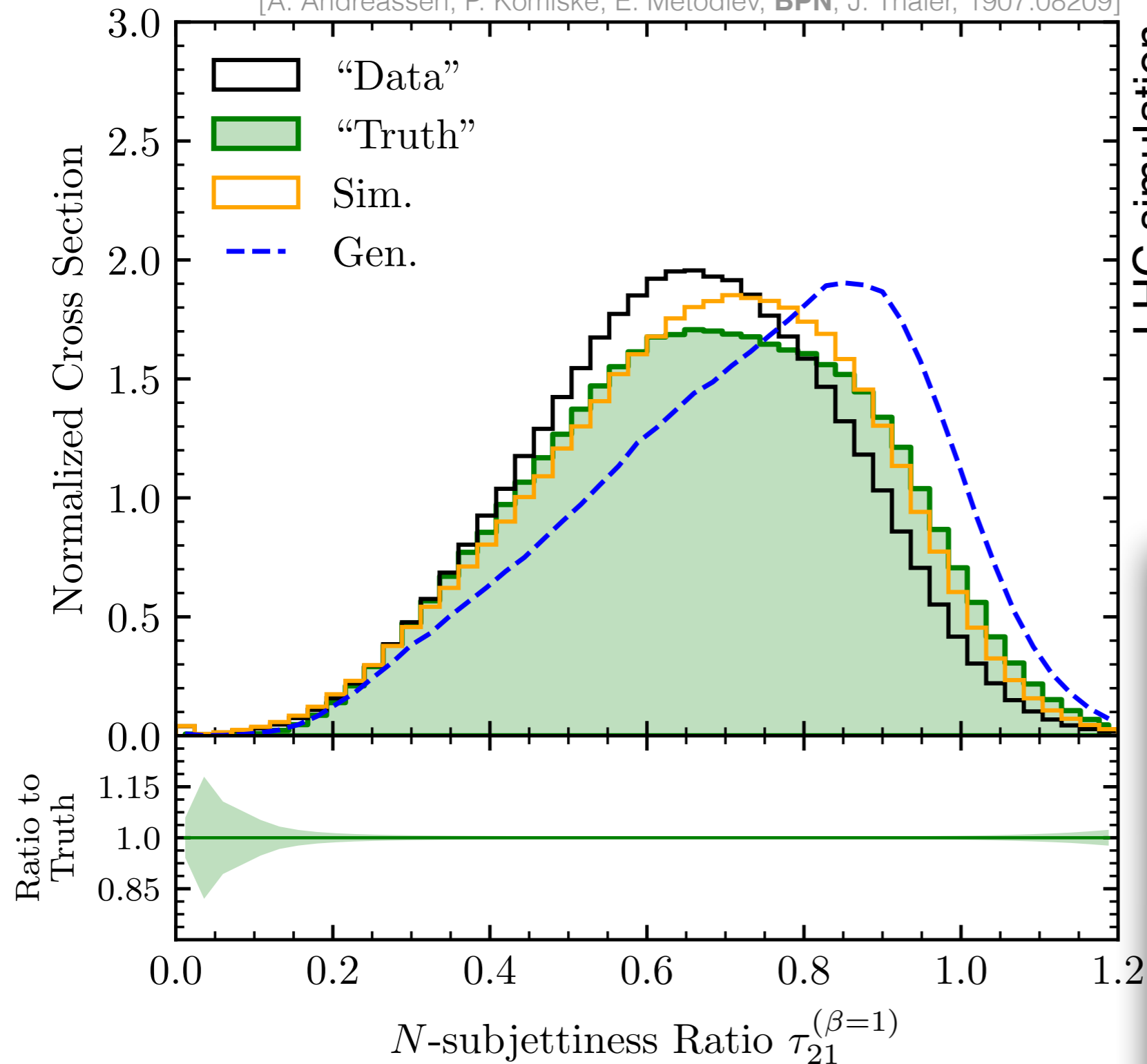
LHC simulation

Consider this observable, which characterizes the substructure



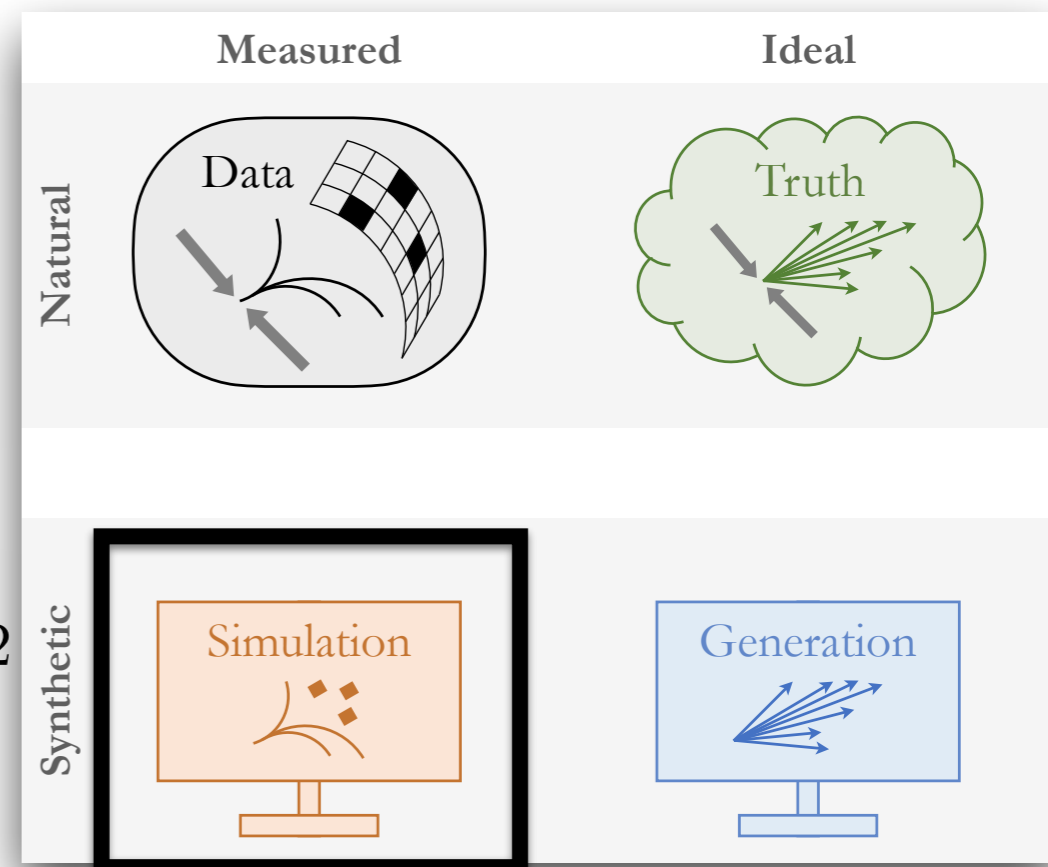
Results

[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]



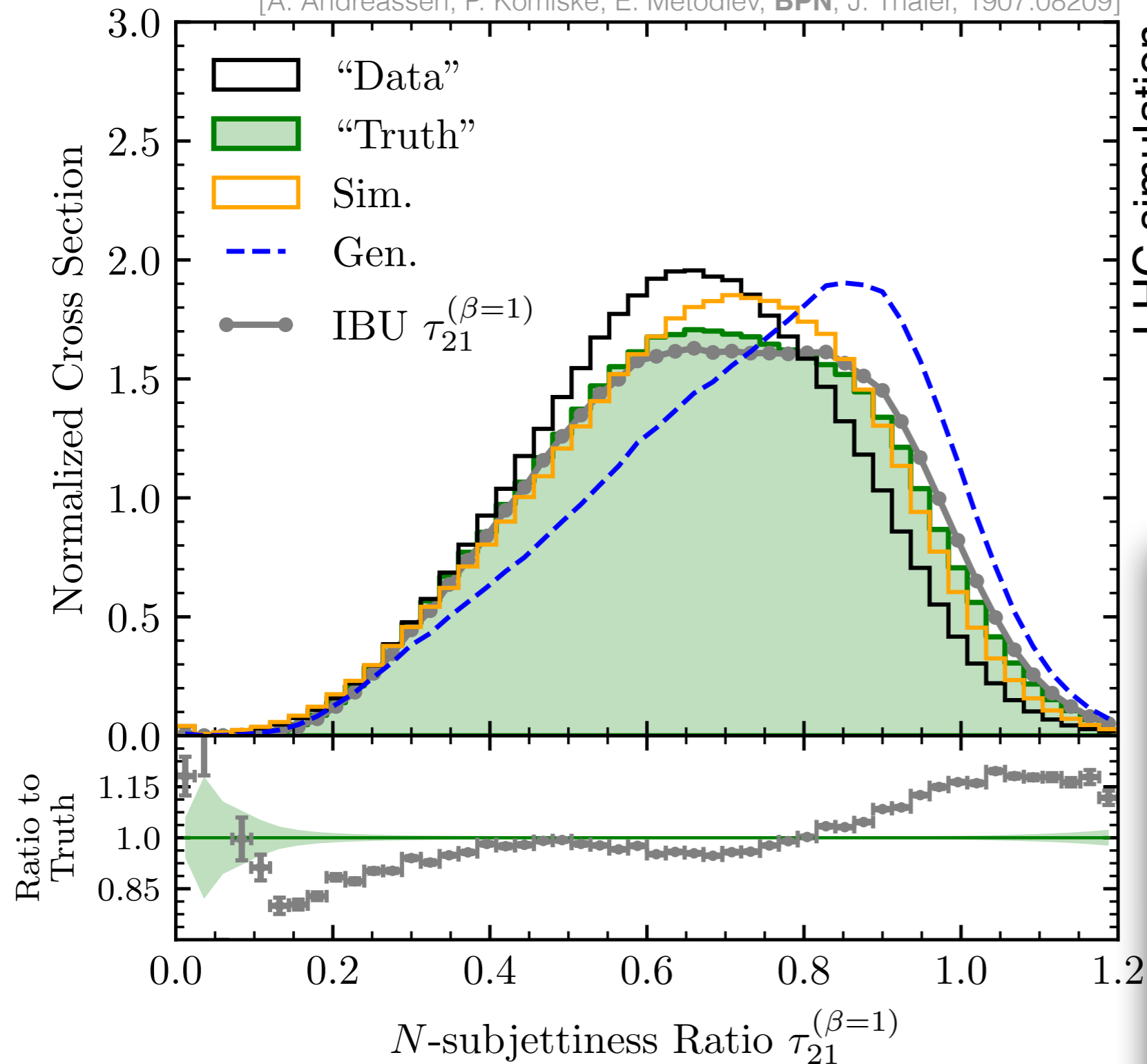
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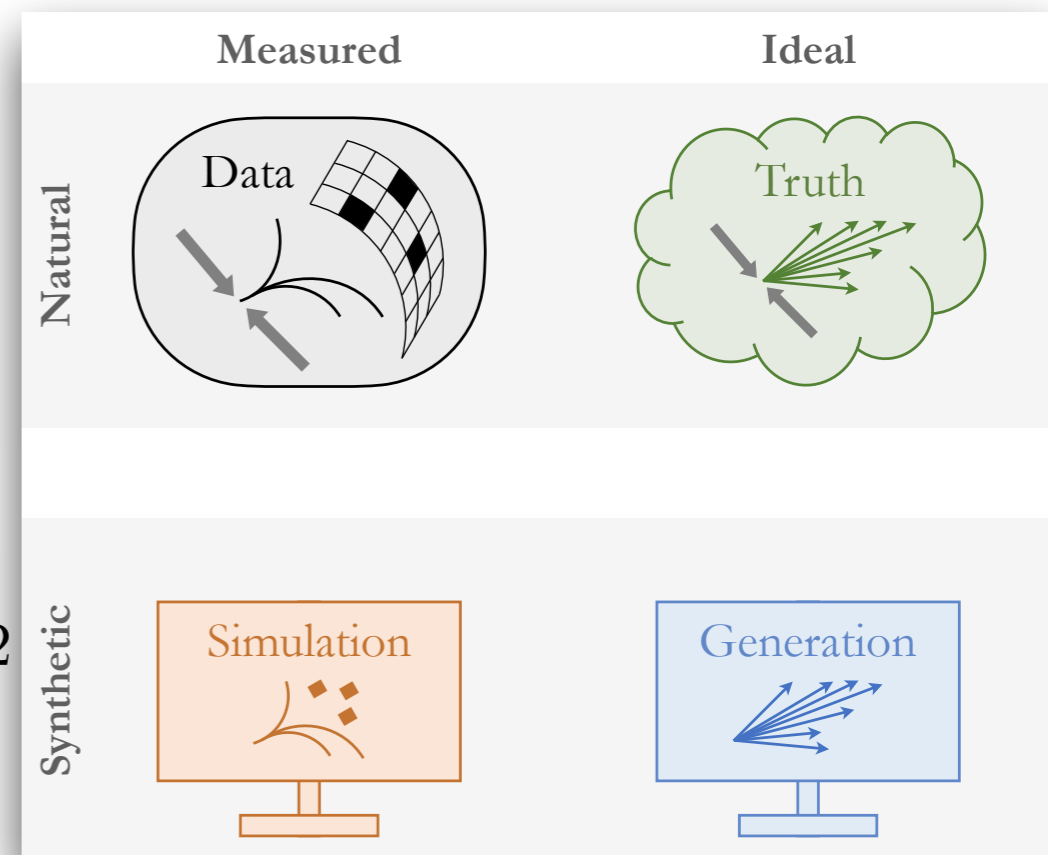
Results

[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]



LHC simulation

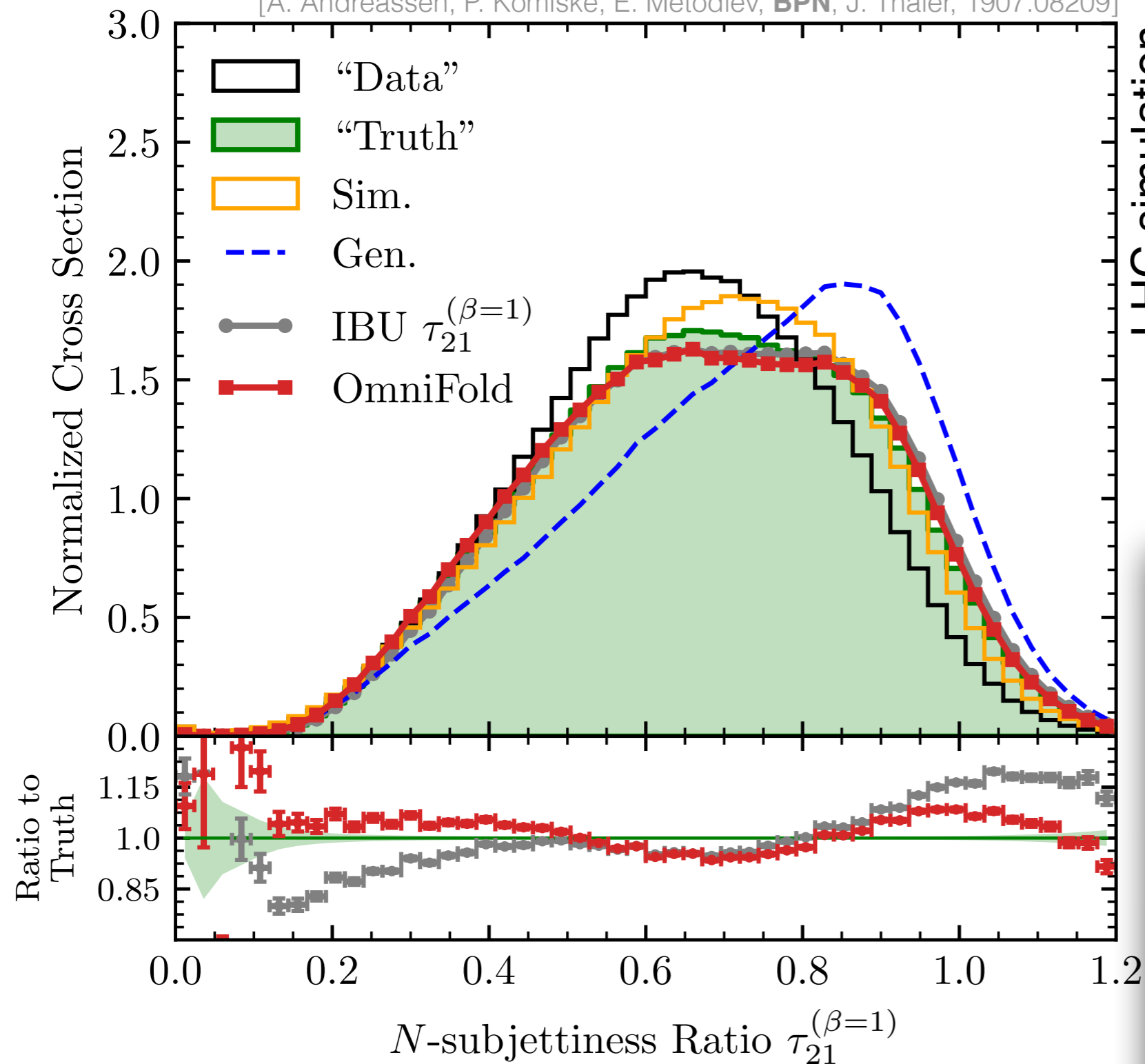
IBU is the current standard. It is a 1D binned and iterative approach.



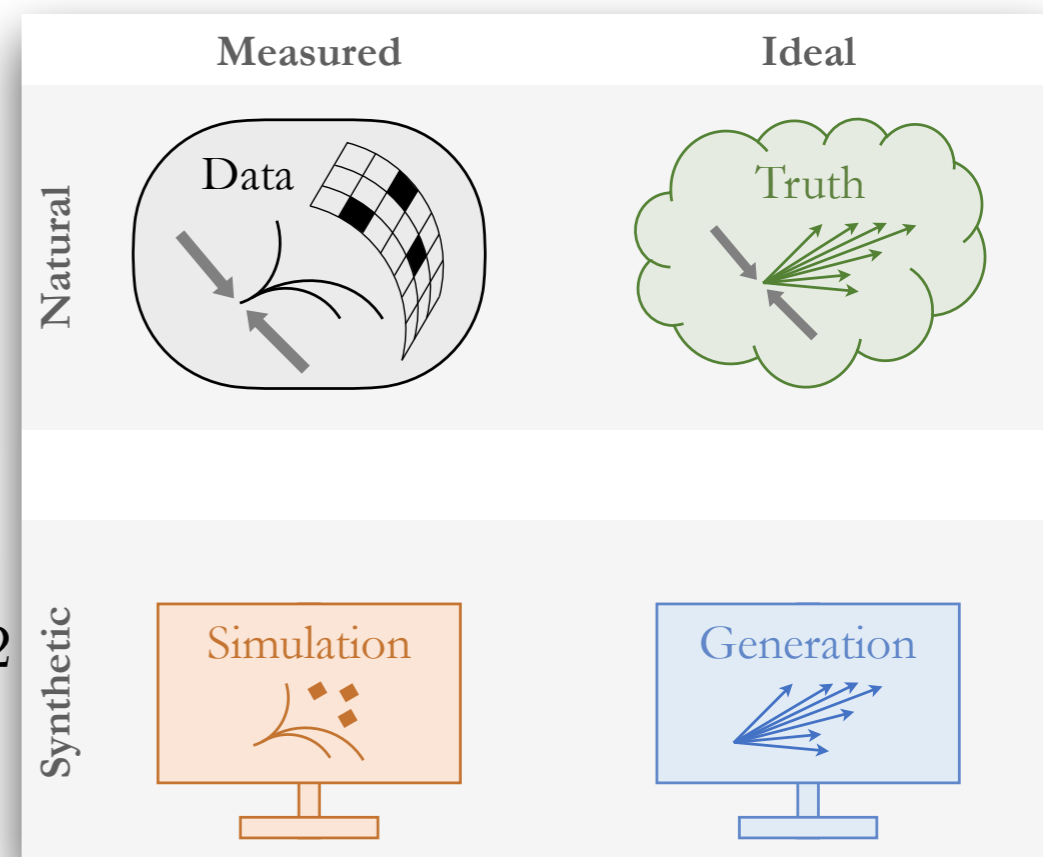
Results

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[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]



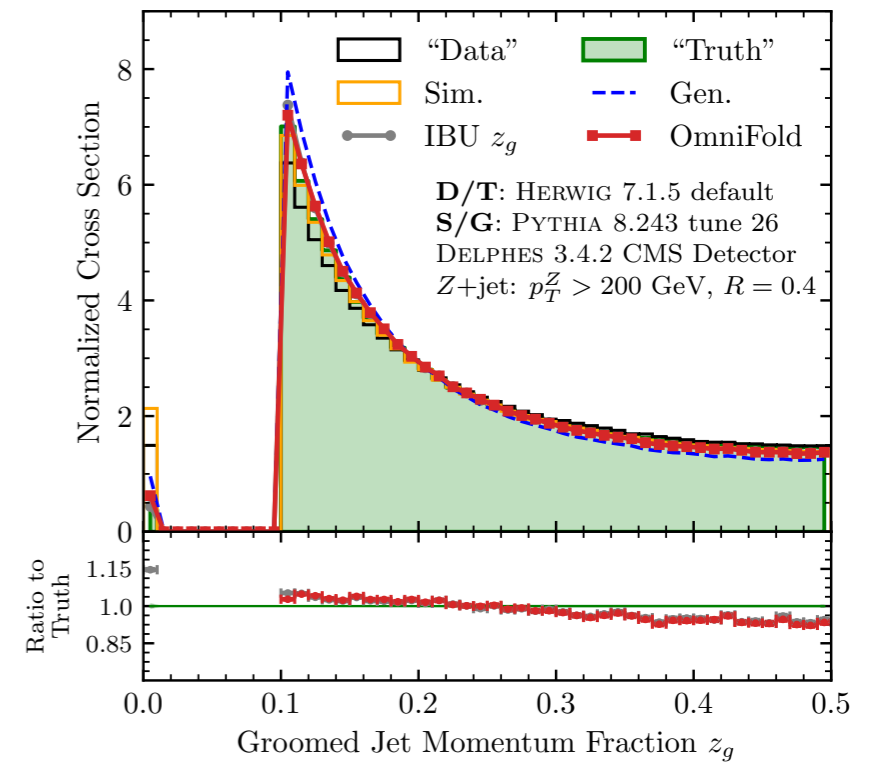
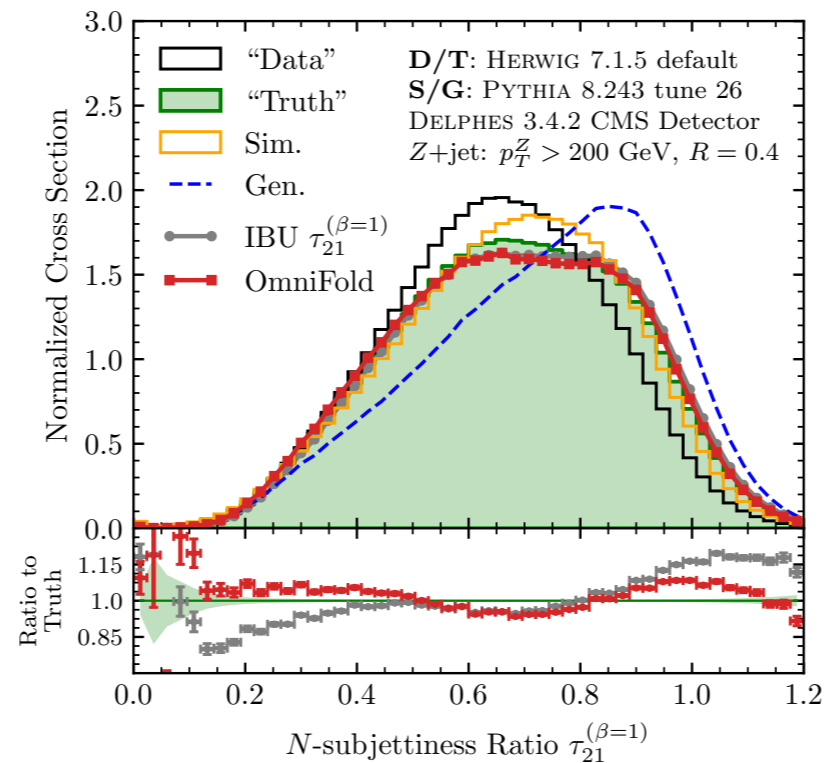
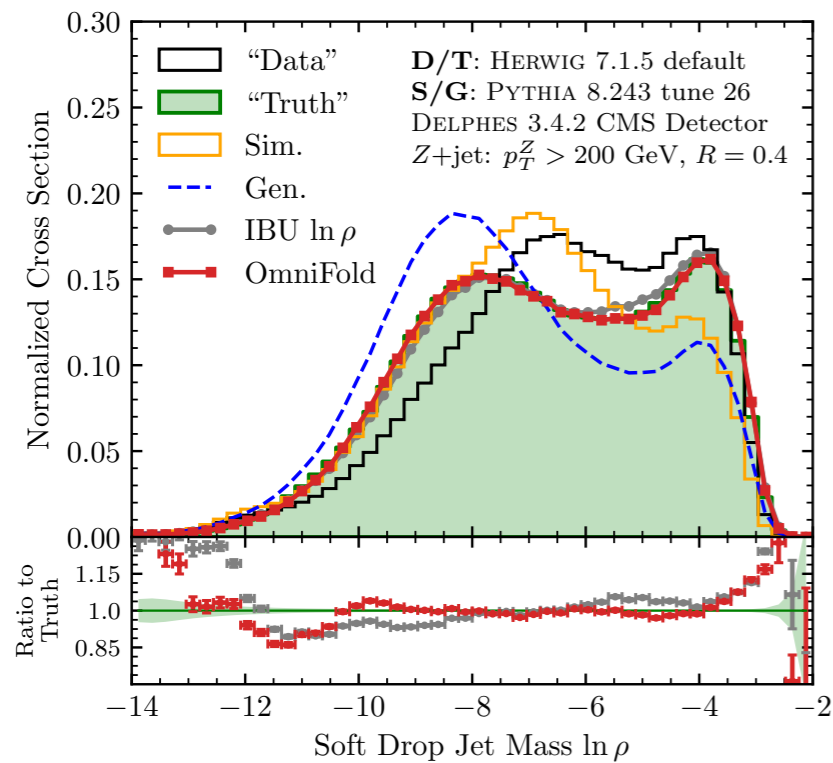
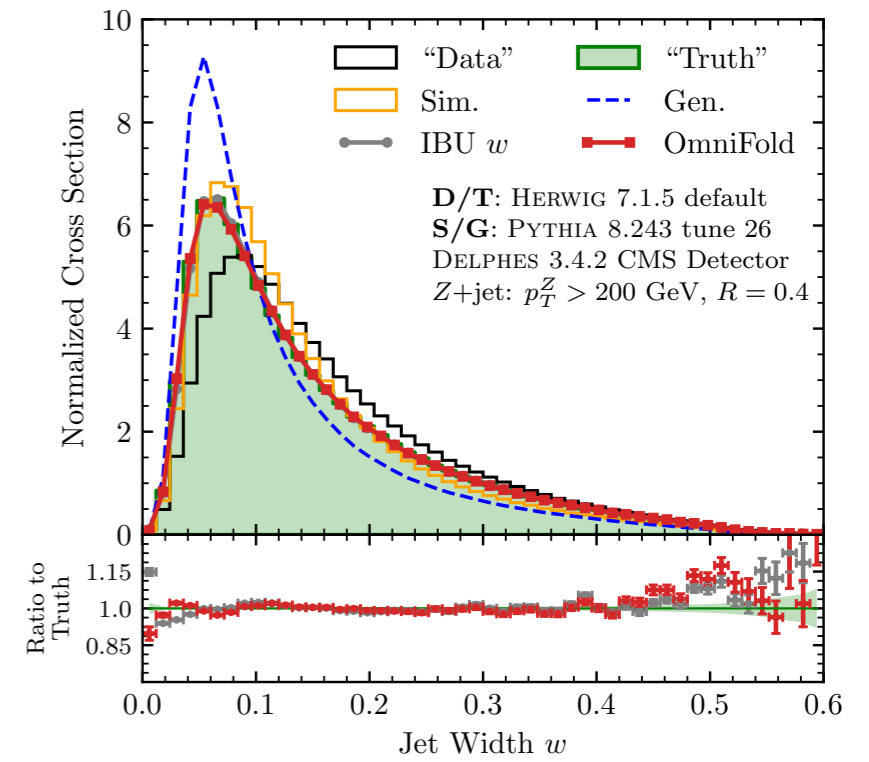
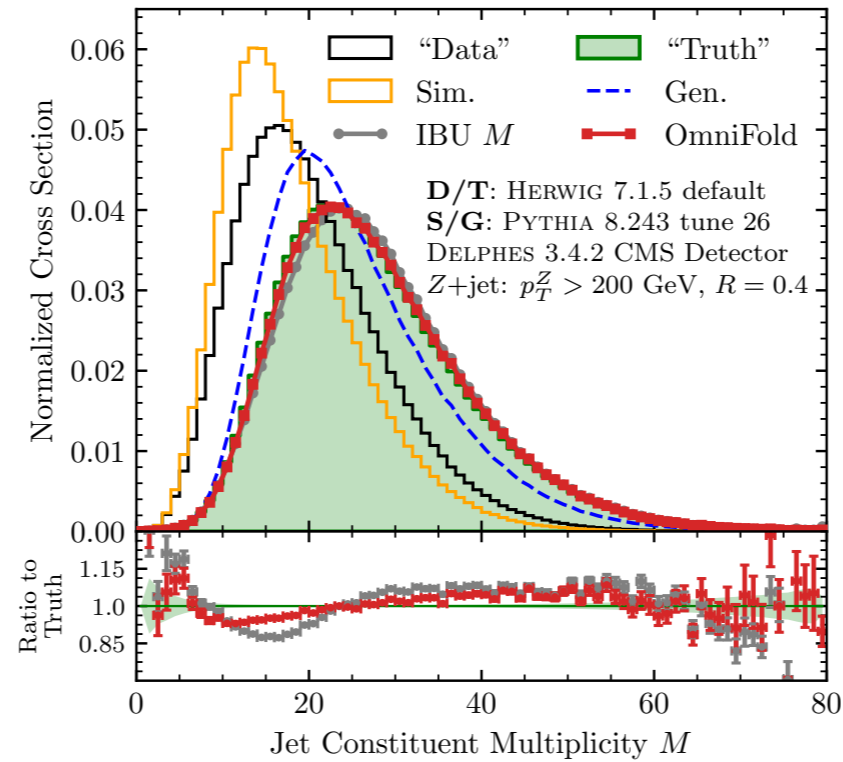
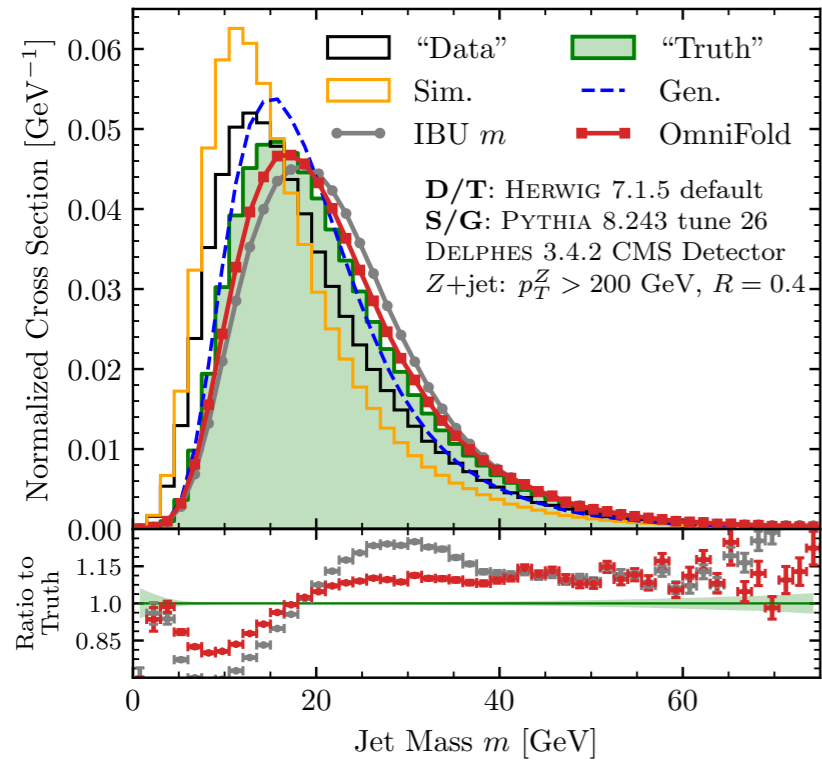
OmniFold
outperforms IBU
even though it is not
tailored to this
observable



Results

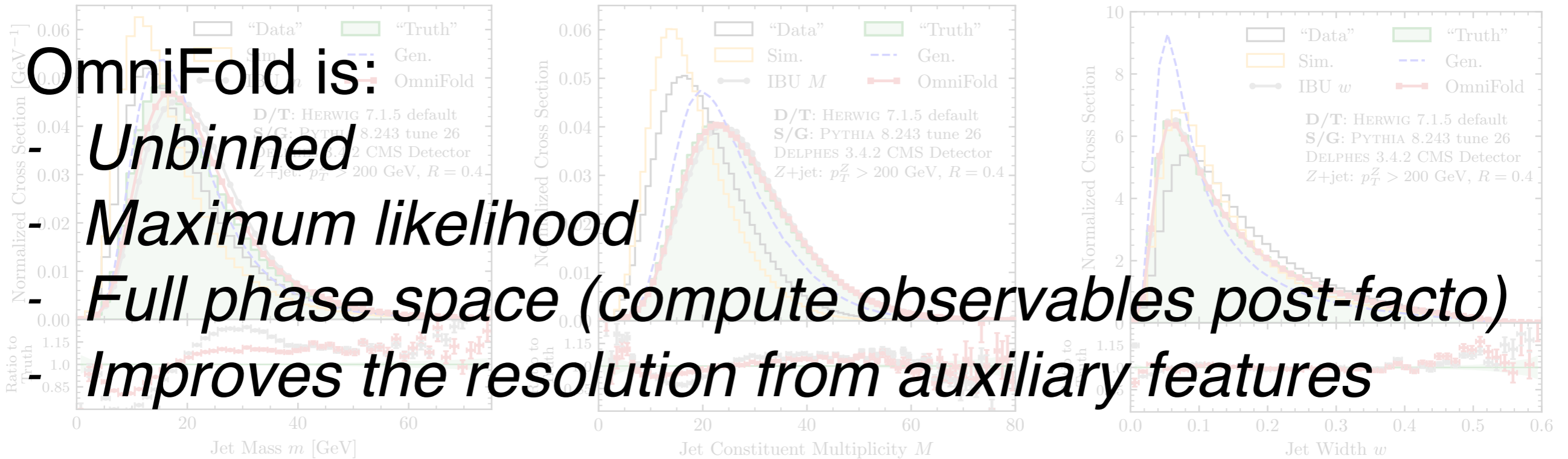
58

[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]



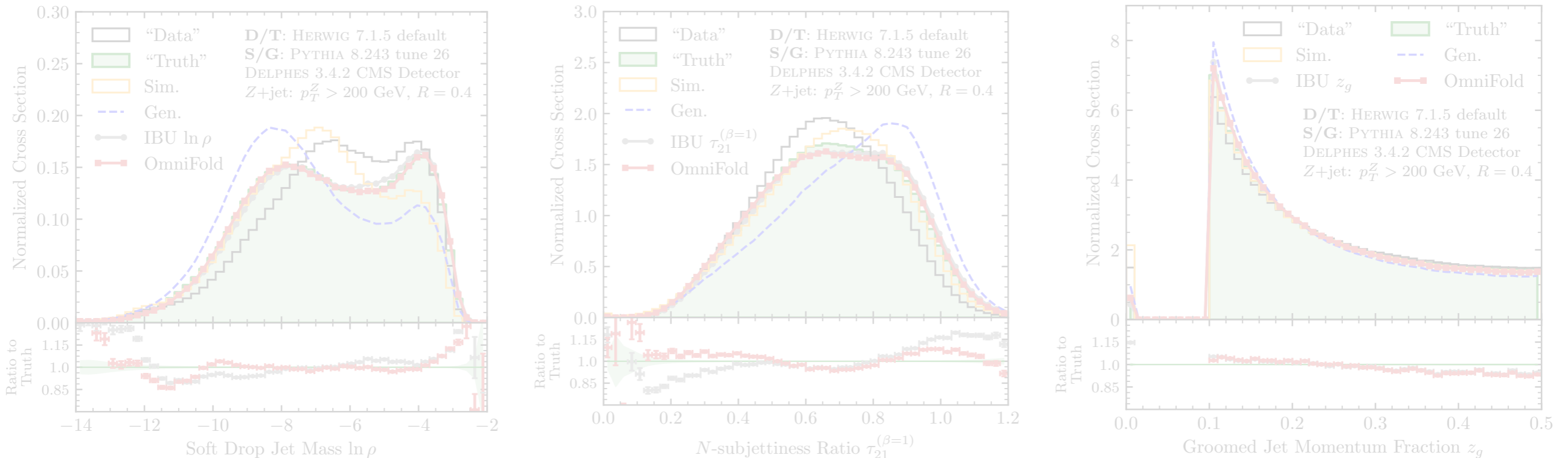
Results

[A. Andreassen, P. Komiske, E. Metodiev, **BPN**, J. Thaler, 1907.08209]



OmniFold is:

- *Unbinned*
- *Maximum likelihood*
- *Full phase space (compute observables post-facto)*
- *Improves the resolution from auxiliary features*



So far, I have assumed that we can readily generate high-fidelity examples from a physics-based simulator.

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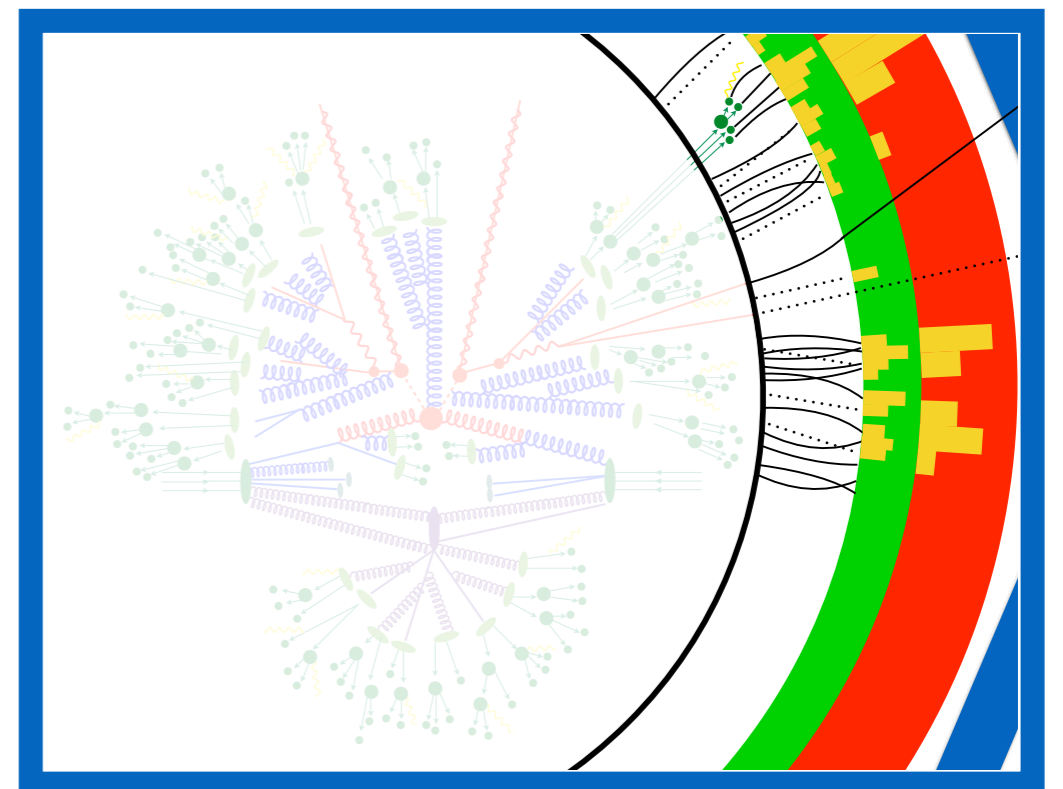
What if the simulator is too **expensive**?

So far, I have assumed that we can readily generate high-fidelity examples from a physics-based simulator.

What if the simulator is too **expensive**?



For example, Geant is an $O(1)$ fraction of all computing in high energy physics



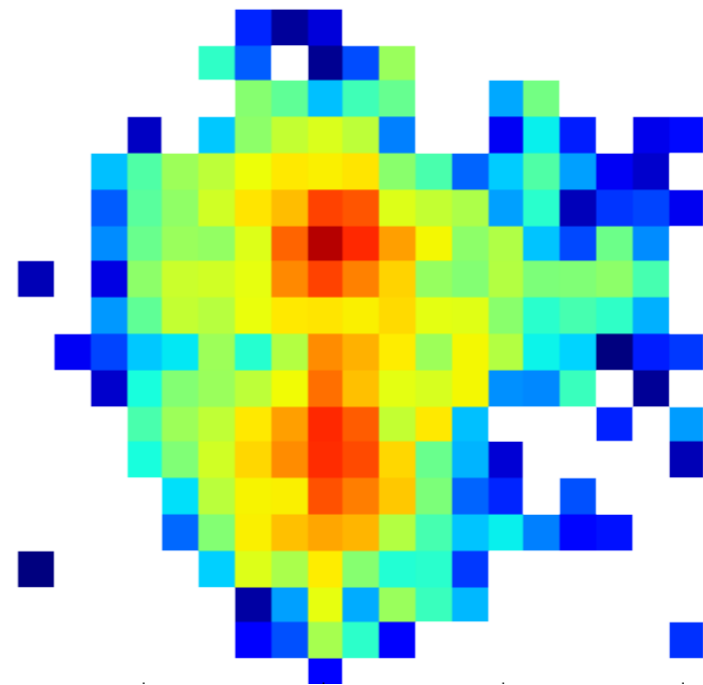
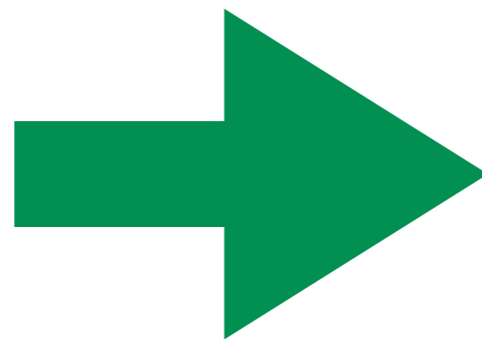
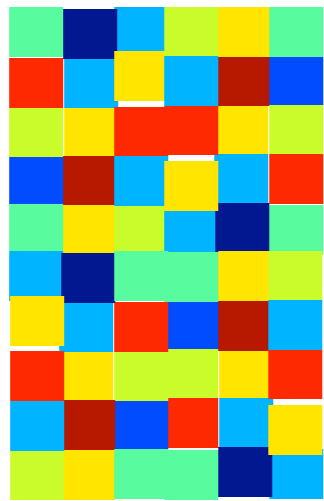
Deep Generative Models

63

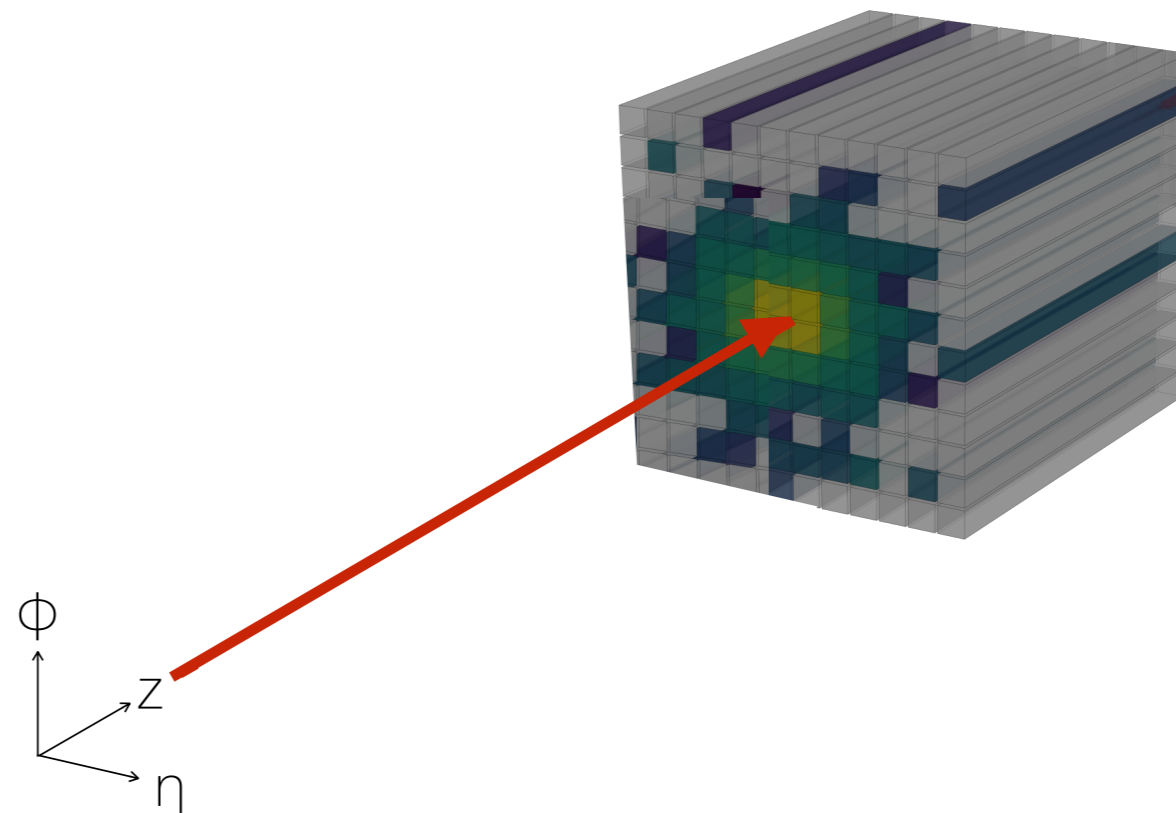
Can we combine our physics-simulator with deep learning?

Can we combine our physics-simulator with deep learning?

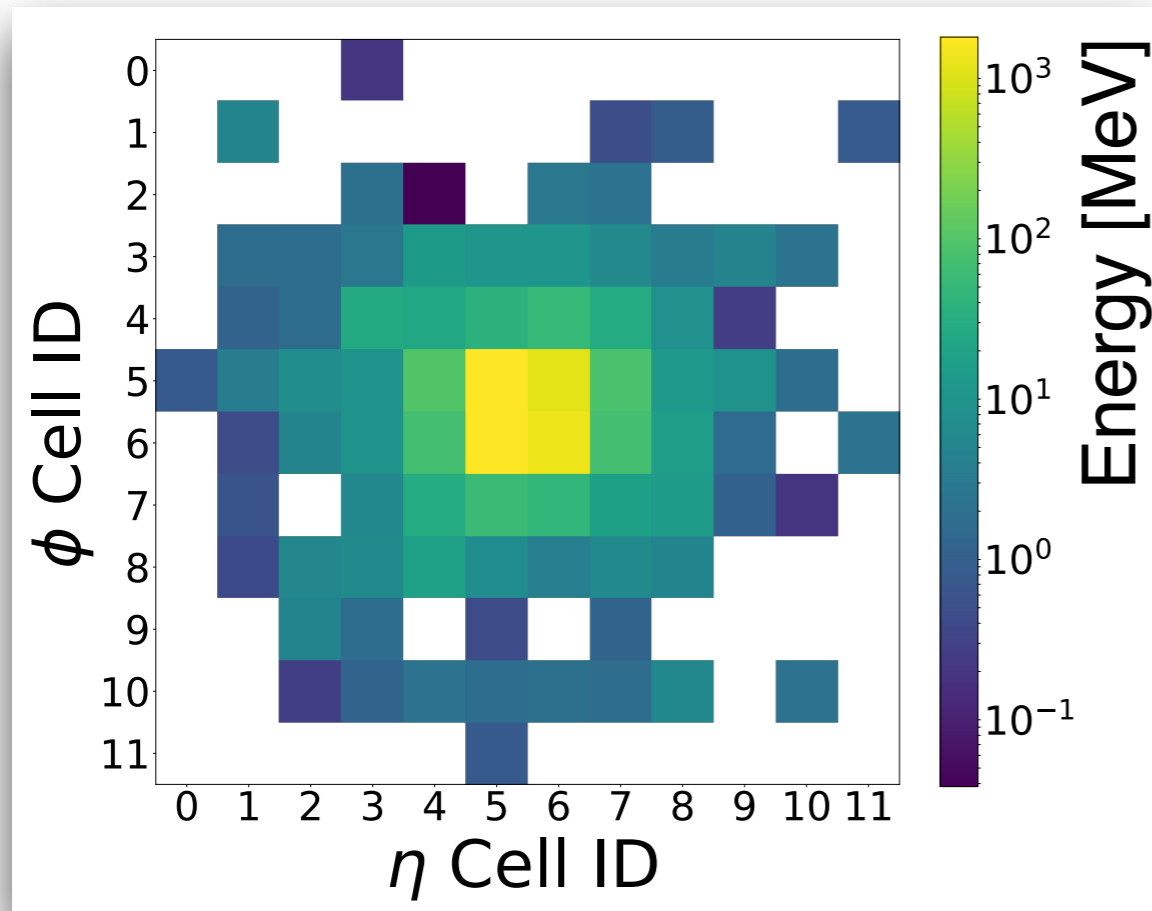
A **generator** is nothing other than a function that maps random numbers to structure.



The slowest simulation corresponds to the densest material (= calorimeter)

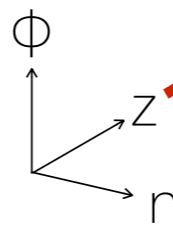
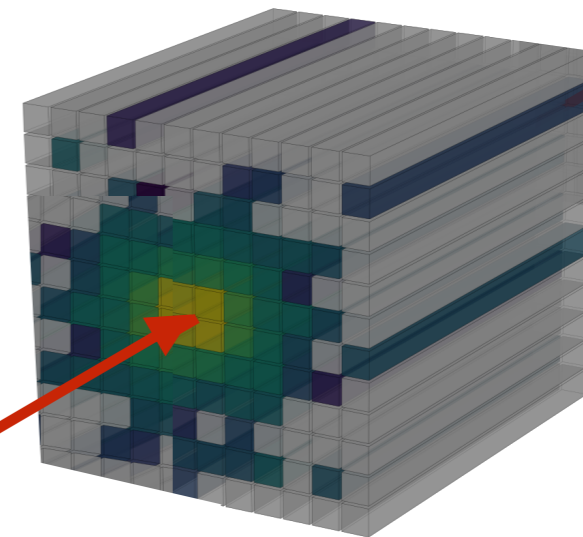


Calorimeter images



The slowest simulation corresponds to the densest material (= calorimeter)

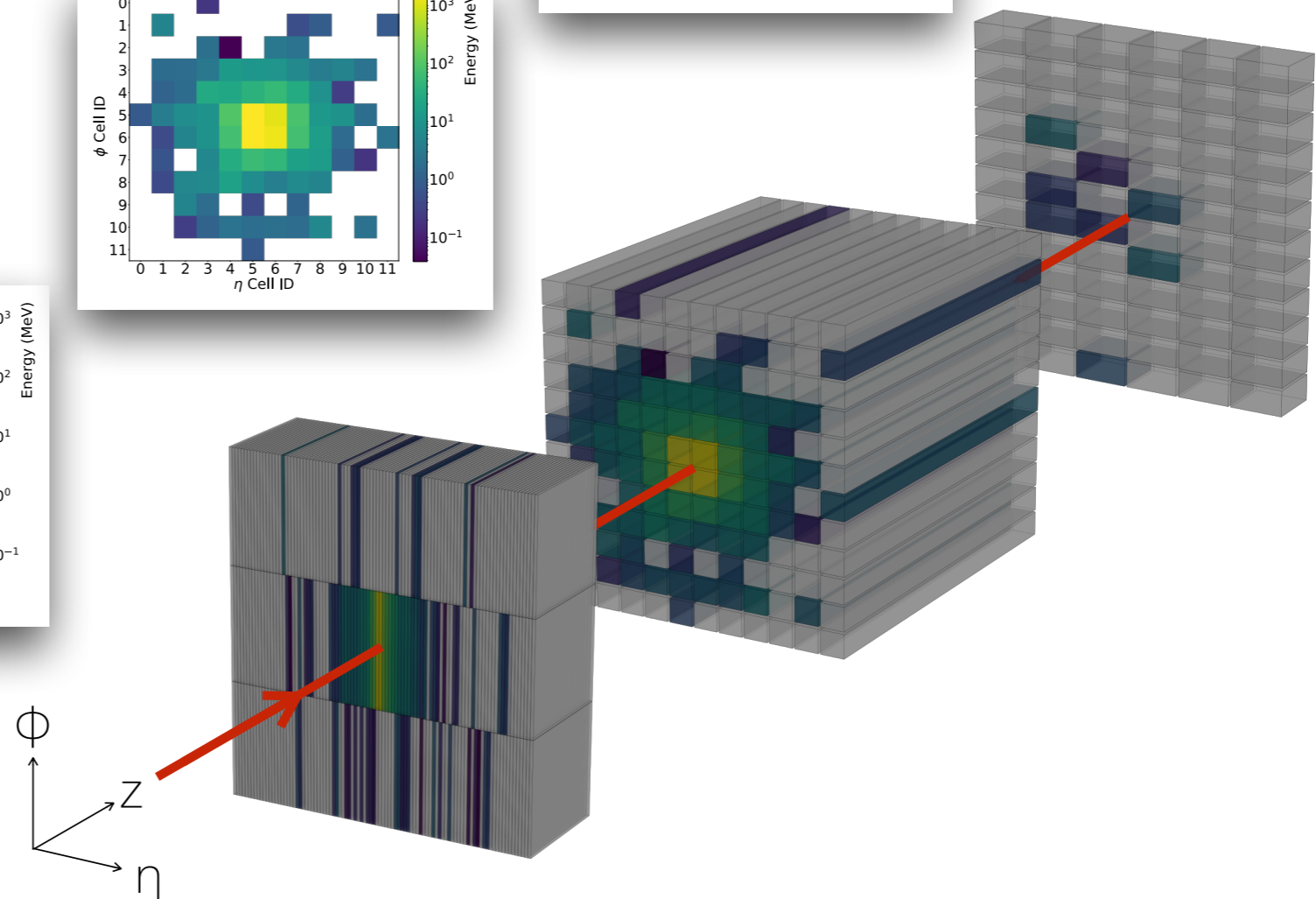
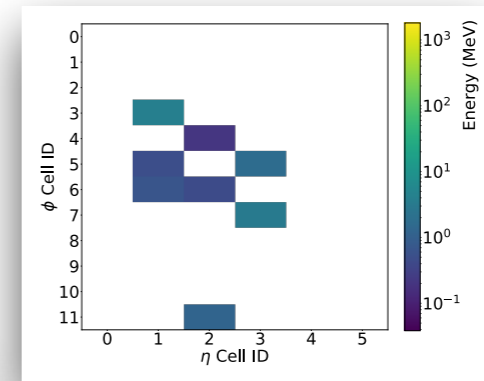
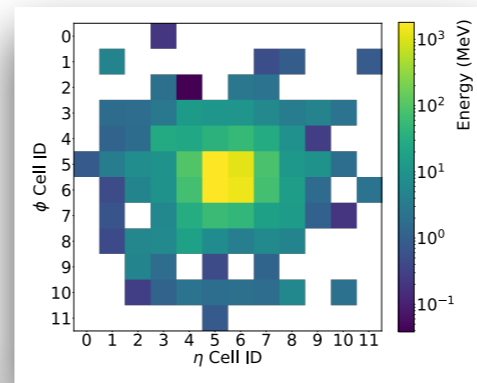
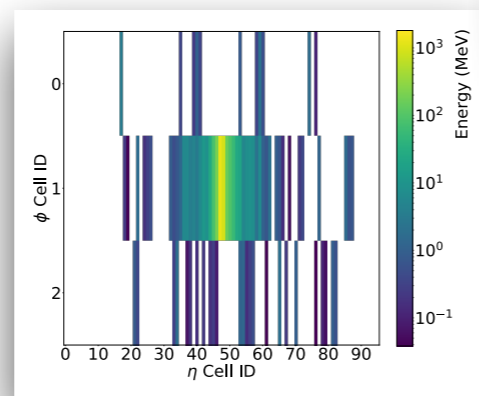
Grayscale images:
Pixel intensity =
energy deposited



Calorimeter images

Challenge: **multiple layers**
with **non-uniform granularity**
and a **causal relationship**?

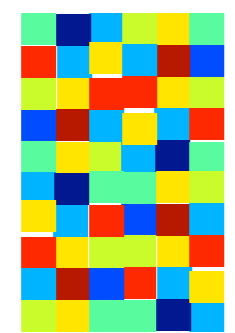
N.B. images are $O(1000)$ dimensional



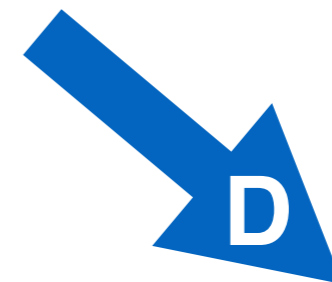
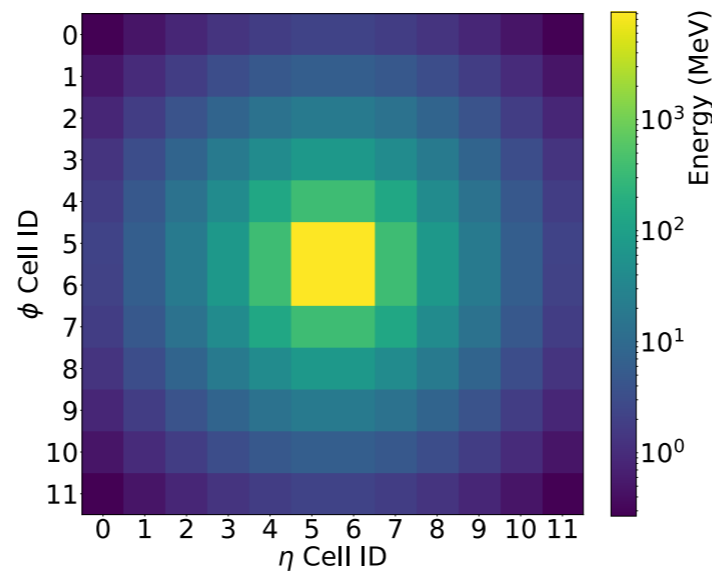
A deep learning solution: GANs

68

Generative Adversarial Networks (GAN):
*A two-network game where one **maps noise to images** and one **classifies images as fake or real**.*

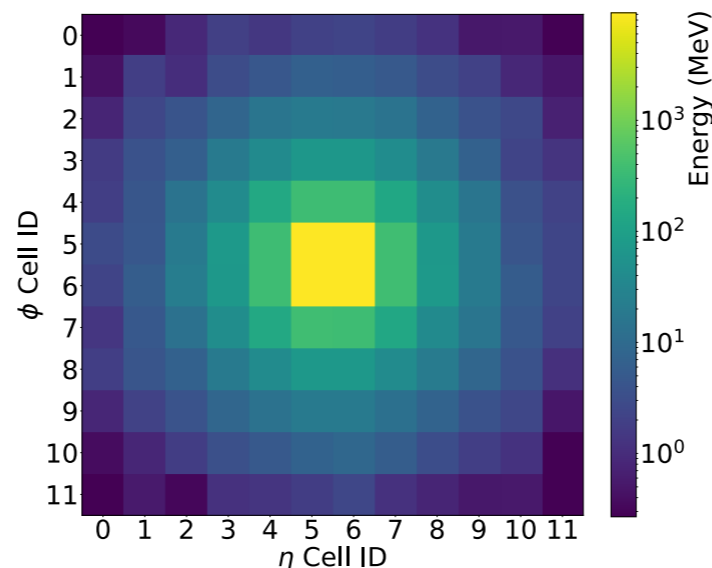


noise



{real, fake}

When **D** is maximally confused, **G** will be a good generator

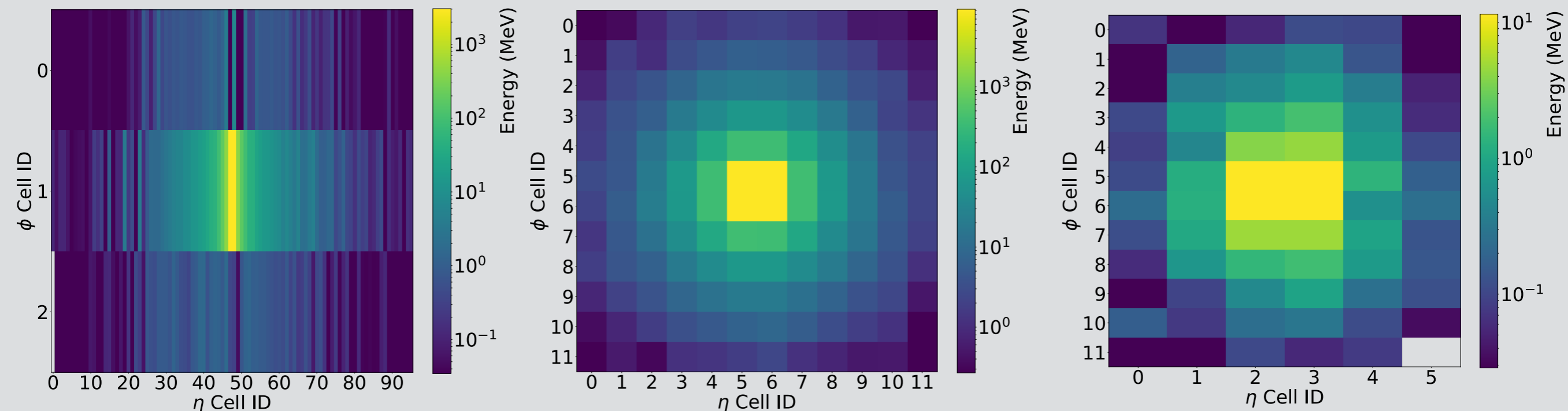
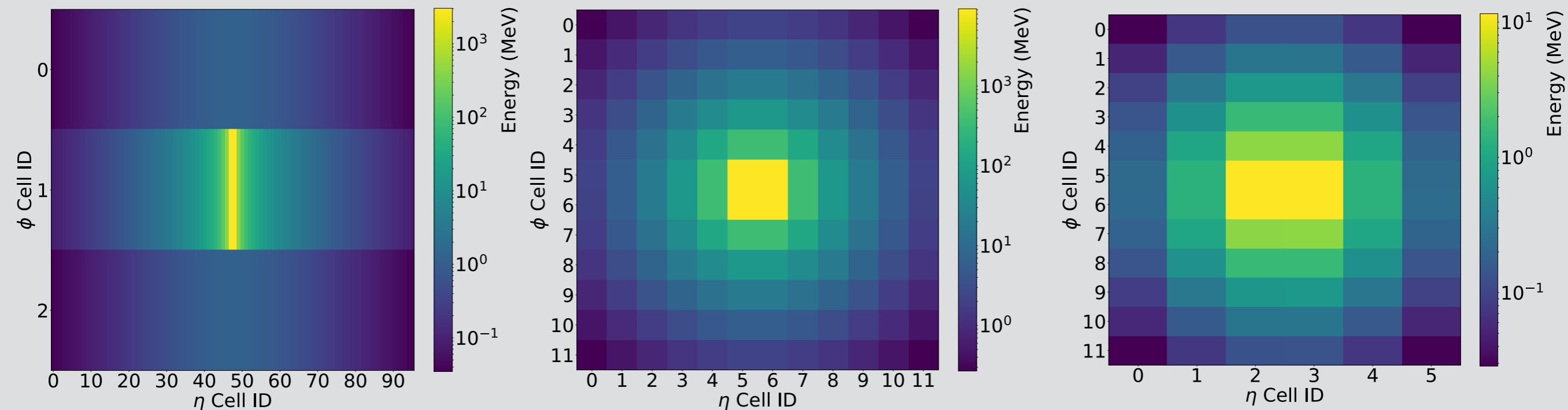


Physics-based simulator

Physics-inspired: CaloGAN



Geant4



CaloGAN Timing

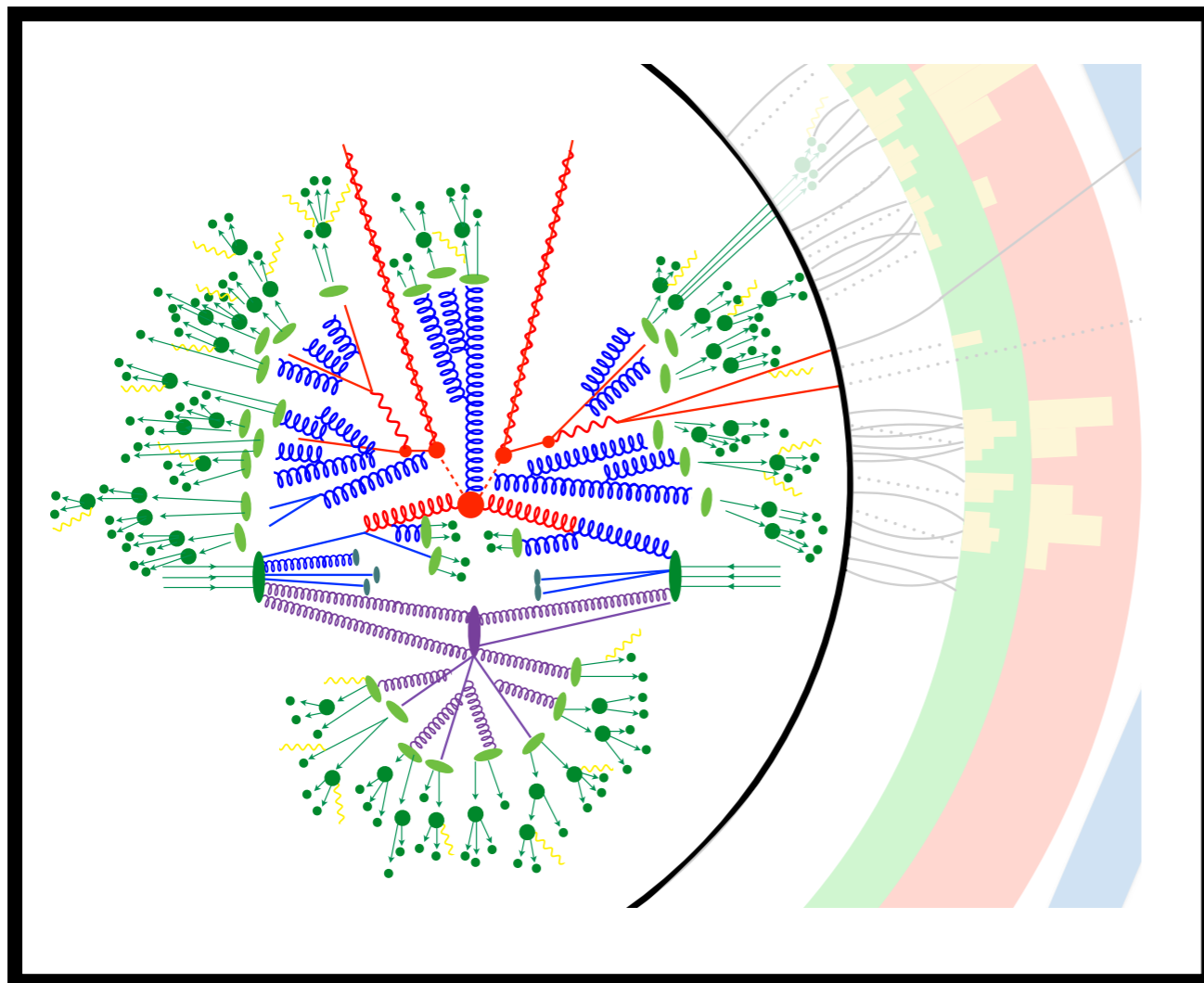


M. Paganini, L. de Oliveira, **BPN**, PRL 120 (2018) 042003

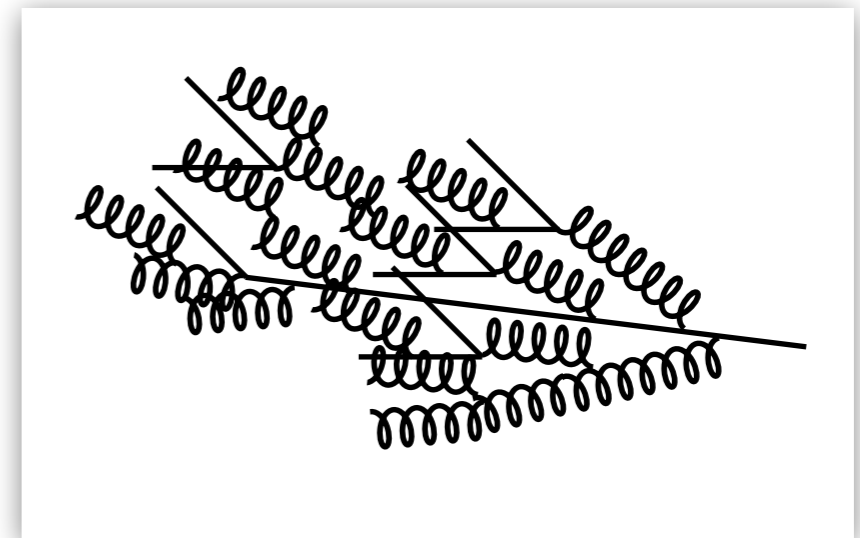
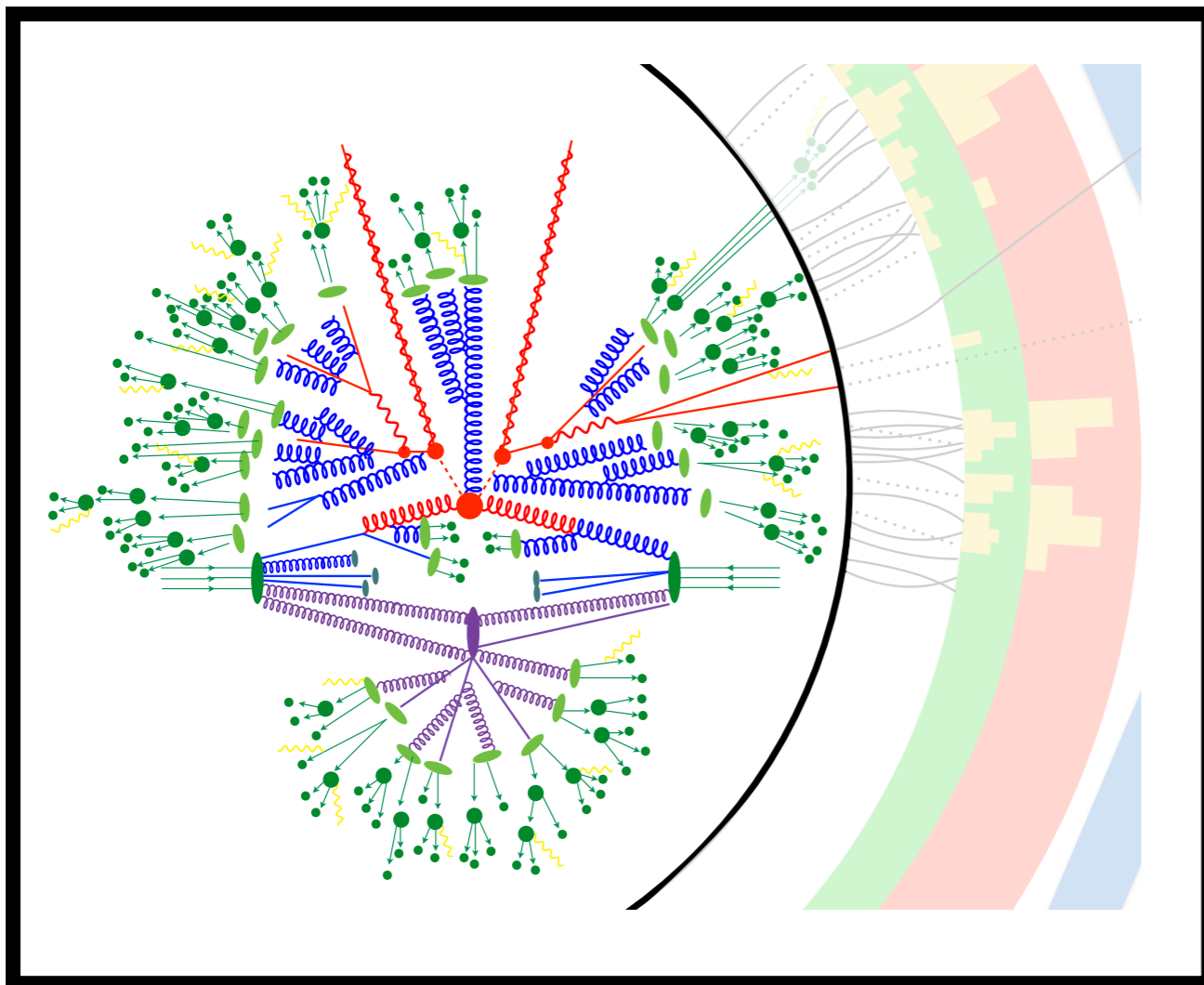
Generation Method	Hardware	Batch Size	milliseconds/shower
GEANT4	CPU	N/A	1772 ←
CALOGAN	CPU	1	13.1
		10	5.11
		128	2.19
		1024	2.03
	GPU	1	14.5
		4	3.68
		128	0.021
		512	0.014
		1024	0.012 ←

(clearly these numbers will change as both technologies improve - this is simply meant to be qualitative and motivating!)

What if the fidelity of the simulation is not good enough?

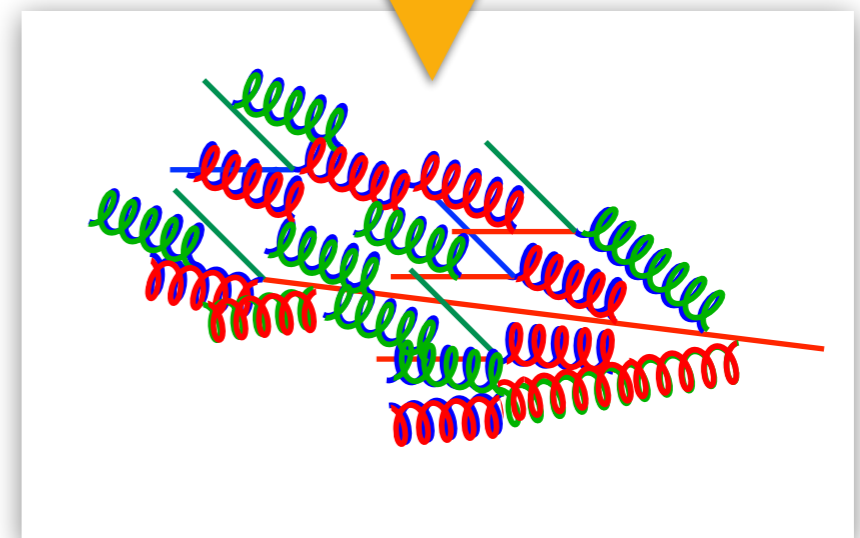
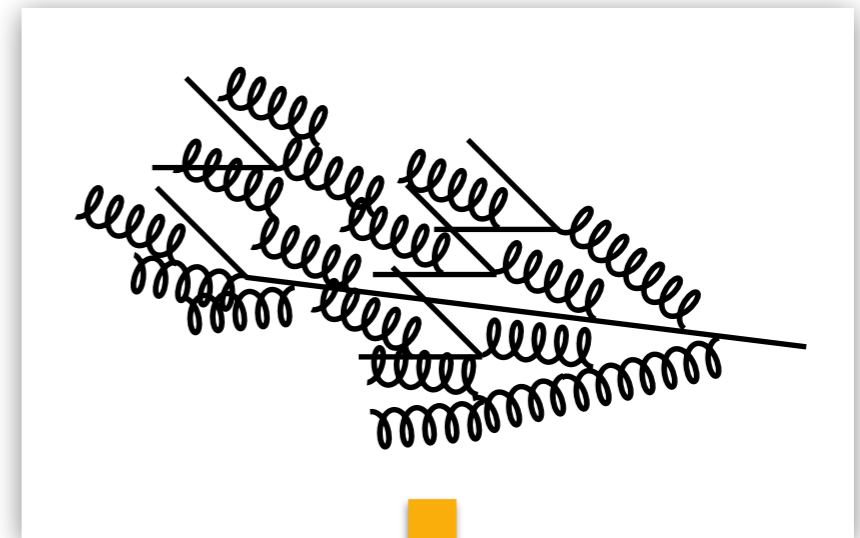
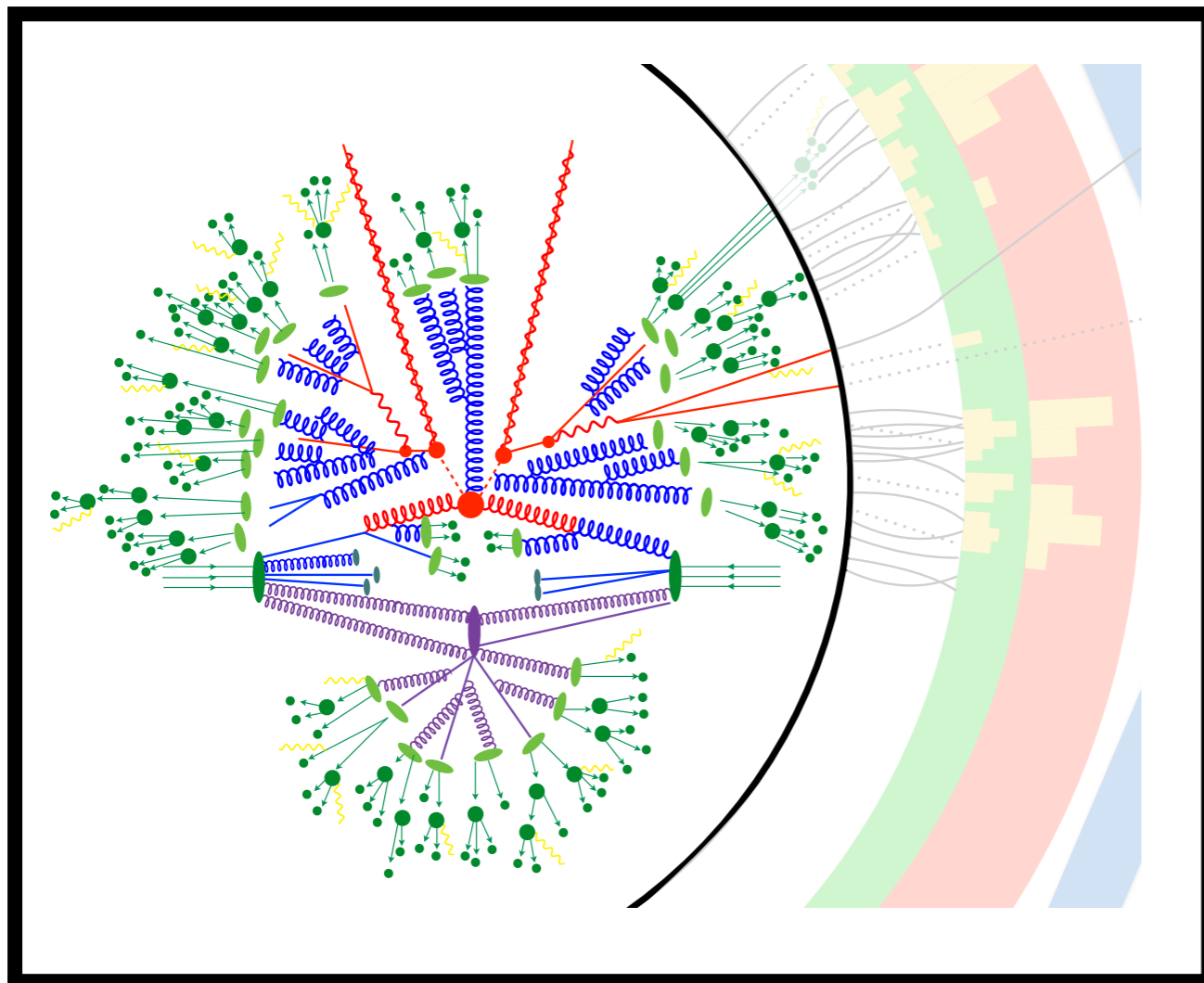


What if the fidelity of the simulation is not good enough?



What if the fidelity of the simulation is not good enough?

Quantum simulations with quantum computers?

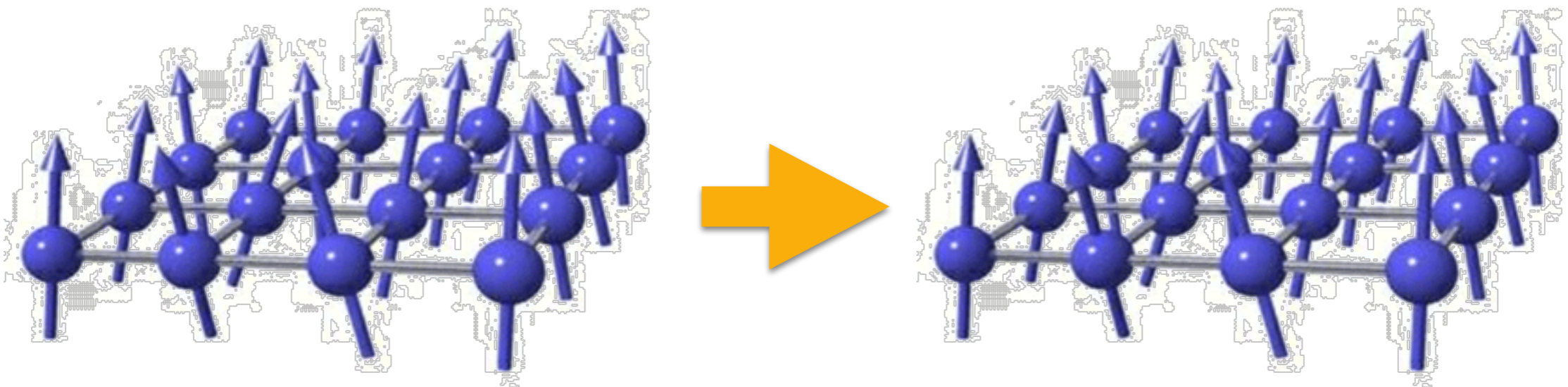


Analog versus Digital Quantum Circuits

74

Goal: implement our system's Hamiltonian (e.g. the SM) in a proxy system ("quantum computer") and let it evolve.

The best quantum computer is the one that looks just like the system you are trying to model!



Analog versus Digital Quantum Circuits

75

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Analog versus Digital Quantum Circuits

76

Goal: implement our system's Hamiltonian (e.g. the SM) in a proxy system ("quantum computer") and let it evolve.

The best quantum computer is the one that looks just like the system you are trying to model!

Not always possible!

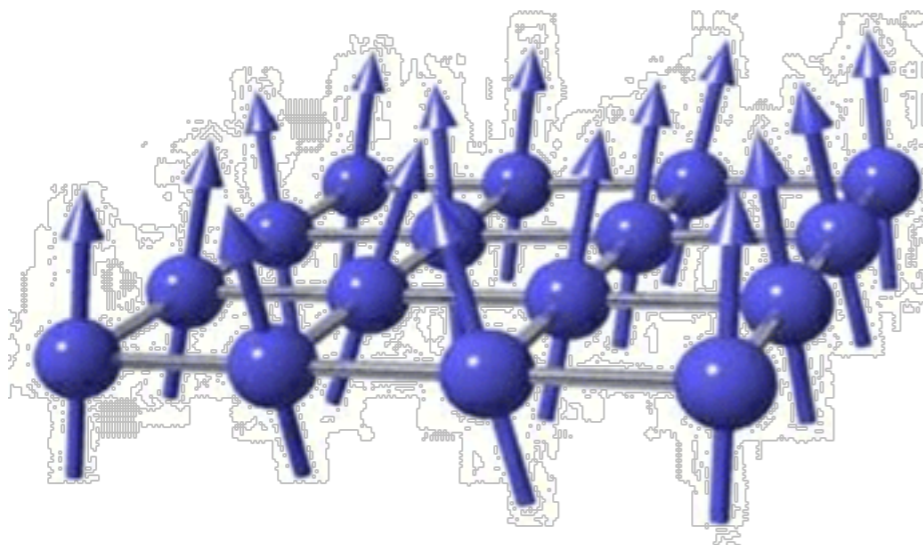


Analog versus Digital Quantum Circuits

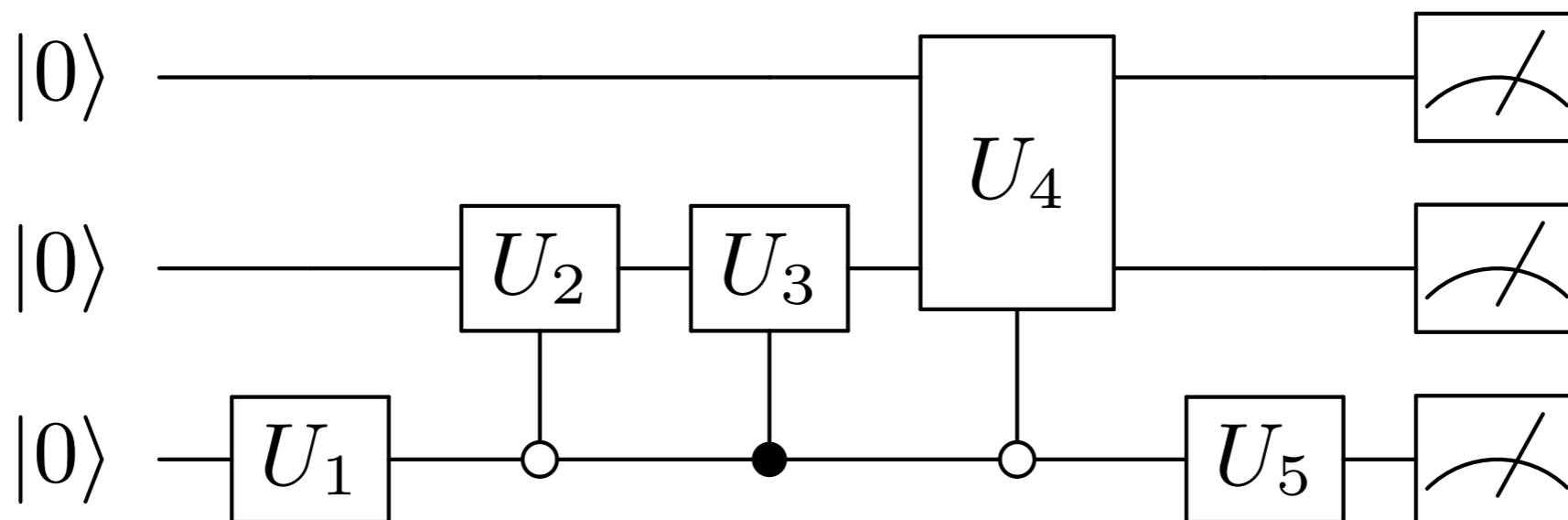
77

Goal: implement our system's Hamiltonian (e.g. the SM) in a proxy system ("quantum computer") and let it evolve.

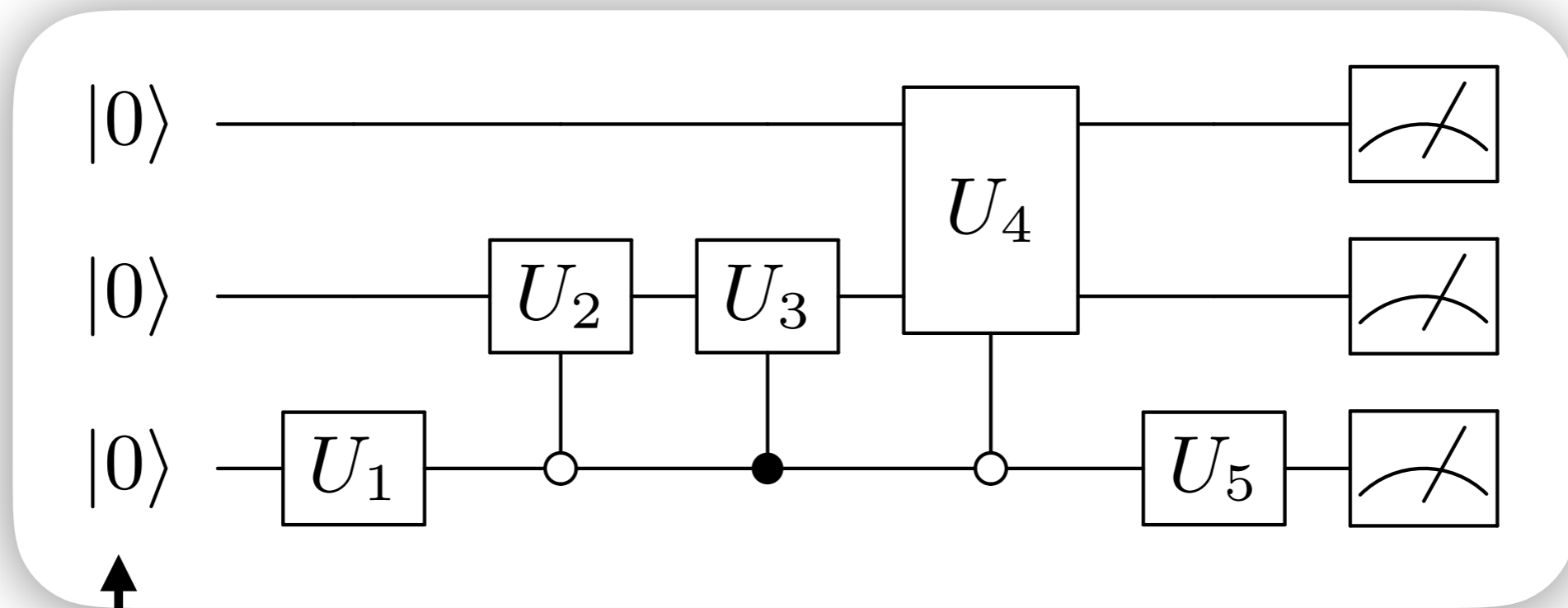
In this setup, the possibilities are endless; the key is efficiency.



Just like a classical computer, one can write programs for a universal quantum computer.

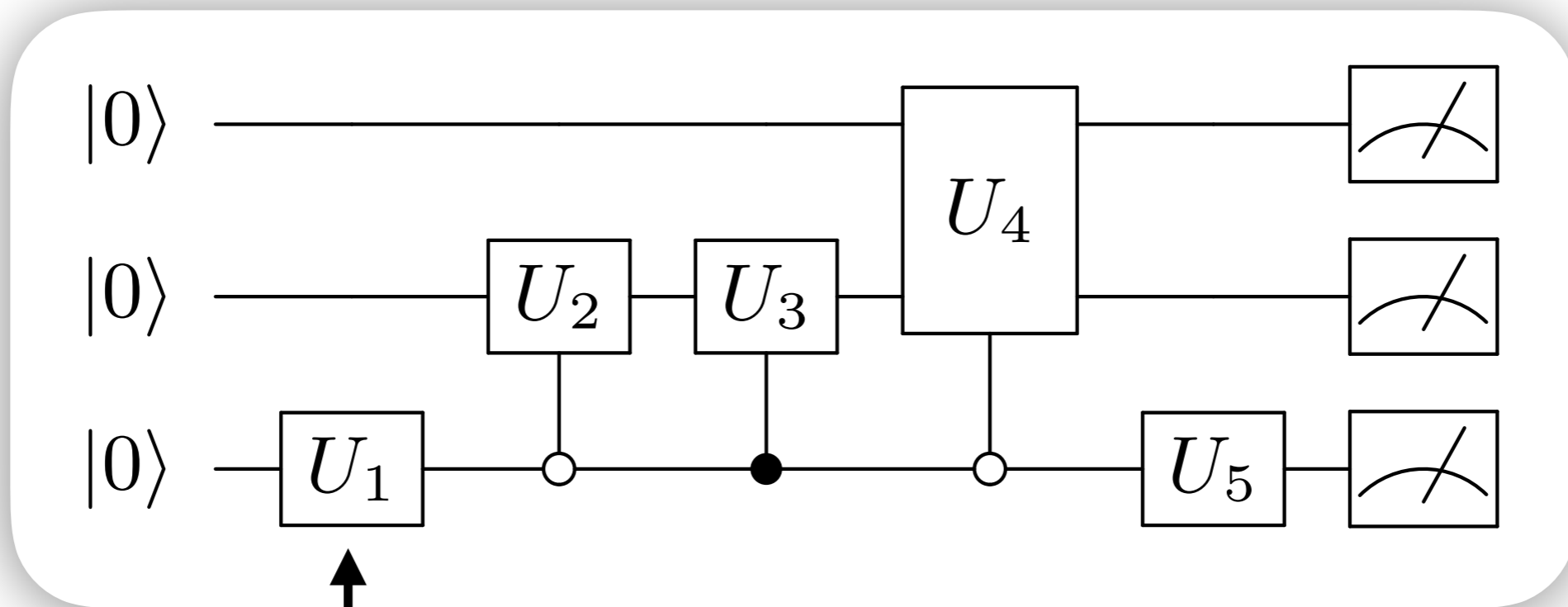


Just like a classical computer, one can write programs for a universal quantum computer.



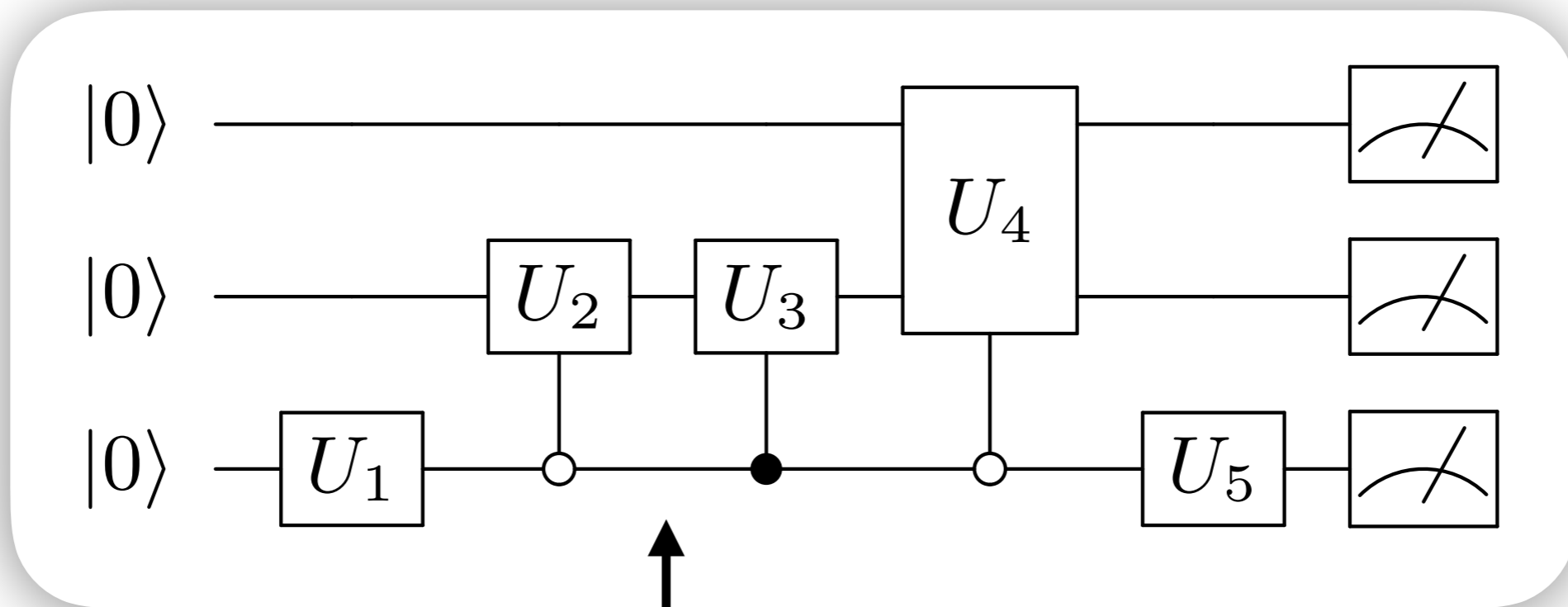
↑
Initialize in the
ground state.

Just like a classical computer, one can write programs for a universal quantum computer.



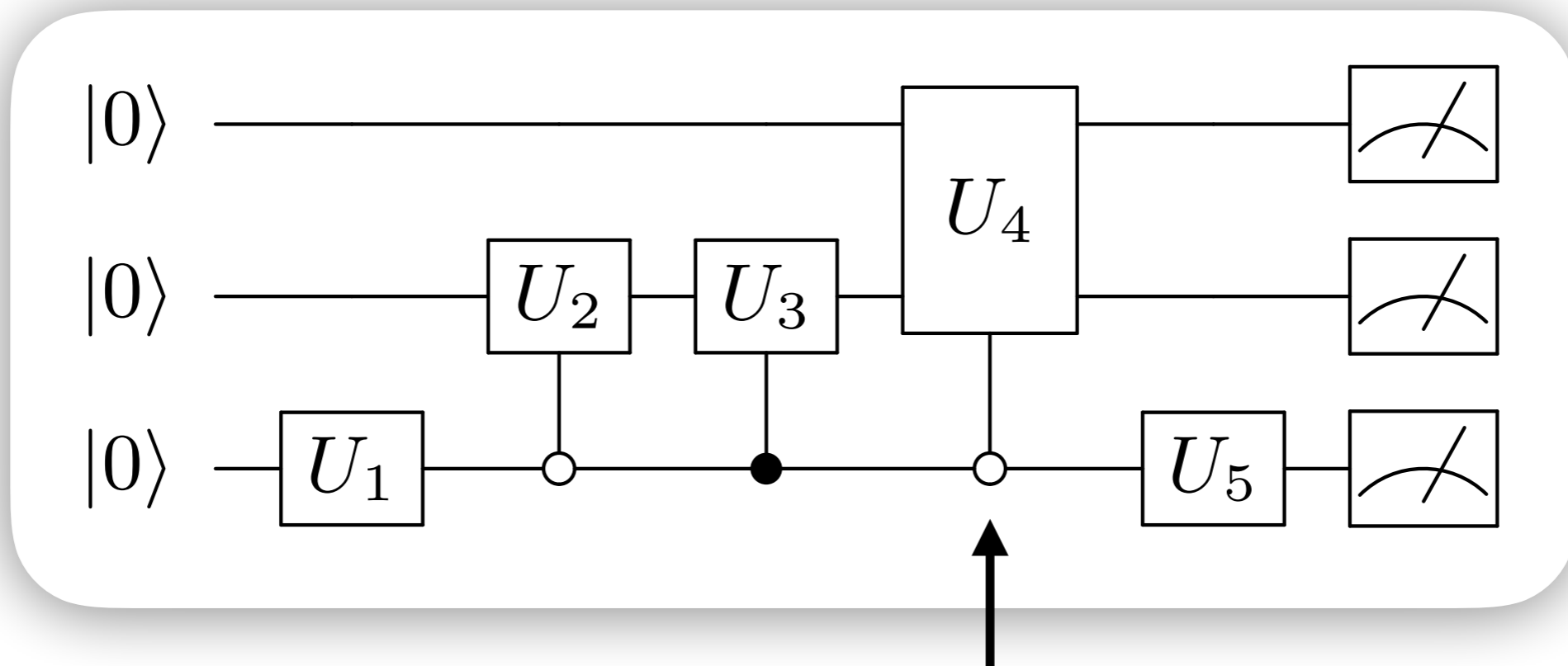
Apply unitary matrix U_1 to the third qubit

Just like a classical computer, one can write programs for a universal quantum computer.



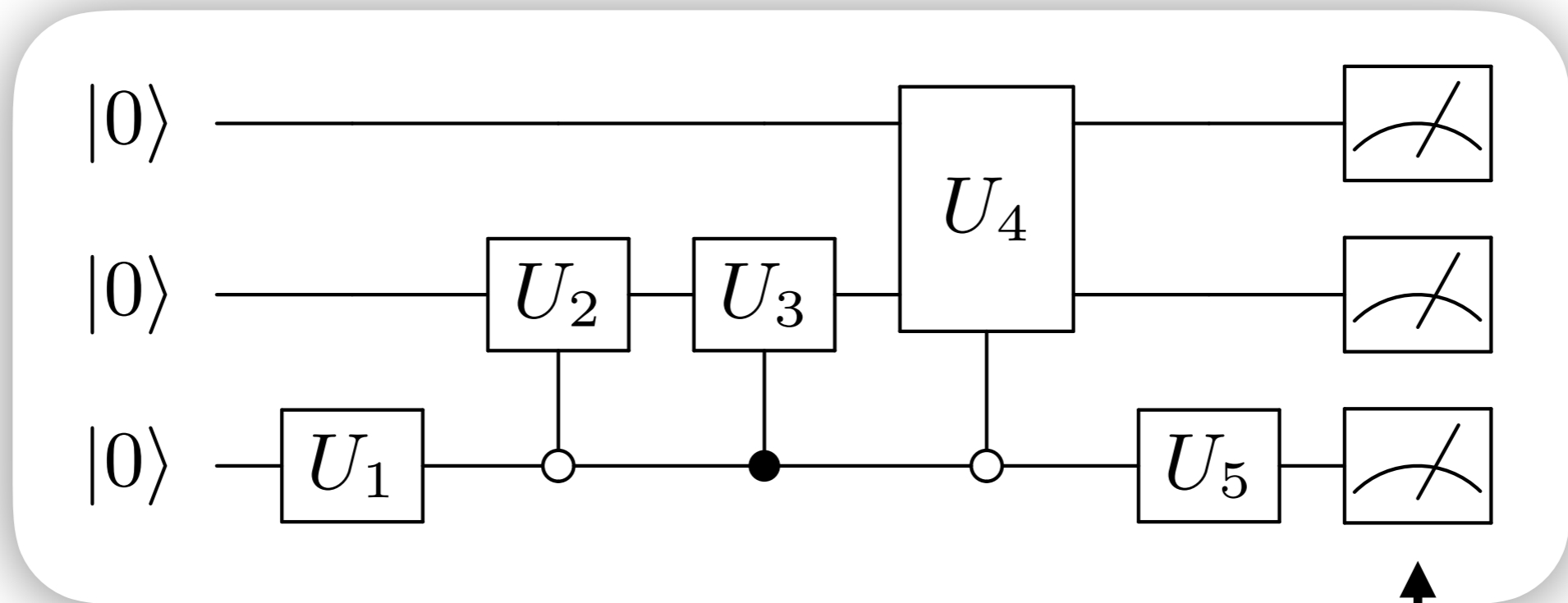
Apply unitary matrix U_2 to the second qubit when the third is 0, else apply U_3 .

Just like a classical computer, one can write programs for a universal quantum computer.

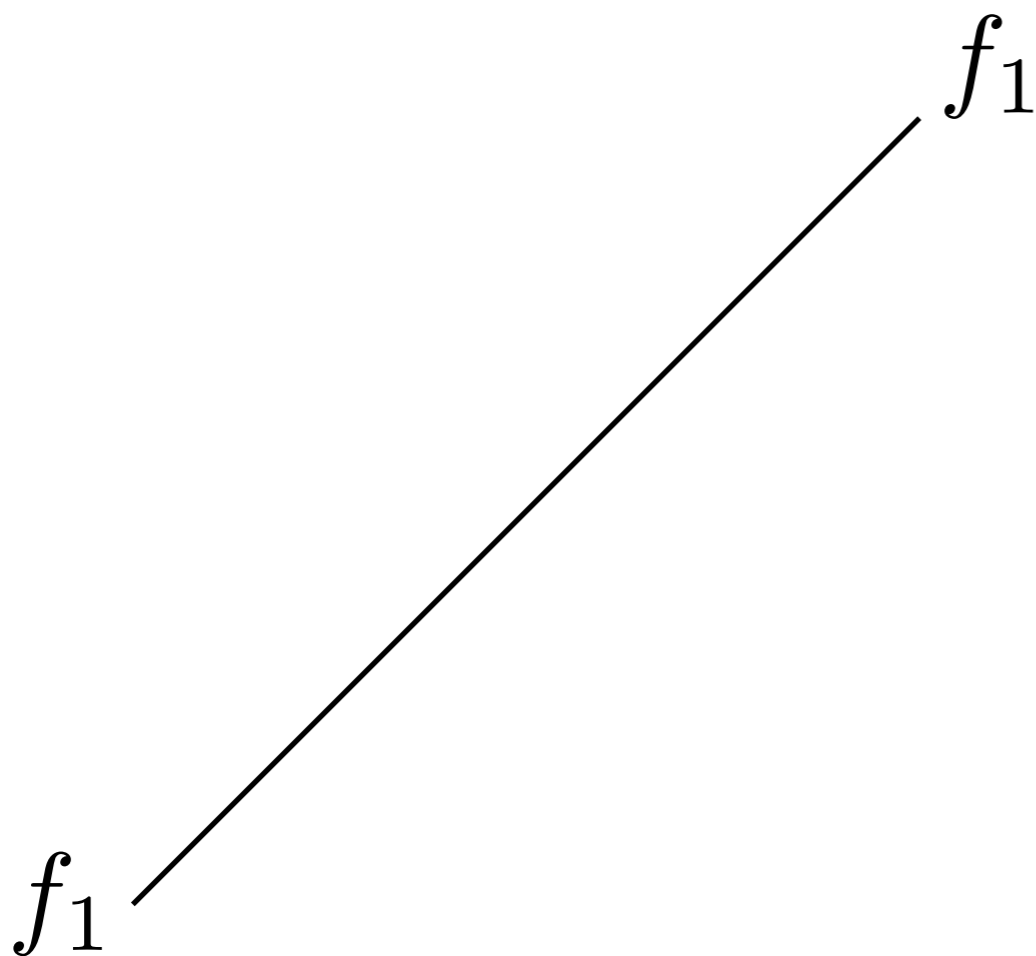


Apply unitary matrix U_4 to both the first and second qubits when the third is 0.

Just like a classical computer, one can write programs for a universal quantum computer.

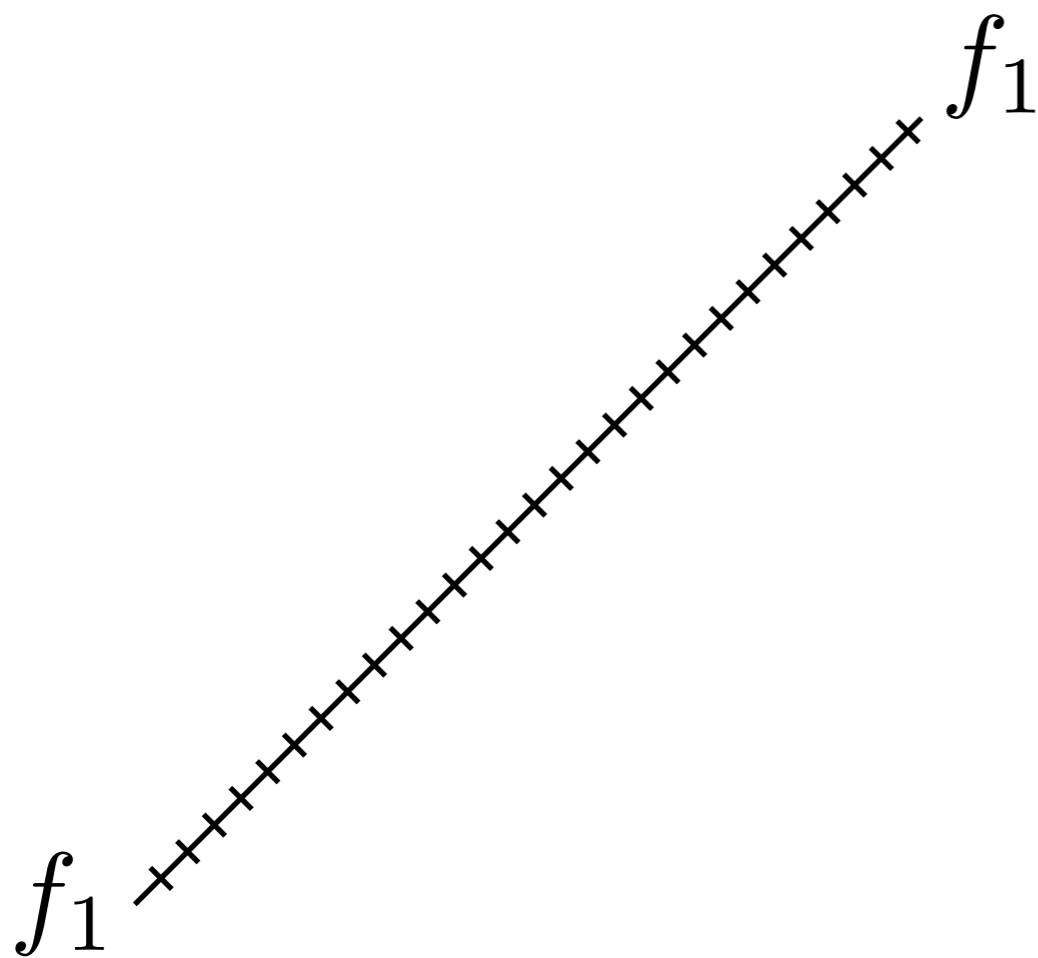


Measure all
the qubits



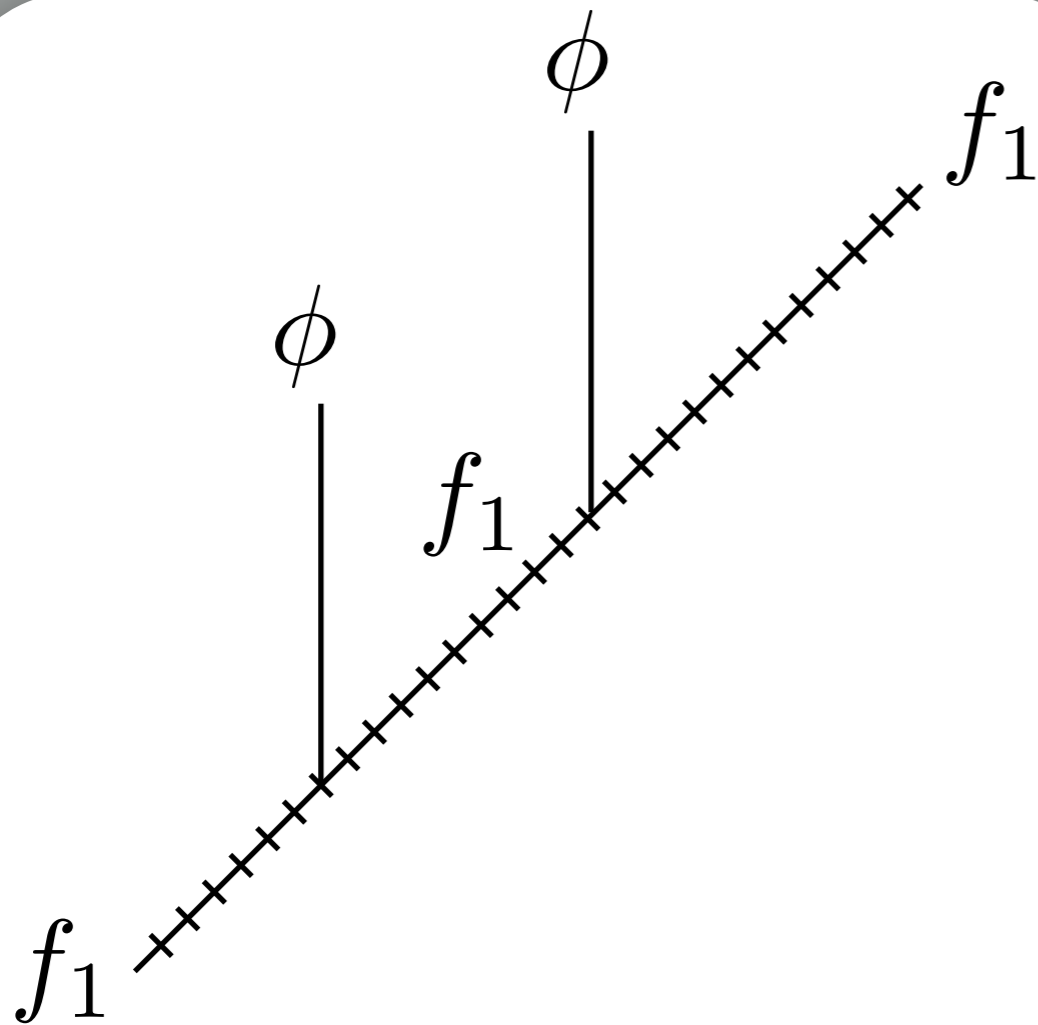
Simplified theory: two fermions f_1 and f_2 .

They can radiate scalars and can mix.



Algorithm: discretize
the phase space

Check for emissions
at each step.



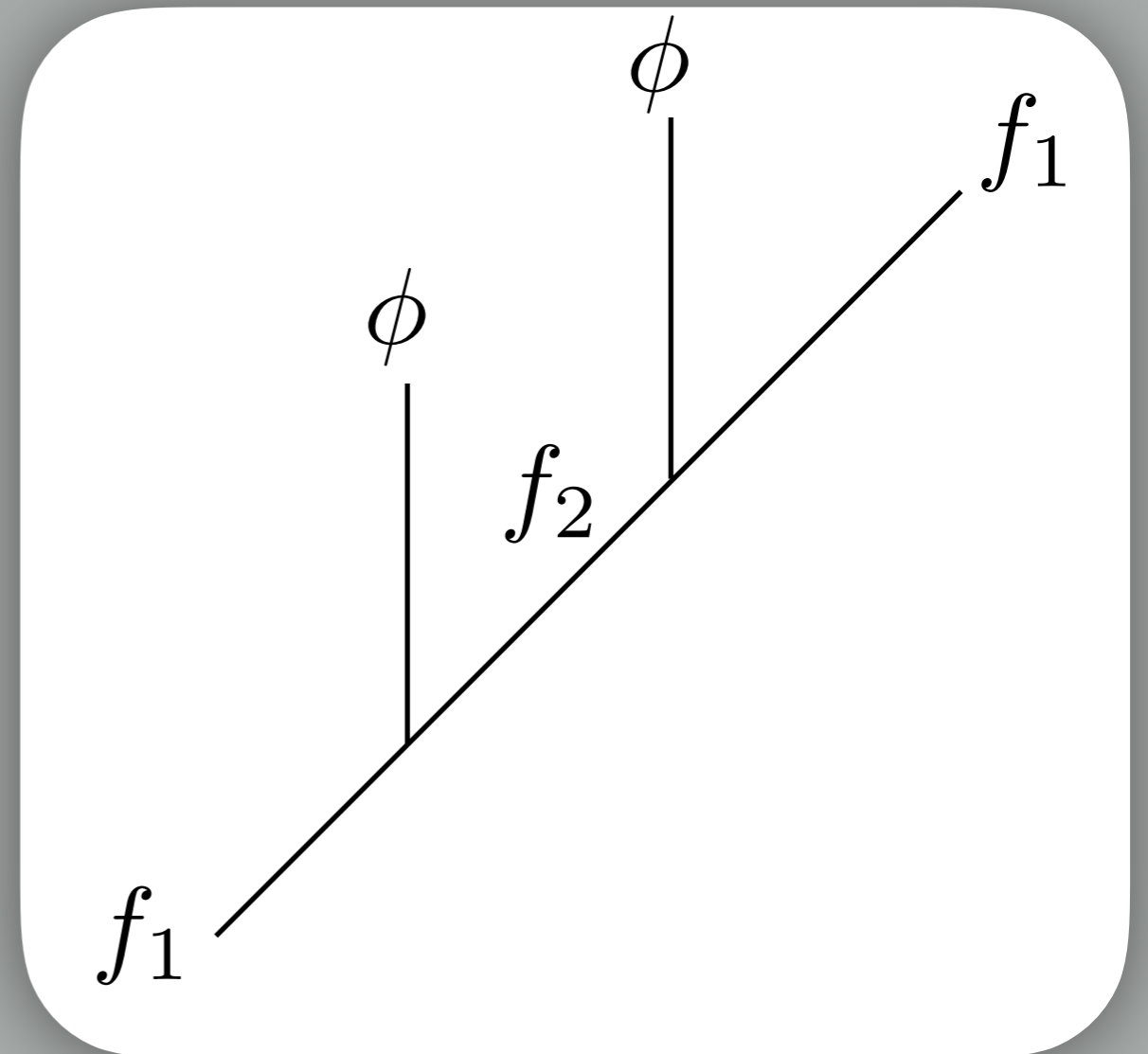
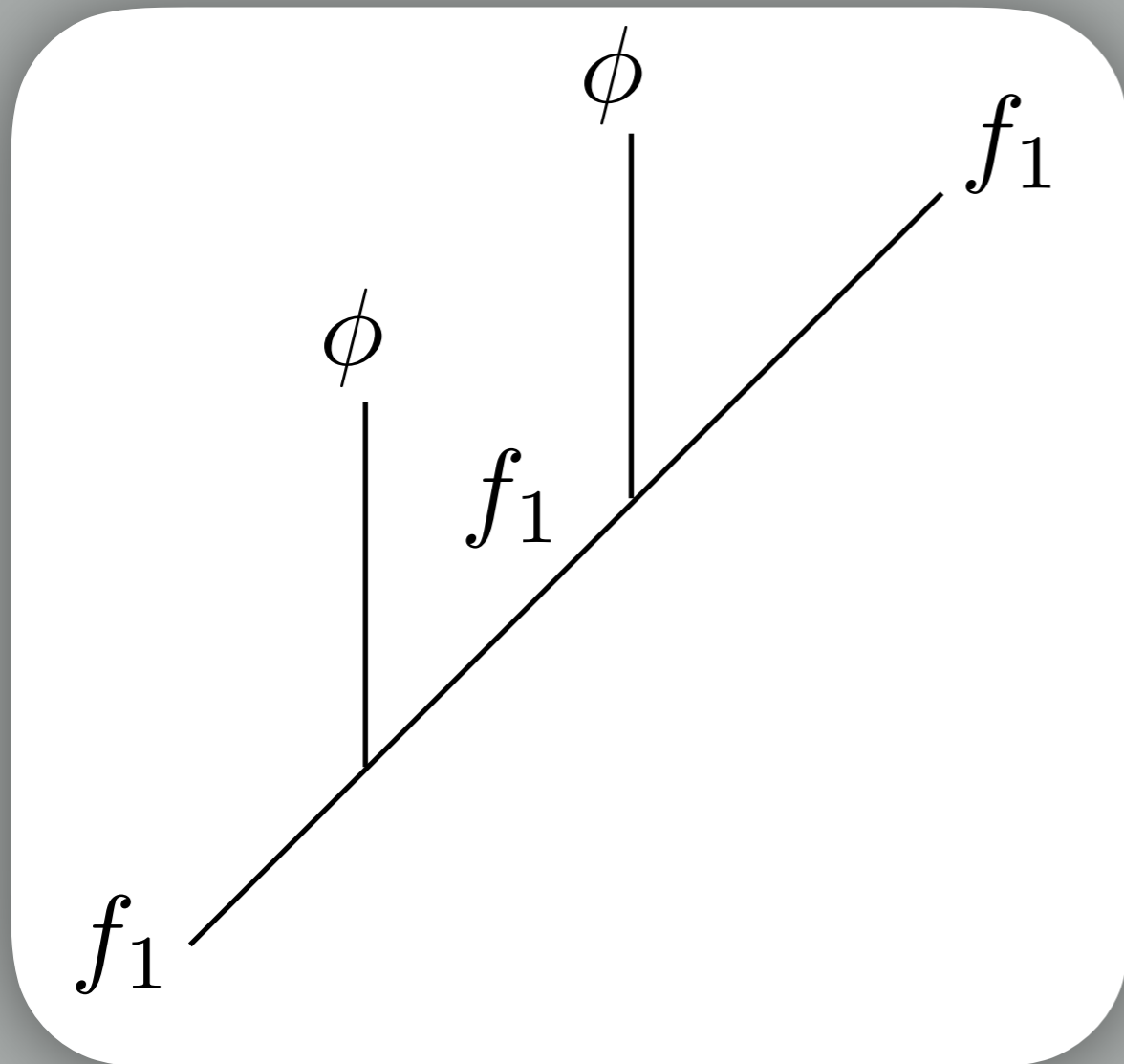
Algorithm: discretize
the phase space

Check for emissions
at each step.

A quantum algorithm for radiation

87

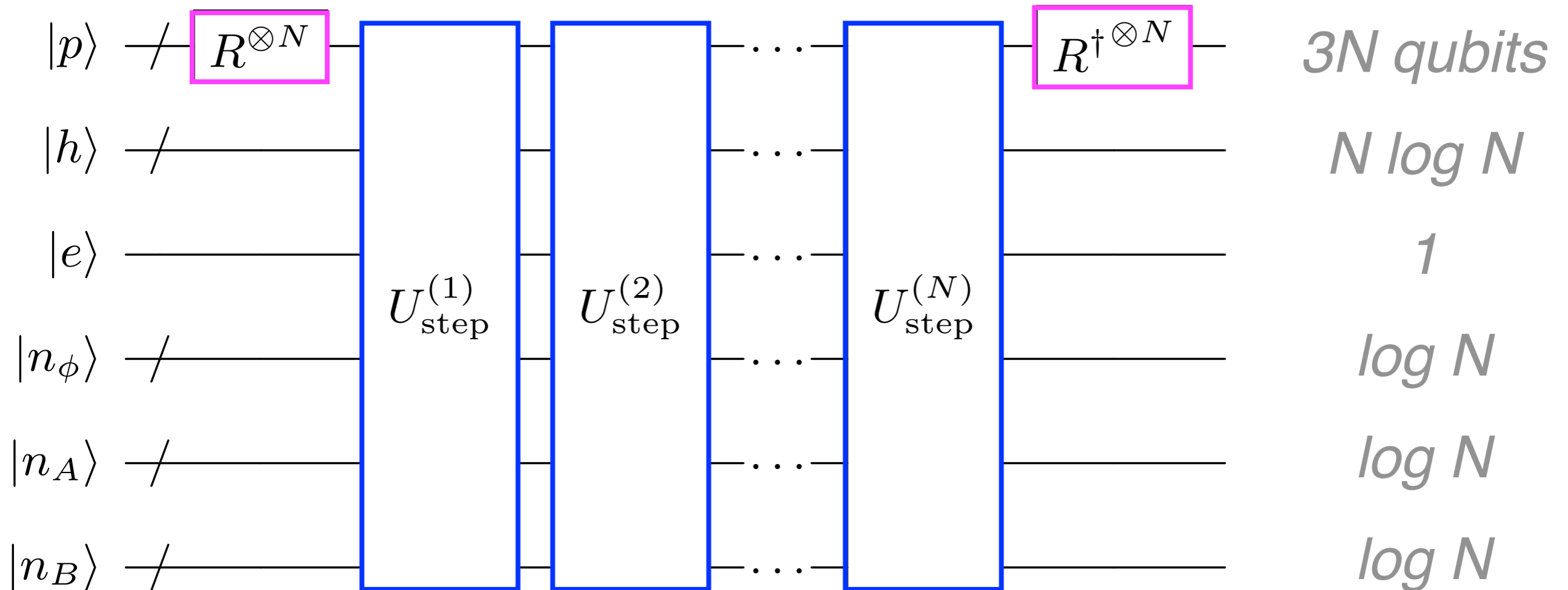
BPN, D. Provasoli, W. de Jong, C. Bauer, 1904.03196



Multiple routes to the same state - interference!

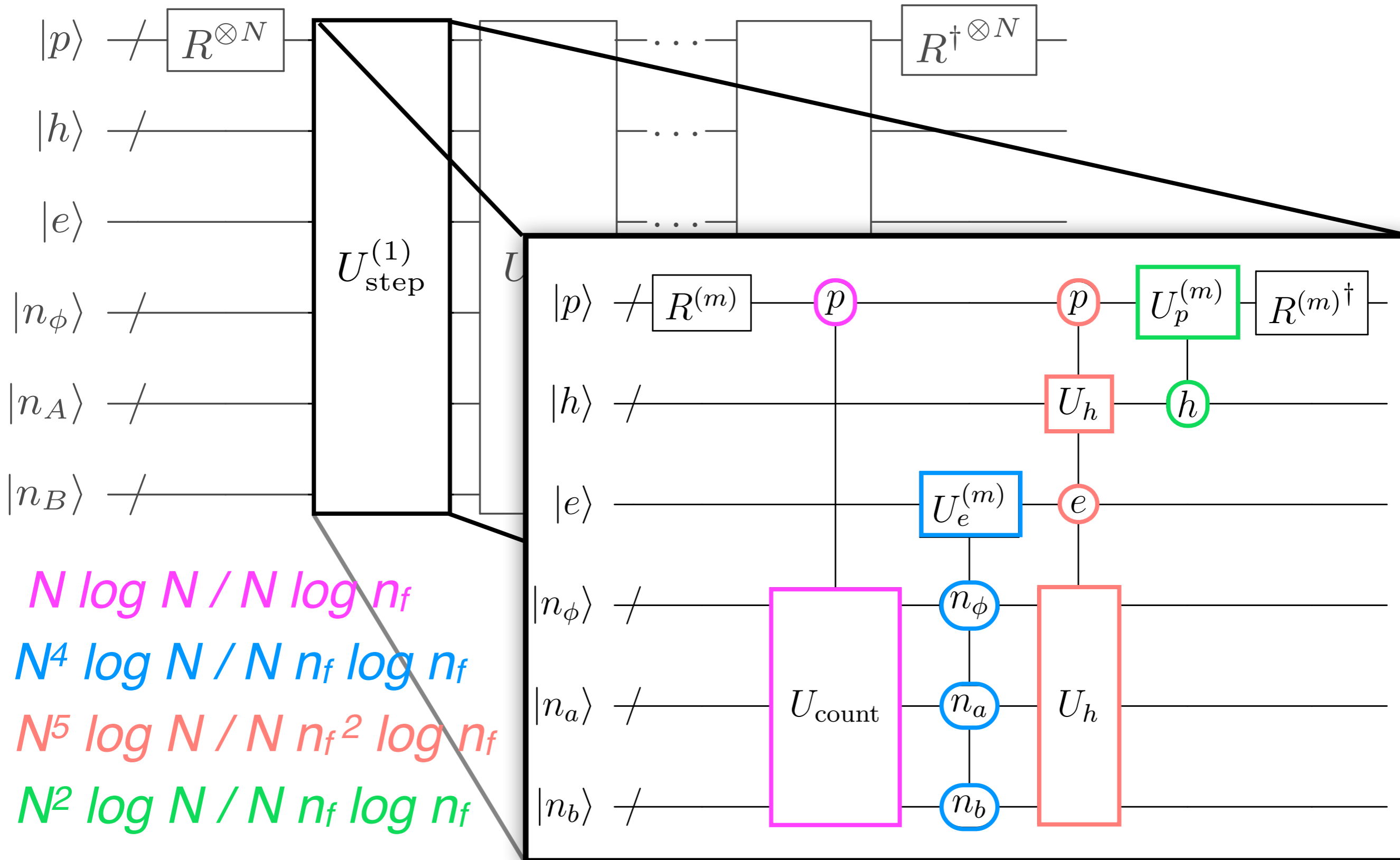
A quantum algorithm for radiation

88



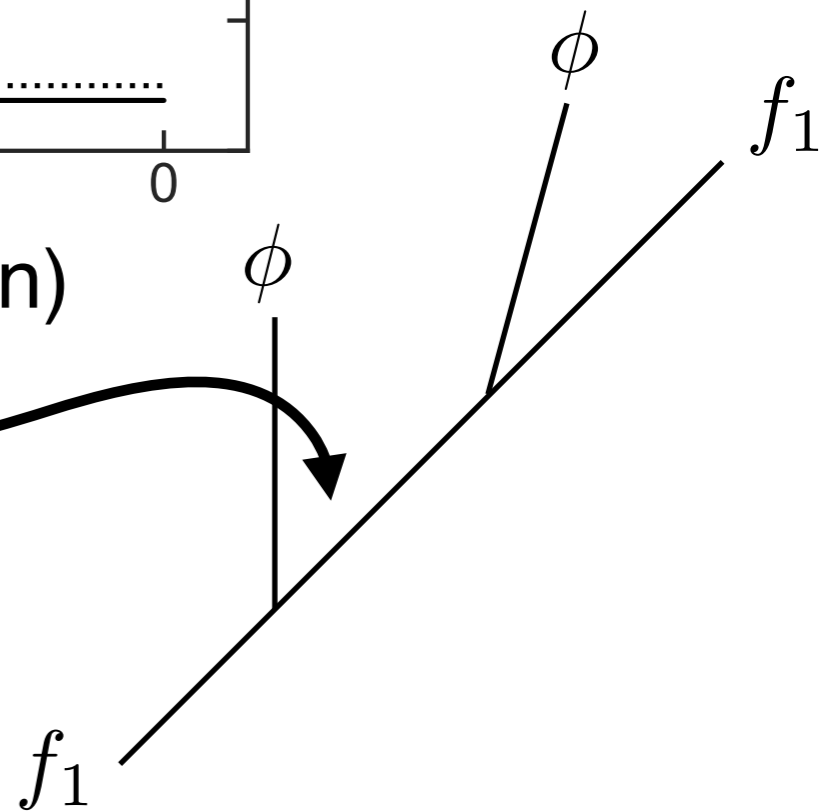
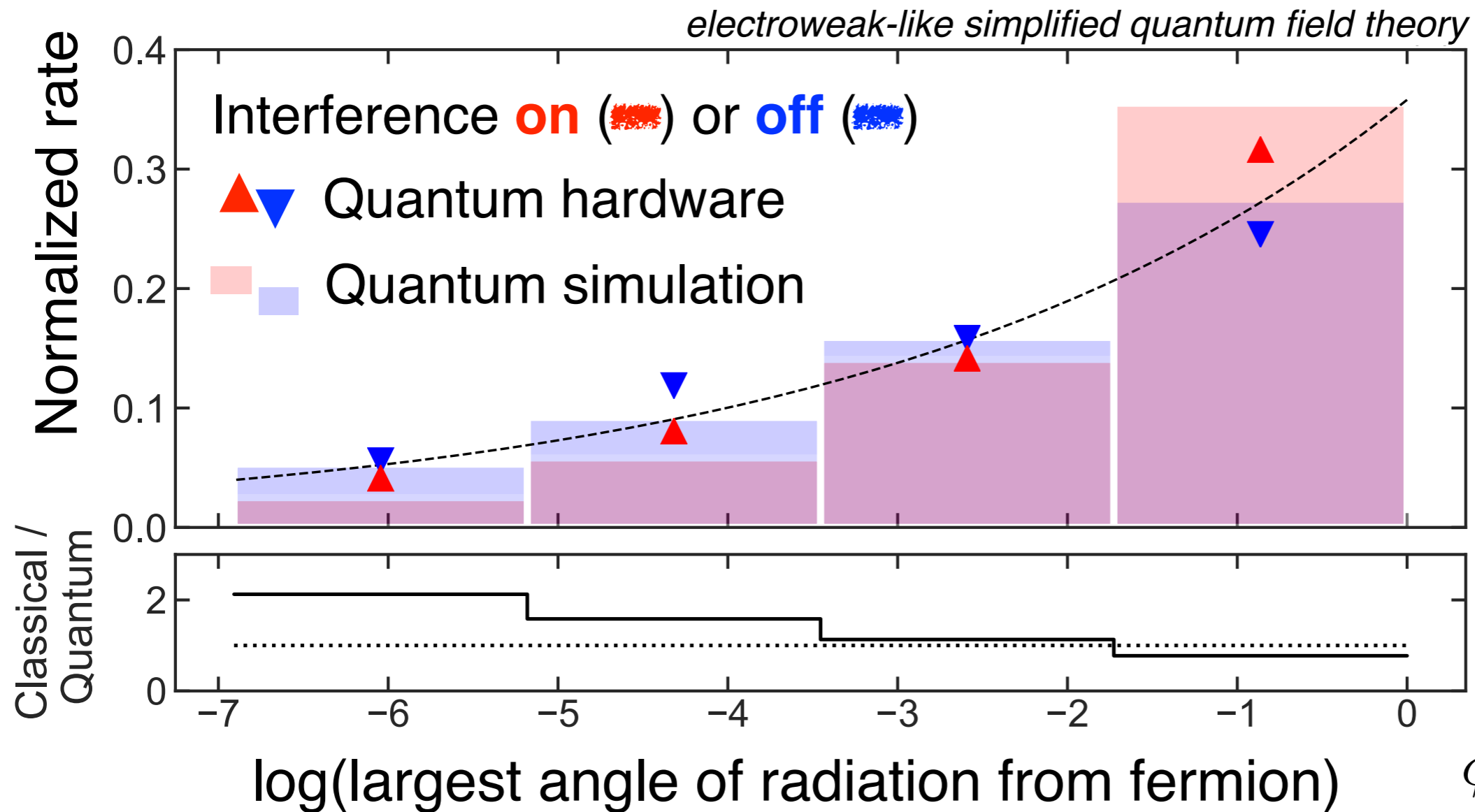
Discretize the shower evolution (e.g. in angle)
& **rotate** to a particle basis without interference.

A quantum algorithm for radiation



$N \log N / N \log n_f$
 $N^4 \log N / N n_f \log n_f$
 $N^5 \log N / N n_f^2 \log n_f$
 $N^2 \log N / N n_f \log n_f$

A quantum algorithm for radiation



BPN, D. Provasoli, W. de Jong, C. Bauer, 1904.03196

D. Provsoli, BPN, W. de Jong, C. Bauer, 1901.08148

From HEP to QIS

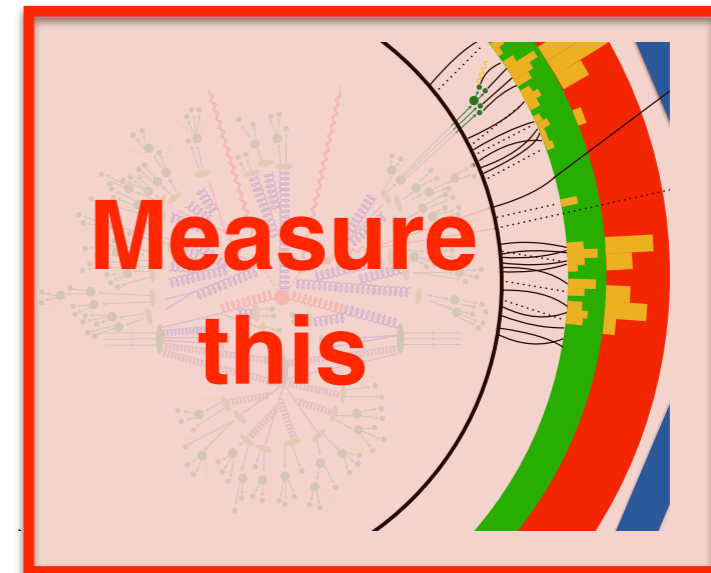
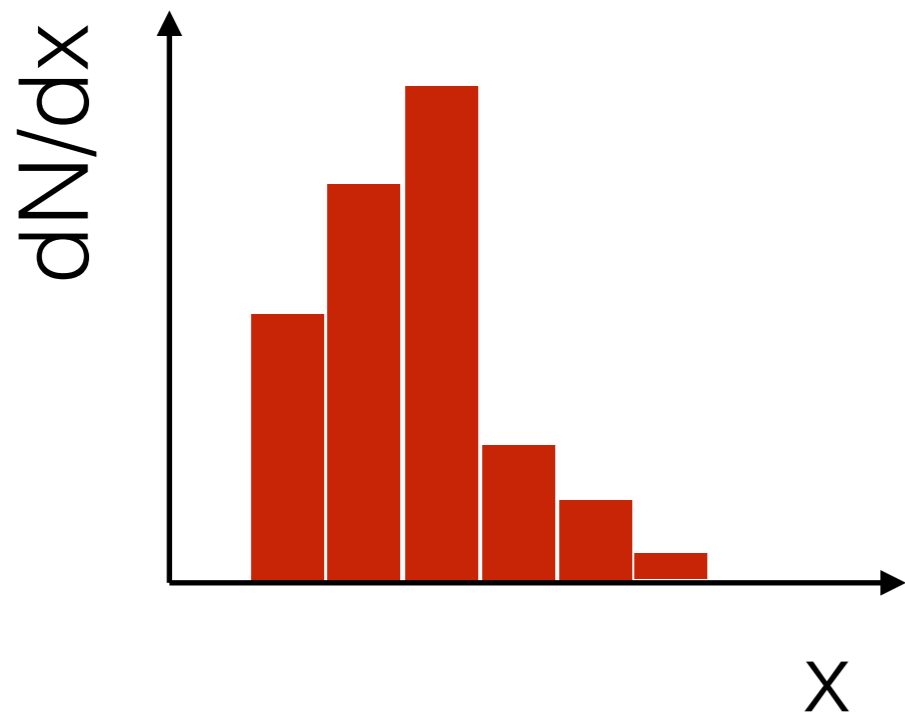


91

In addition to basic algorithms dev. for QFT, I have discovered new ways to improve quantum computing **in general**

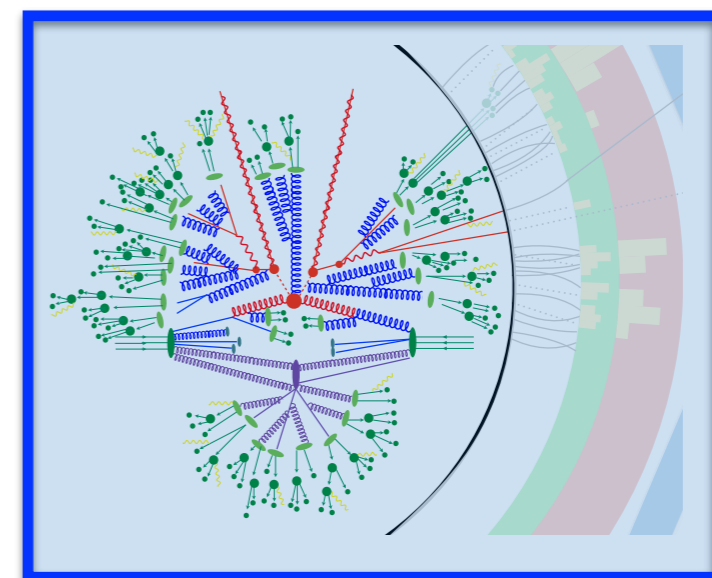
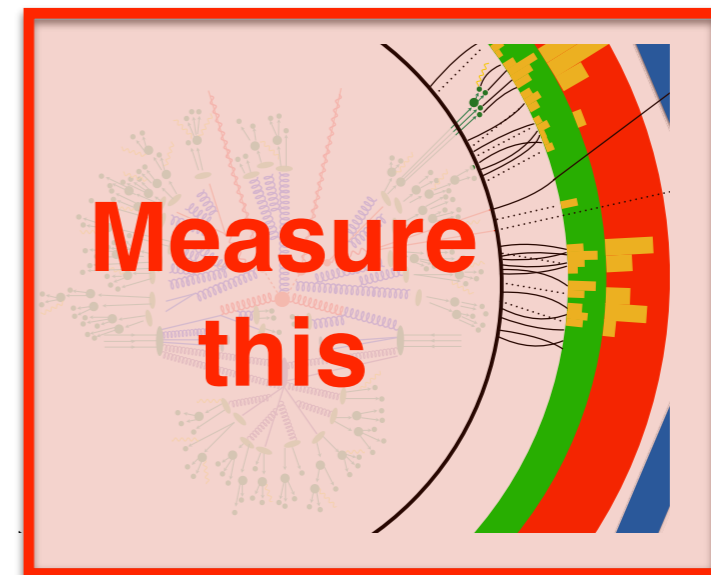
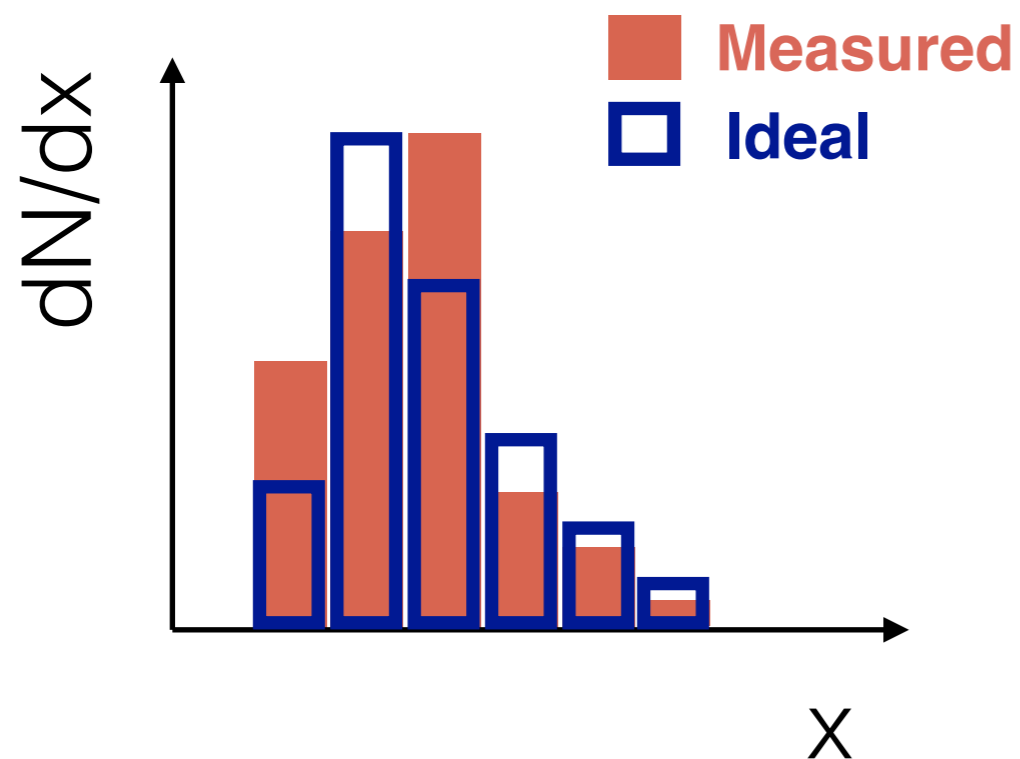
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High Energy Physics



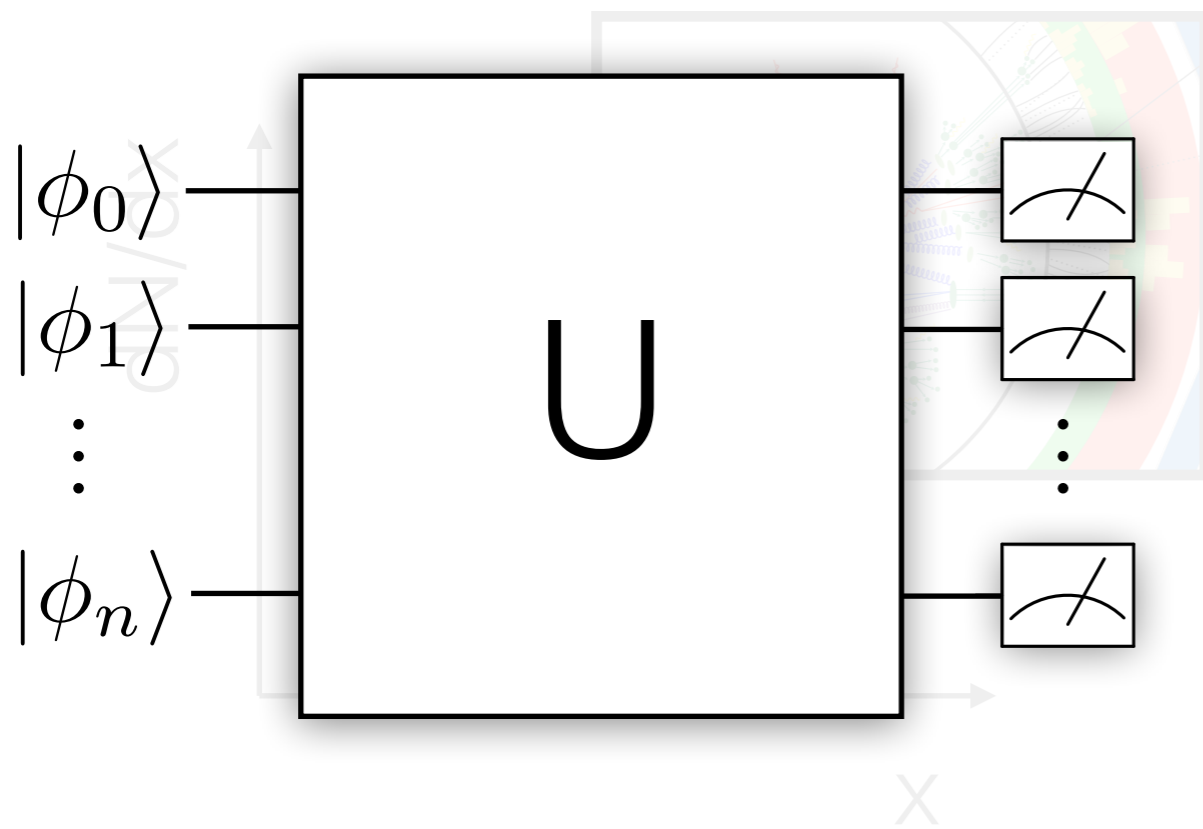
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High Energy Physics

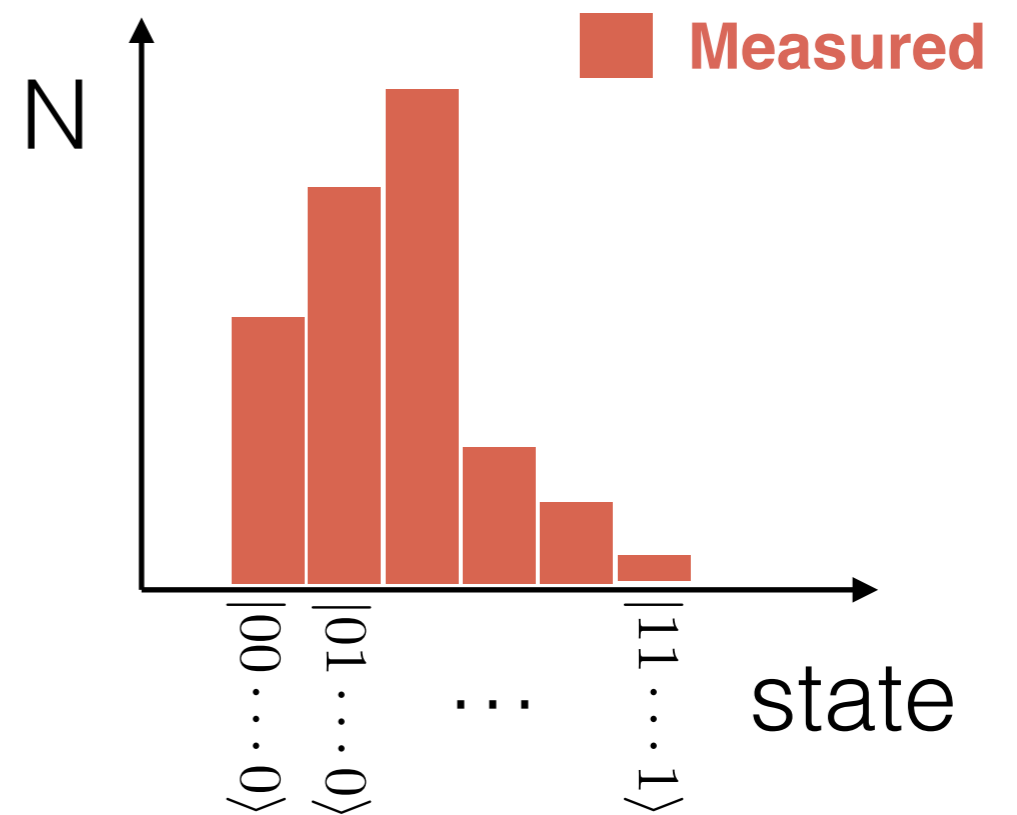


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High Energy Physics

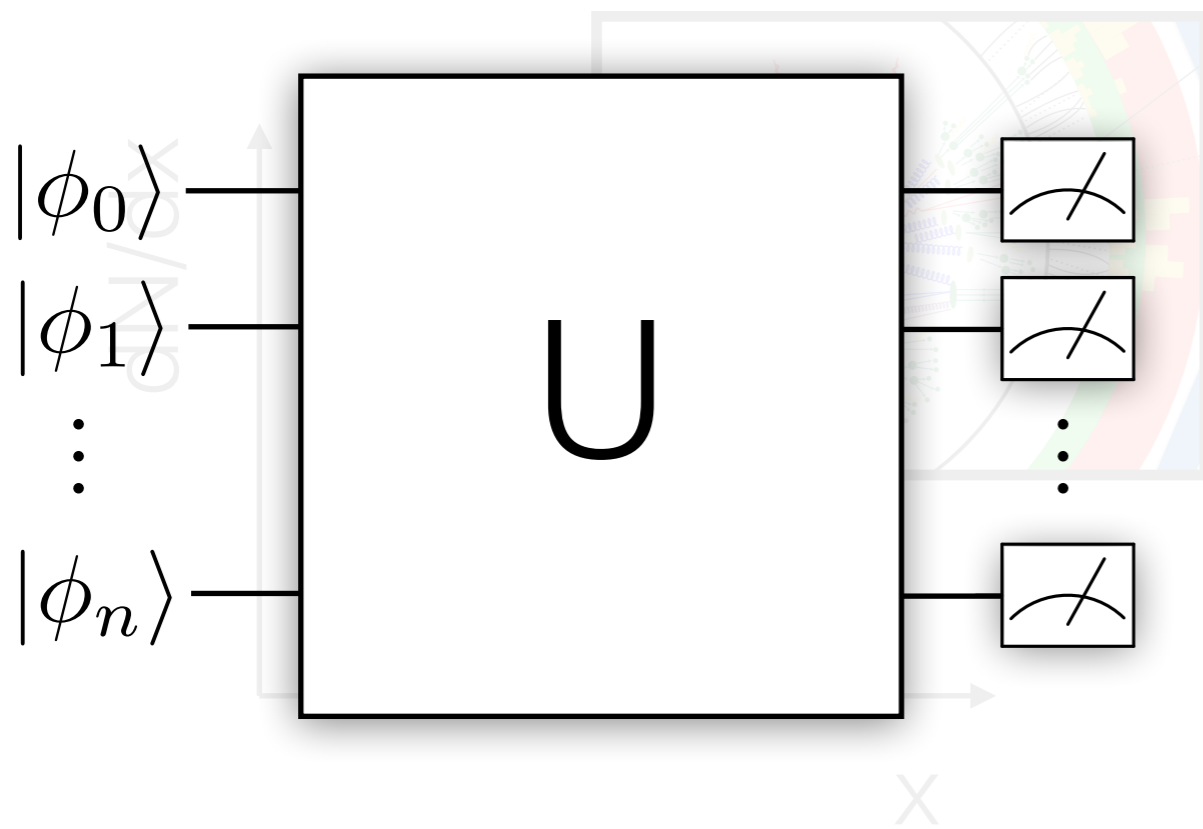


Quantum Computing

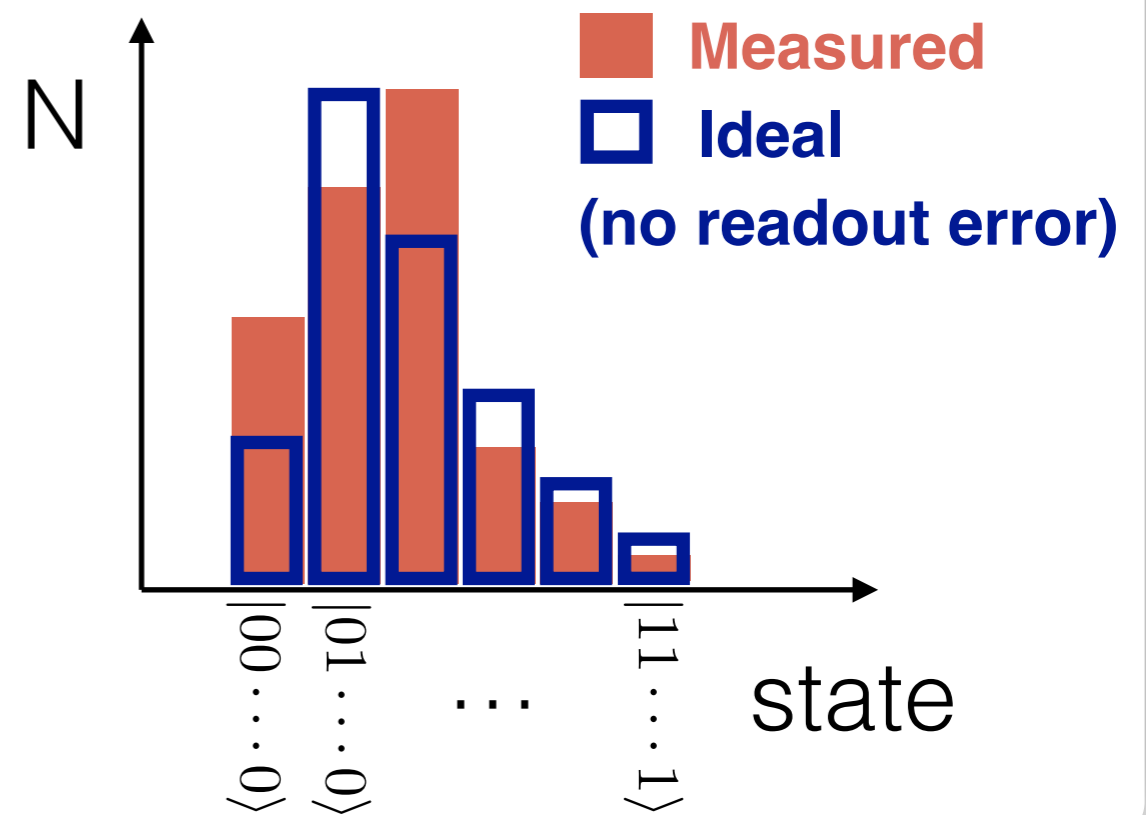


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High Energy Physics

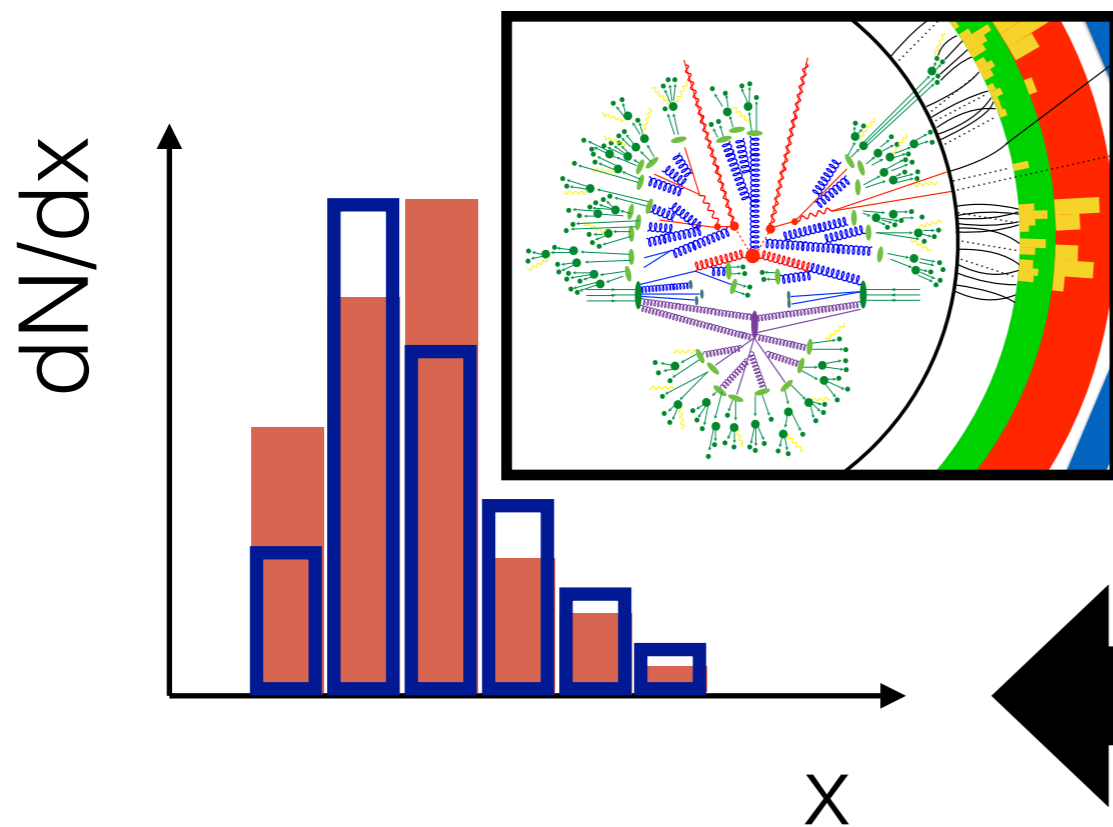


Quantum Computing

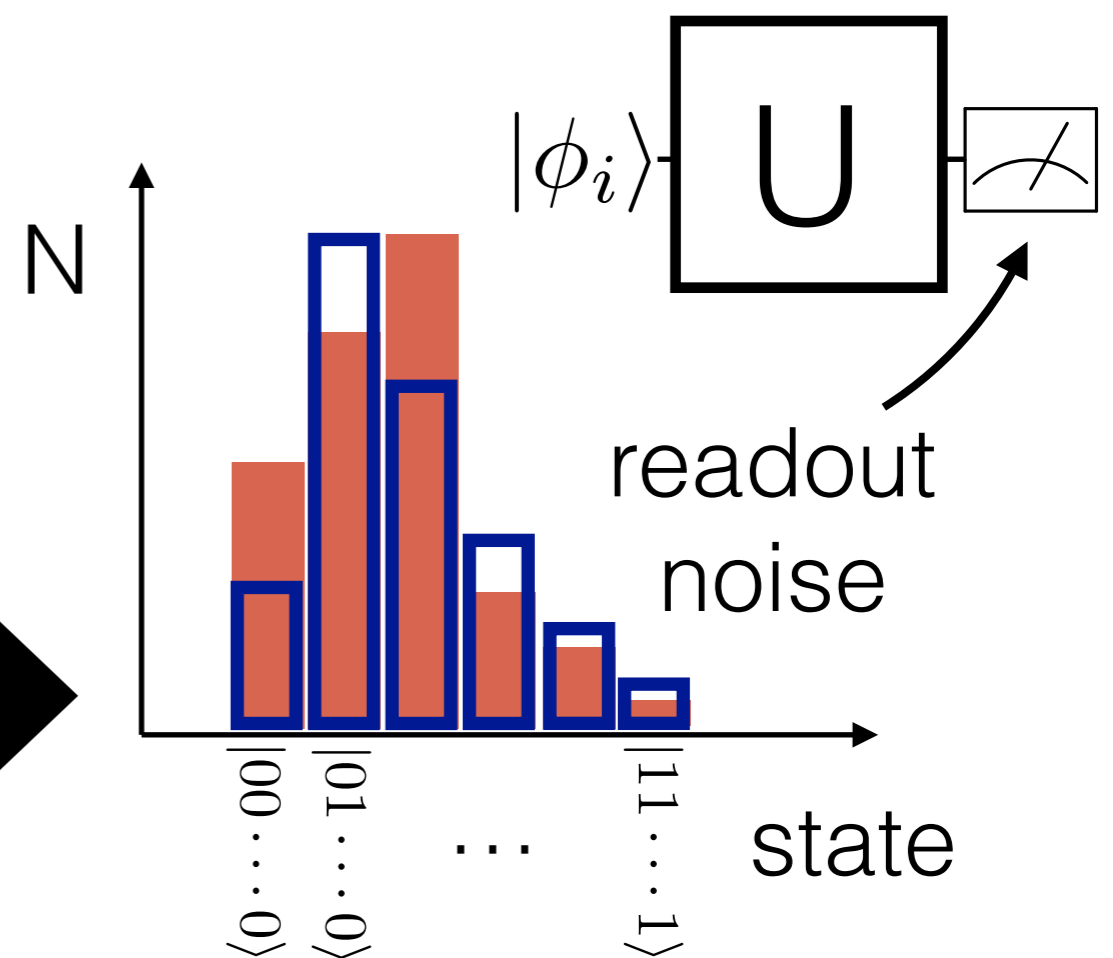


In addition to basic algorithms dev. for QFT, I have discovered new ways to improve quantum computing **in general**

High Energy Physics



Quantum Computing



Outline for today

97

Theoretical and experimental questions motivate a deep exploration **of the fundamental structure of nature**

Key **challenge** and **opportunity**: *hypervariate phase space*
& *hyper spectral data*

Likelihood-Free
inference

**Deep learning
& Quantum
computing for
fundamental
physics**

**Label-Free
learning**

[Deconvolution/Unfolding]

[Generative models]

[Weak supervision]

[Anomaly detection]

“But what are the uncertainties on your NN”?

- *question asked by every reviewer*



“But what are the uncertainties on your NN”?

- question asked by every reviewer

Determining uncertainties associated with a NN analysis can be tricky (ask me more later)



“But what are the uncertainties on your NN”?

- question asked by every reviewer

Determining uncertainties associated with a NN analysis can be tricky (ask me more later)

BPN, 1909.03081

...one point is clear: NN's exploit **high-dimensional correlations**; these are hard to model & it is hard to know how our accuracy.

Option 1: Work hard to understand the true nuisance parameters in the hypervariate parameter space.

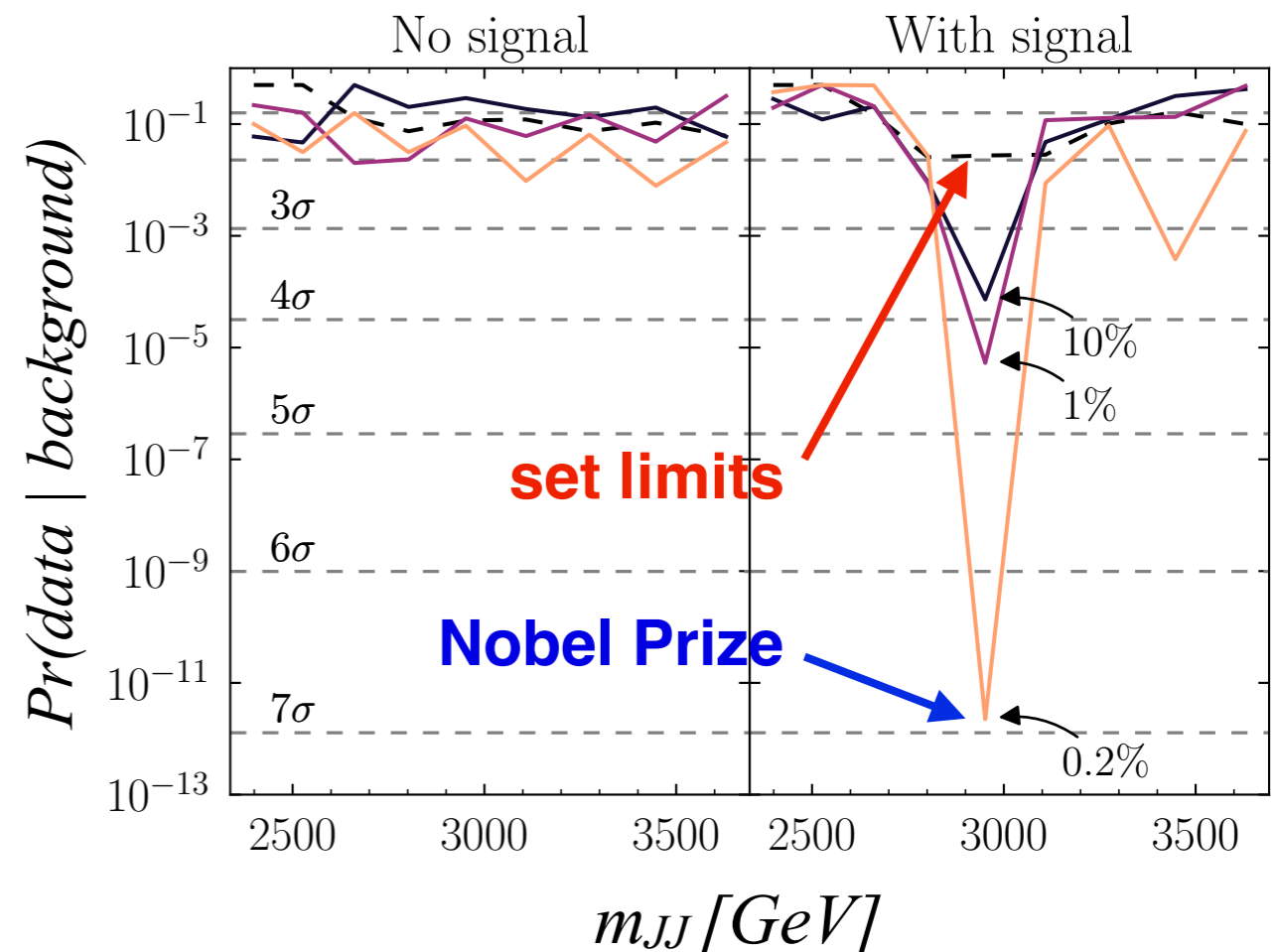
*Can borrow from **AI safety** to set bounds.*

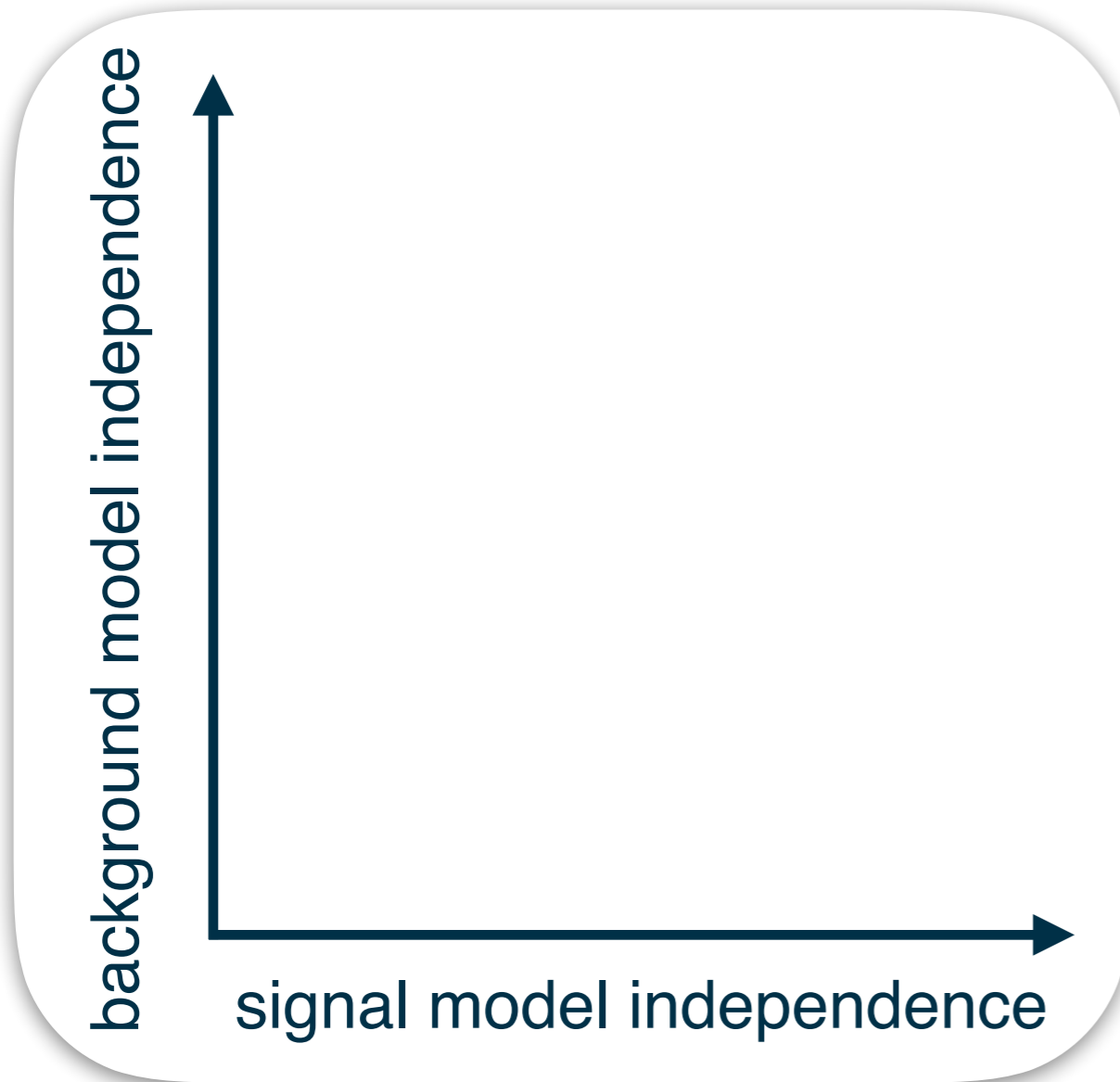
BPN and C. Shimmin, MLPS, NeurIPS 2019

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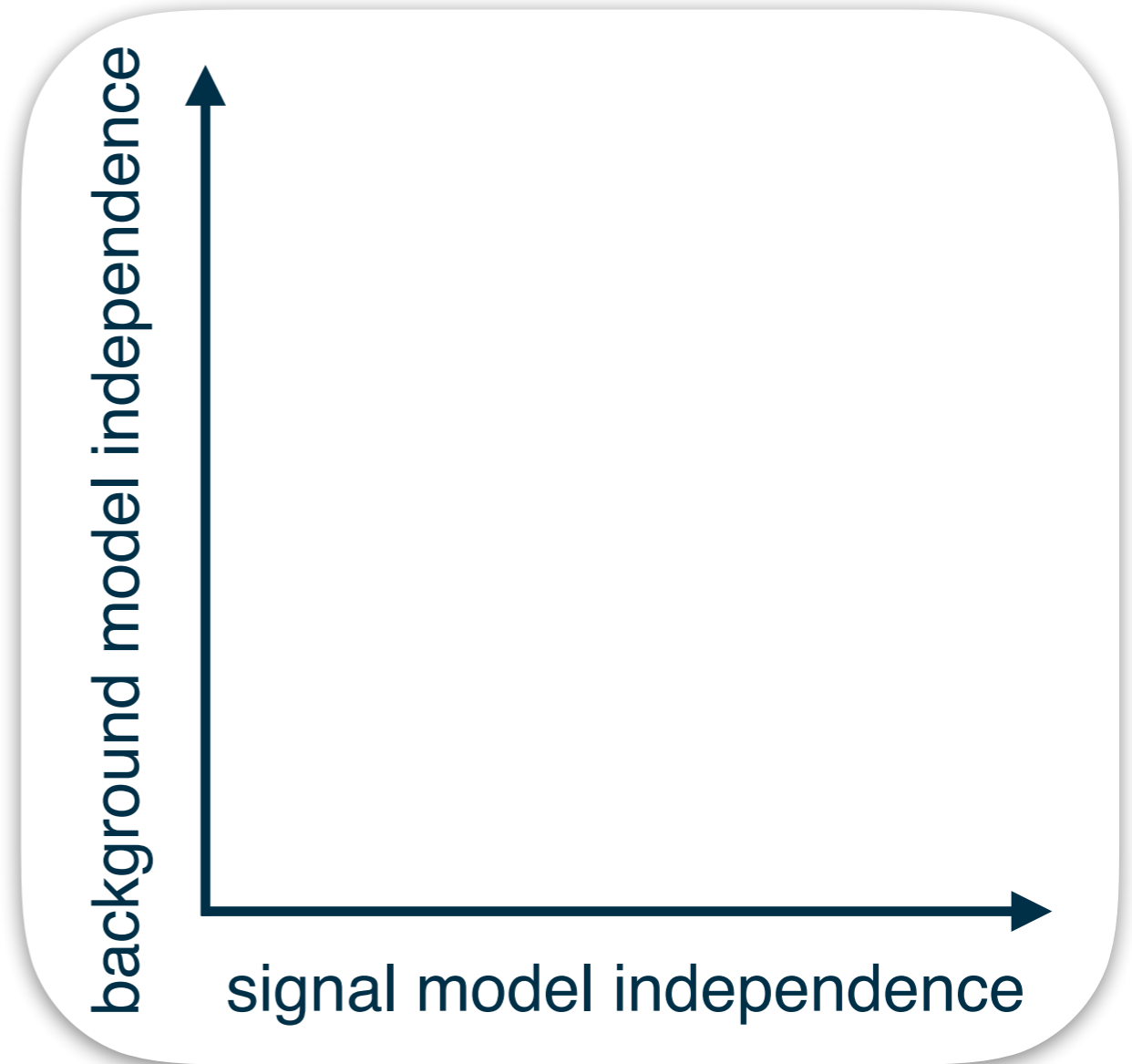
Can borrow from *AI safety* to set bounds.
BPN and C. Shimmin, MLPS, NeurIPS 2019

Option 2:
Don't use simulation!
(not always possible!)





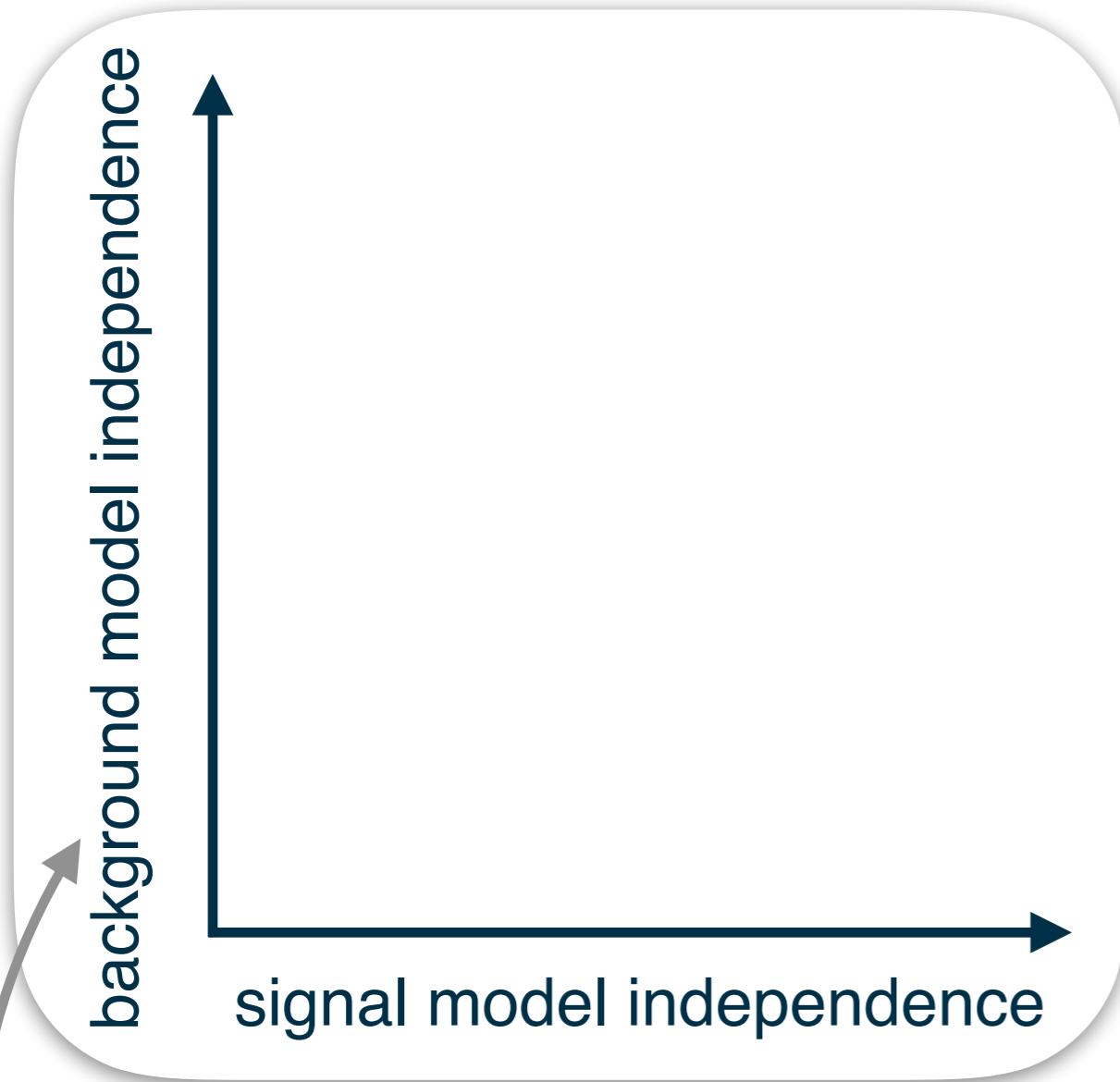
Signal sensitivity



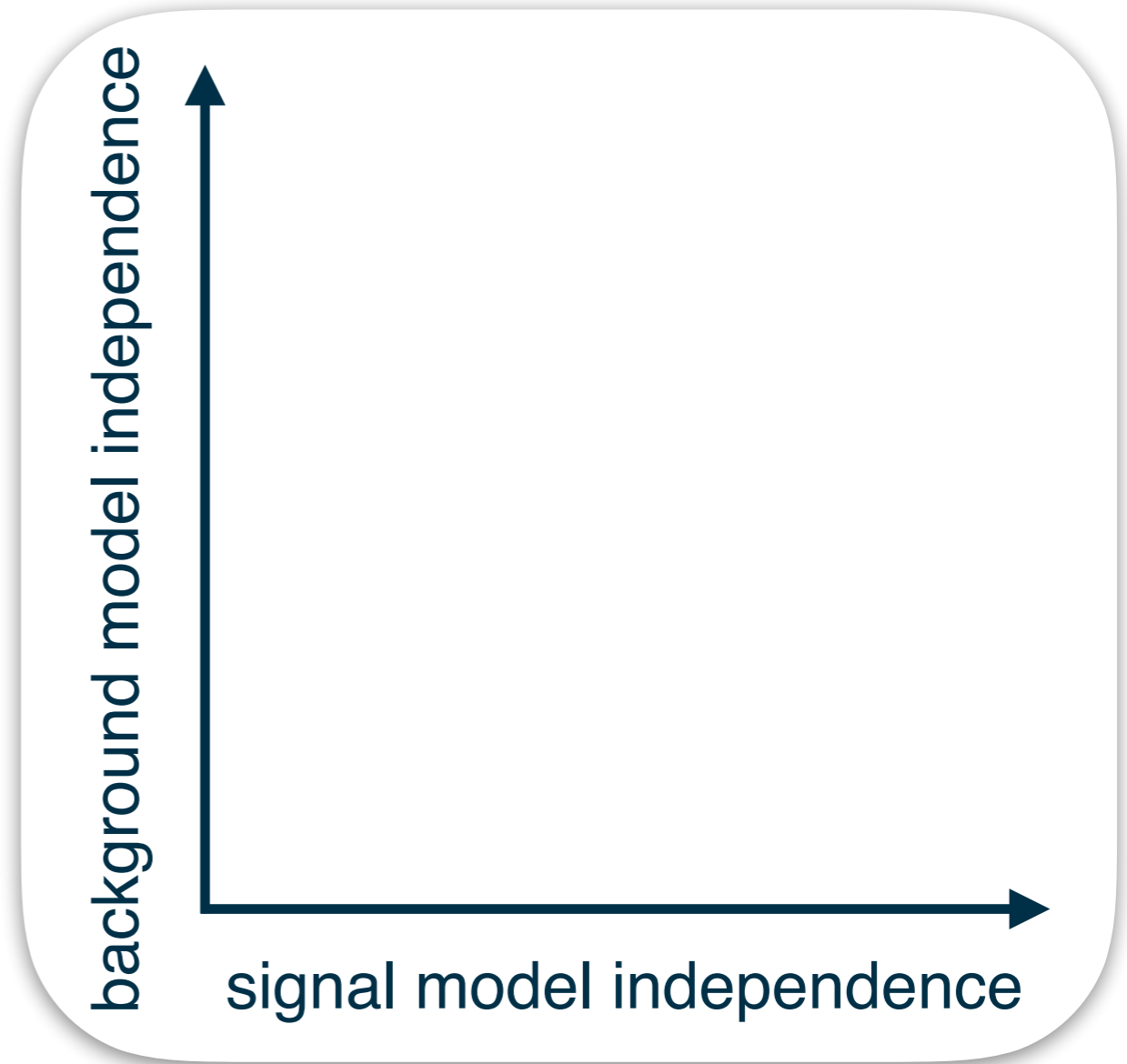
Background specificity

Suppose you want to search for a new signal process

Model dependence



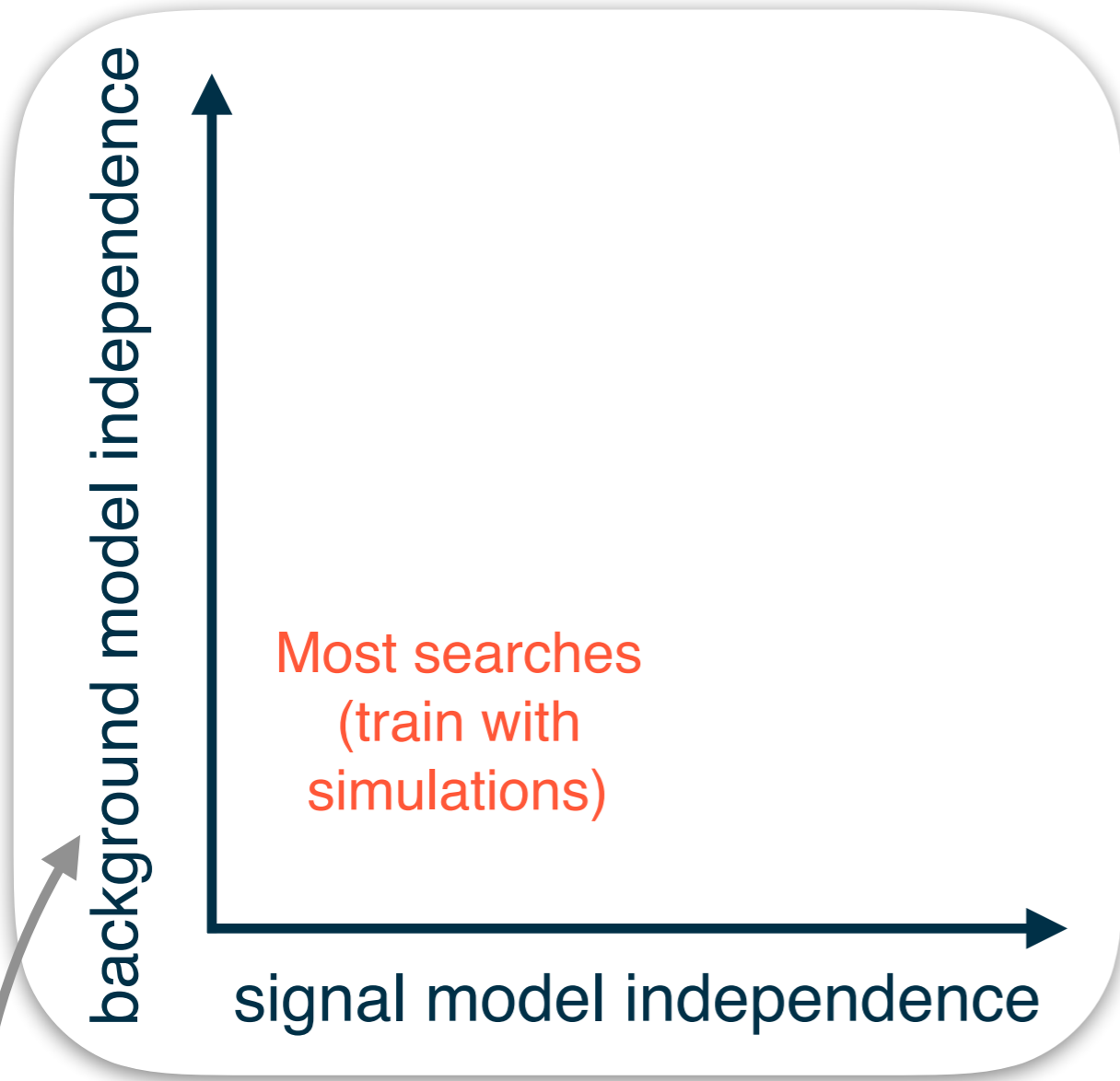
Signal sensitivity



Background specificity

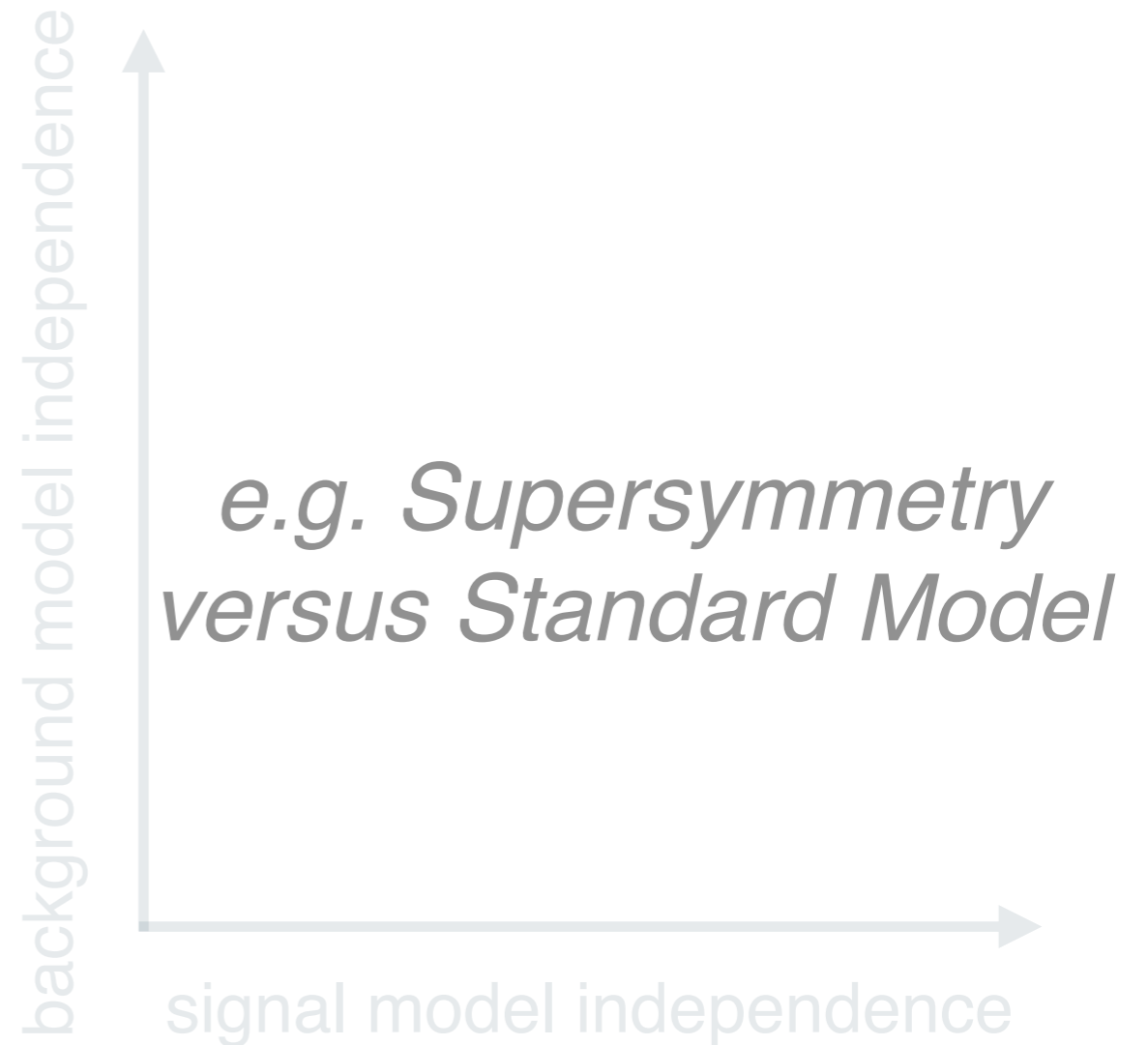
Standard Model

Model dependence



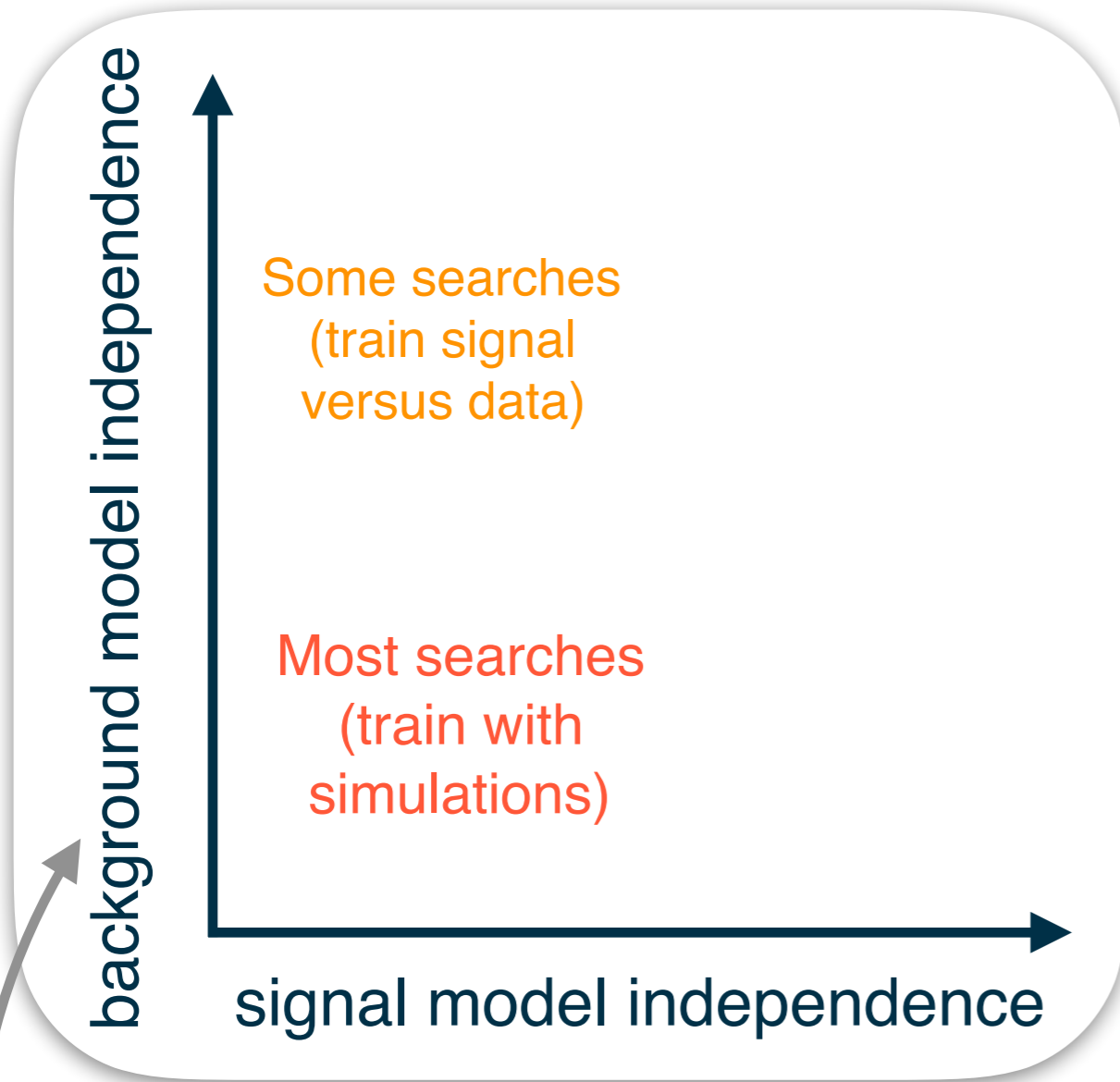
Signal sensitivity

*Standard
Model*



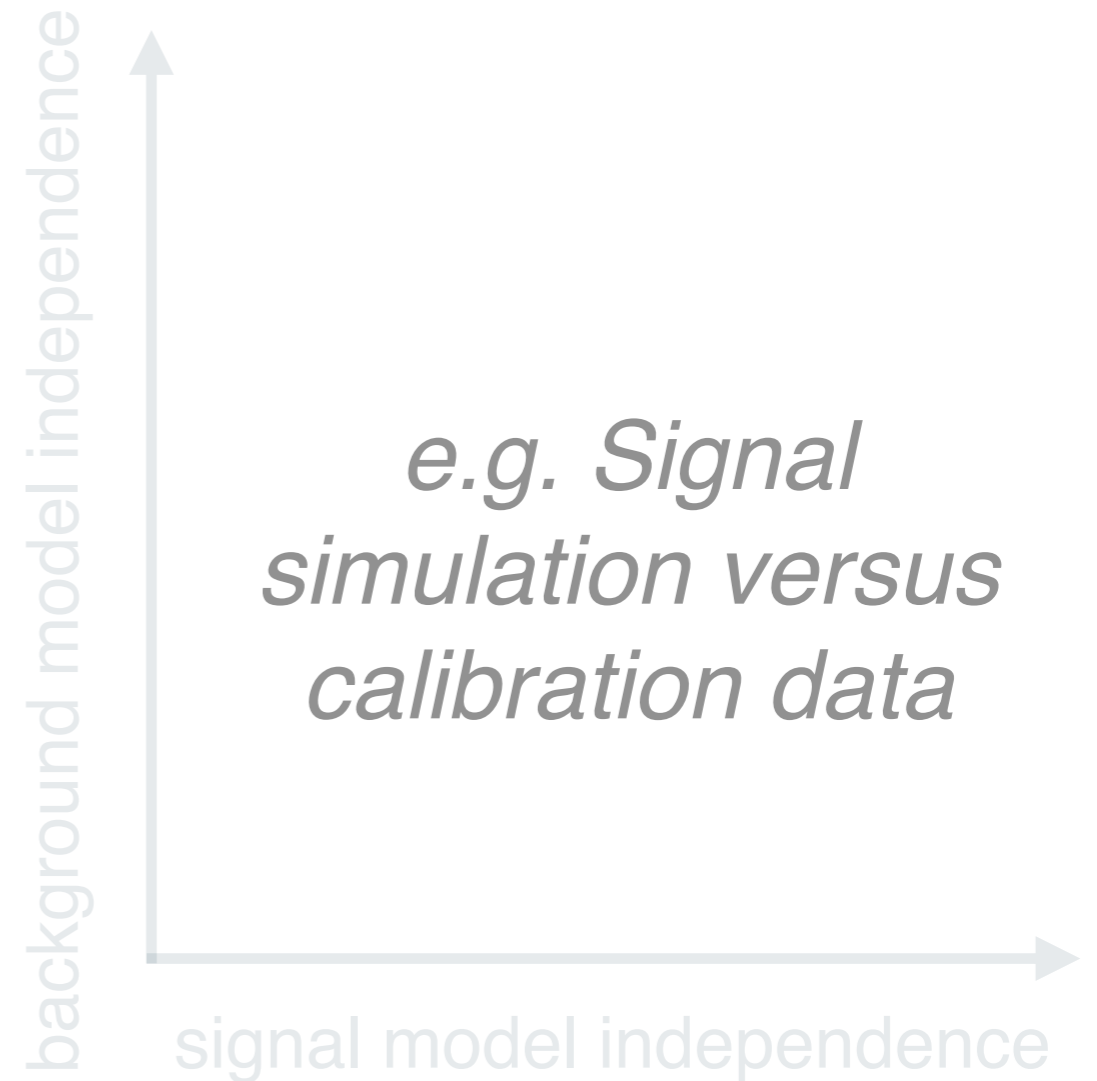
Background specificity

Model dependence



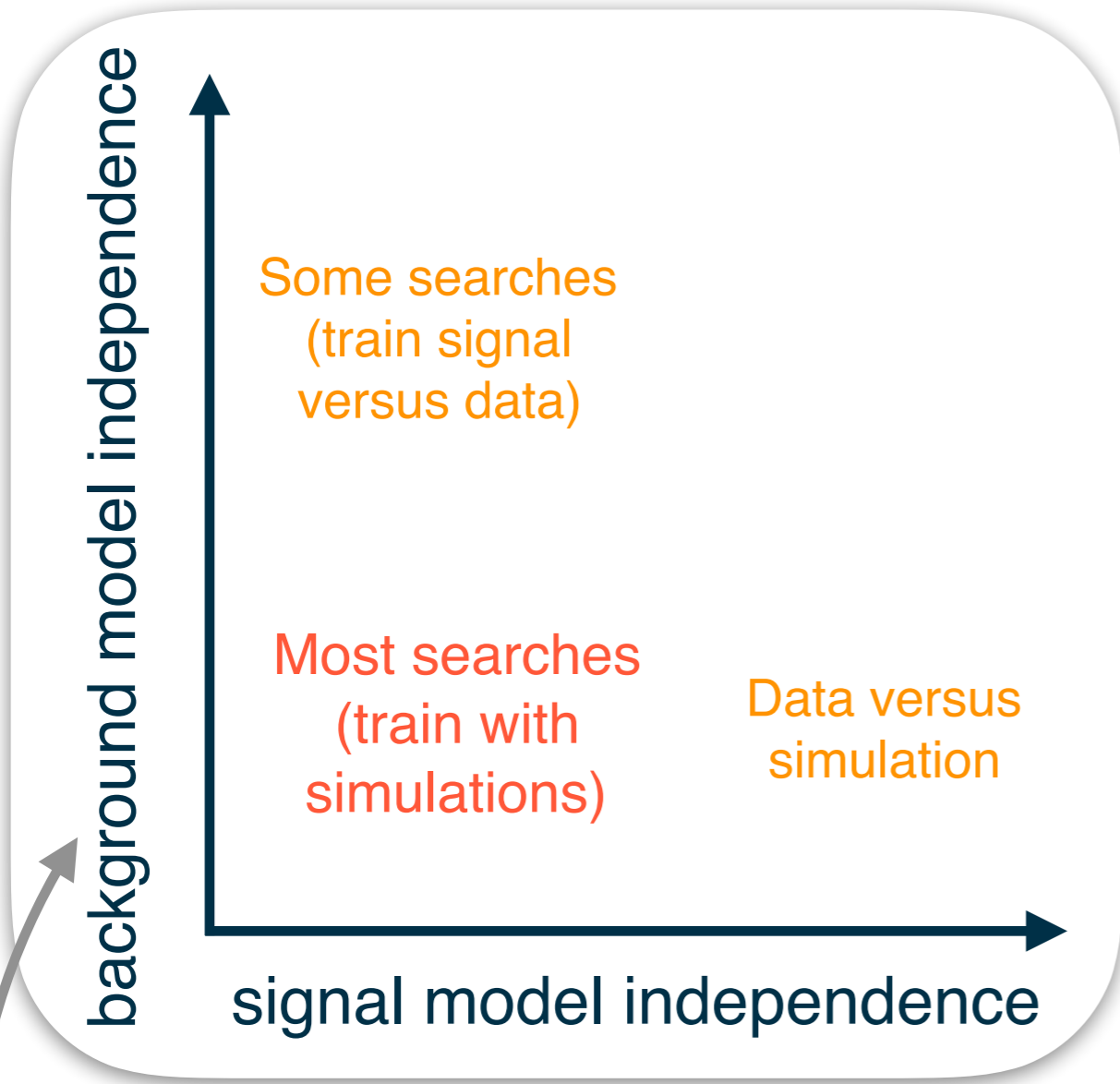
Signal sensitivity

*Standard
Model*



Background specificity

Model dependence



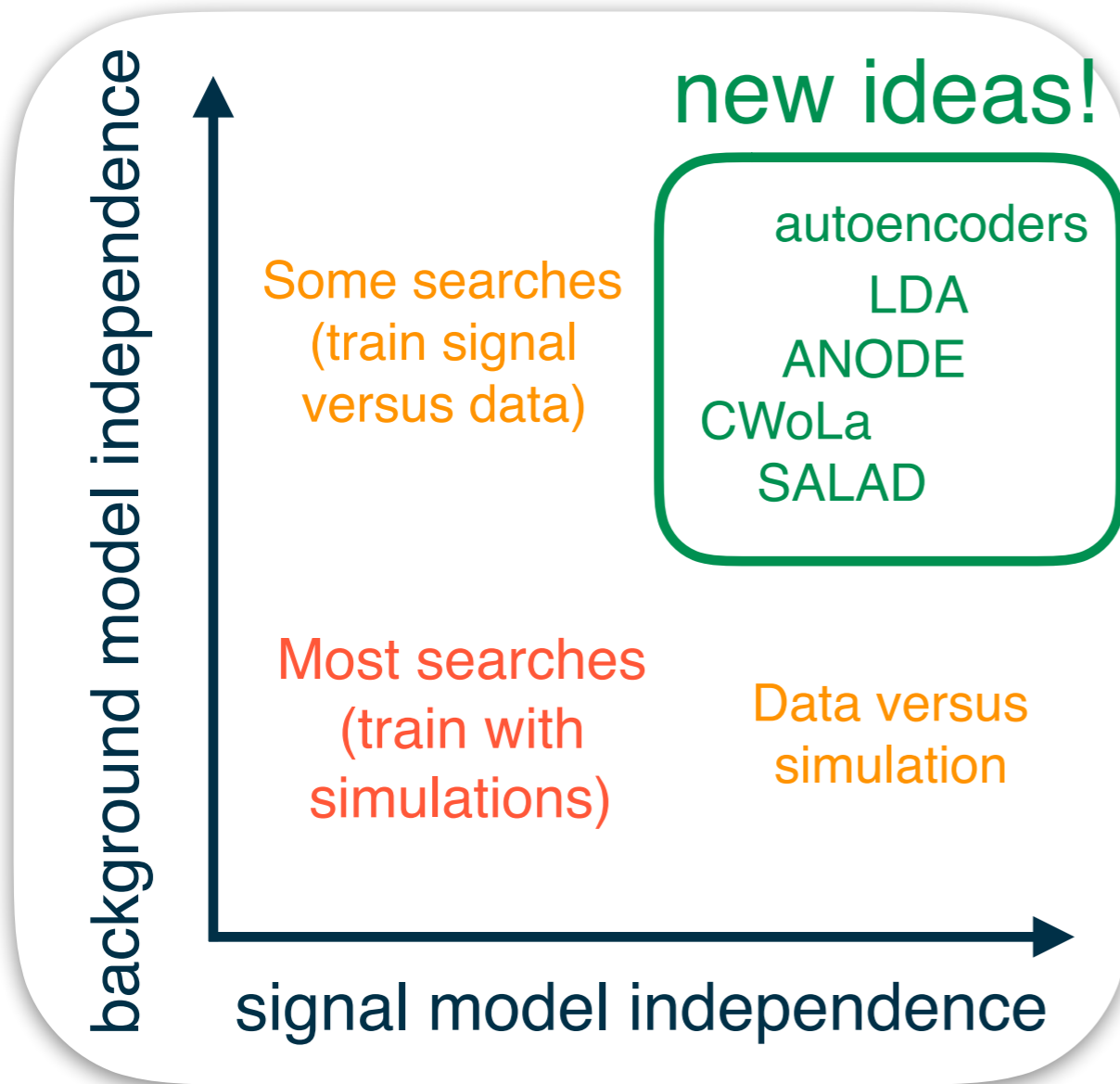
Signal sensitivity

Background specificity

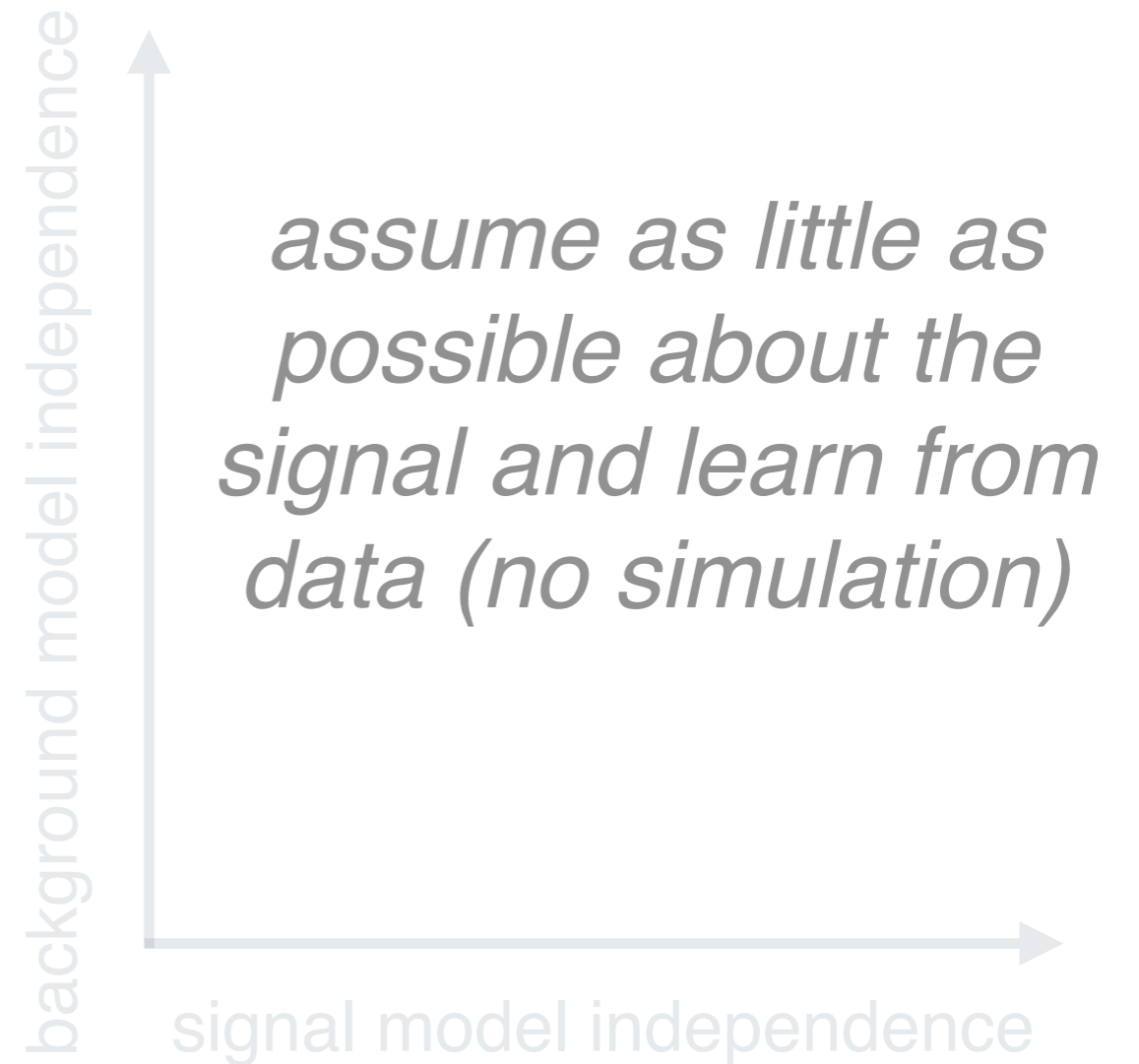
*Standard
Model*

Model dependence

108



Signal sensitivity



Background specificity

M. Farina, Y. Nakai, D. Shih, 1808.08992 + others

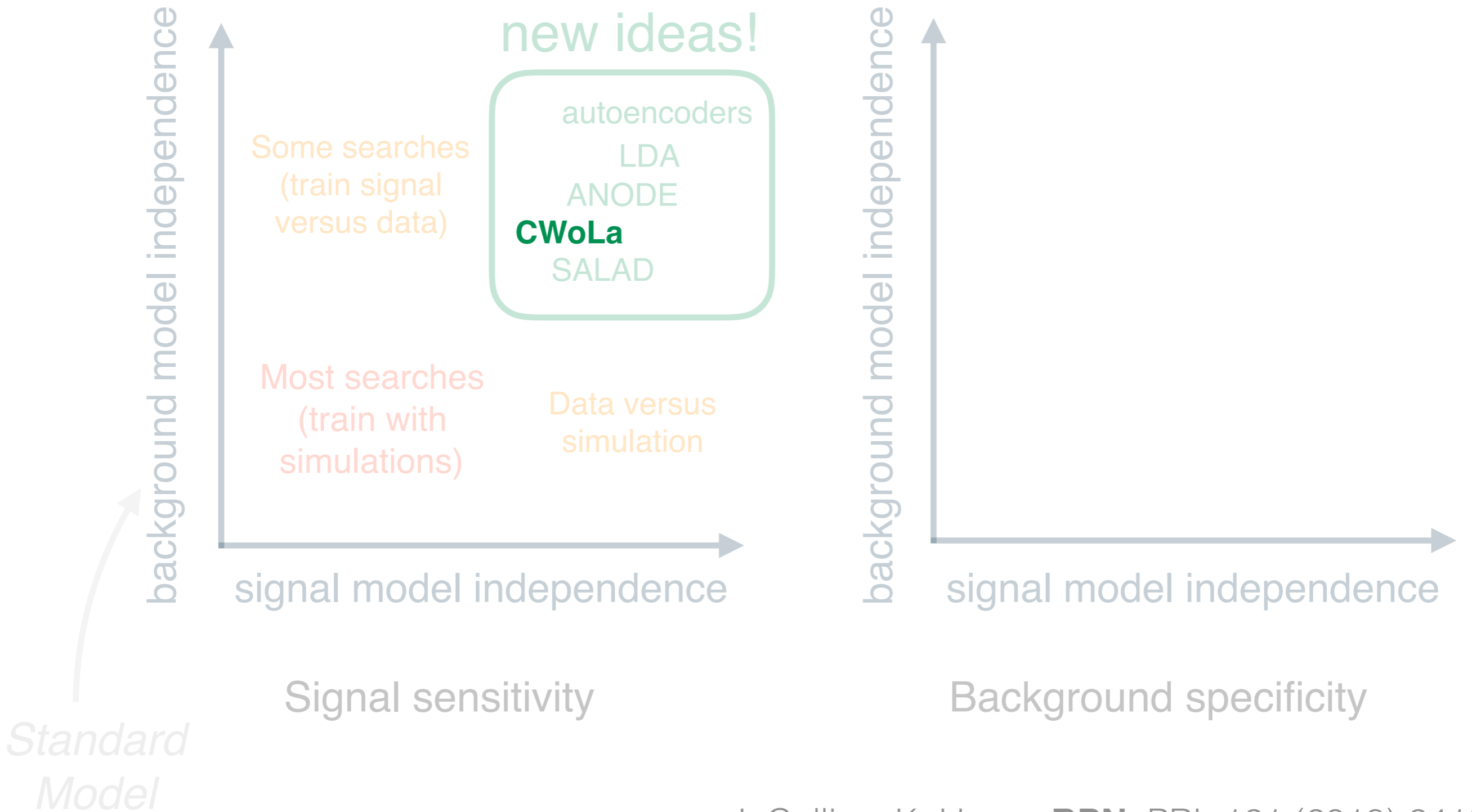
B. Dillon et al., PRD 100 (2019) 056002

BPN, D. Shih, 2001.04990

J. Collins, K. Howe, **BPN**, PRL 121 (2018) 241803

A. Andreassen, **BPN**, D. Shih, 2001.05001

Model dependence



What is the problem?

110

Why can't I just pay some physicists to label events and then train a neural network using those labels?



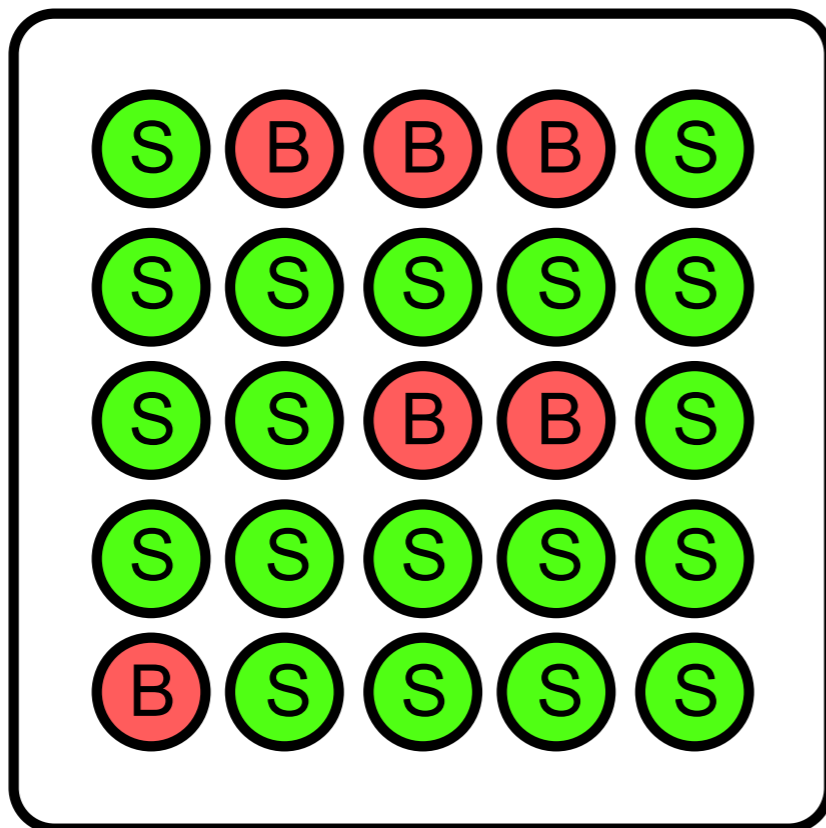
Image credit: pixabay.com

Answer: this is not cats-versus-dogs ... thanks to quantum mechanics it is **not possible to know** what happened.

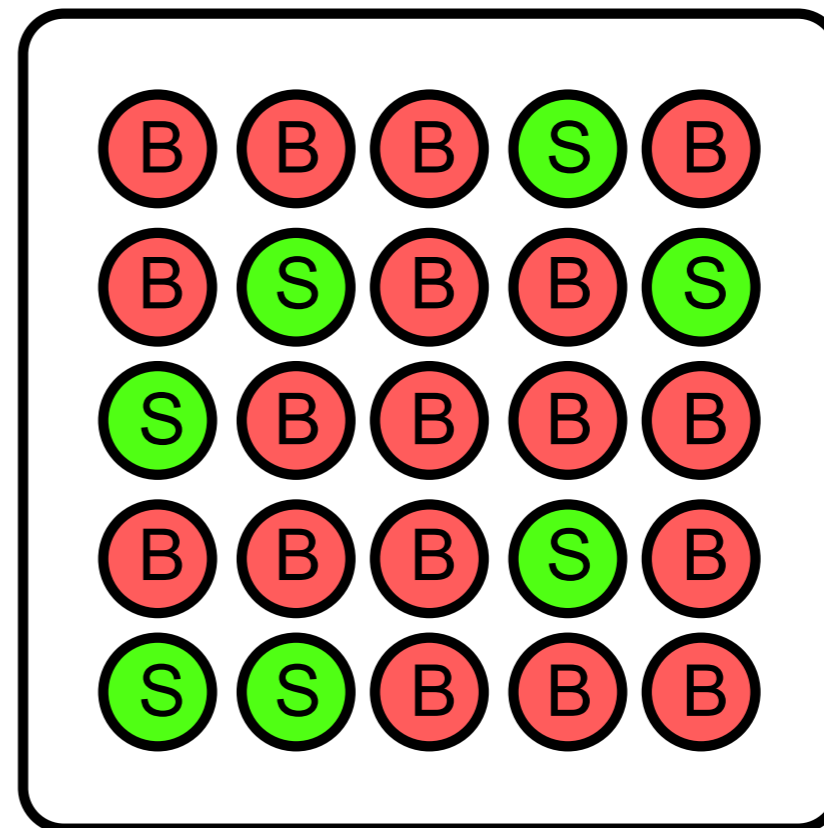
What is the problem?

The data are unlabeled and in the best case, come to us as mixtures of two classes (“signal” and “background”).

Mixed Sample 1



Mixed Sample 2

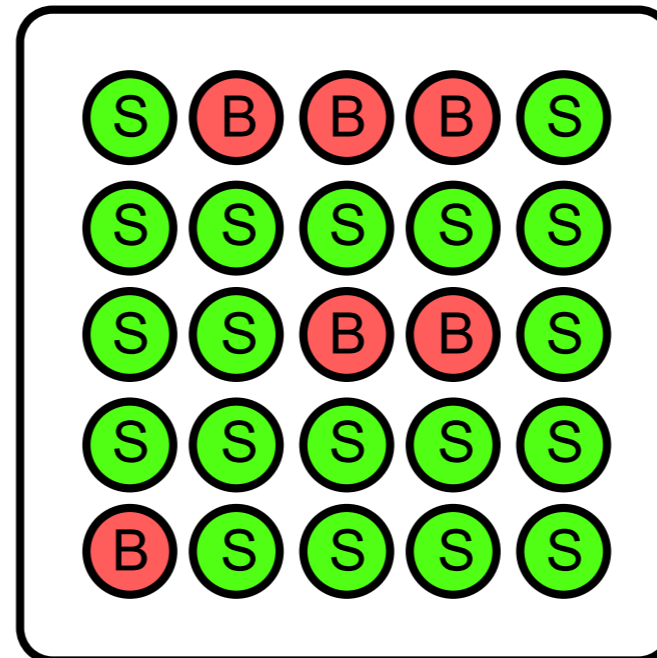


(we don't get to observe the color of the circles)

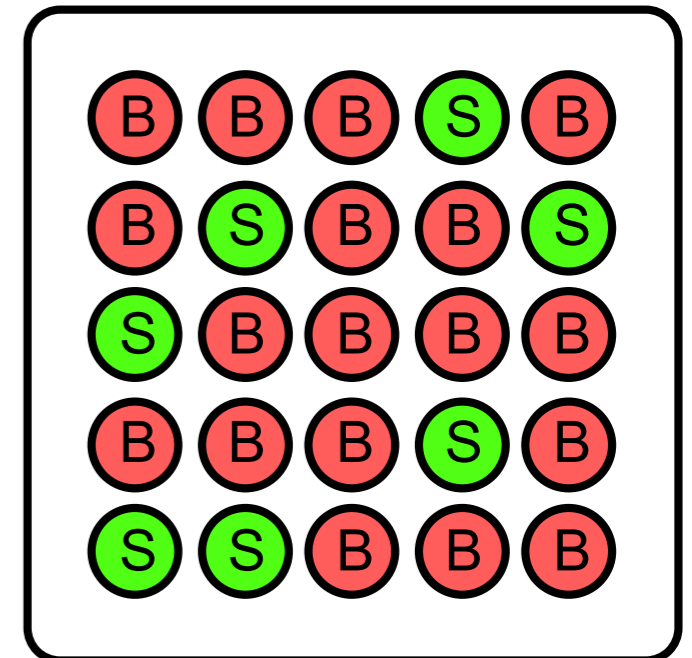
Weak supervision: *Classification Without Labels*

Can we learn
without any label
information?

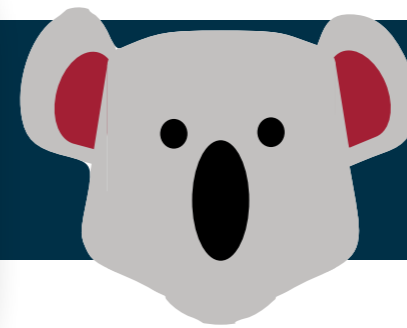
Mixed Sample 1



Mixed Sample 2



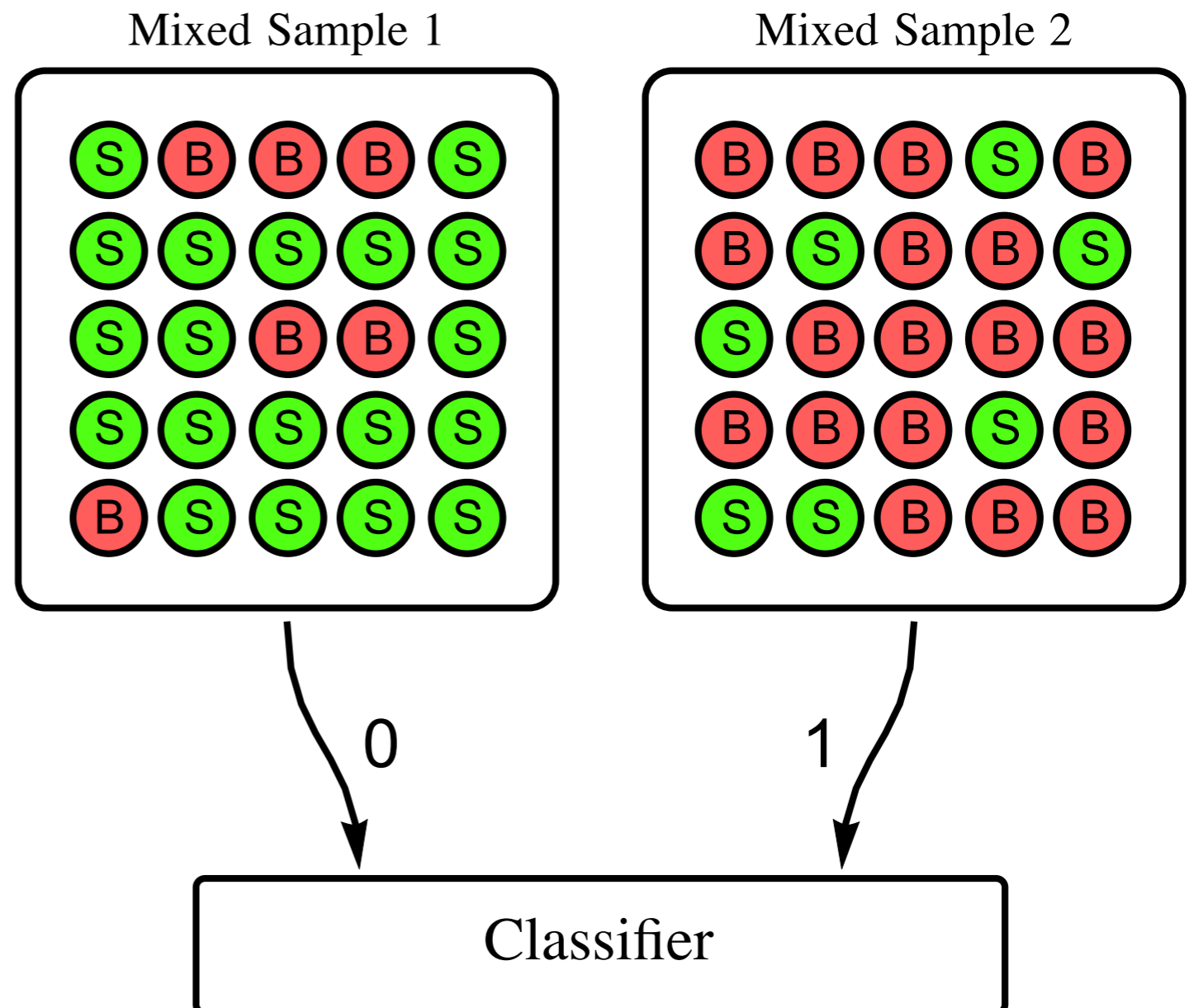
Weak supervision: *Classification Without Labels*



Can we learn
without any label
information?

Yes !

*Training on impure
samples is
(asymptotically)
equivalent to training
on pure samples*



How can we use CWoLa to **hunt for new** particles?

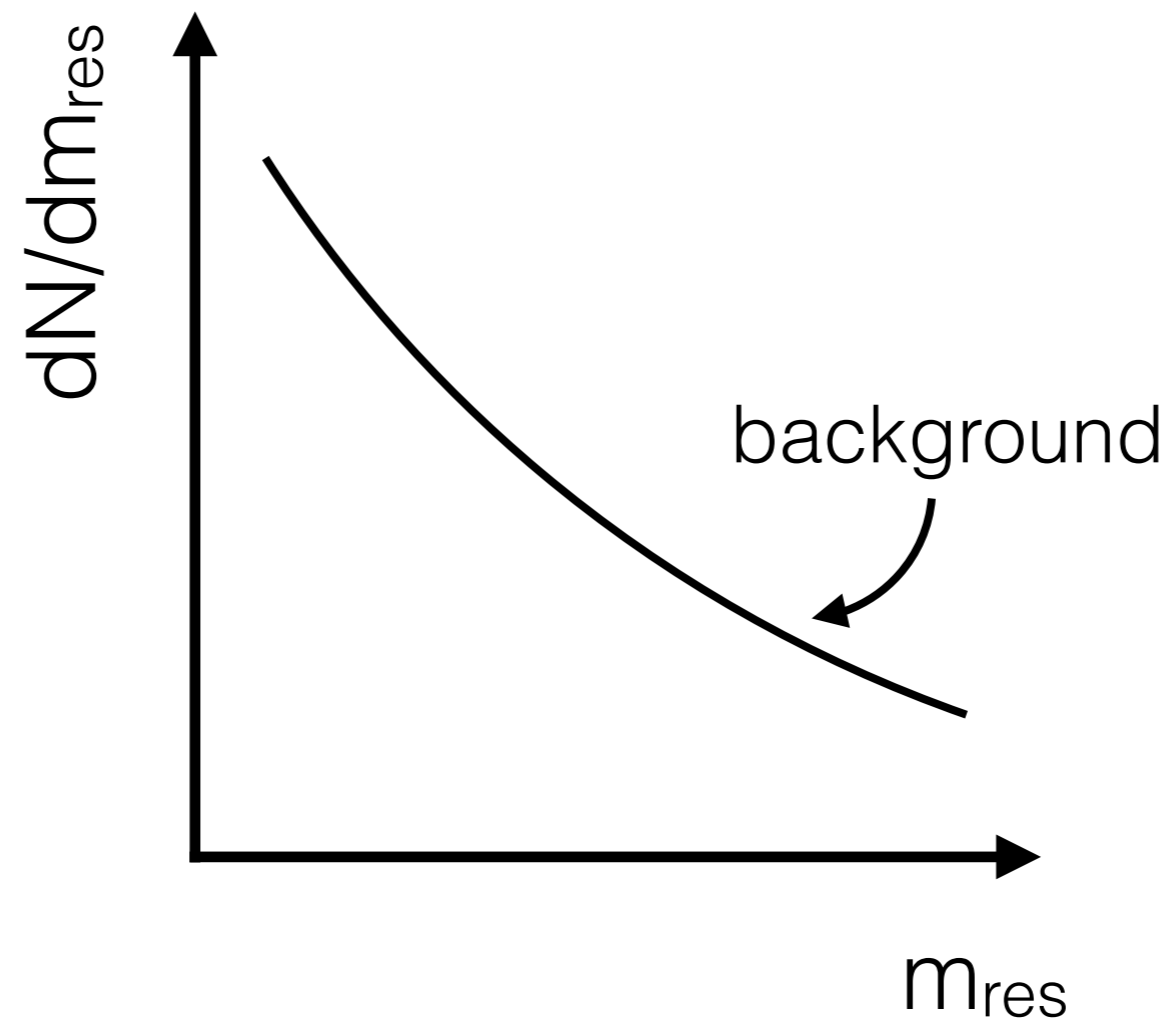
How can we use CWoLa to **hunt for new** particles?



*Image from *The Courier Mail*. Koala is actually being freed - I do not condone violence against these animals!

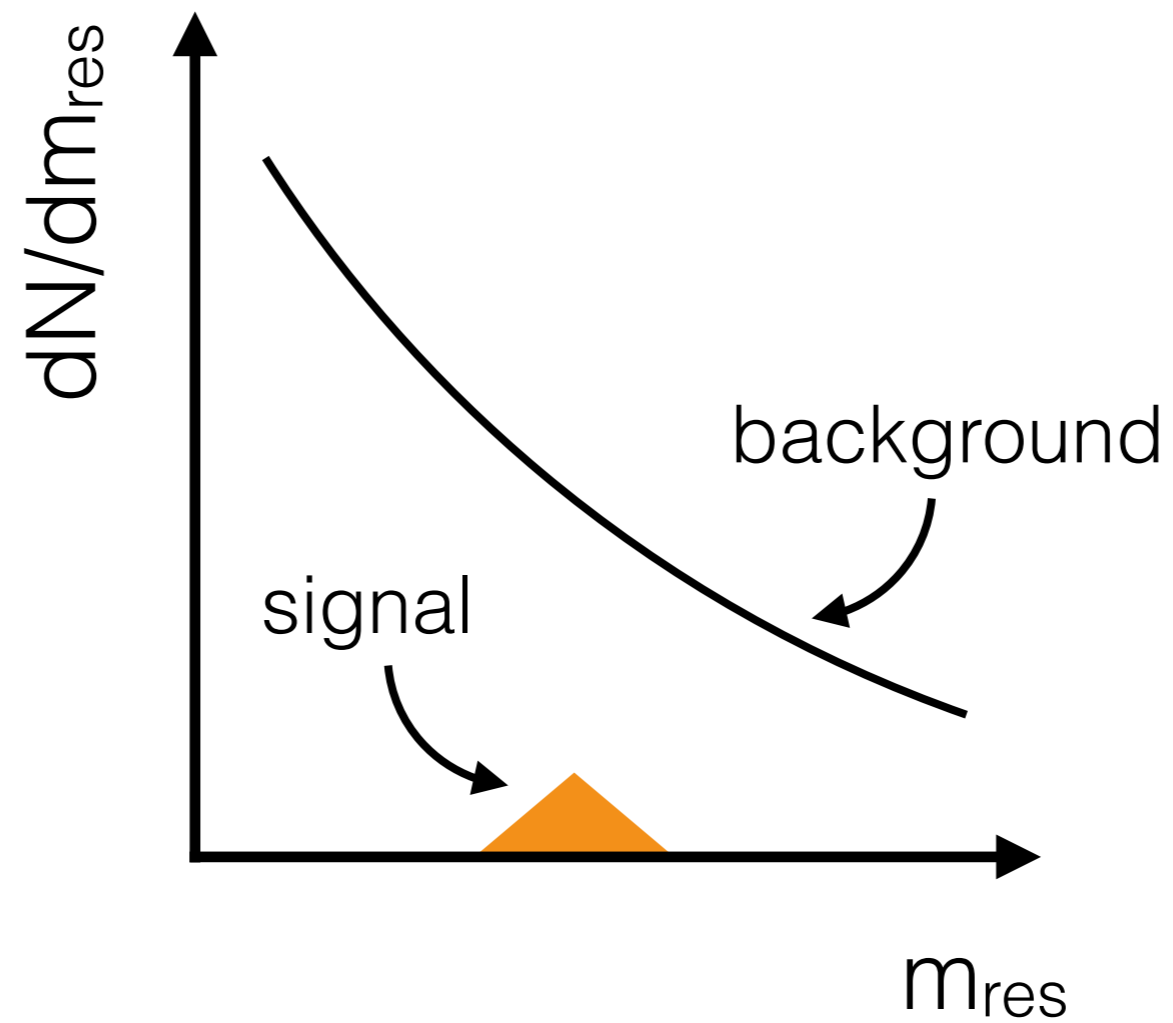
CWoLa Hunting

J. Collins, K. Howe, **BPN**,
Phys. Rev. Lett. 121 (2018) 241803



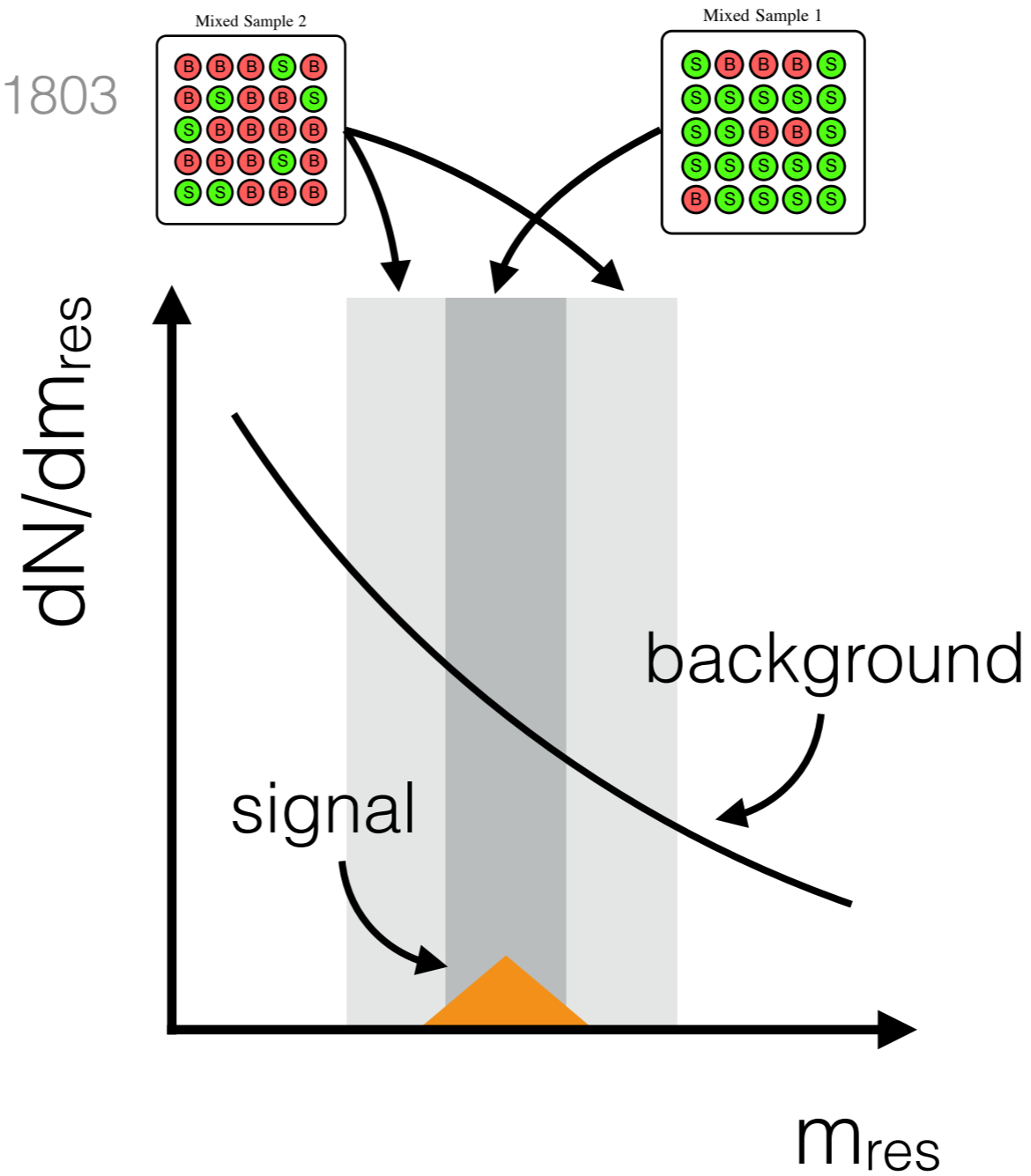
CWoLa Hunting

J. Collins, K. Howe, **BPN**,
Phys. Rev. Lett. 121 (2018) 241803



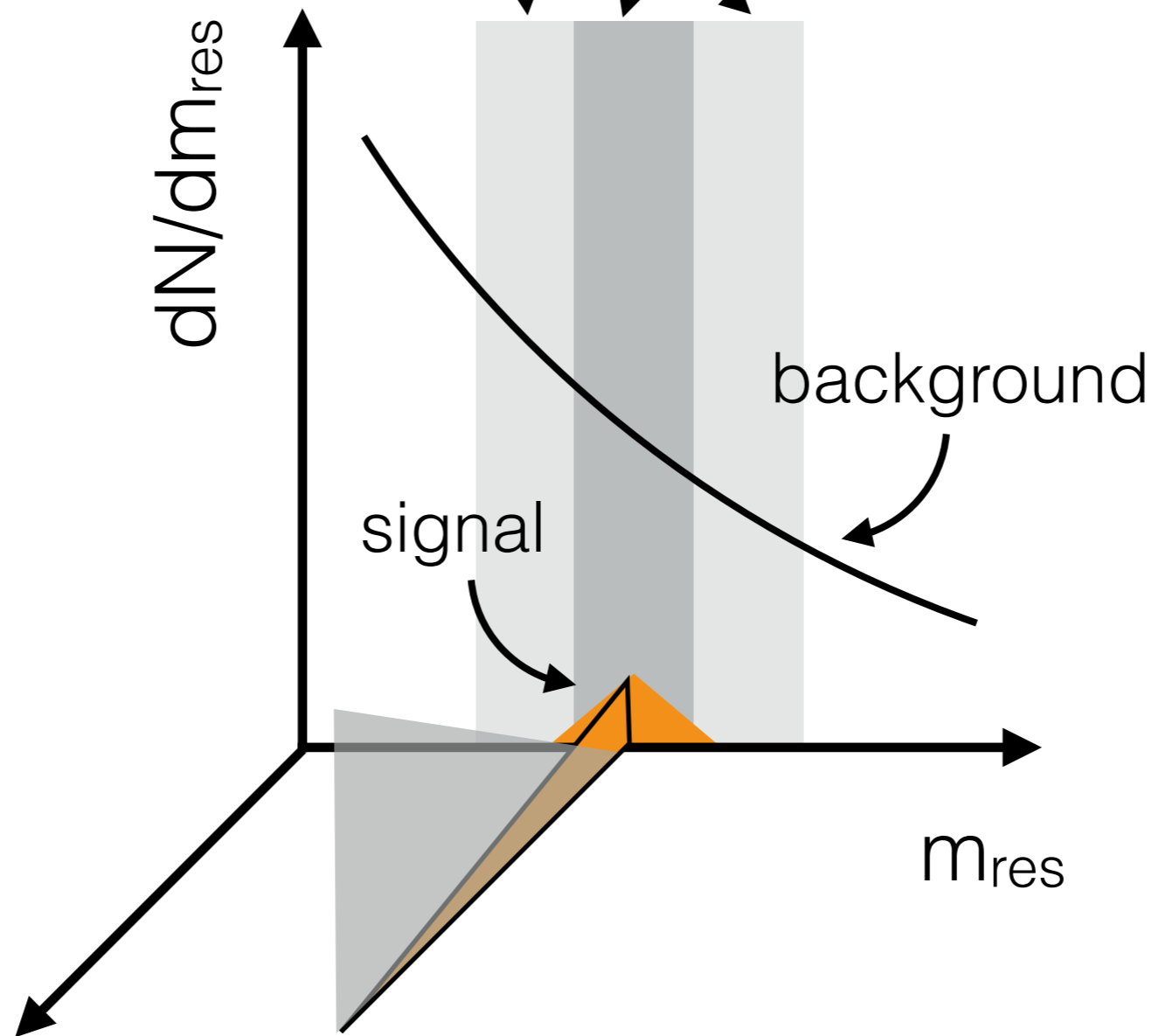
CWoLa Hunting

J. Collins, K. Howe, **BPN**,
Phys. Rev. Lett. 121 (2018) 241803



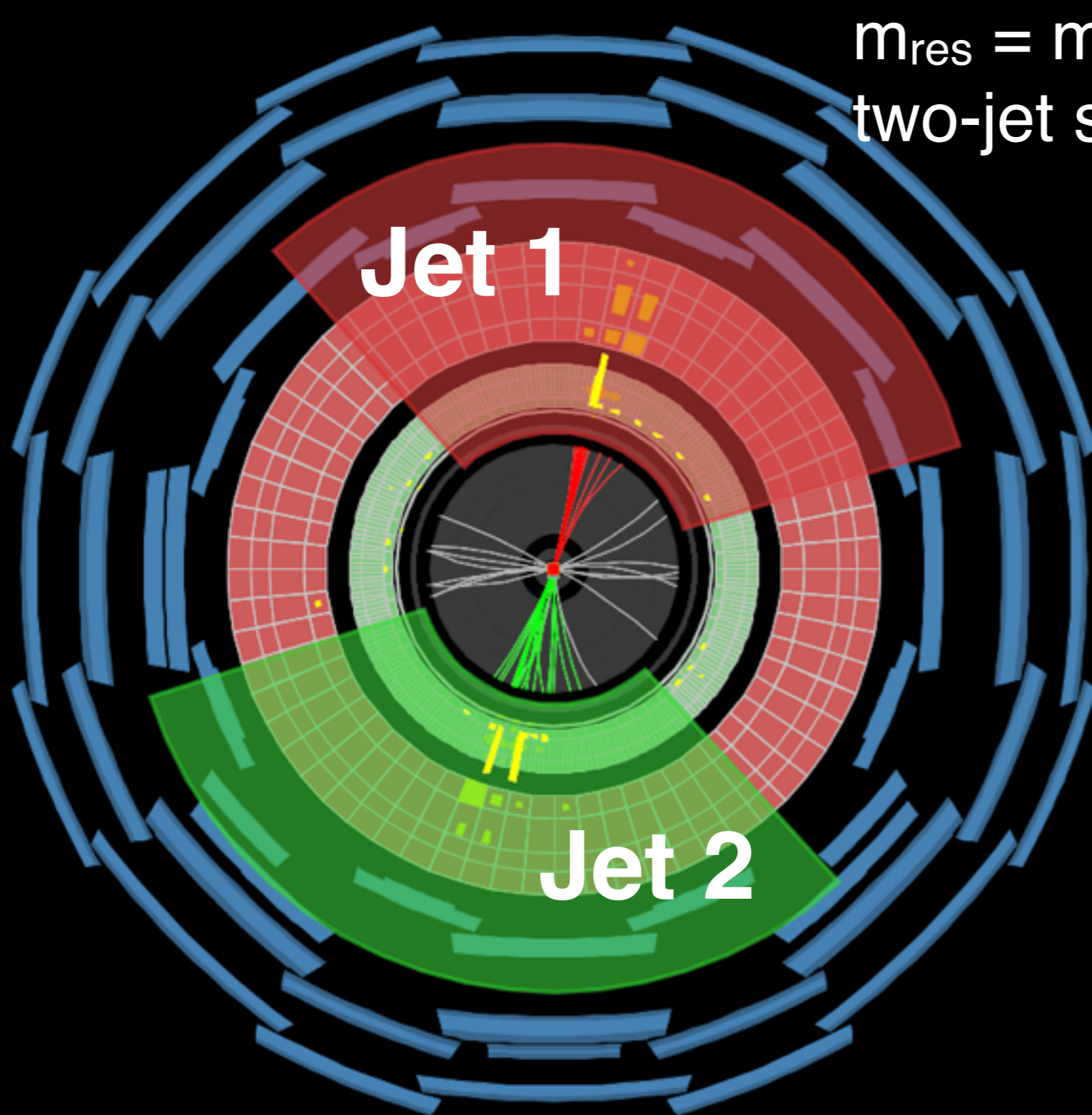
CWoLa Hunting

J. Collins, K. Howe, **BPN**,
Phys. Rev. Lett. 121 (2018) 241803

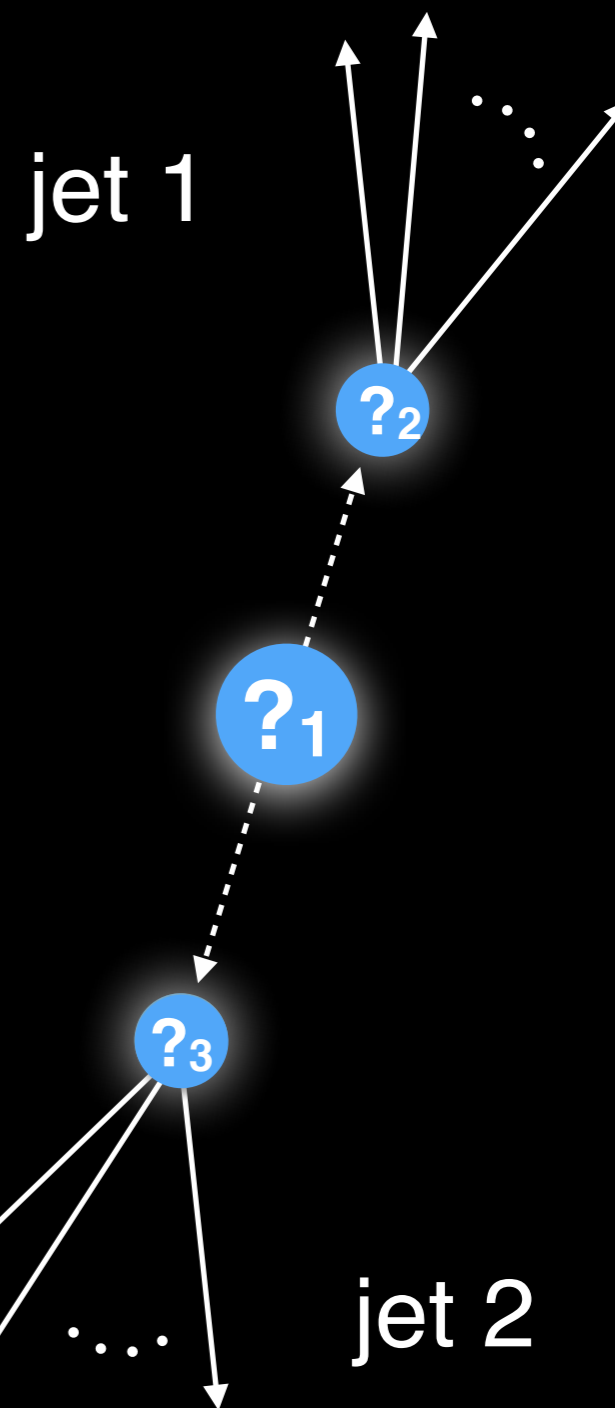


+ be careful to not pay a big trails factor
(ask if interested)

Example: two-“jet” search



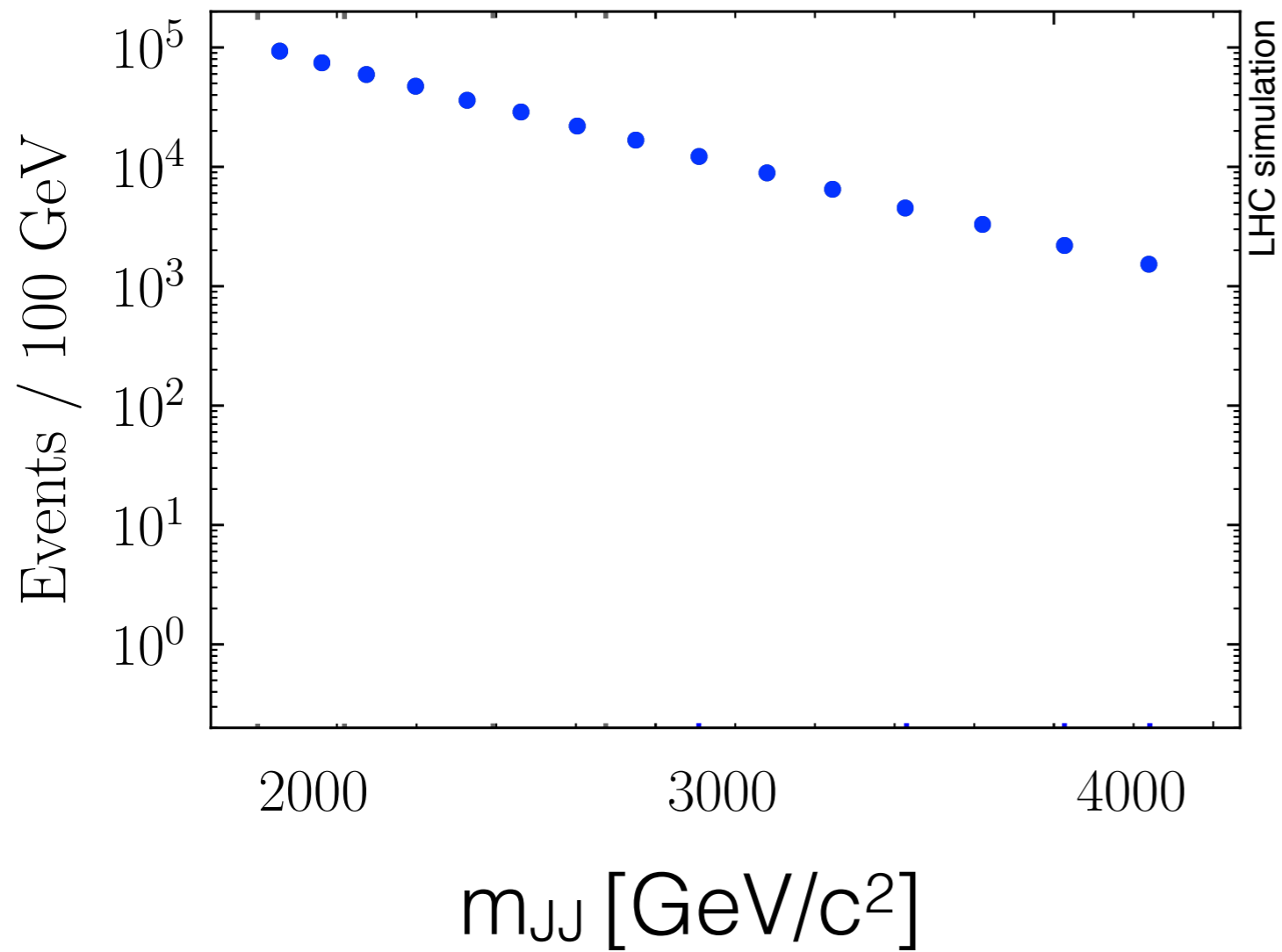
m_{res} = mass of two-jet system



collisions in/out of page

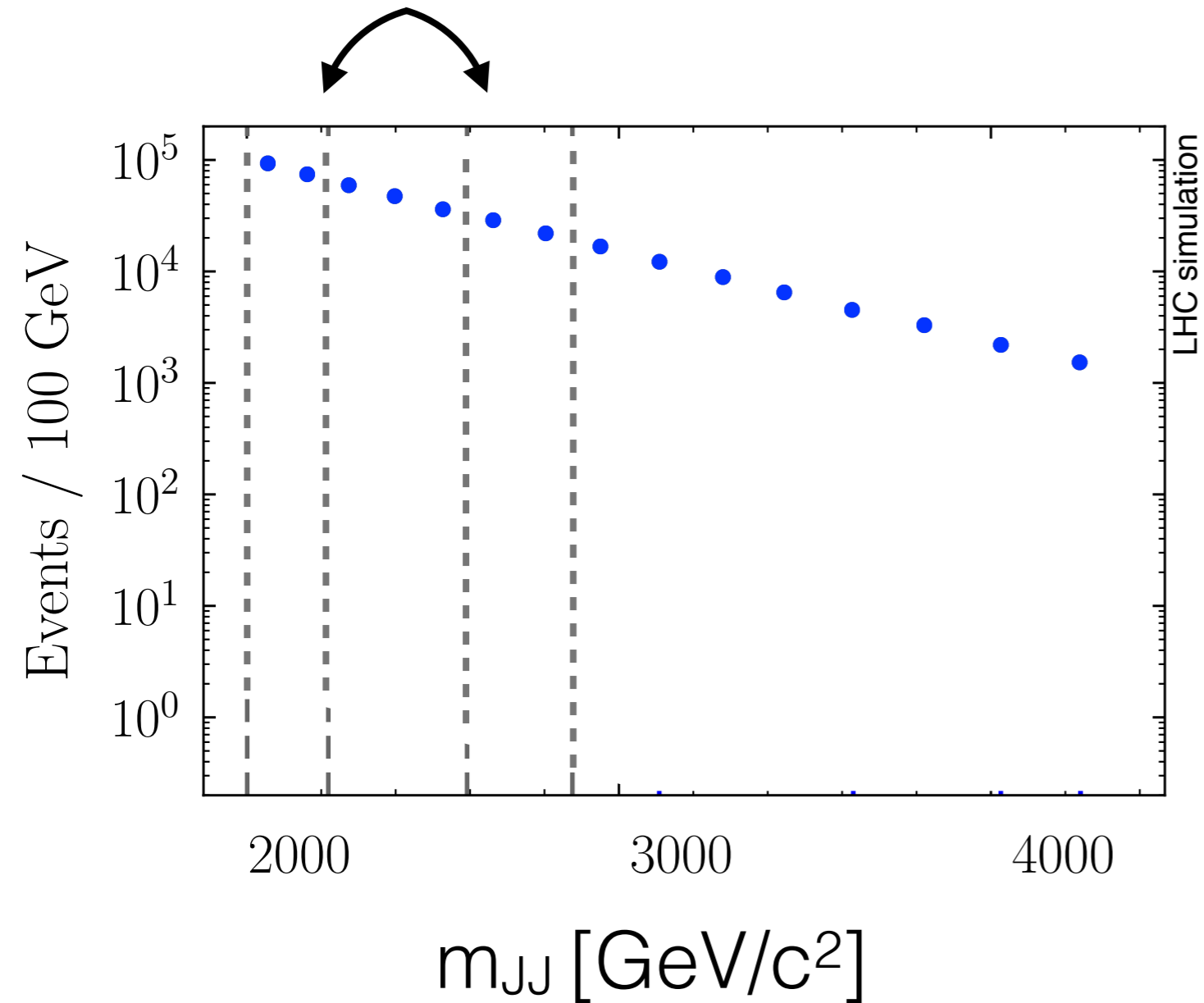
y = many features of the two jets

Example: two-jet search

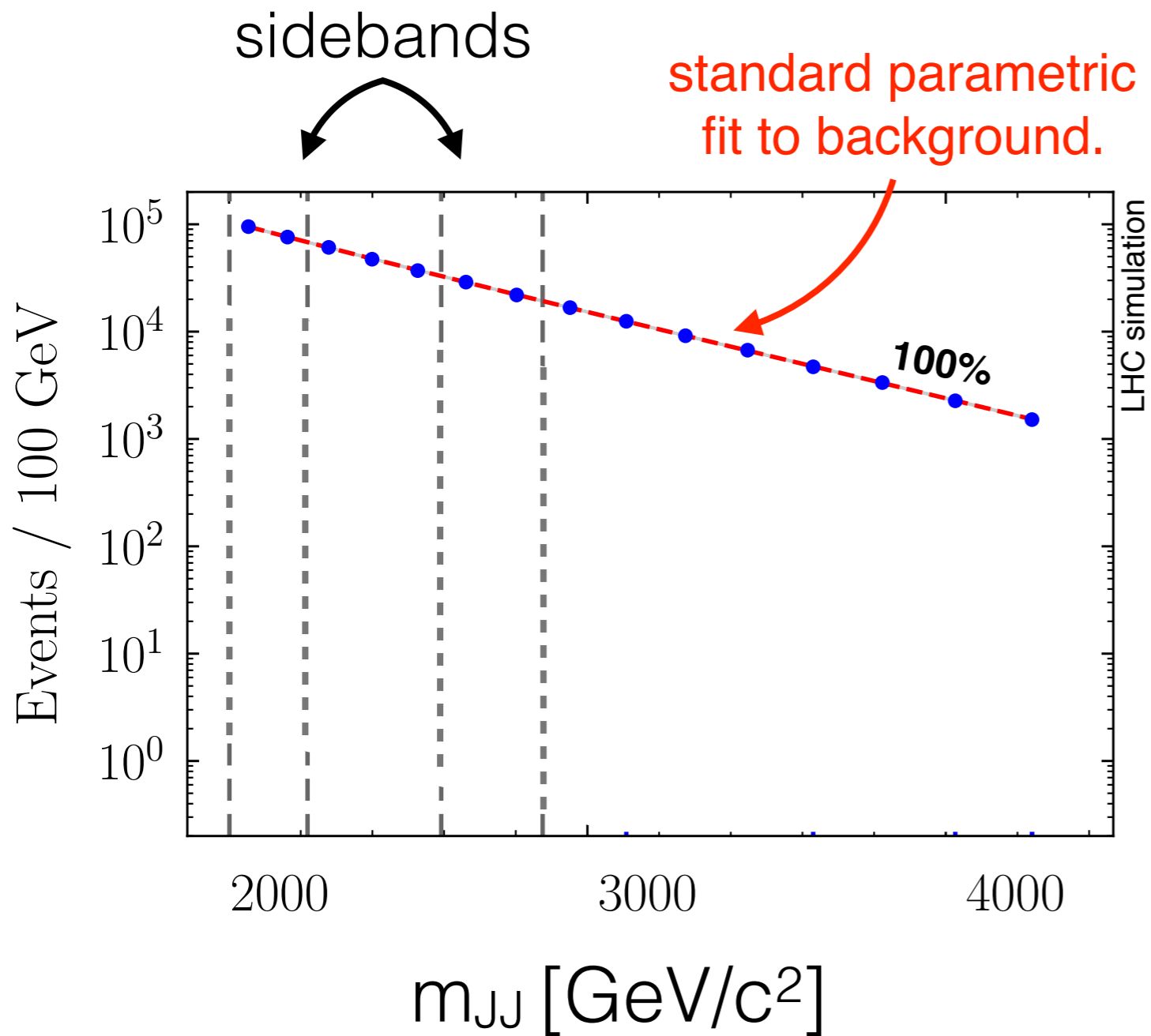


Example: two-jet search

sidebands



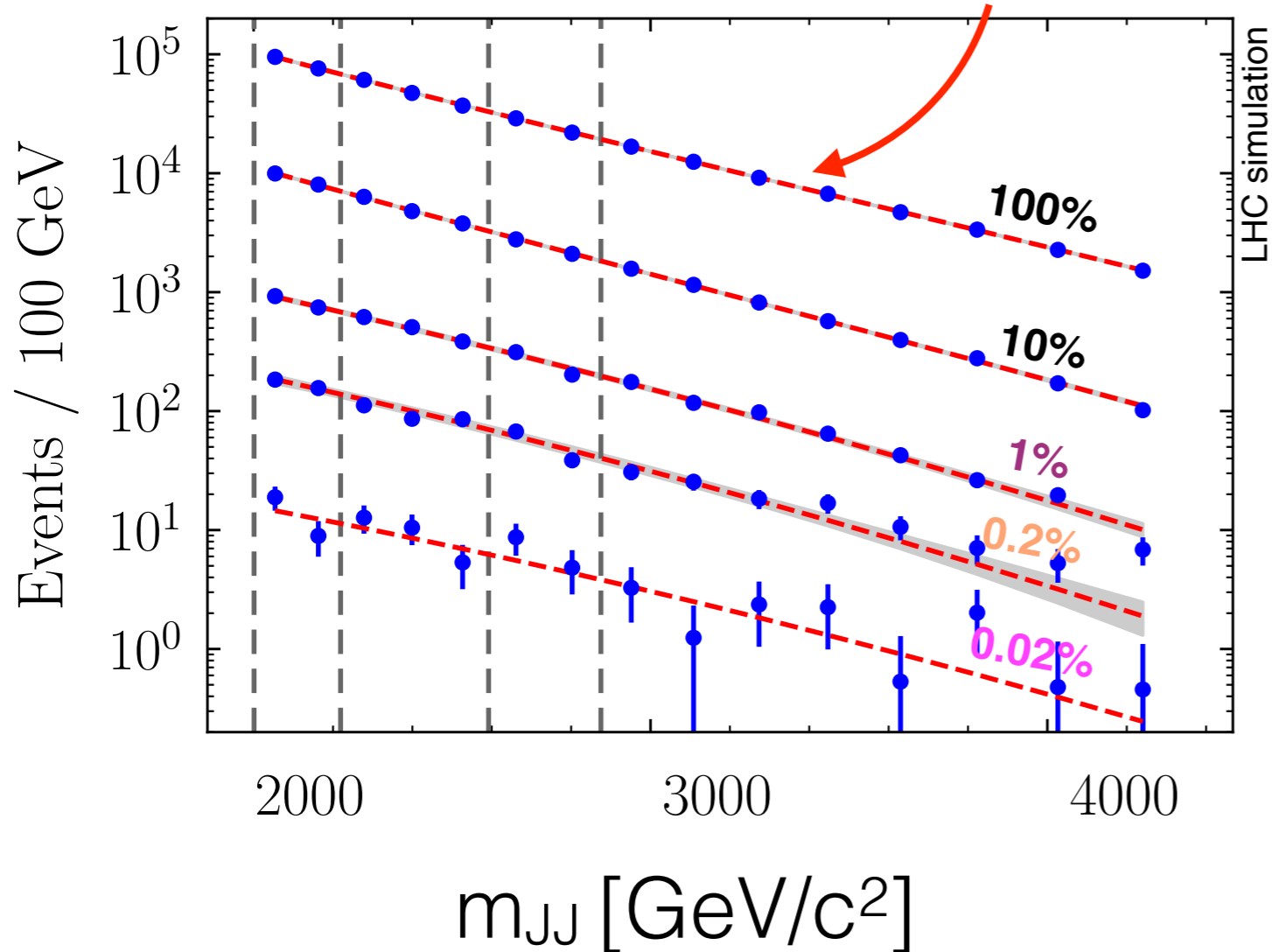
Example: two-jet search



Example: two-jet search

sidebands

standard parametric
fit to background.



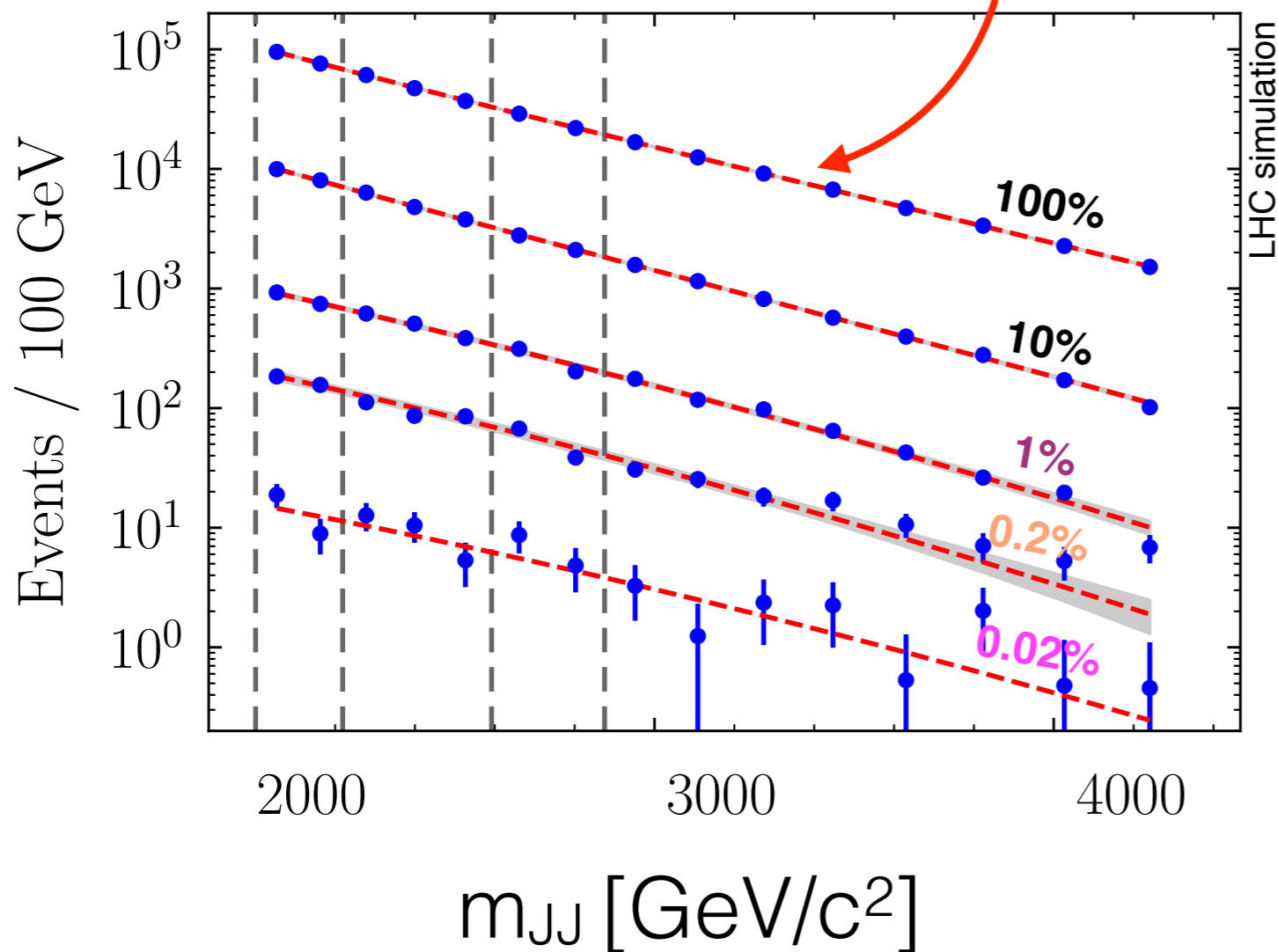
- no cut on NN
- most 10% signal-region-like
- most 1% signal-region-like
- most 0.2% signal-region-like

Example: two-jet search

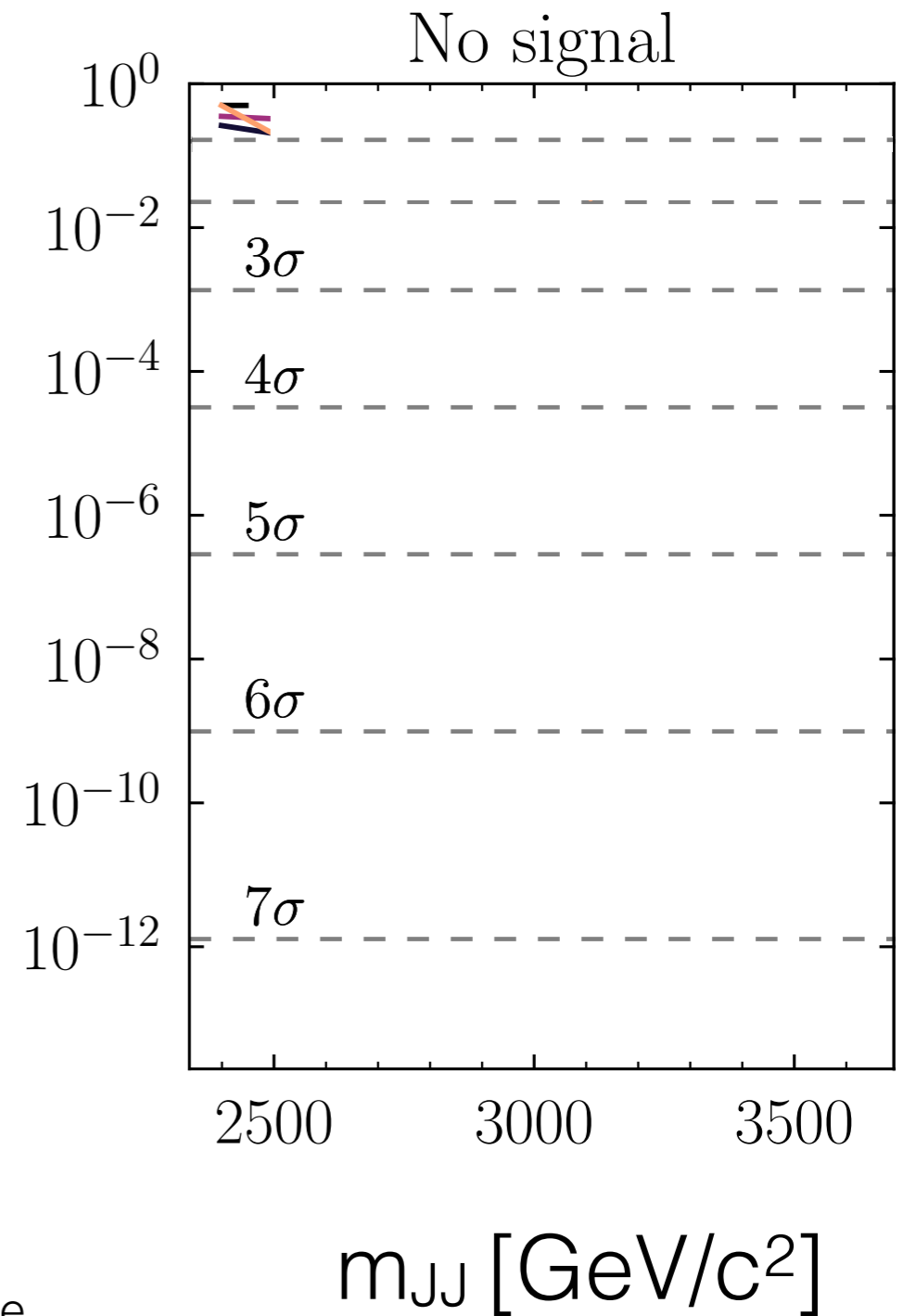


sidebands

standard parametric fit to background.

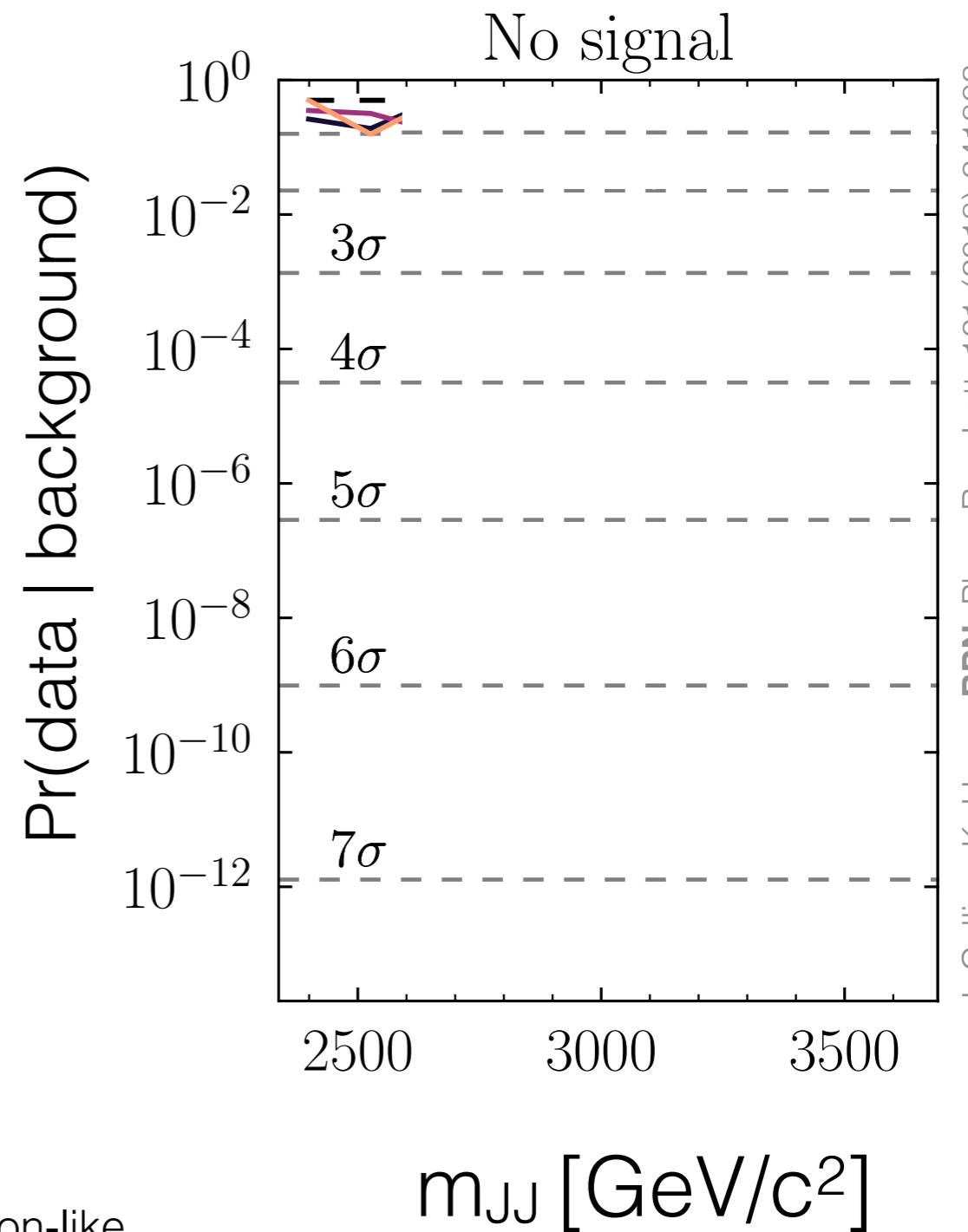
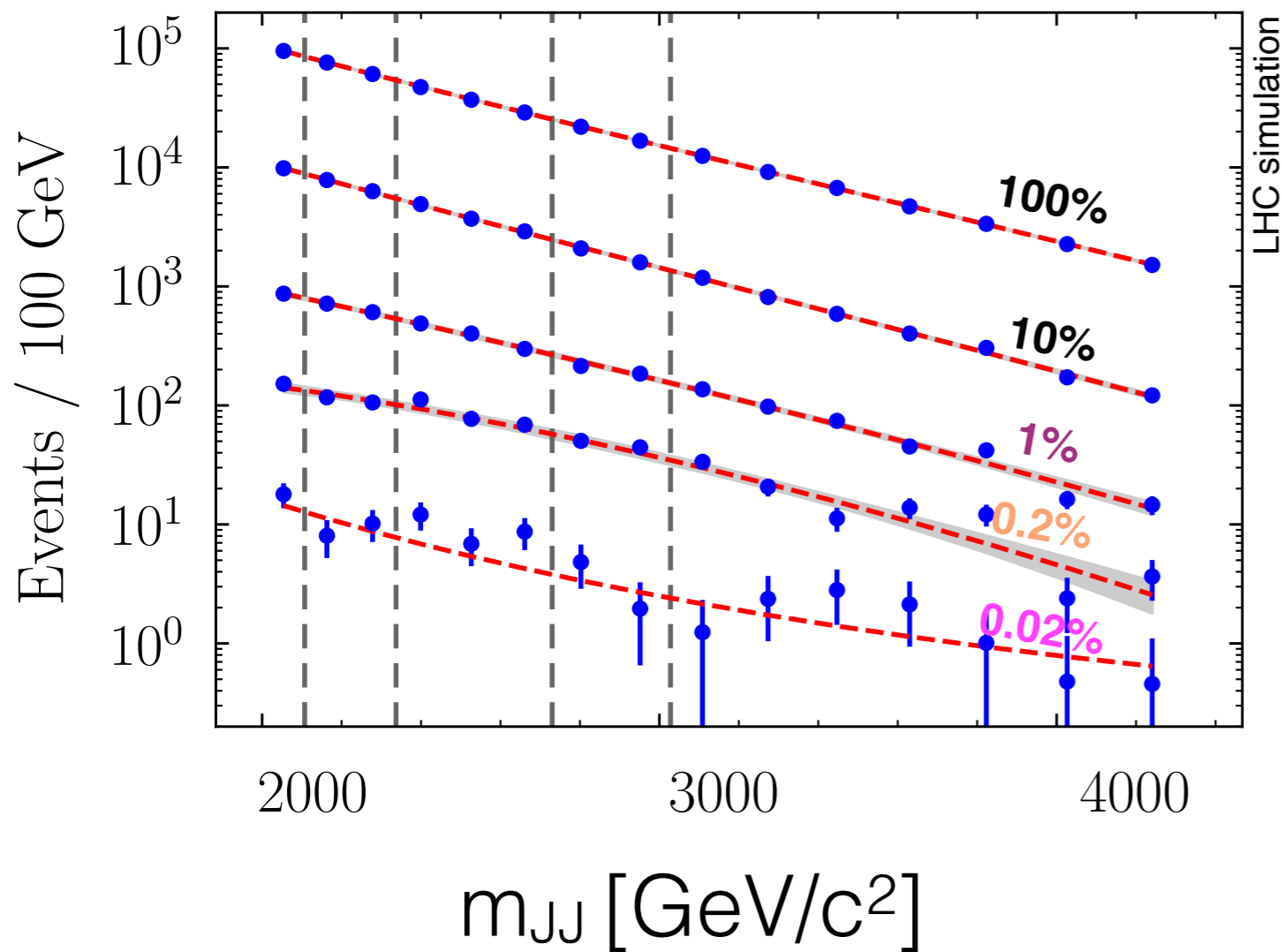


Pr(data | background)



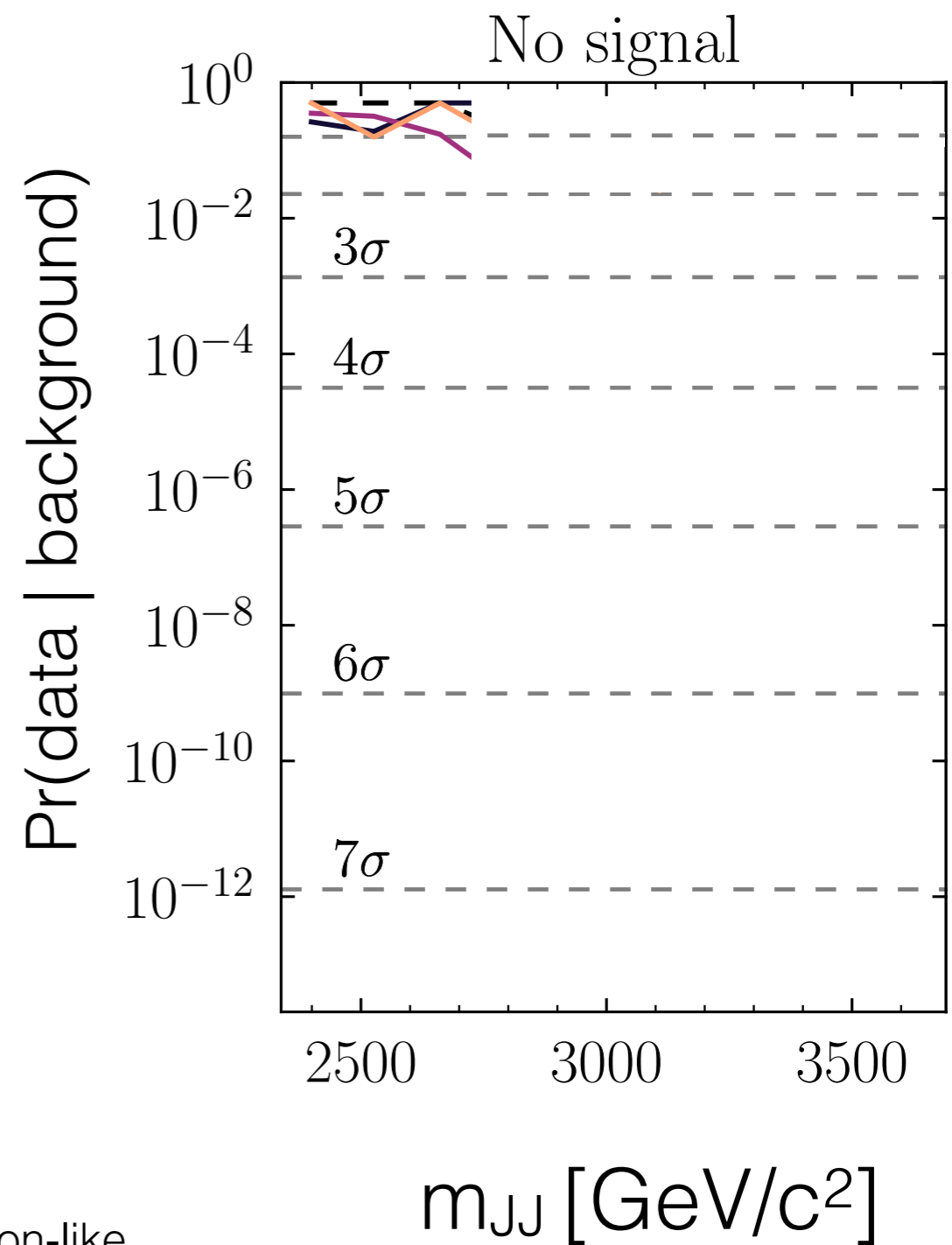
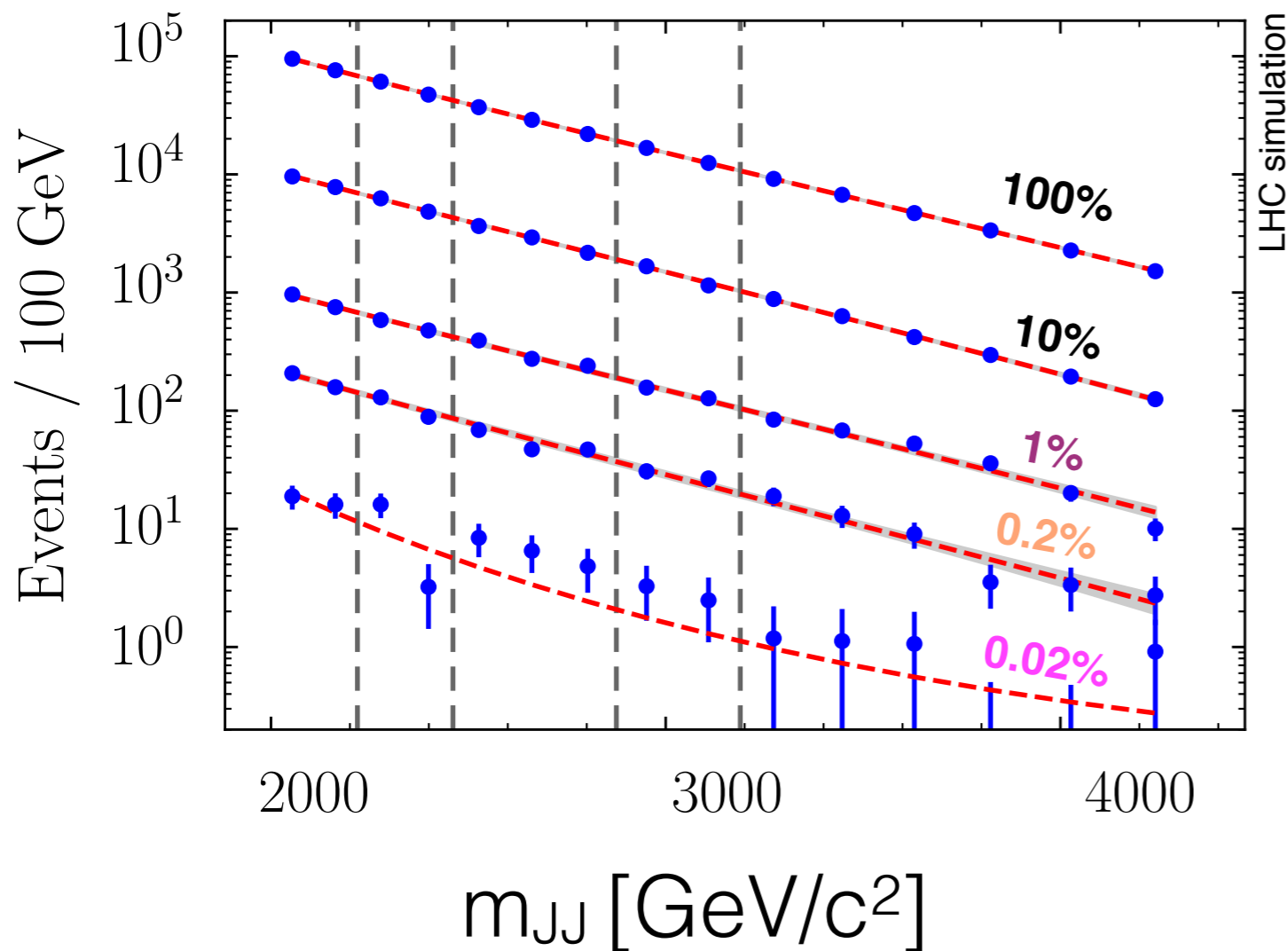
- no cut on NN
- most 10% signal-region-like
- most 1% signal-region-like
- most 0.2% signal-region-like

Example: two-jet search



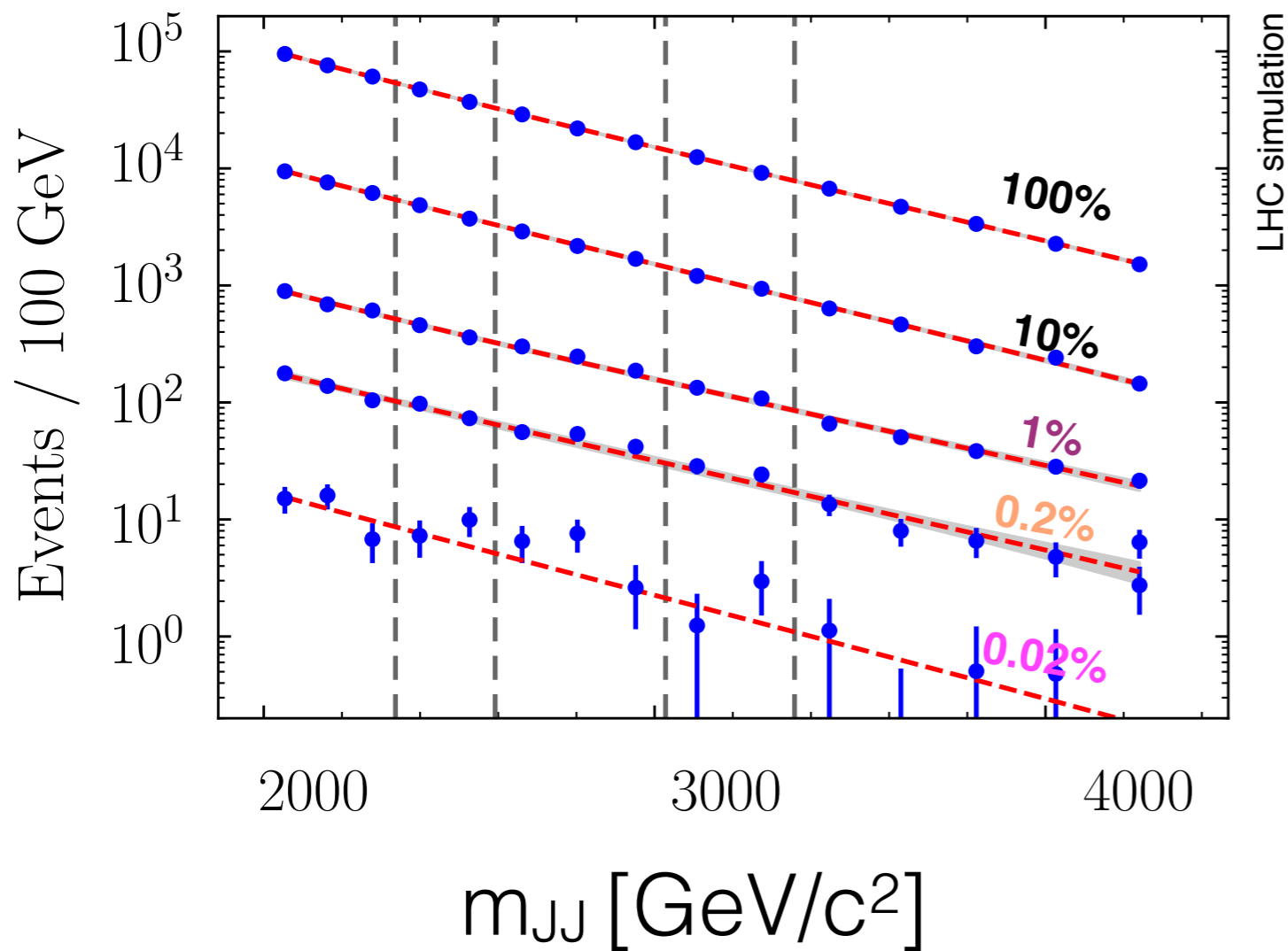
- ⋯ no cut on NN
- most 10% signal-region-like
- most 1% signal-region-like
- most 0.2% signal-region-like

Example: two-jet search



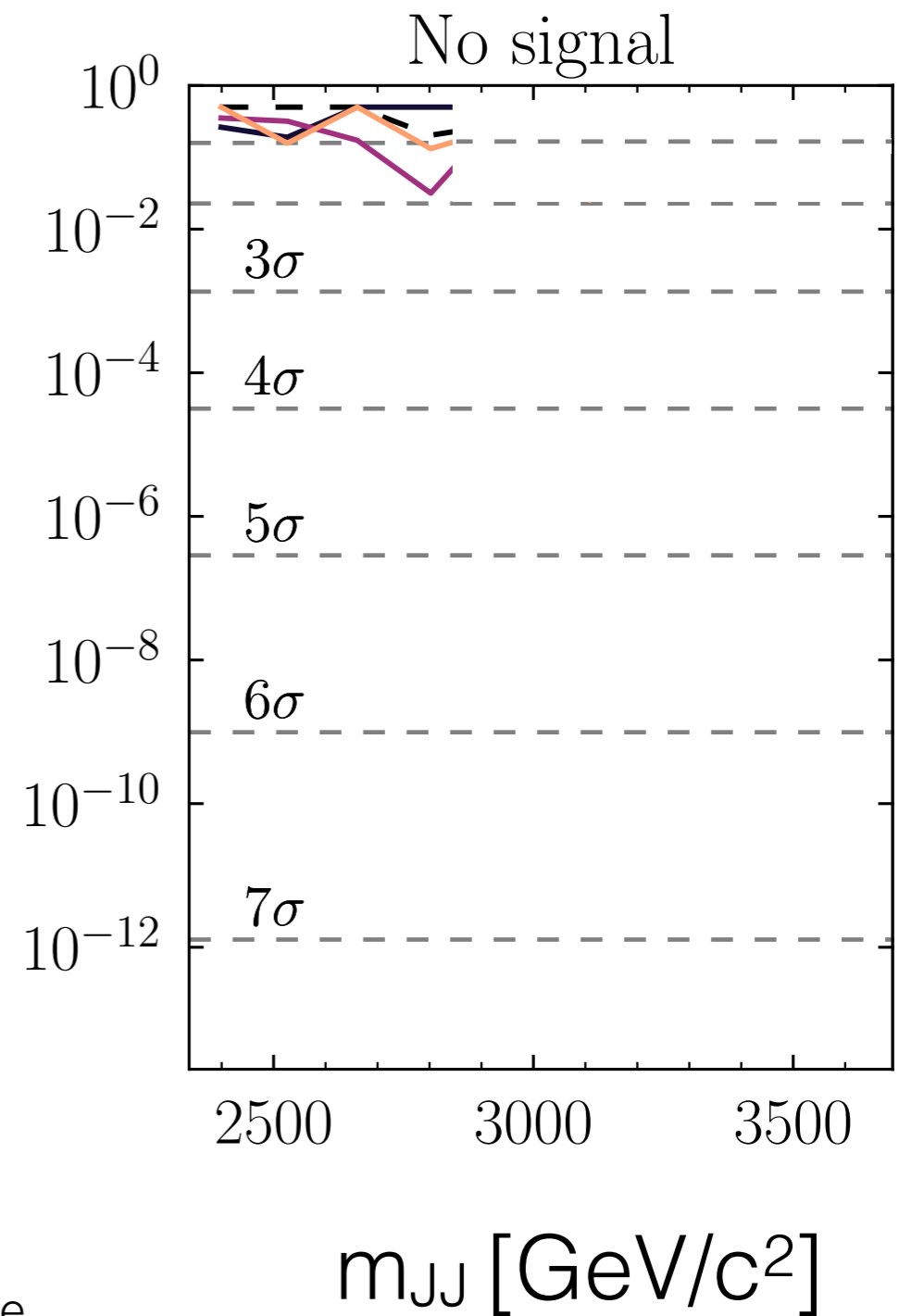
- ⋯ no cut on NN
- most 10% signal-region-like
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- most 0.2% signal-region-like

Example: two-jet search



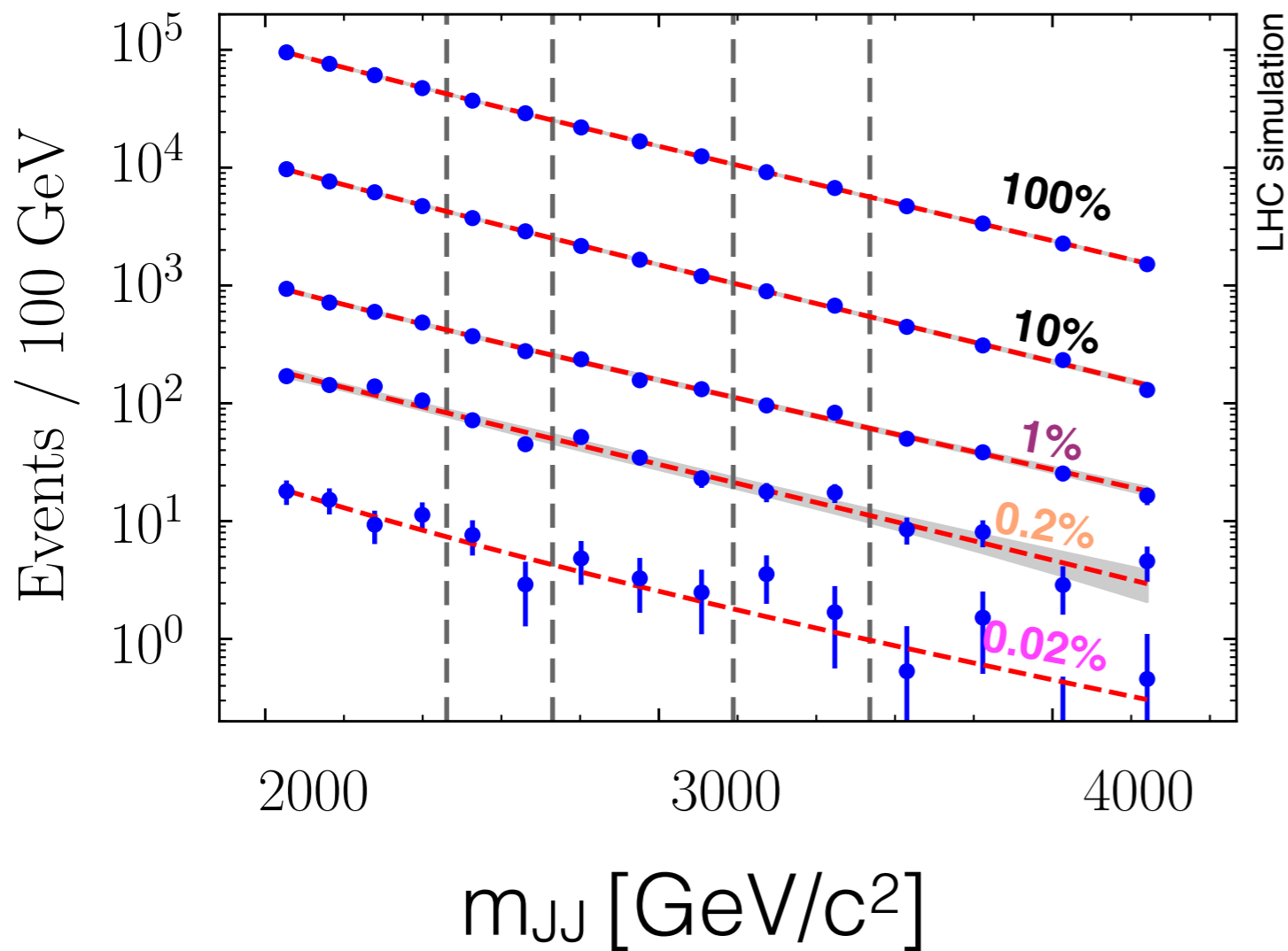
LHC simulation

Pr(data | background)

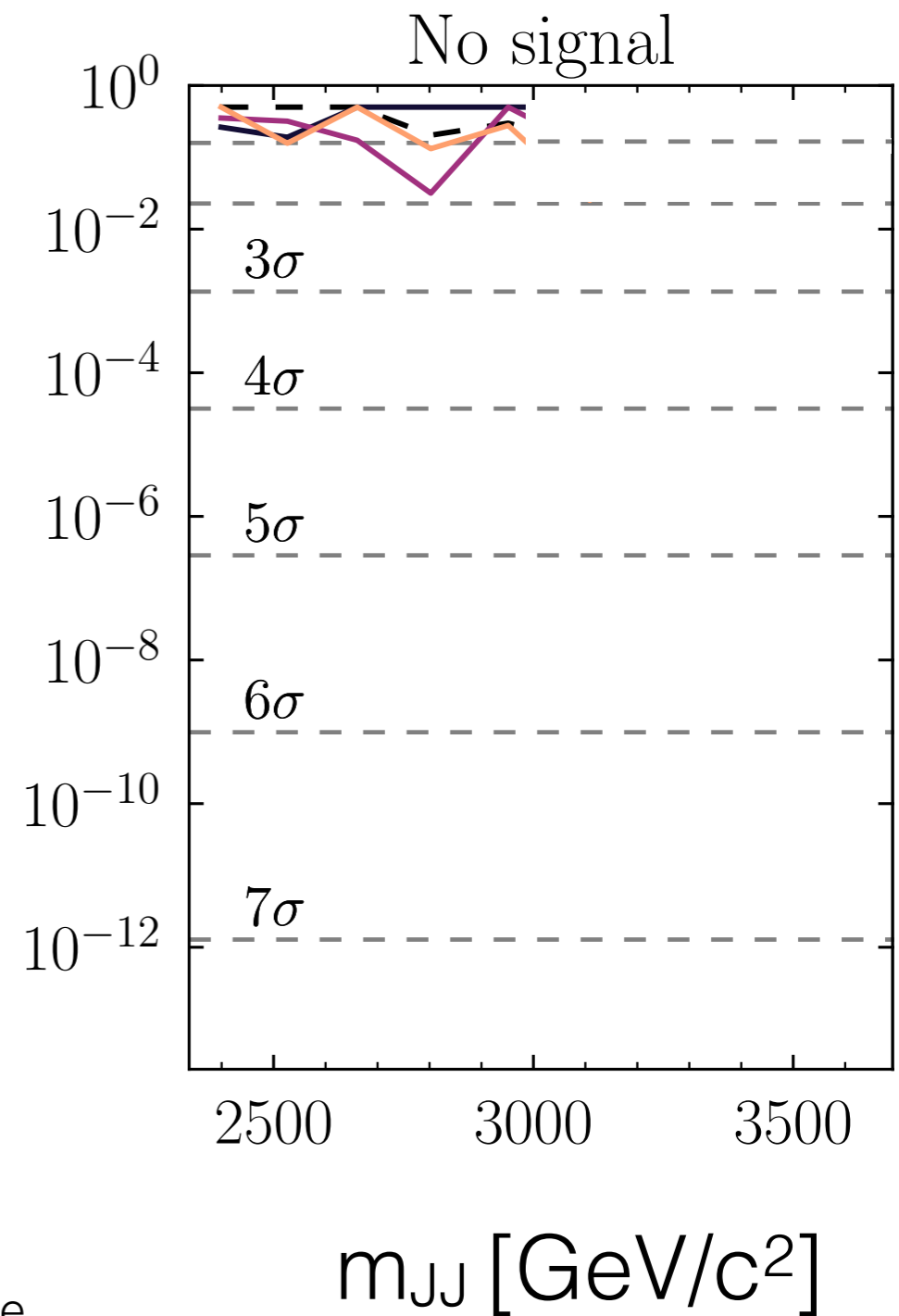


- ⋯ no cut on NN
- most 10% signal-region-like
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- most 0.2% signal-region-like

Example: two-jet search

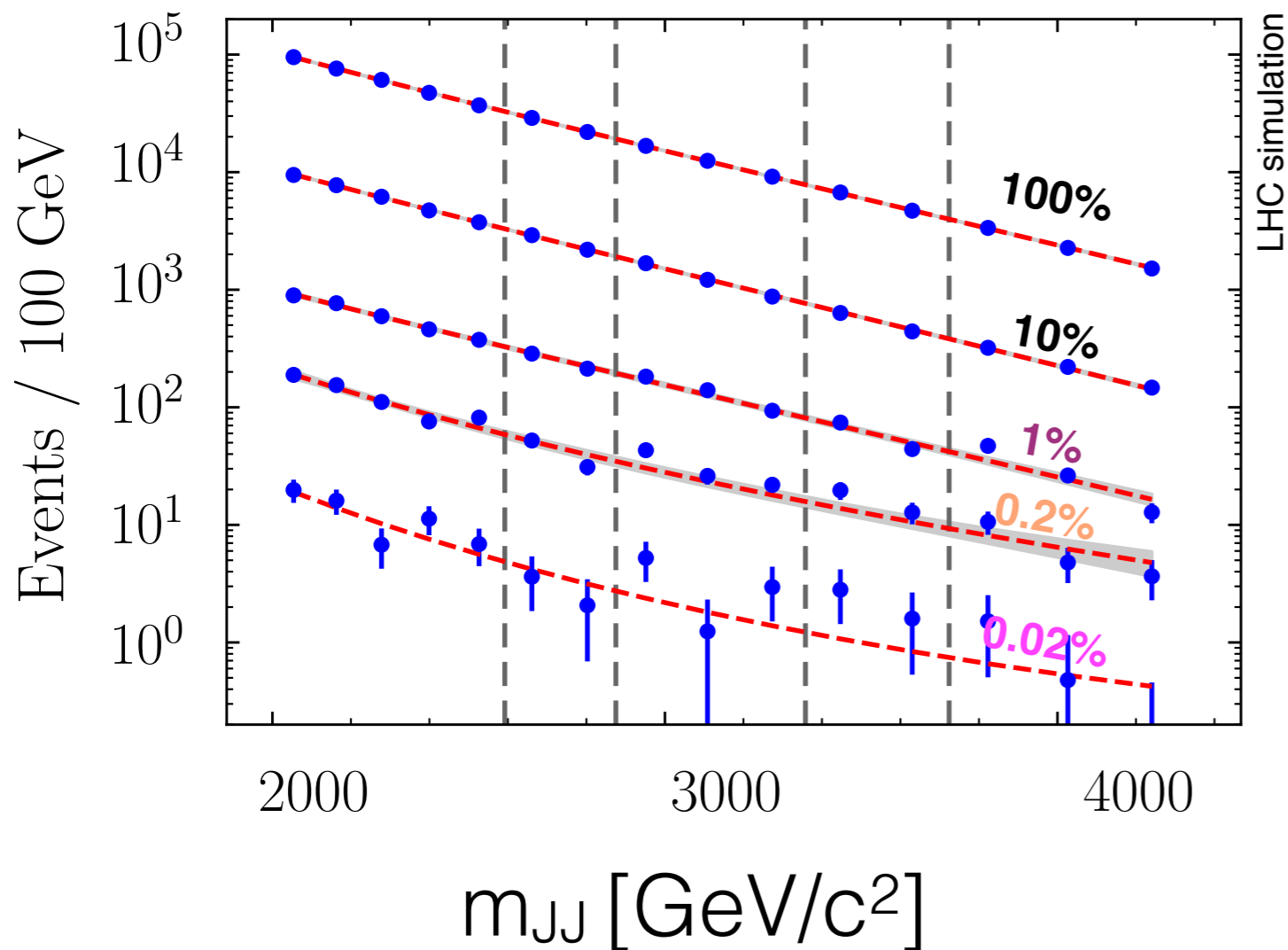


Pr(data | background)

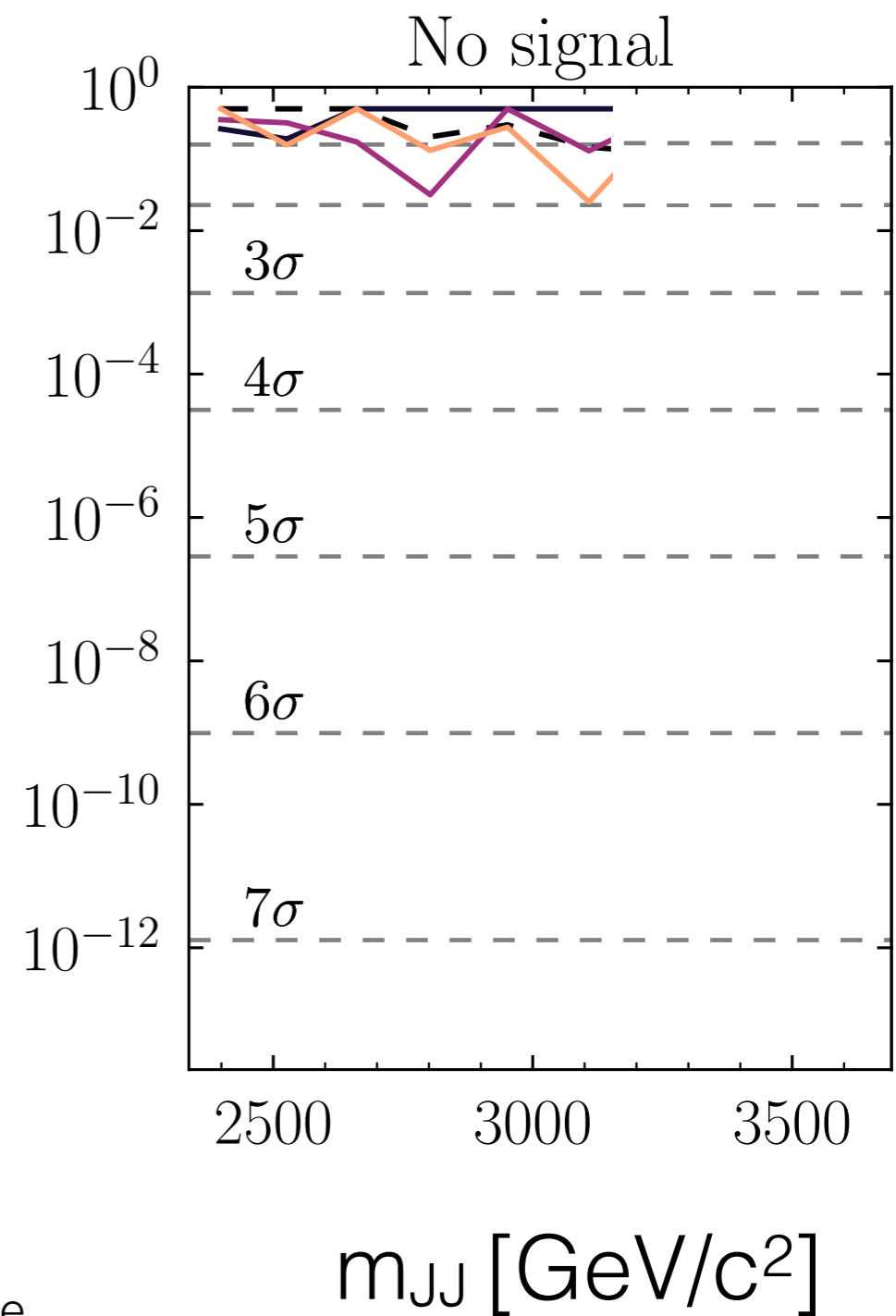


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Example: two-jet search

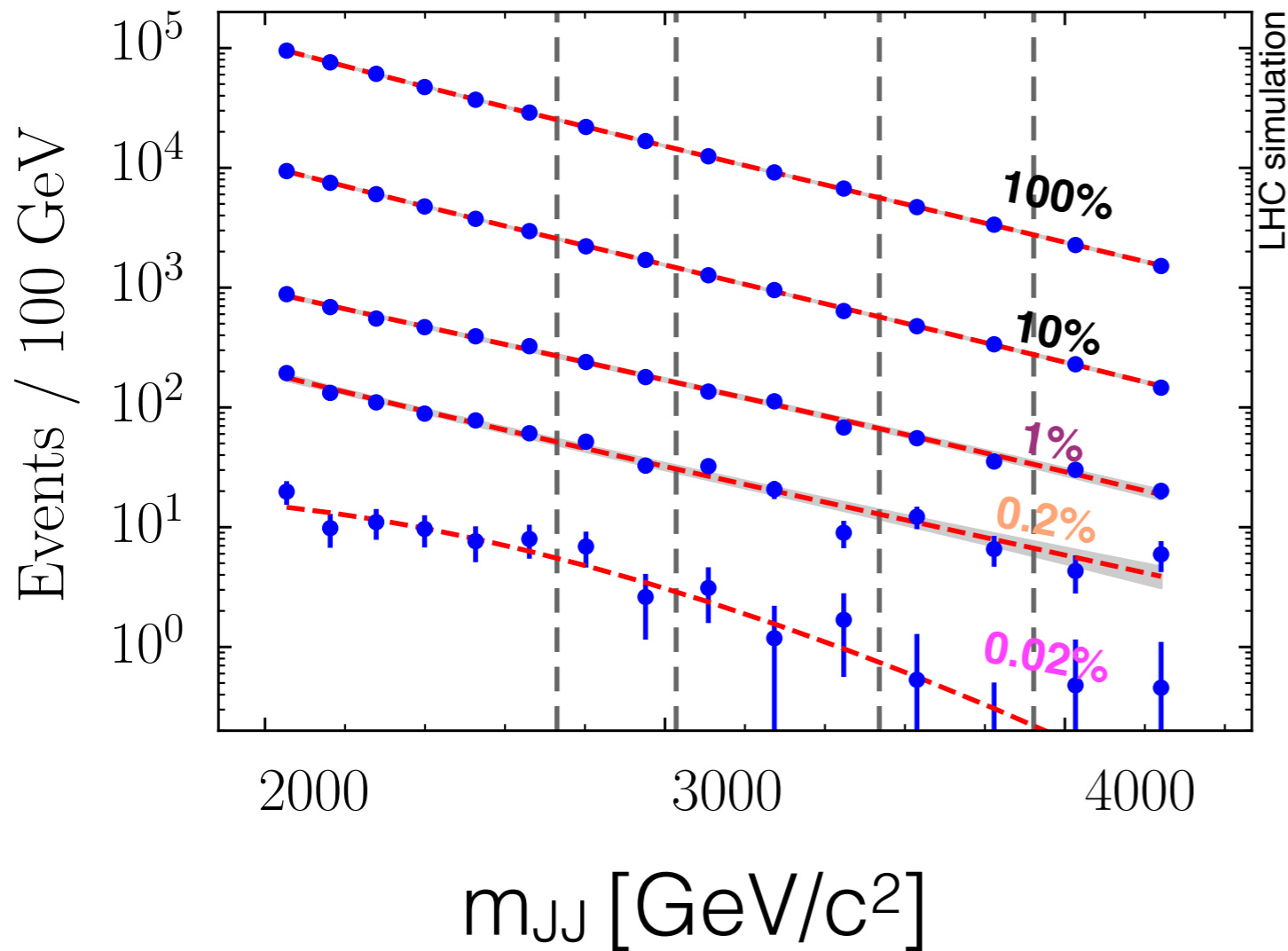


Pr(data | background)

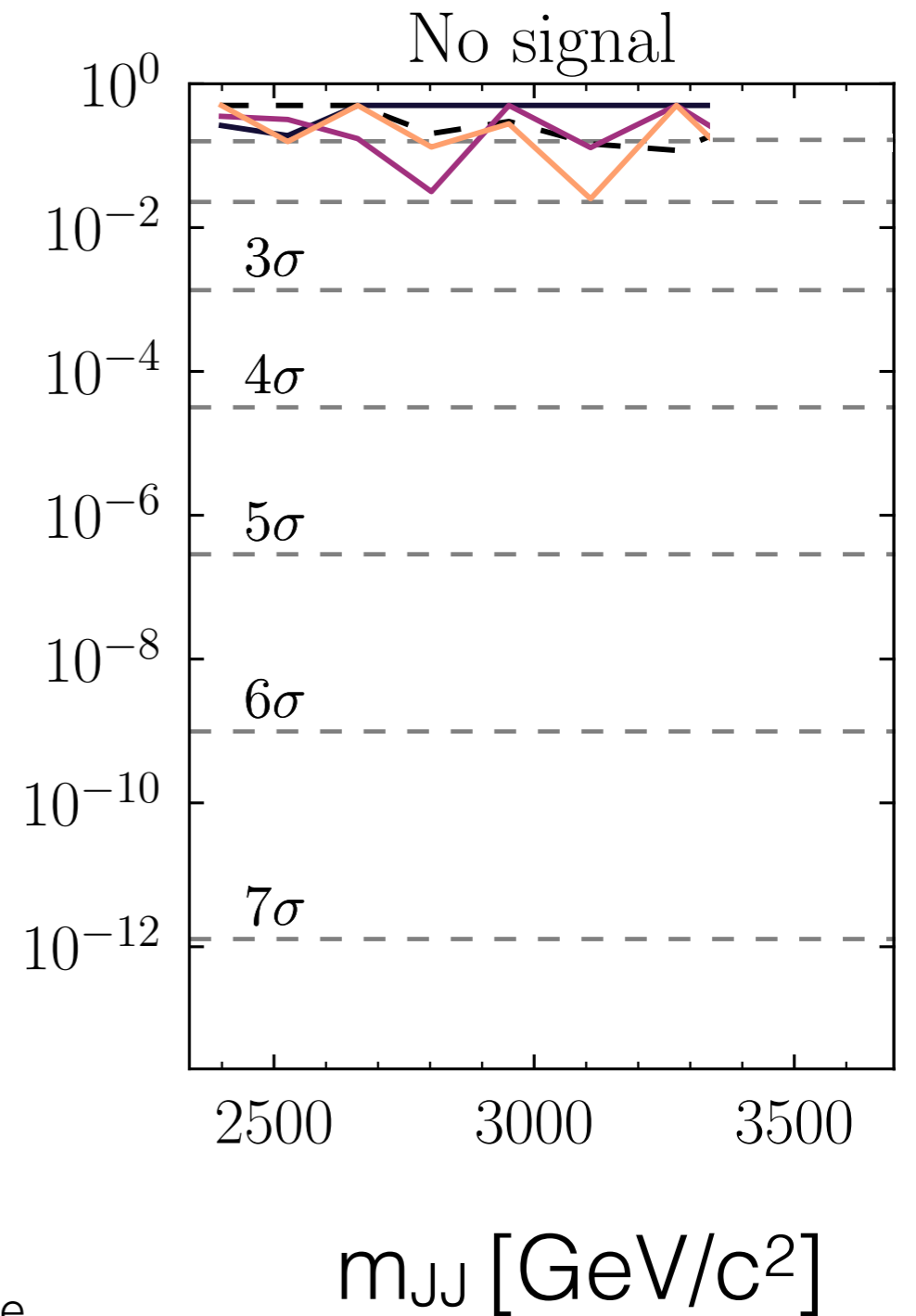


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Example: two-jet search

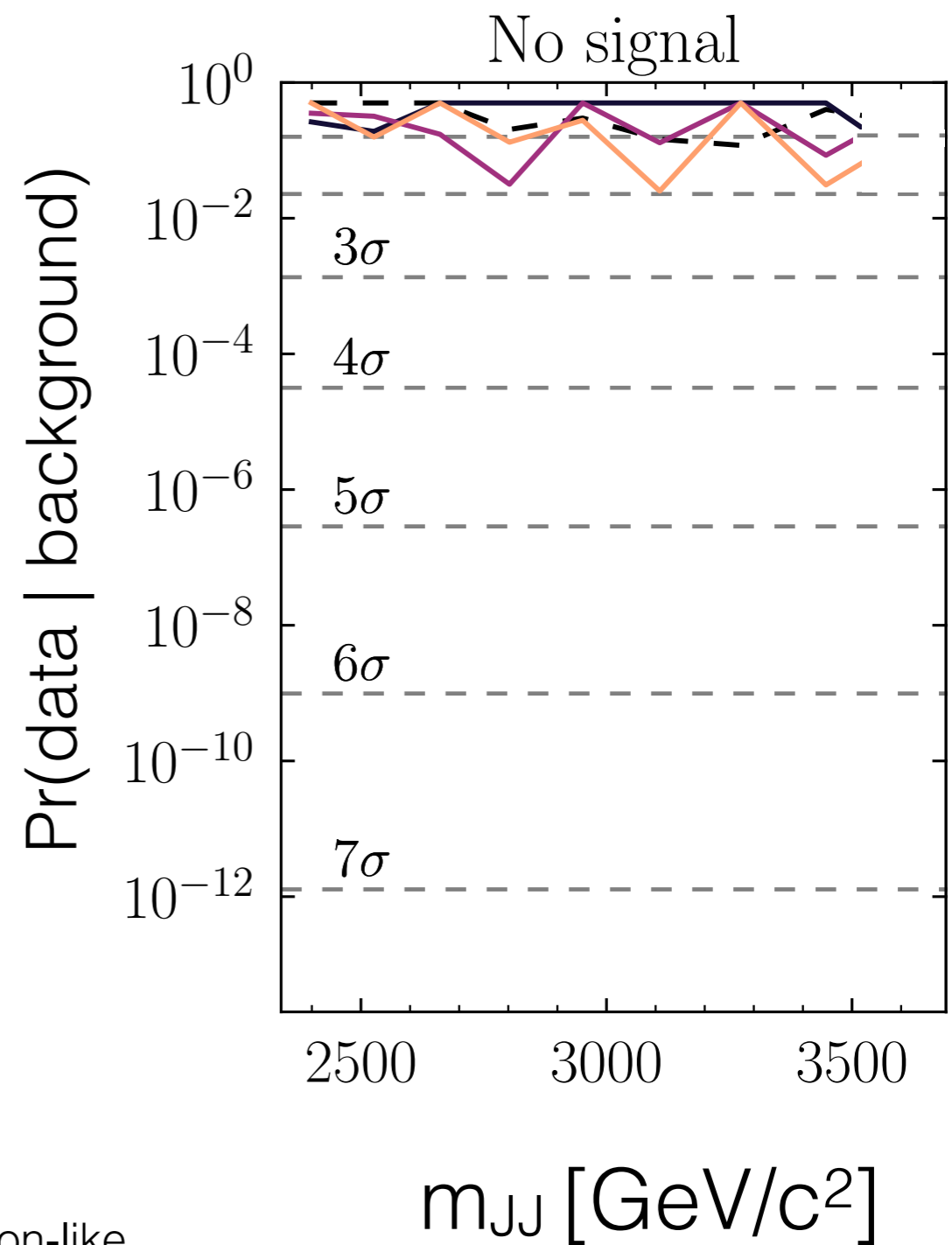
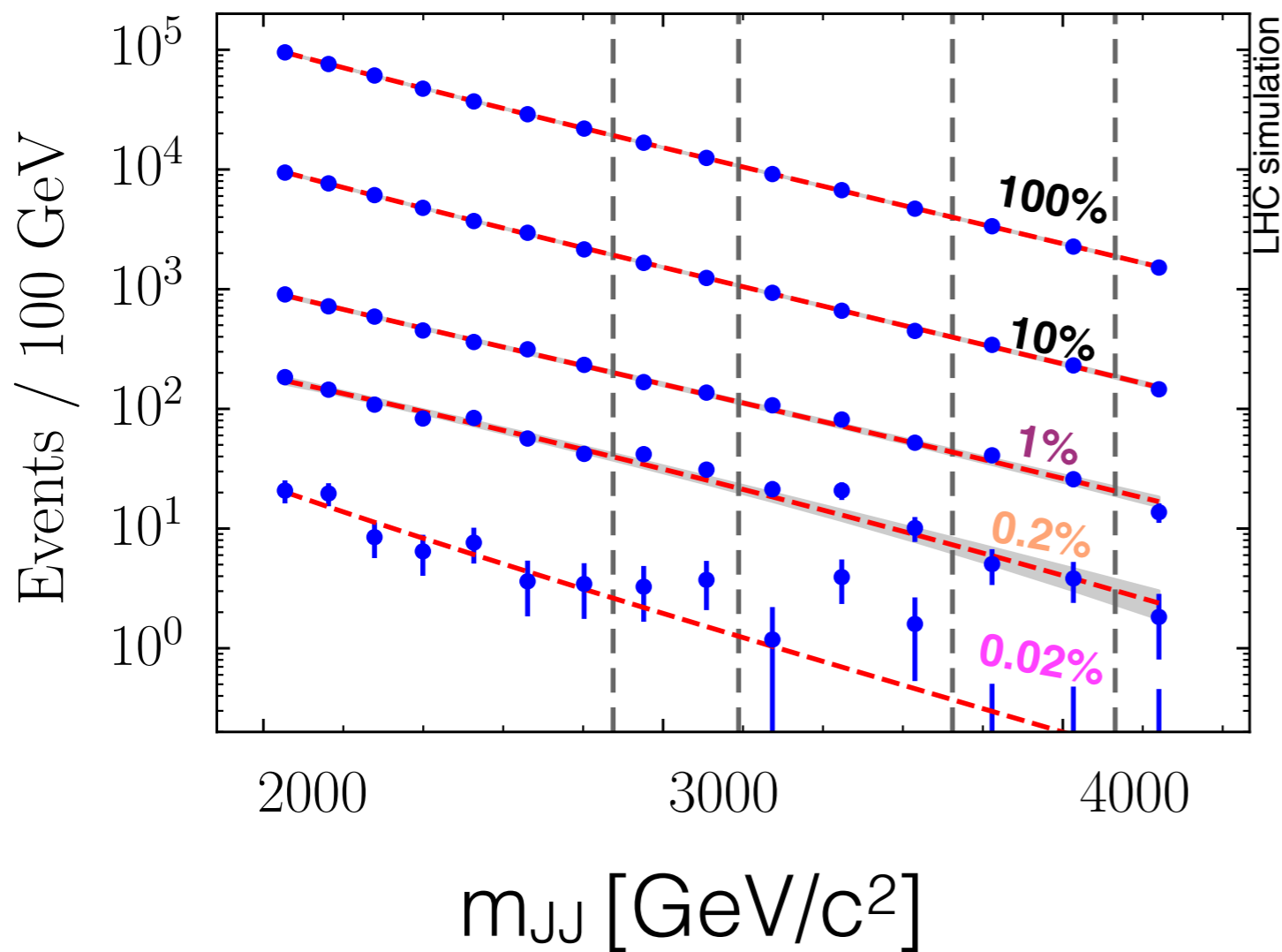


Pr(data | background)



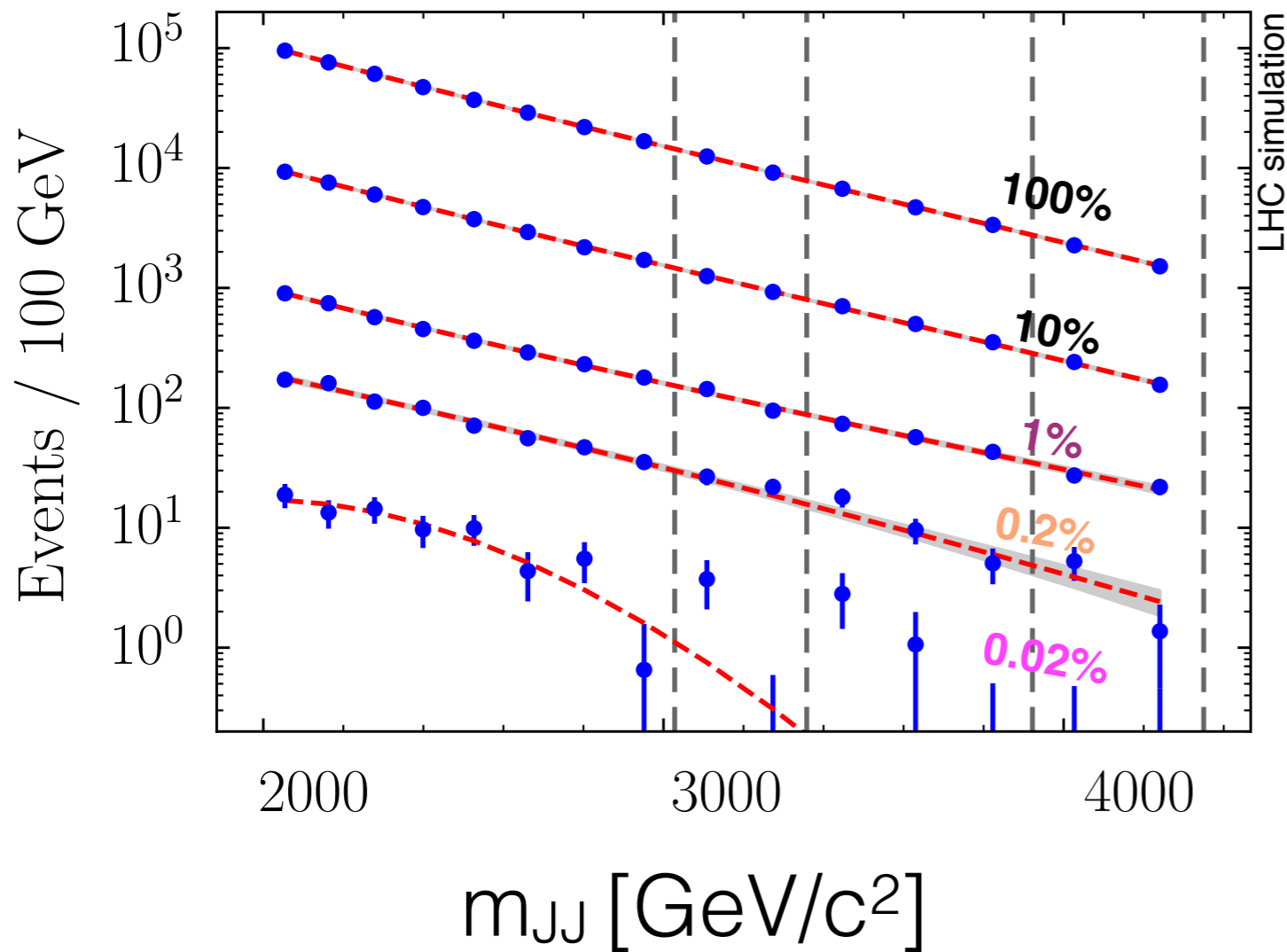
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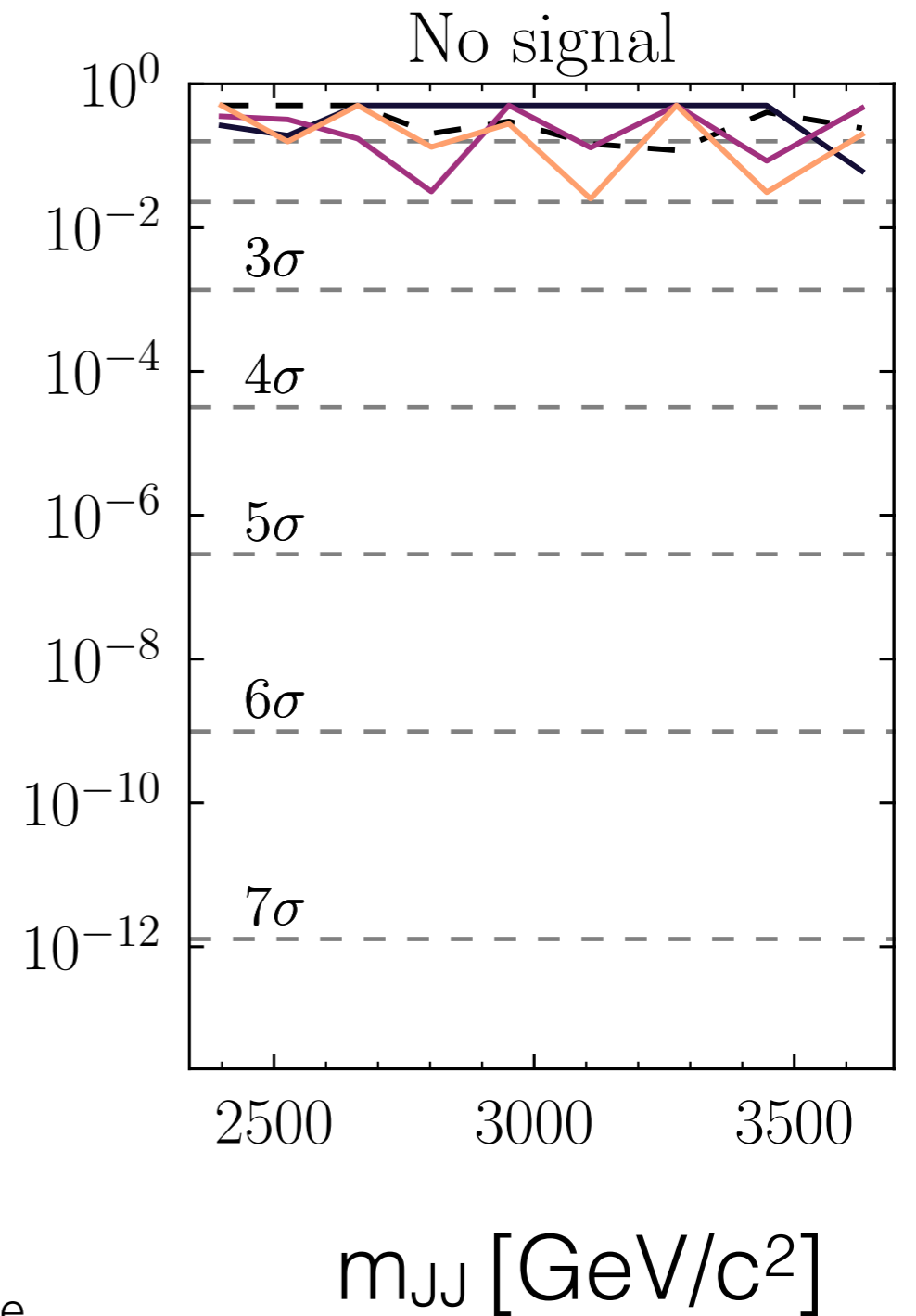


- no cut on NN
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- most 0.2% signal-region-like

Example: two-jet search



Pr(data | background)

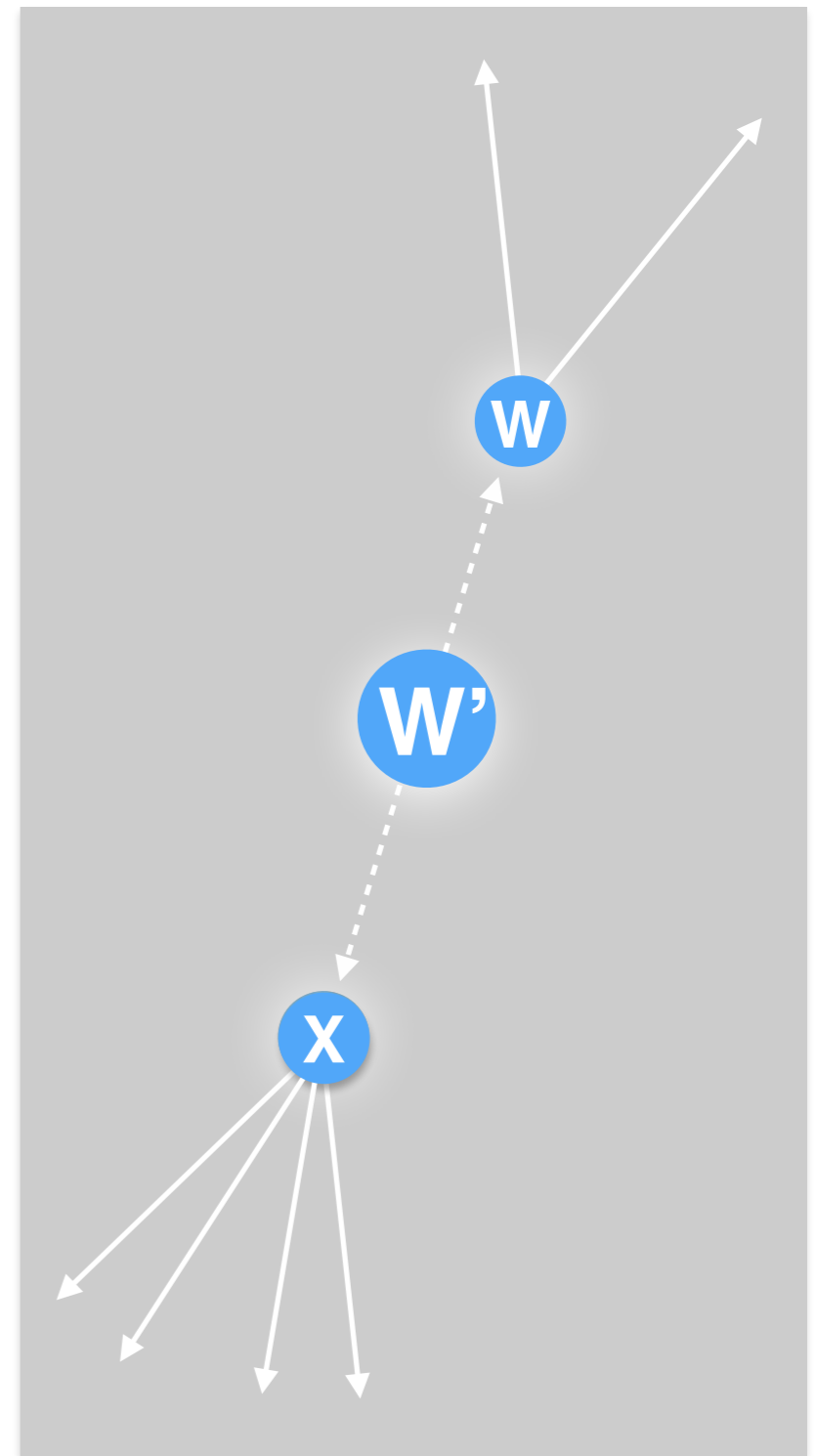
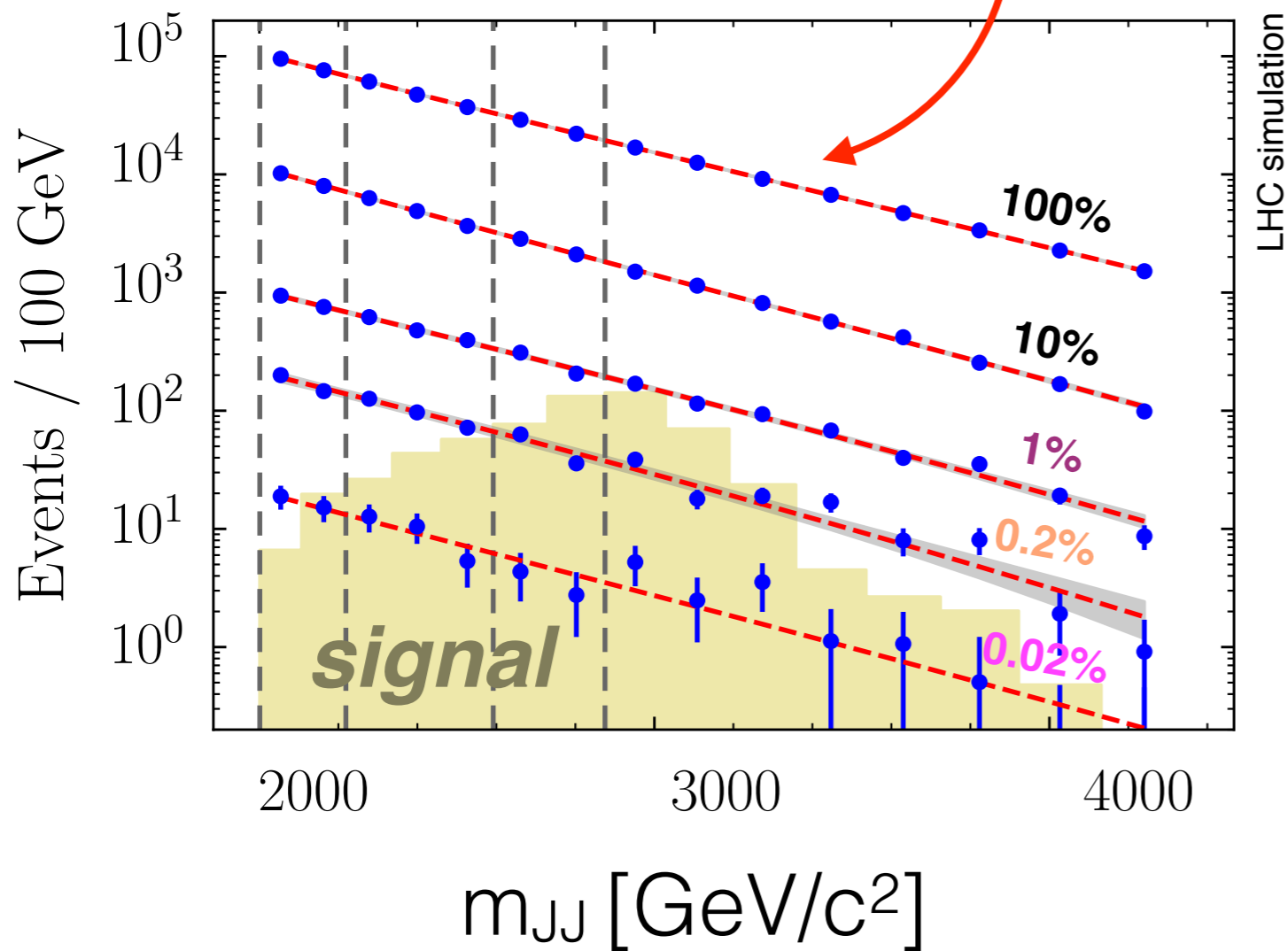


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- most 1% signal-region-like
- most 0.2% signal-region-like

...and when there is a signal?

sidebands

standard parametric
fit to background.

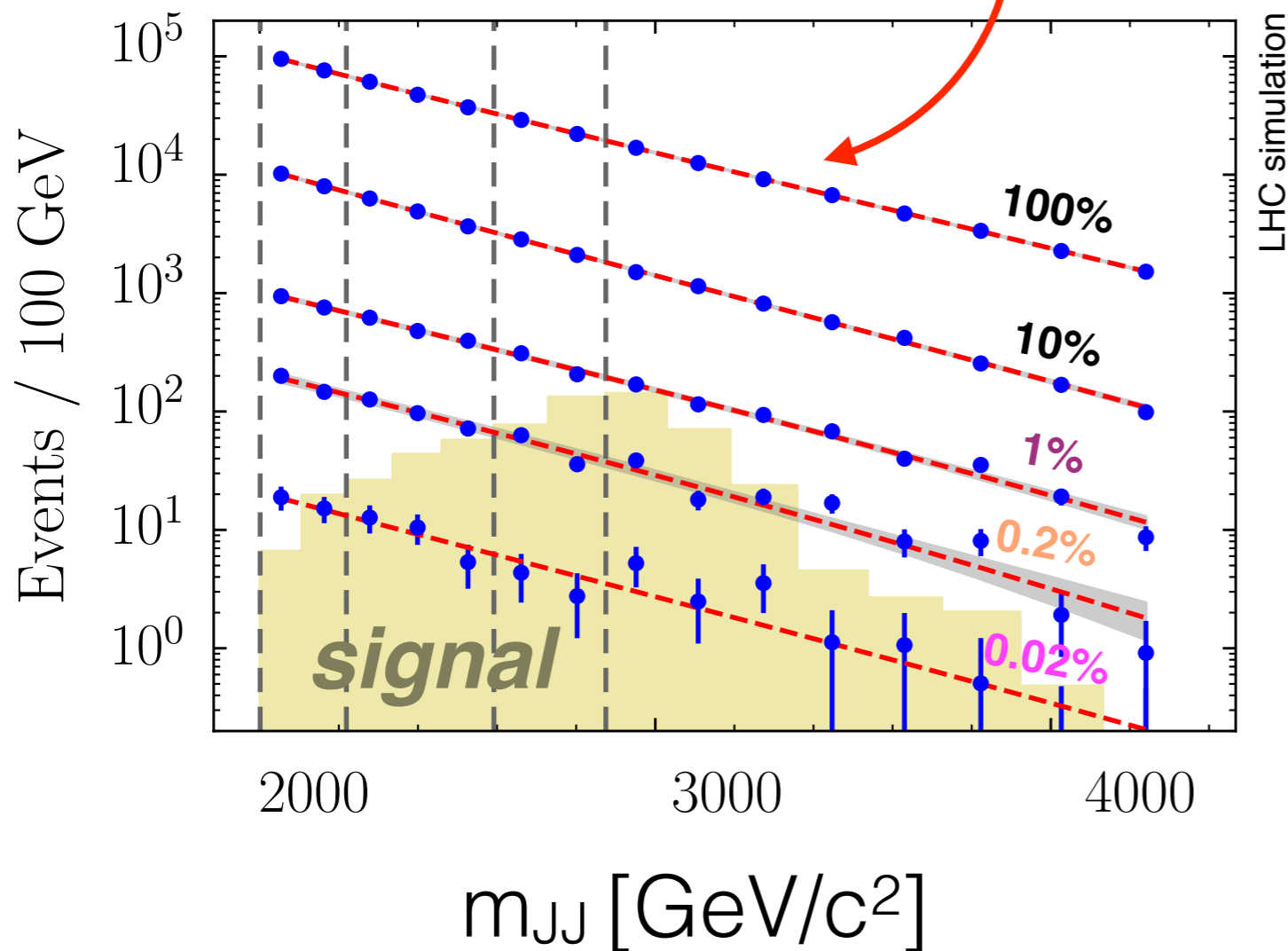


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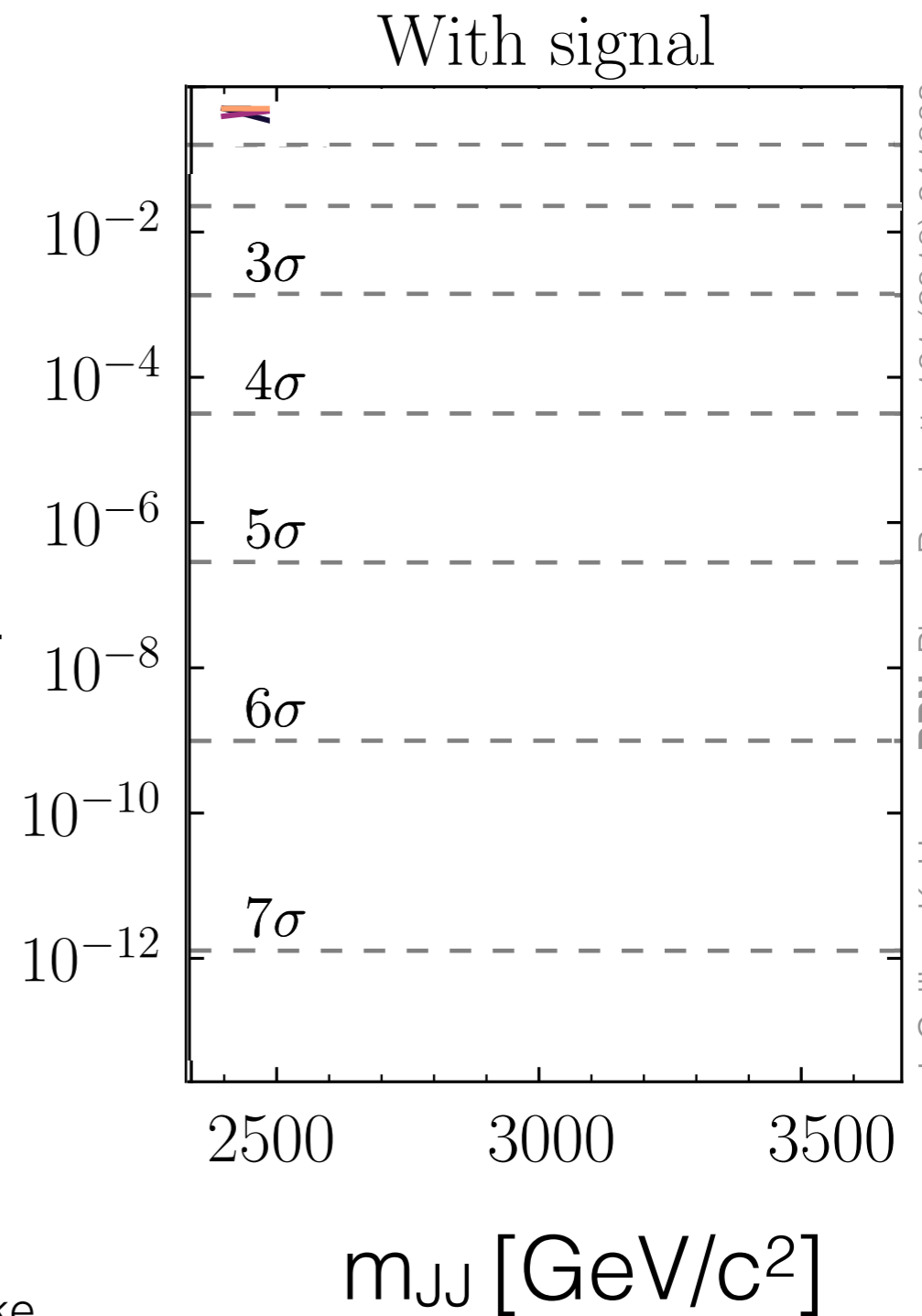
...and when there is a signal?

sidebands

standard parametric fit to background.

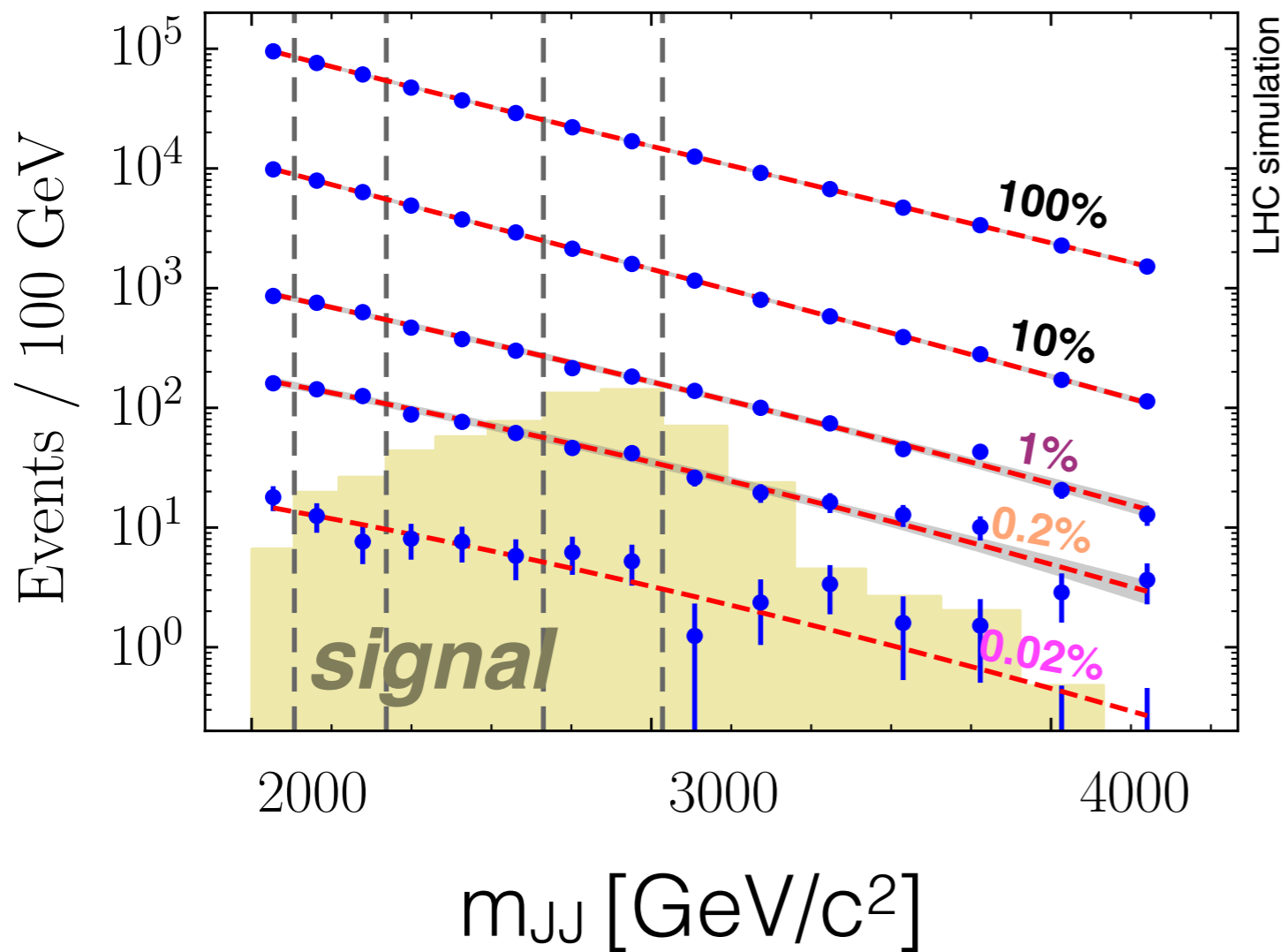


Pr(data | background)

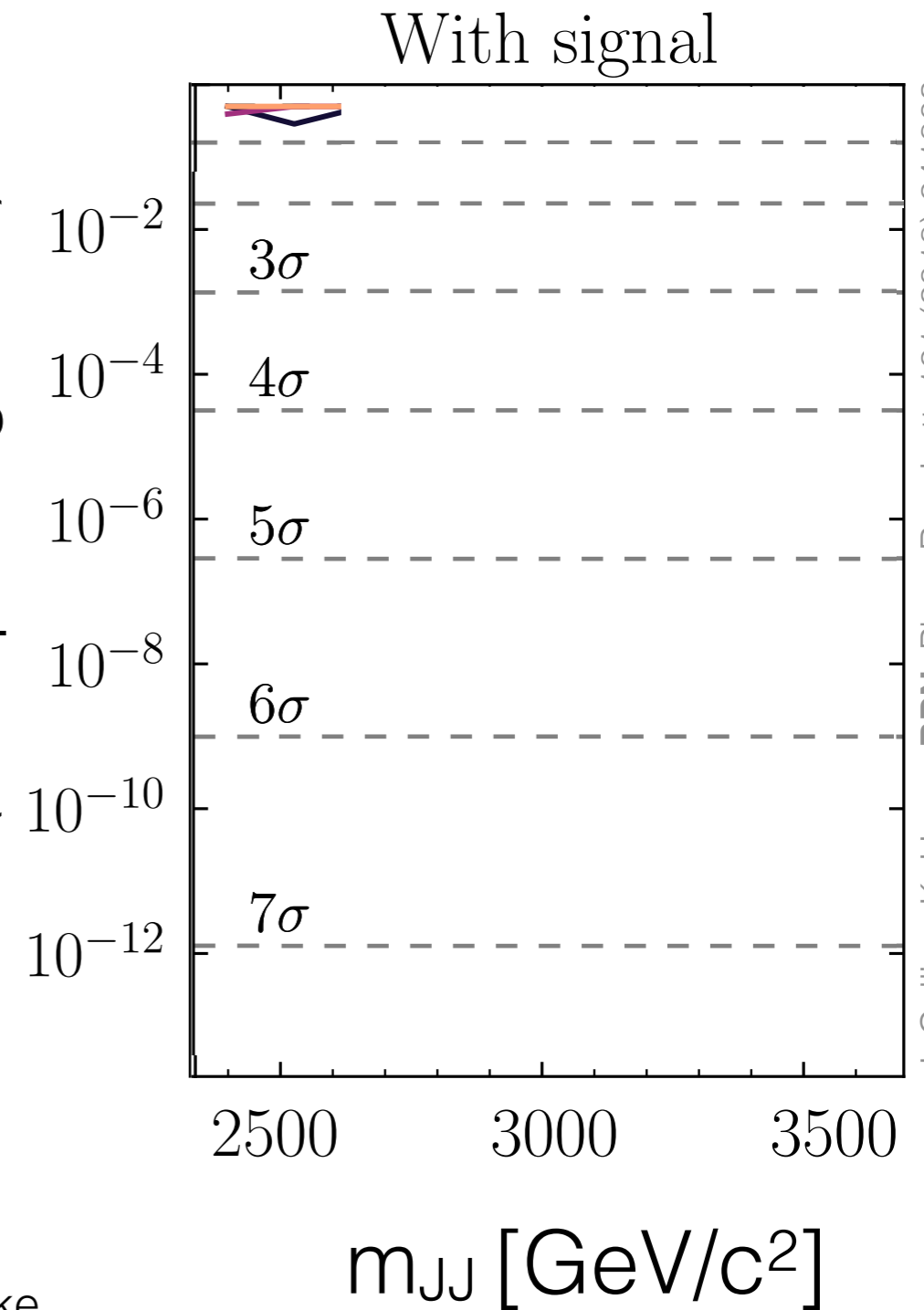


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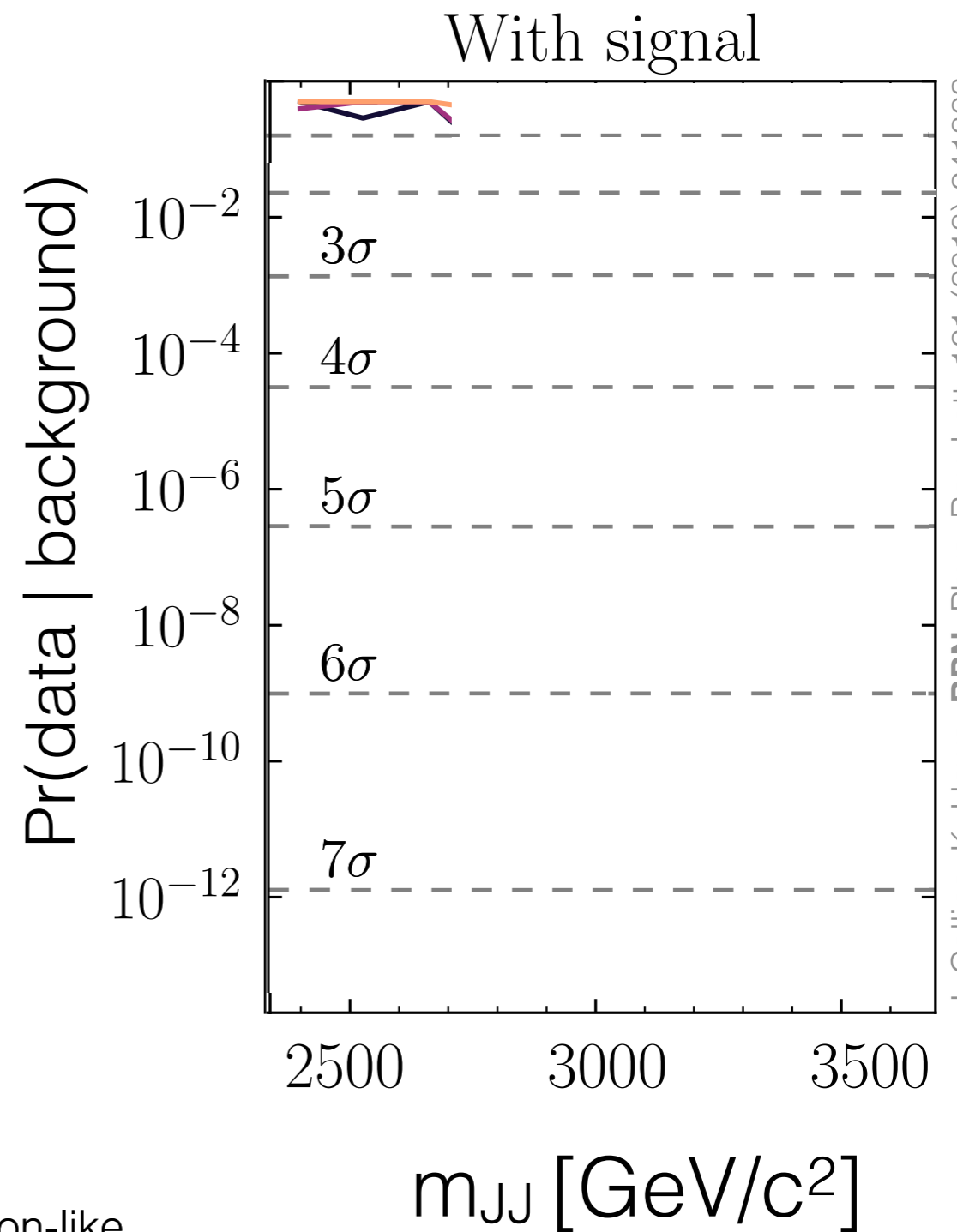
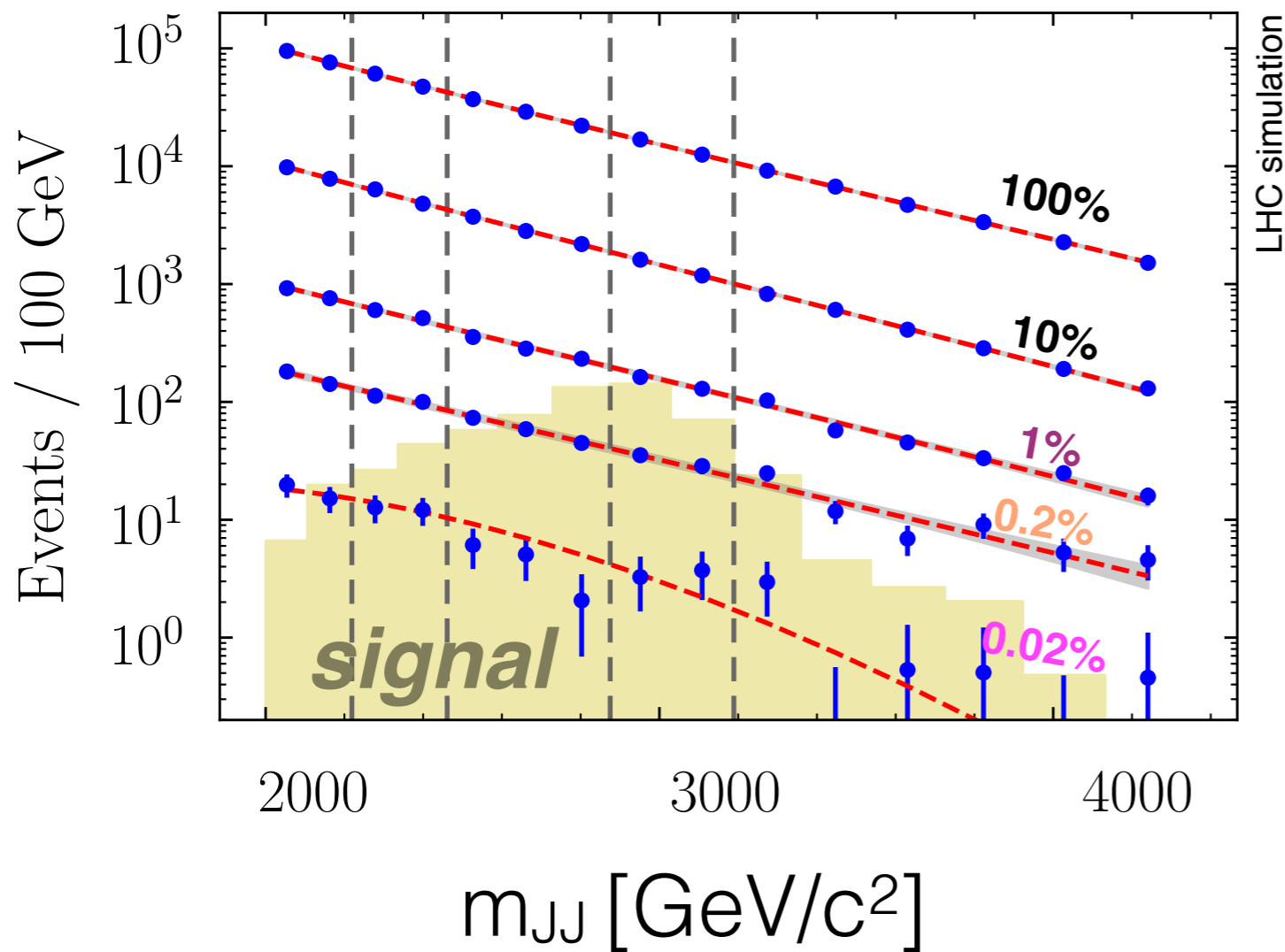


Pr(data | background)



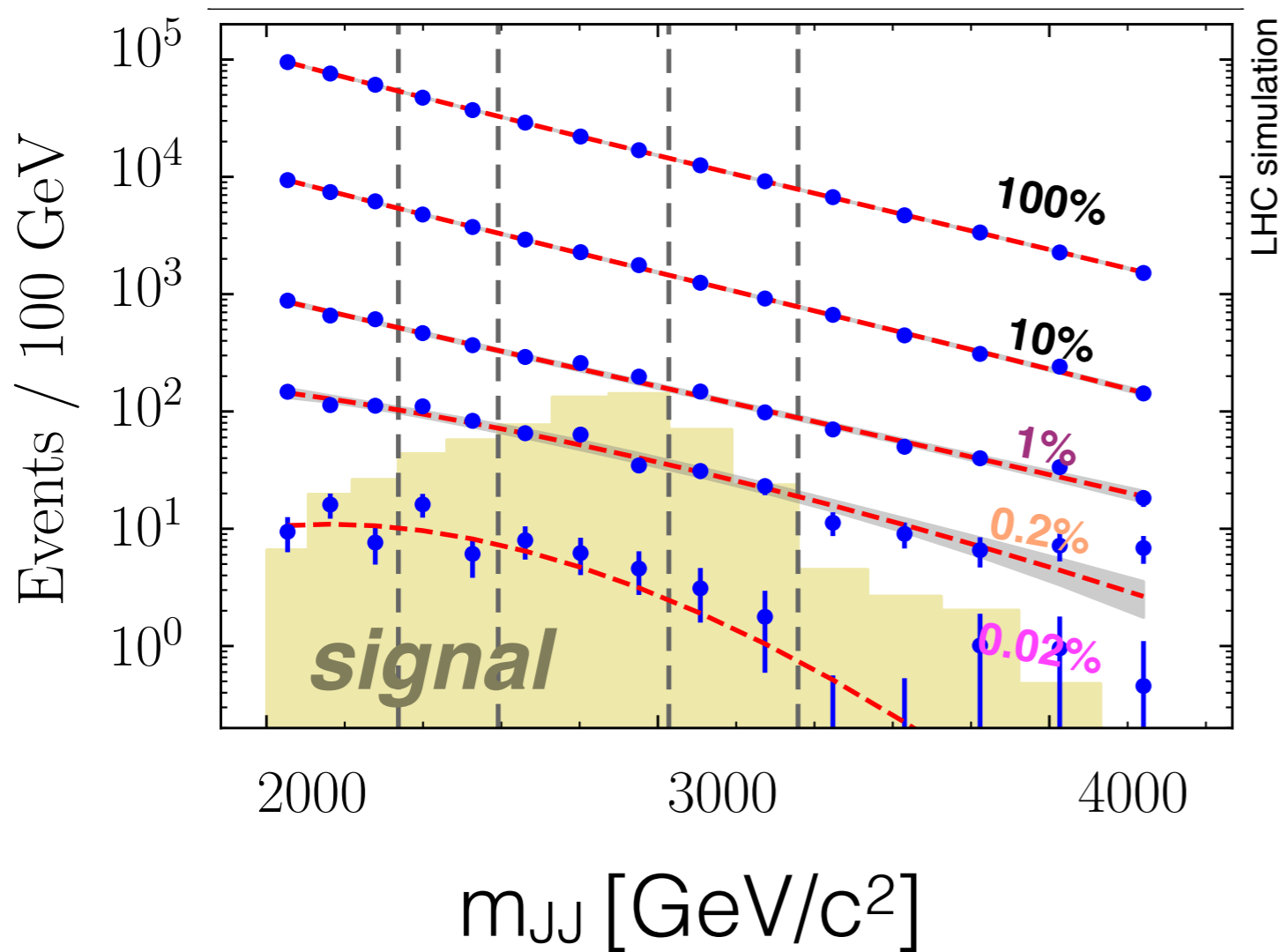
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- most 10% signal-region-like
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...and when there is a signal?

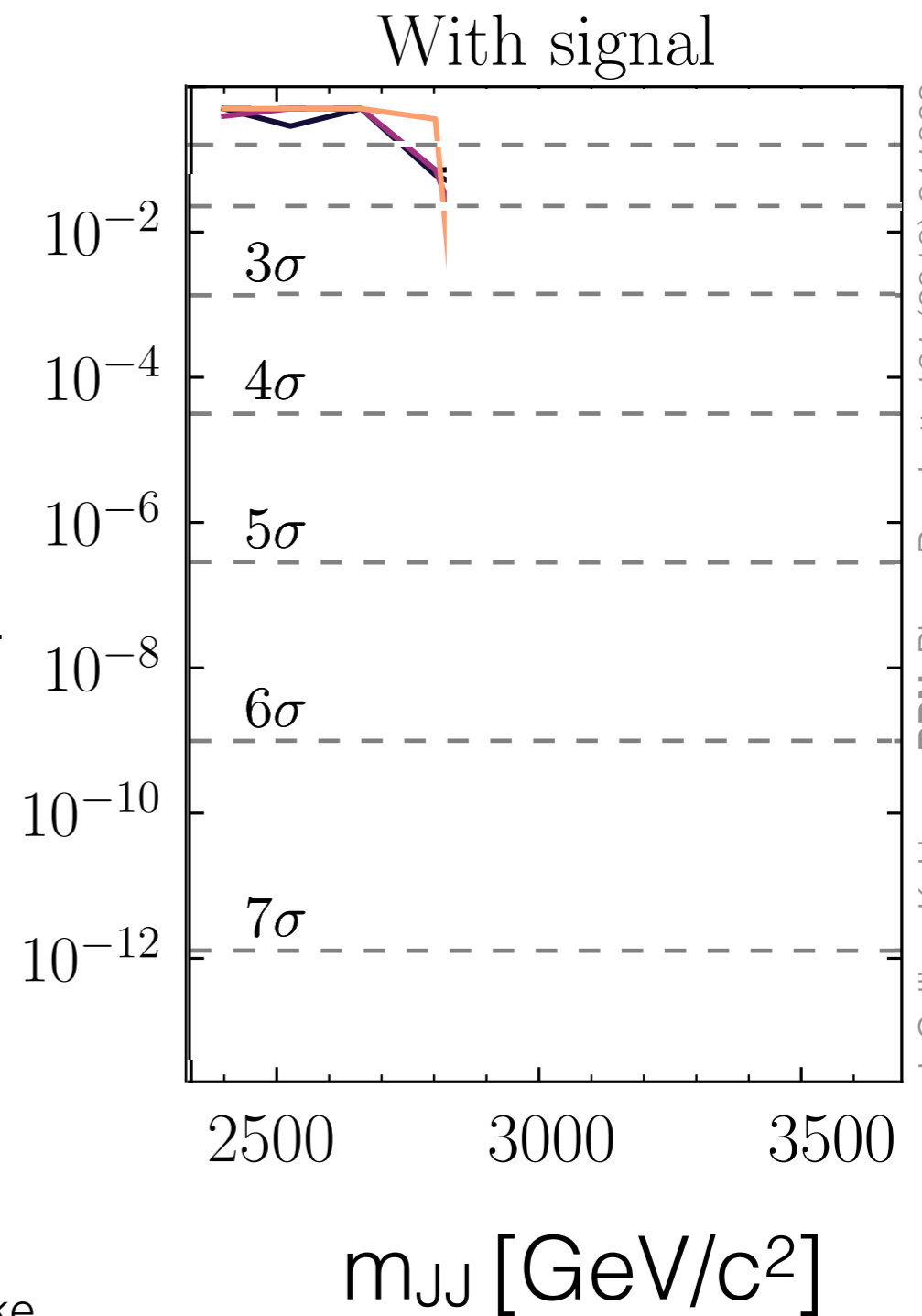


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- most 10% signal-region-like
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...and when there is a signal?

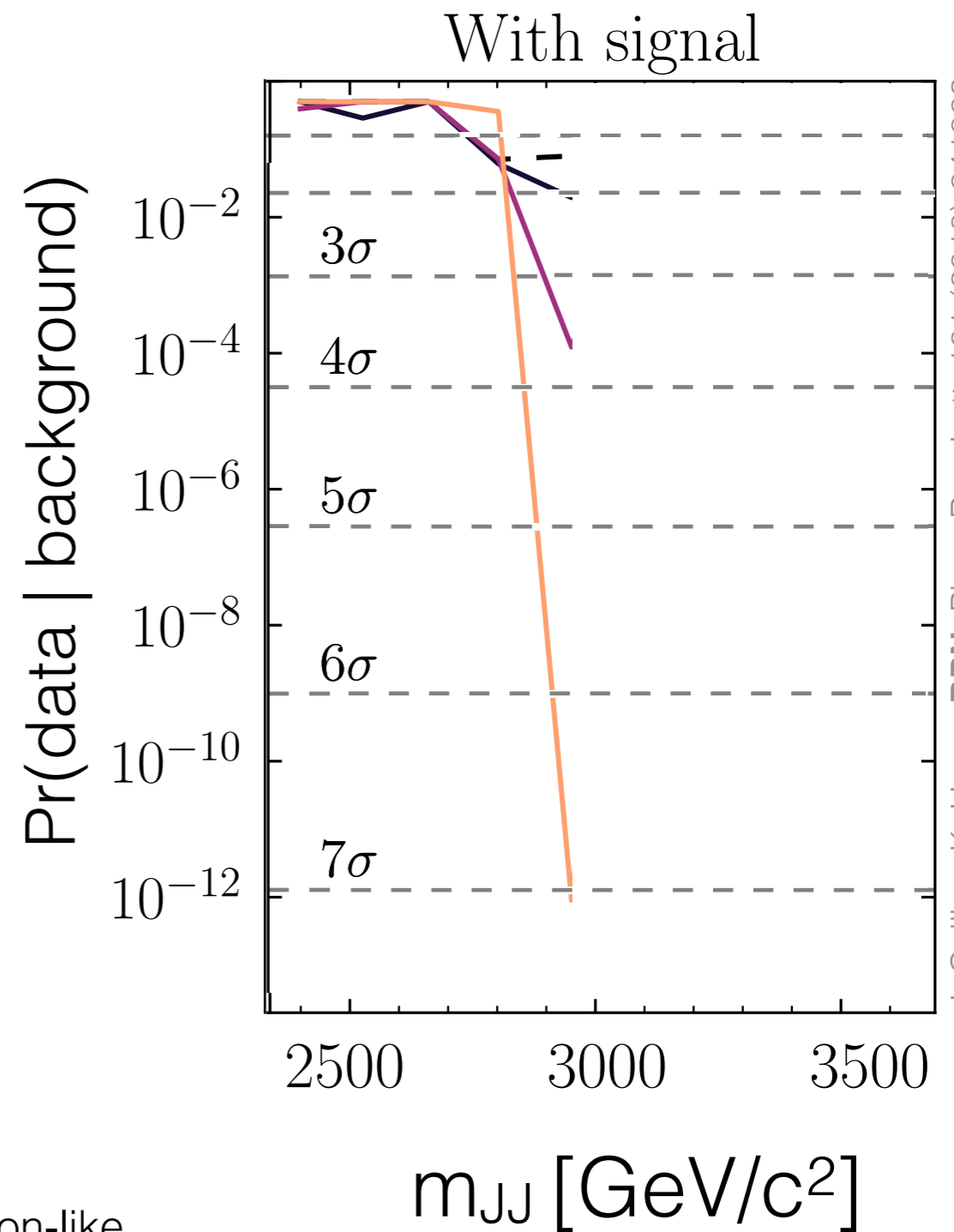
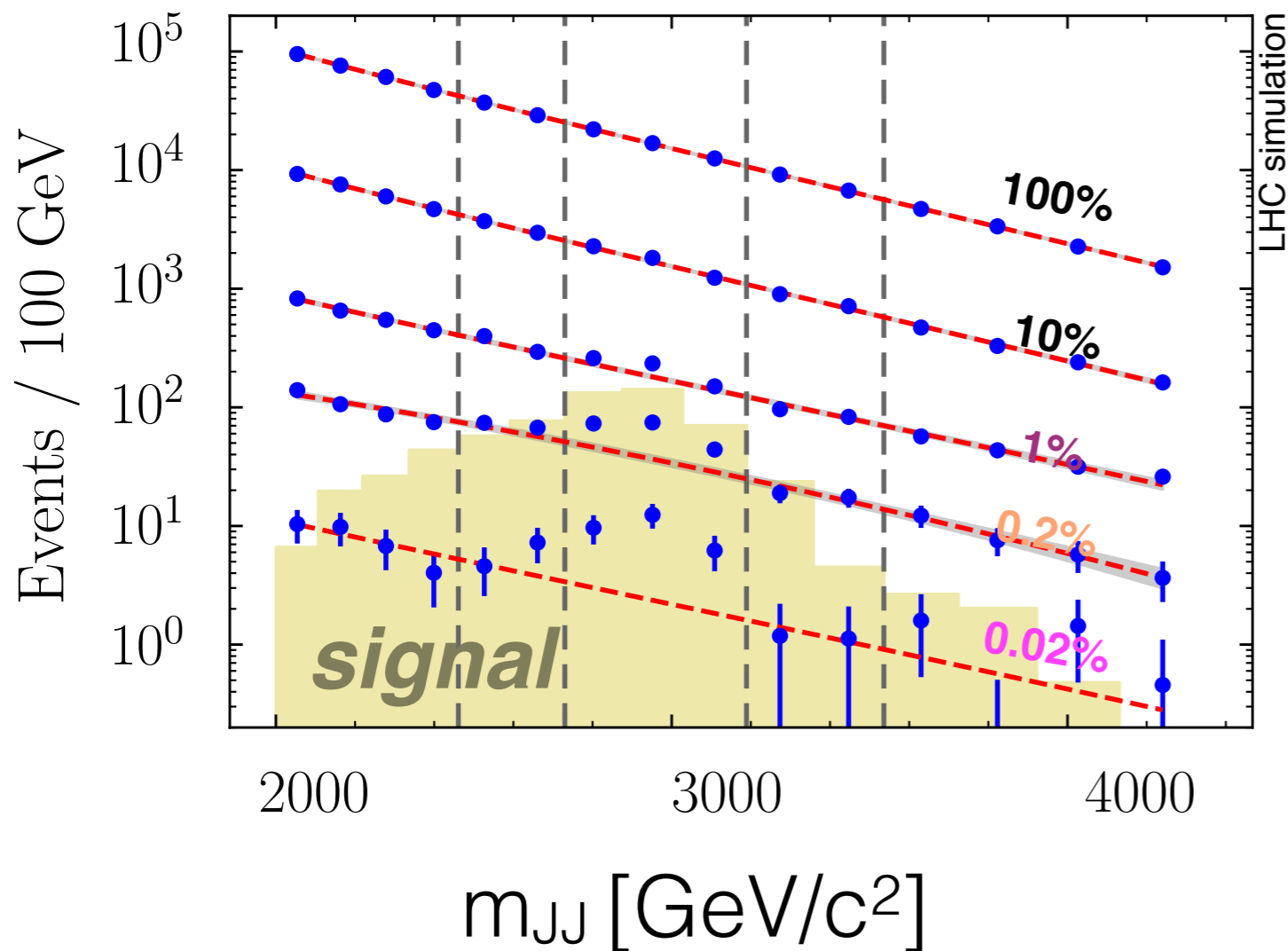


Pr(data | background)



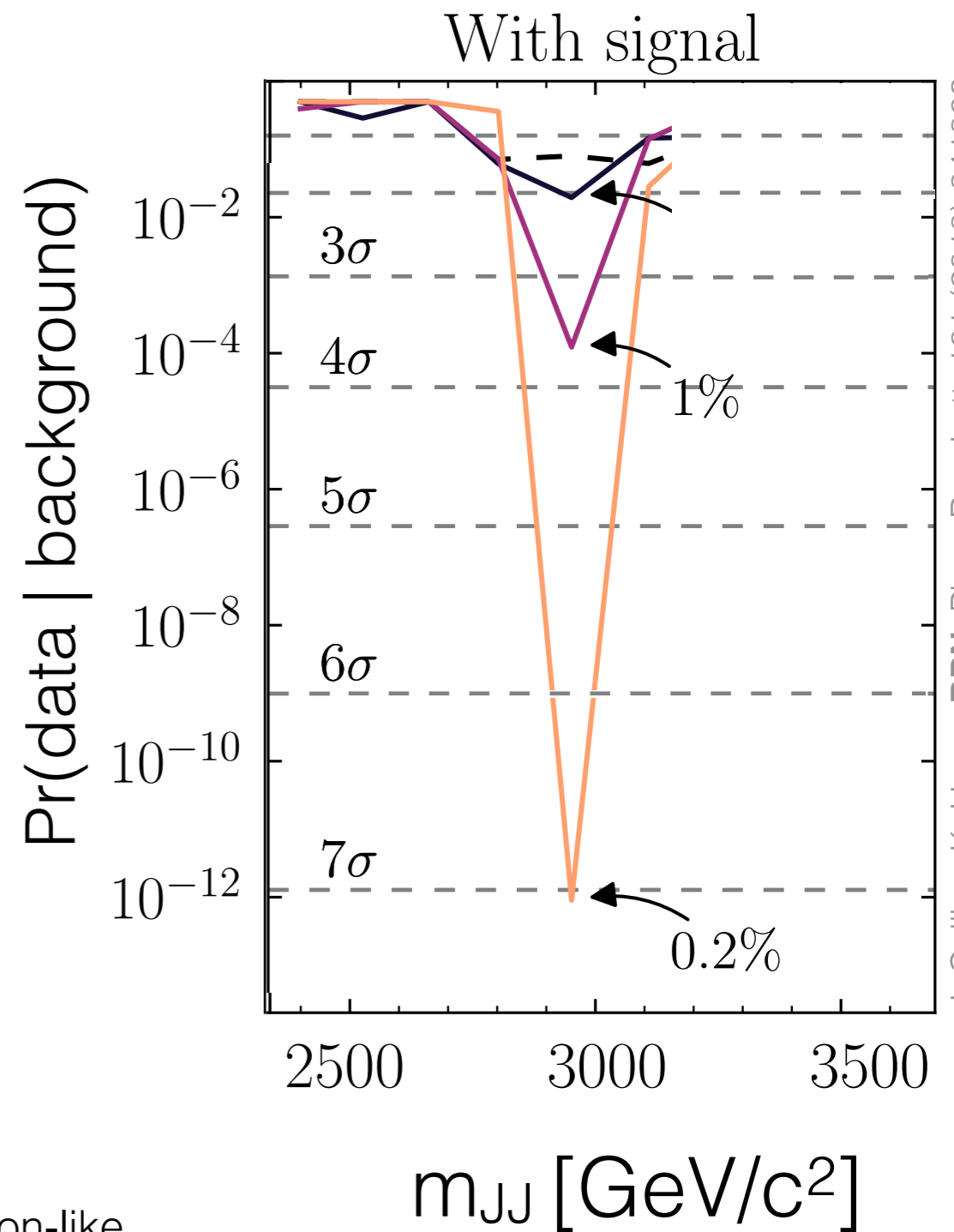
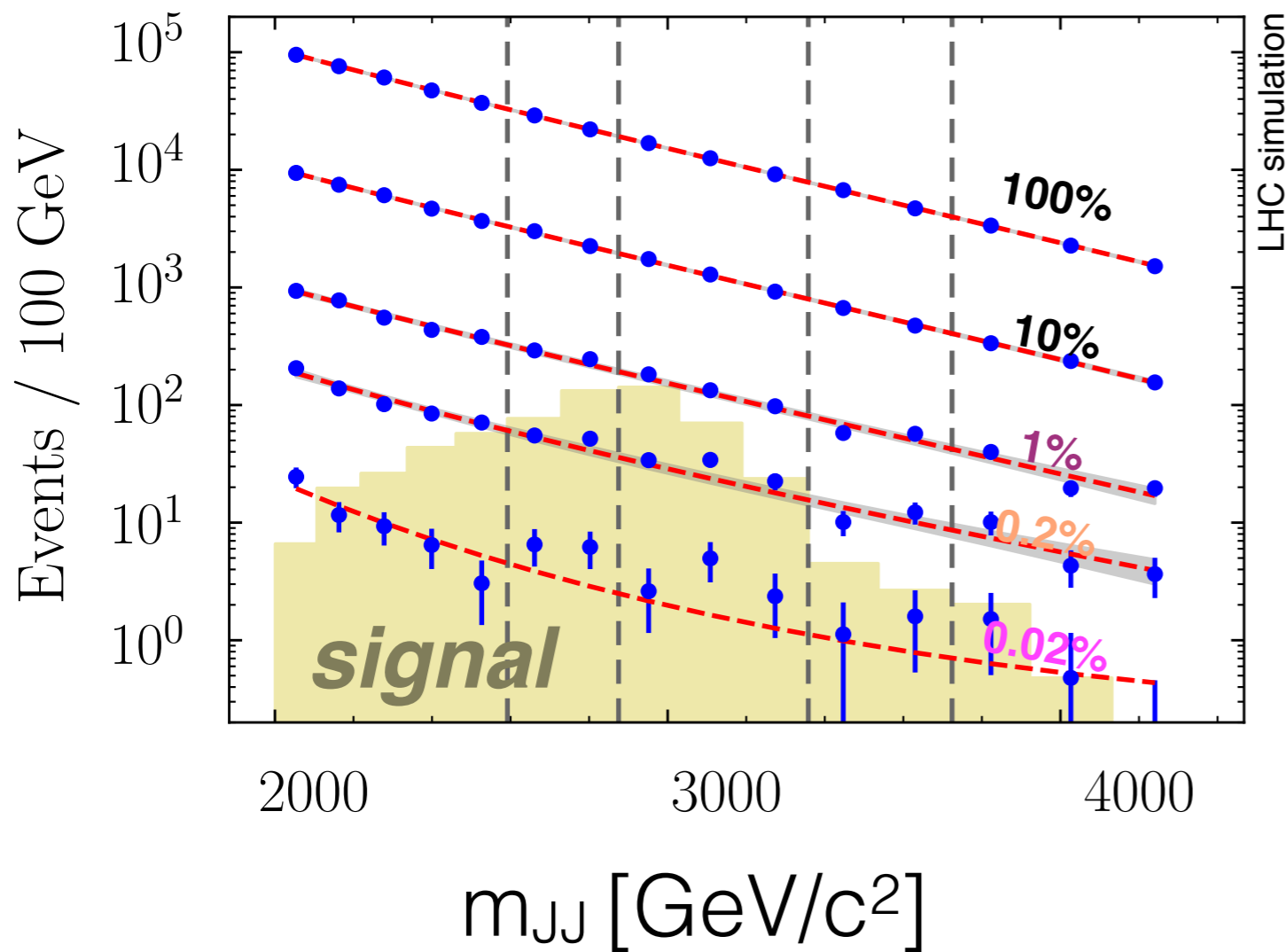
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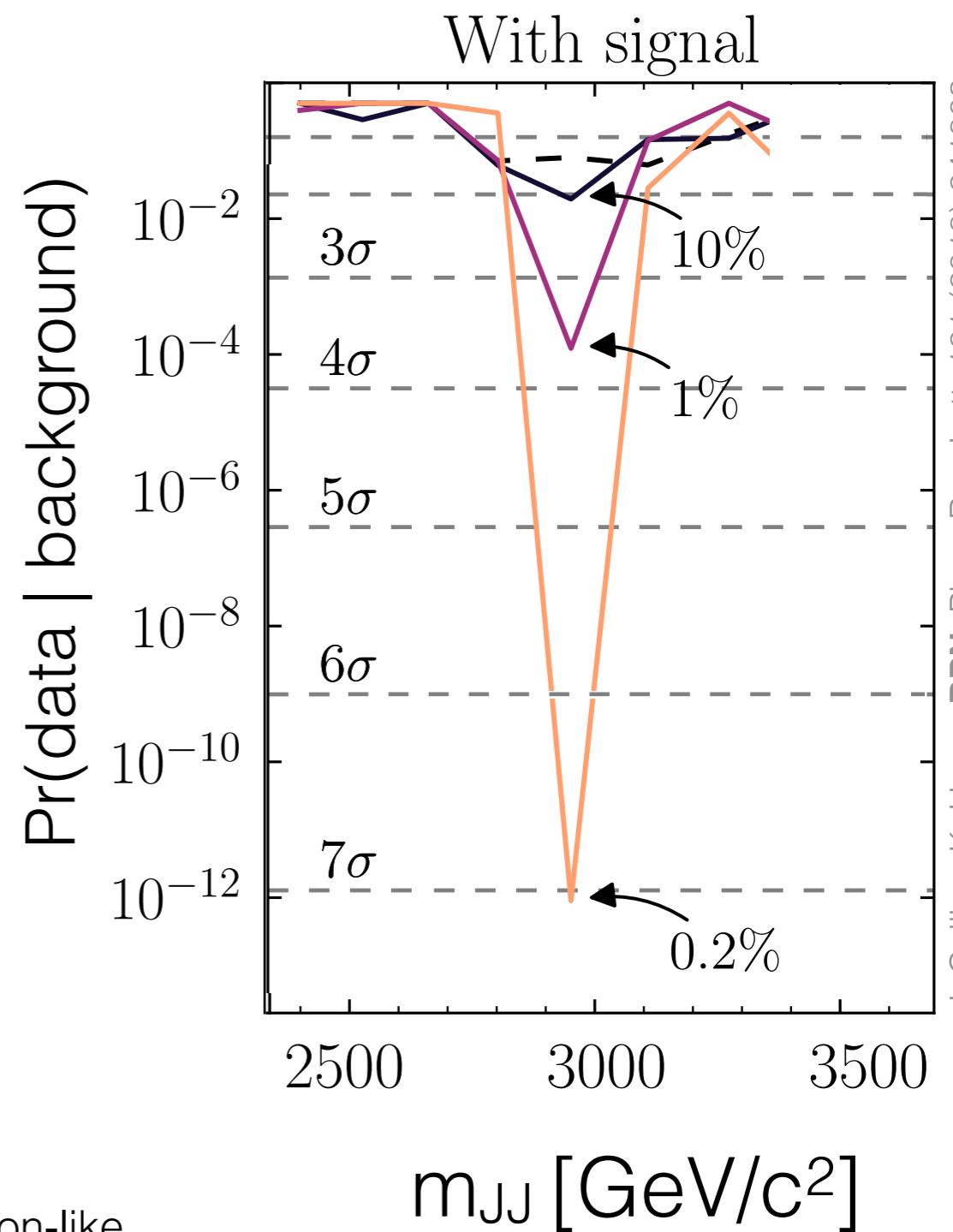
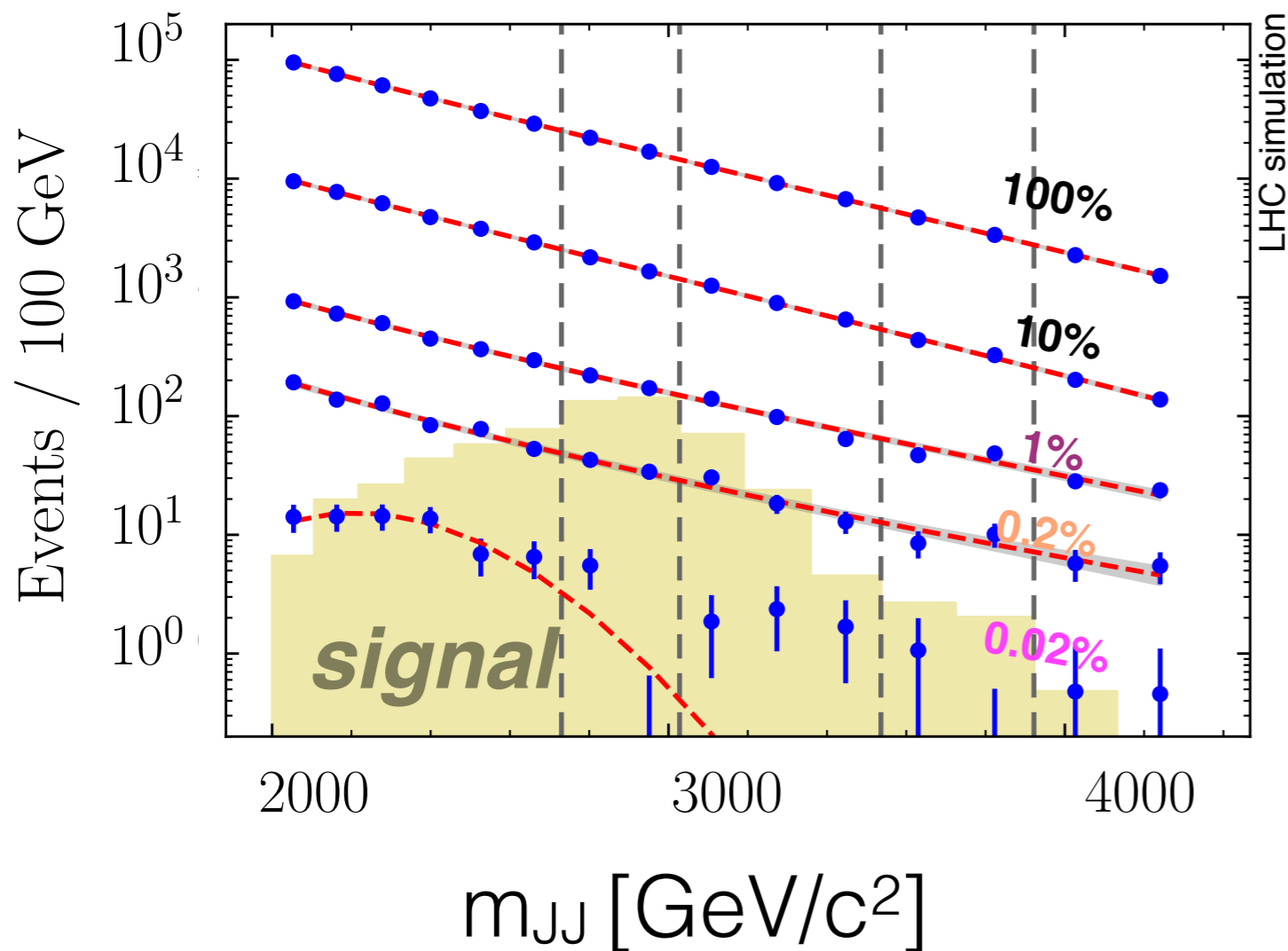
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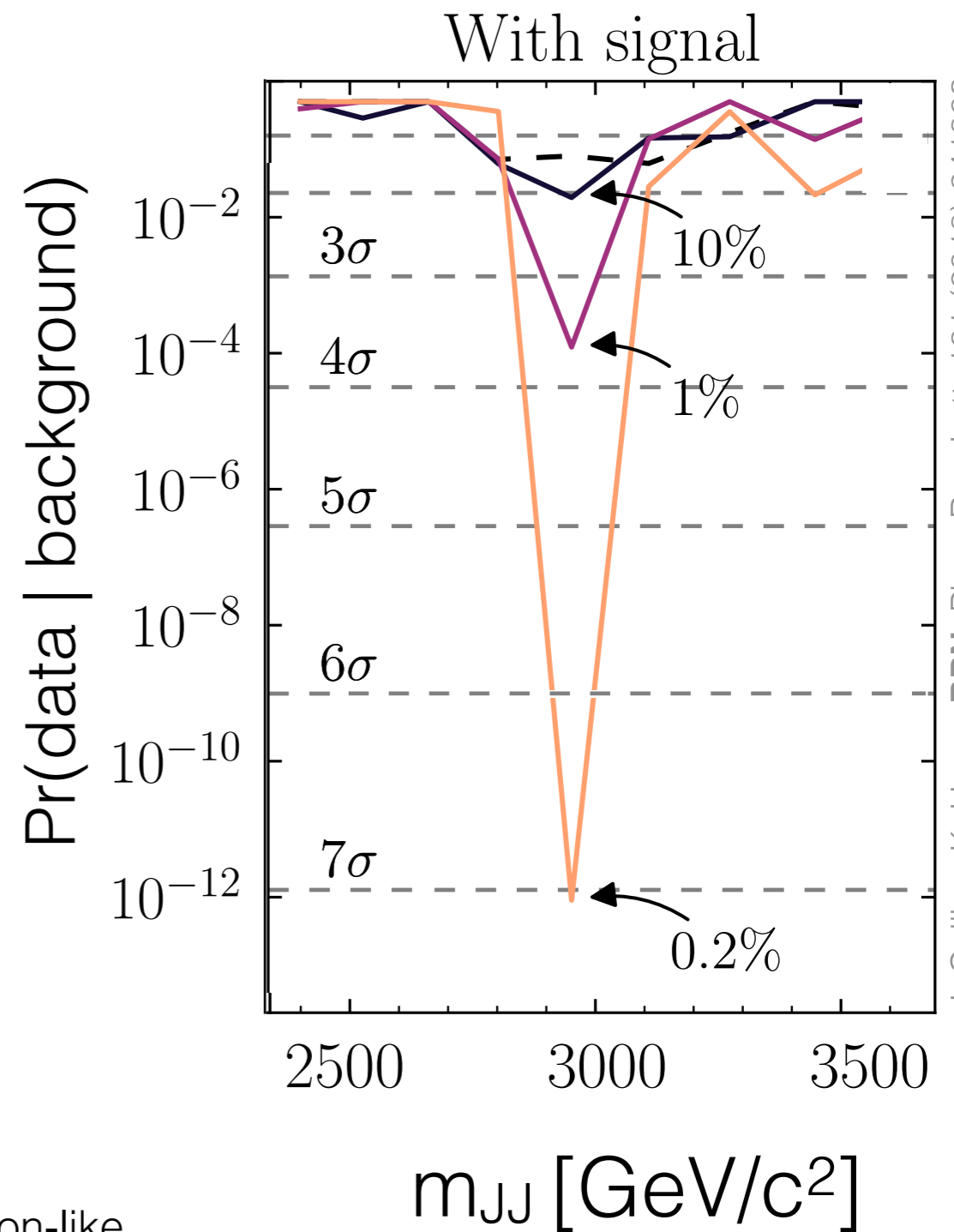
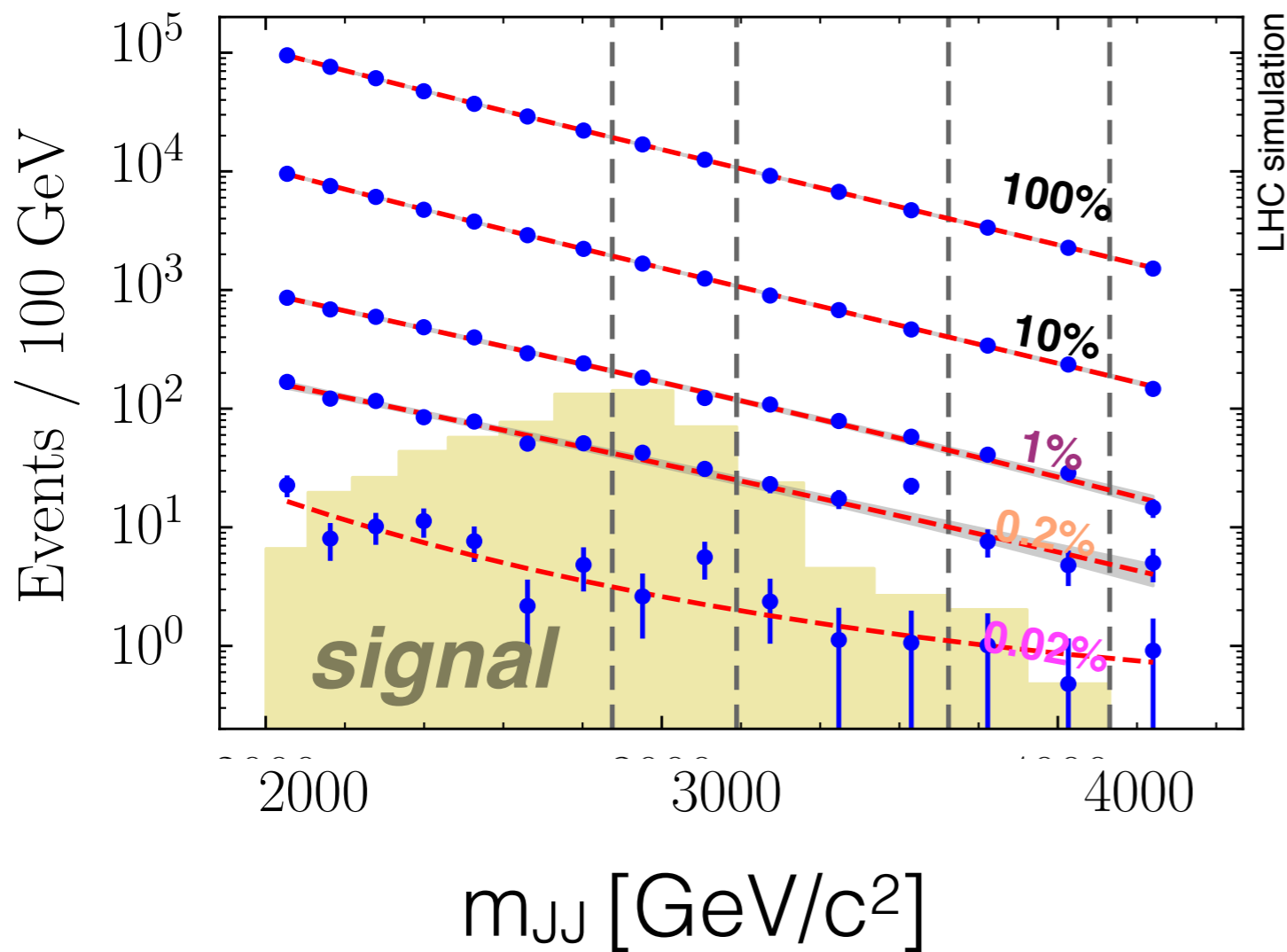
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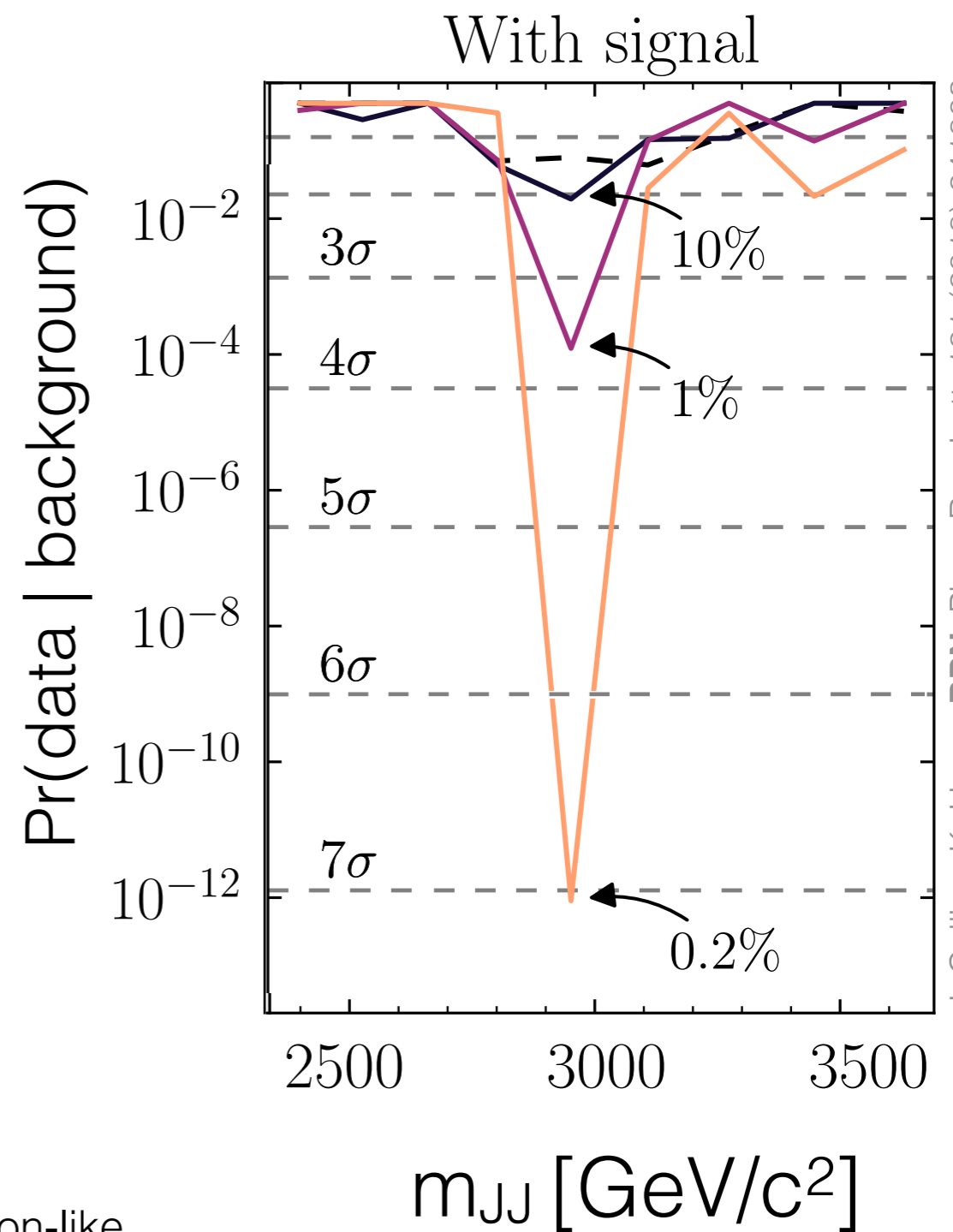
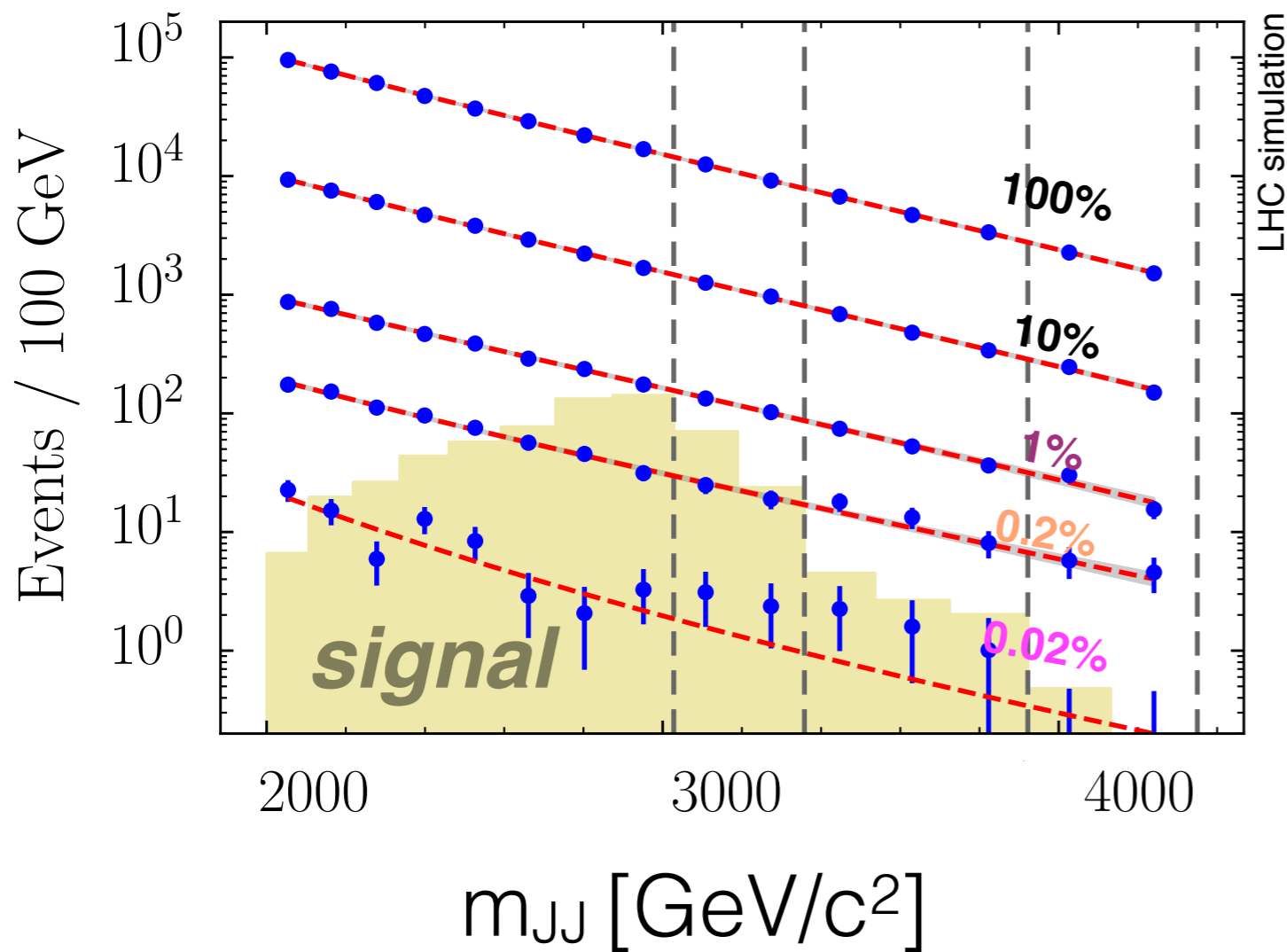
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...and when there is a signal?



- no cut on NN
- most 10% signal-region-like
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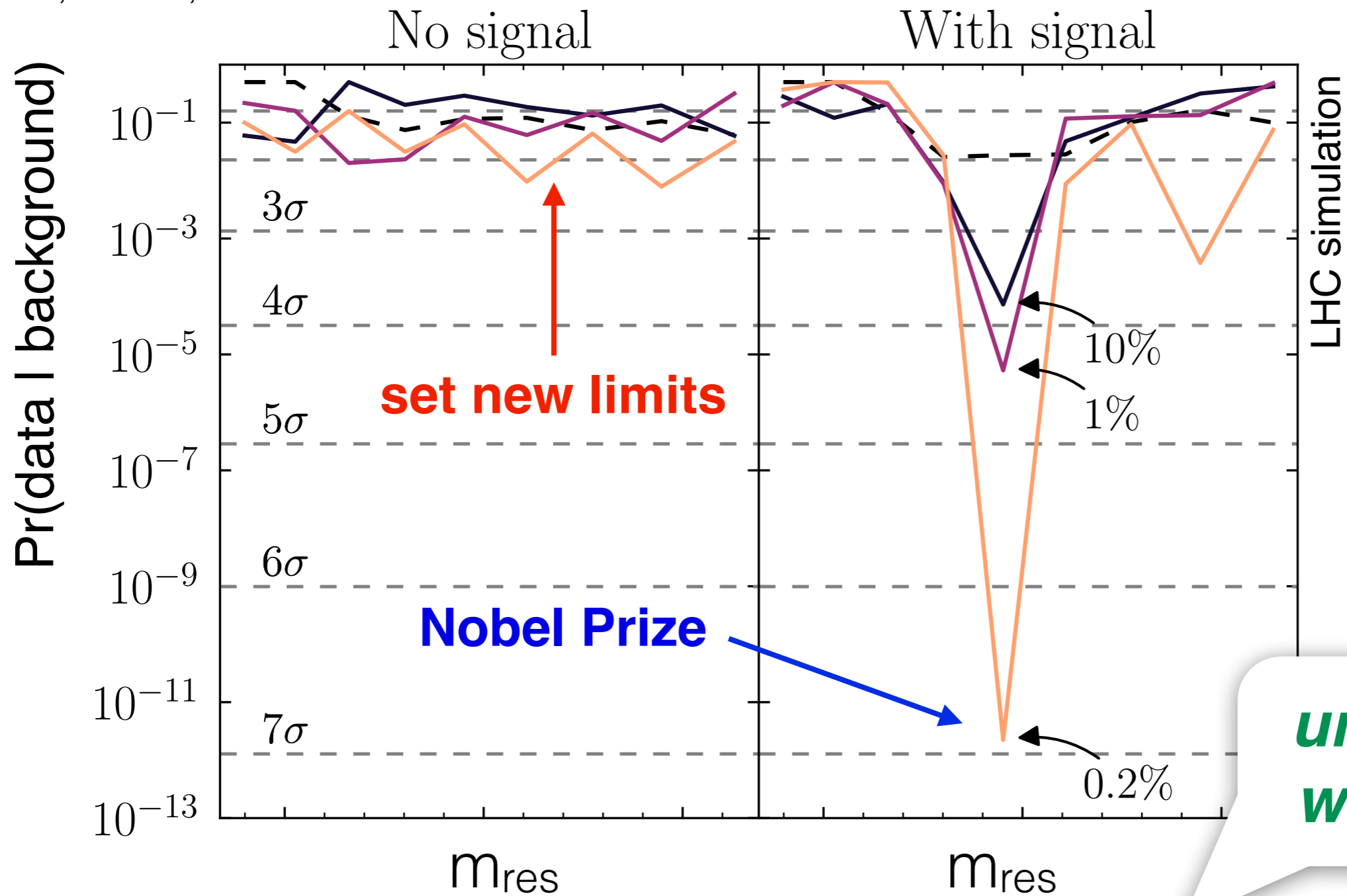
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CWoLa hunting: overview

[Phys. Rev. Lett. 121 \(2018\) 241803](#)

A. Cukierman, **BPN**, and the ATLAS Collaboration, in preparation

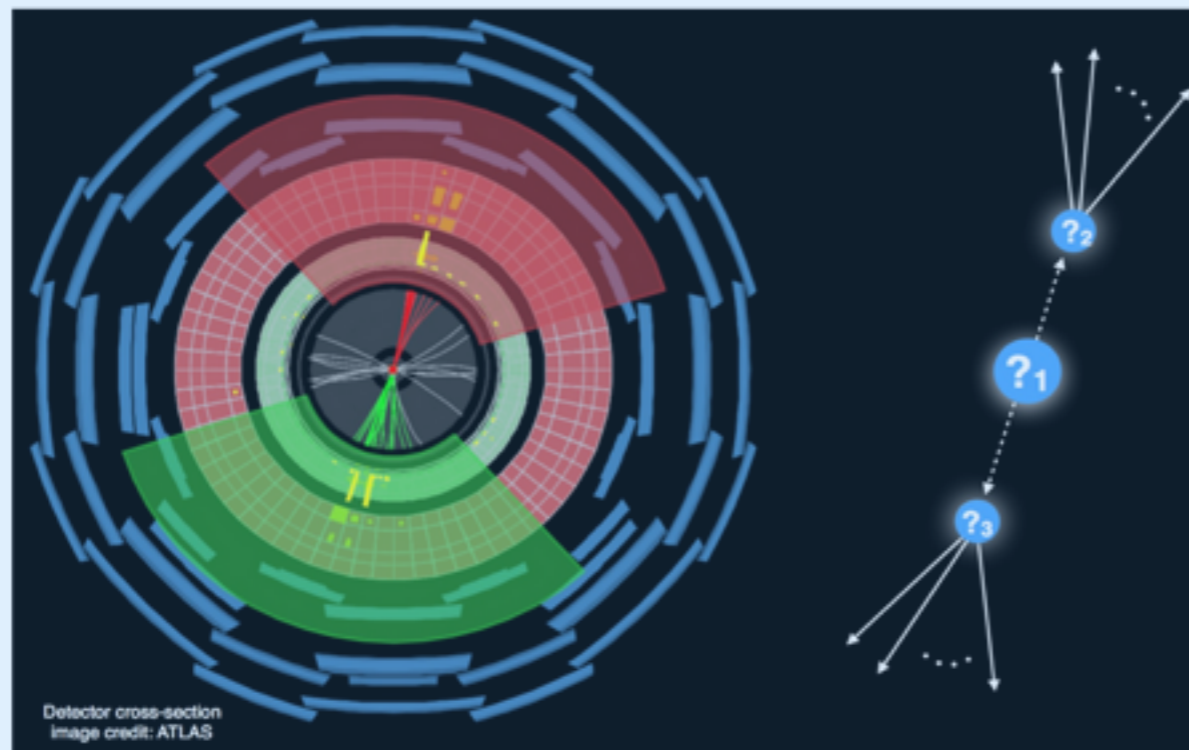
J. Collins, K. Howe, **BPN**



*Our first data result from **ATLAS** will come out this spring!*

I believe that anomaly detection will become a significant effort at the LHC and beyond.

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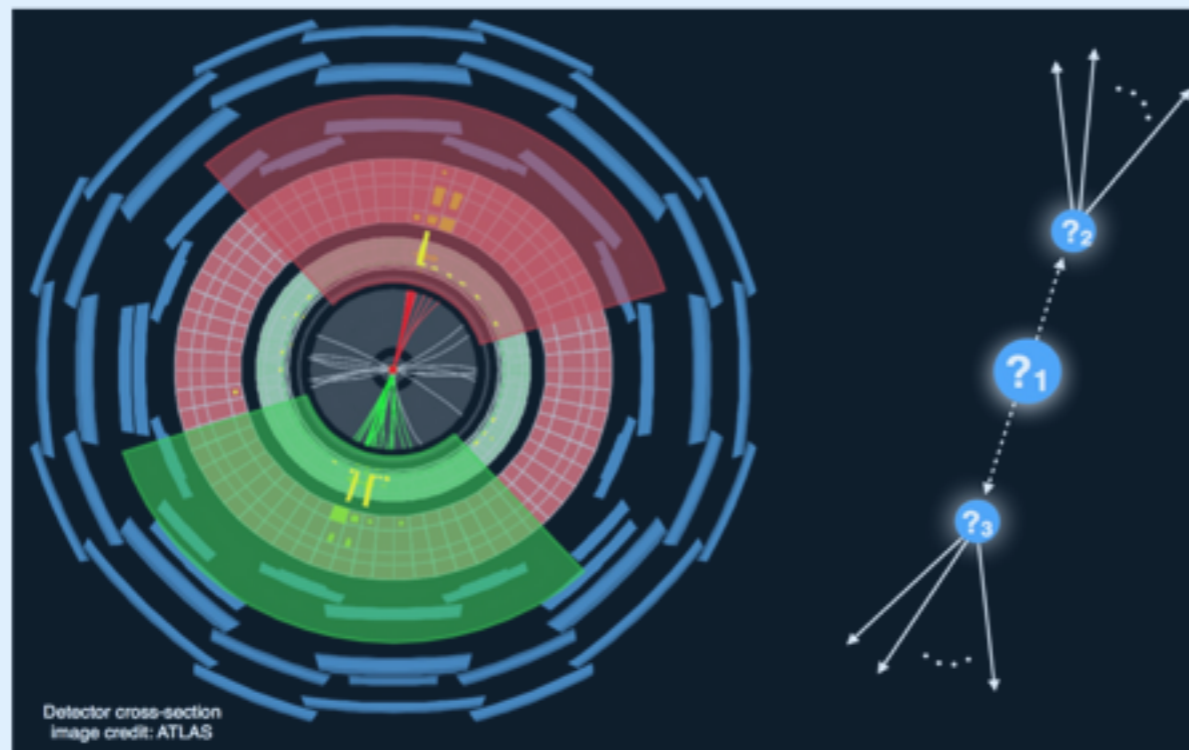


LHC Olympics 2020



<https://indico.cern.ch/event/809820>

I believe that anomaly detection will become a significant effort at the LHC and beyond.



LHC Olympics 2020



<https://indico.cern.ch/event/809820>

No one algorithm will cover all possibilities - we will need a variety of methods to ensure broad coverage!

Theoretical and experimental questions motivate a deep exploration **of the fundamental structure of nature**

Key **challenge** and **opportunity**: *hypervariate phase space* & *hyper spectral data*

Likelihood-Free inference

Deep learning & Quantum computing for fundamental physics

Label-Free learning

[Deconvolution/Unfolding]

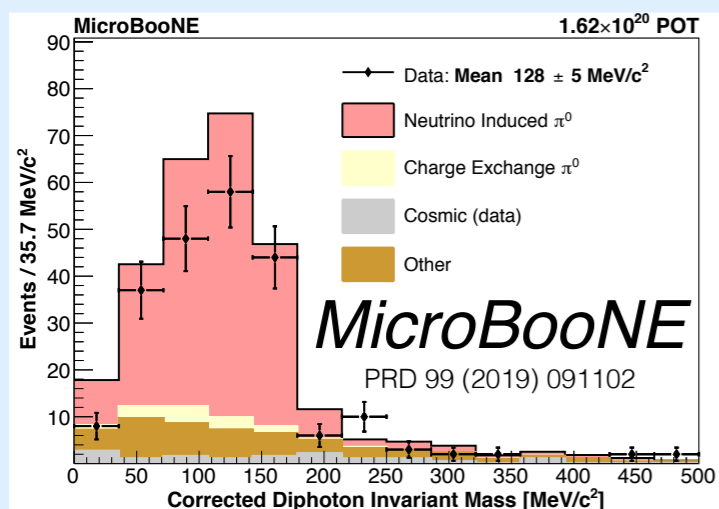
[Generative models]

[Weak supervision]

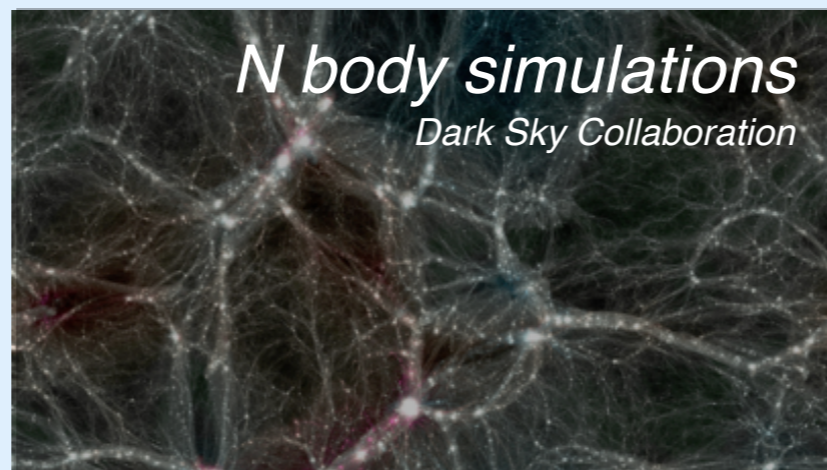
[Anomaly detection]

The methods I have highlighted will lead to cross-cutting R&D to further SLAC's fundamental science goals

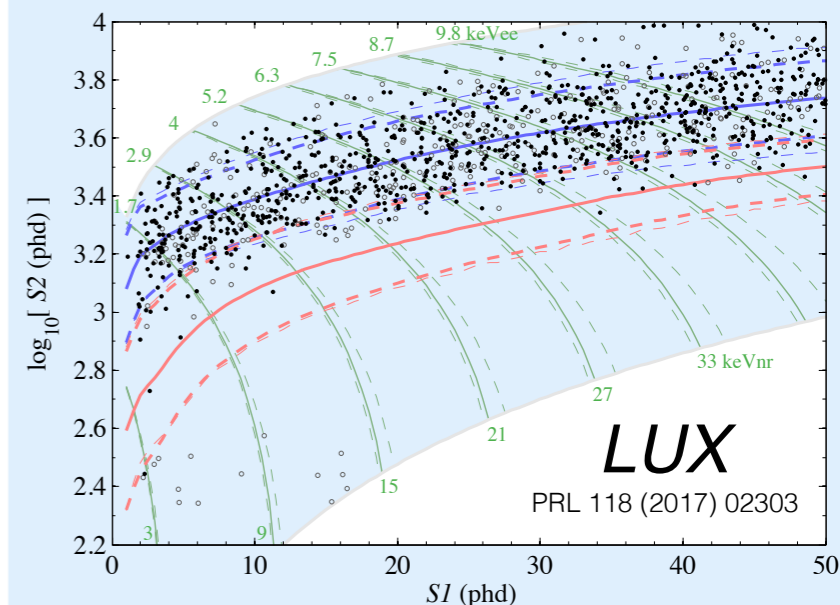
Likelihood-free inference



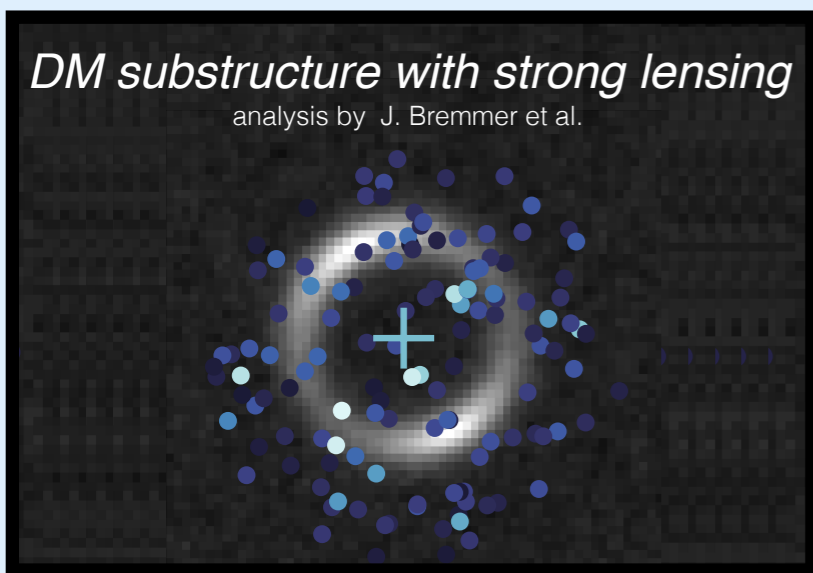
Generative Models



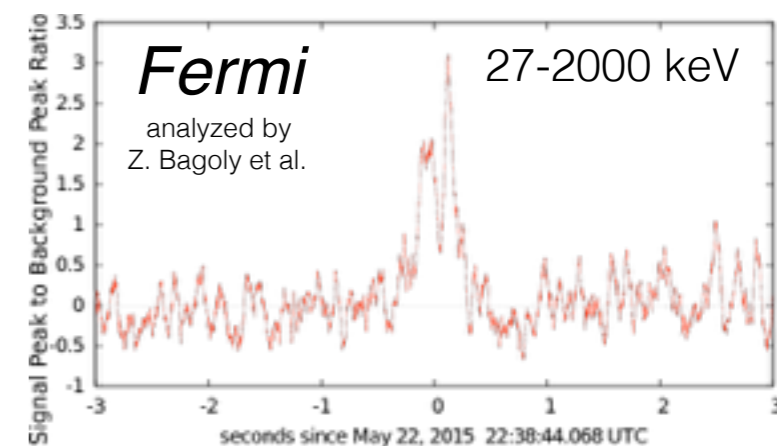
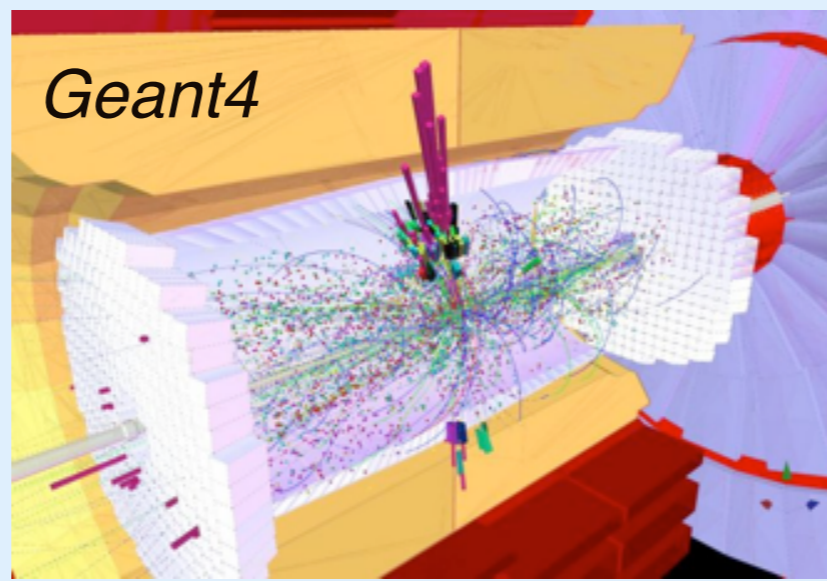
Anomaly Detection



DM substructure with strong lensing
analysis by J. Bremmer et al.



Geant4



The future: collaborations

150



Connect with Stanford CS weak supervision experts for physics apps.

NESAP for Learning



co-PI for distributed GAN training for accelerated calorimeter simulation on next CPU/GPU supercomputer

QuantISED HEP initiative



Continuing to study quantum computing for particle/nuclear physics



5-year Advanced Scientific Computing Research (ASCR) multi-institute team working on error mitigation



Rare Processes, Precision Measurements
and Dark Sector Production

Cosmic Frontier

Energy Frontier

Neutrino Physics Frontier

Theory Frontier

**Computational
Frontier**

*N.B. ML & QIS not
part of last Snowmass!*

Accelerator Science and
Technology Frontier

The future: community planning

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Rare Processes, Precision Measurements
and Dark Sector Production



Cosmic Frontier



Energy Frontier



Neutrino Physics Frontier



Theory Frontier

Computational Frontier

*N.B. ML & QIS not
part of last Snowmass!*

Accelerator Science and
Technology Frontier



Theoretical and experimental questions motivate a deep exploration **of the fundamental structure of nature**

Key **challenge** and **opportunity**: *hypervariate phase space* & *hyper spectral data*

**Likelihood-Free
inference**

**Deep learning
& Quantum
computing for
fundamental
physics**

**Label-Free
learning**

[Deconvolution/Unfolding]

[Generative models]

[Weak supervision]

[Anomaly detection]

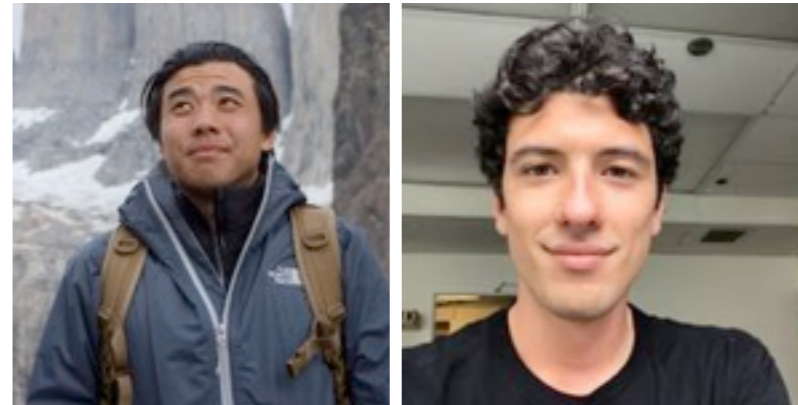
Thank you - (under)graduate students

154

Jet physics



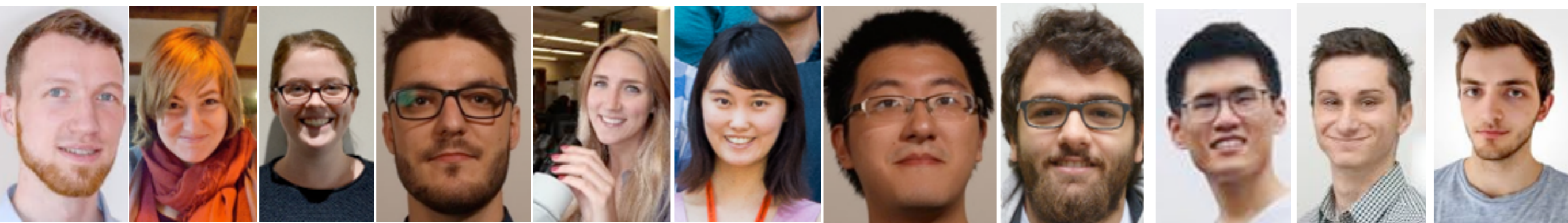
Quantum computing

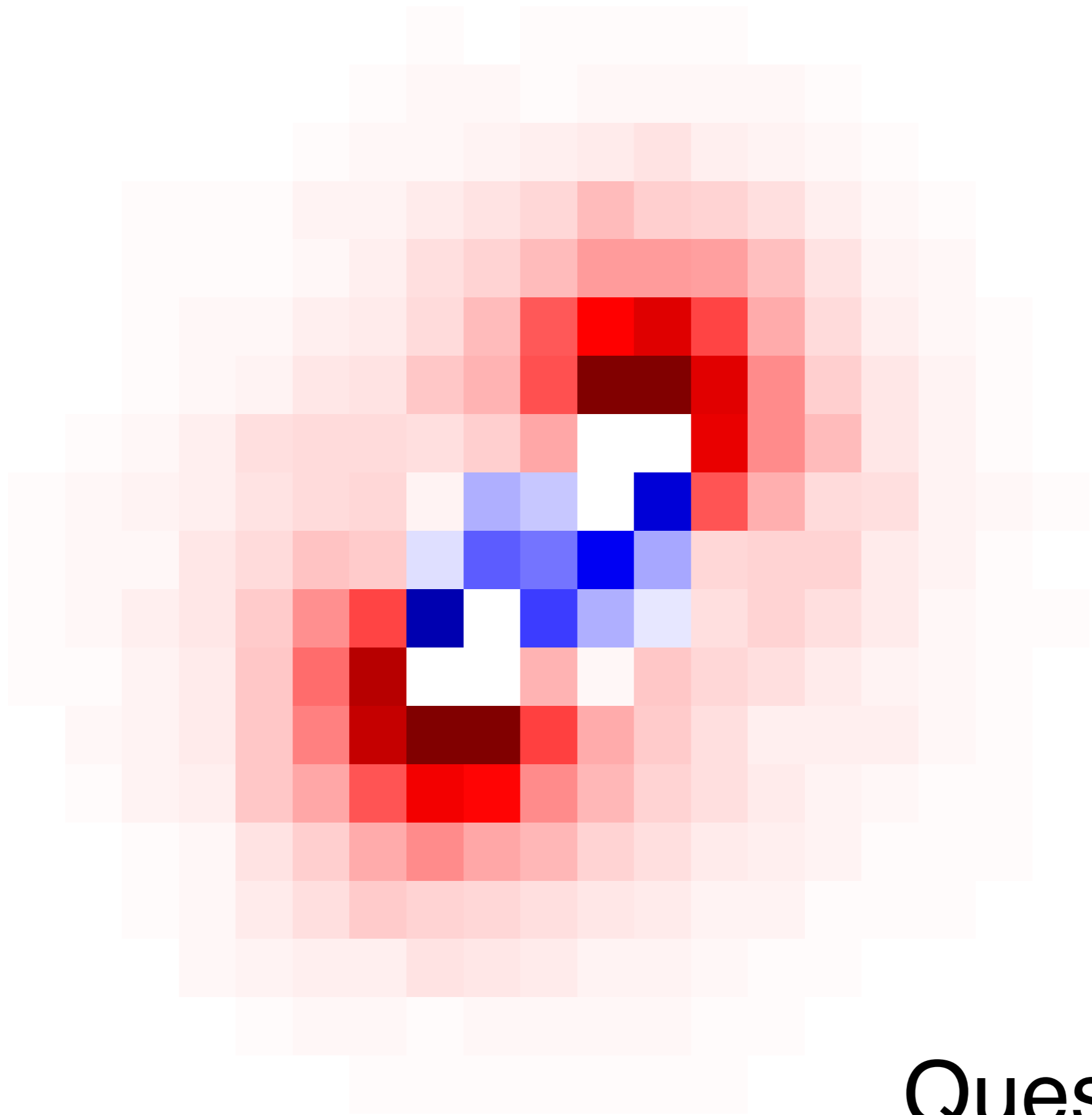


Deep learning



Radiation damage / Silicon detector research





Questions?

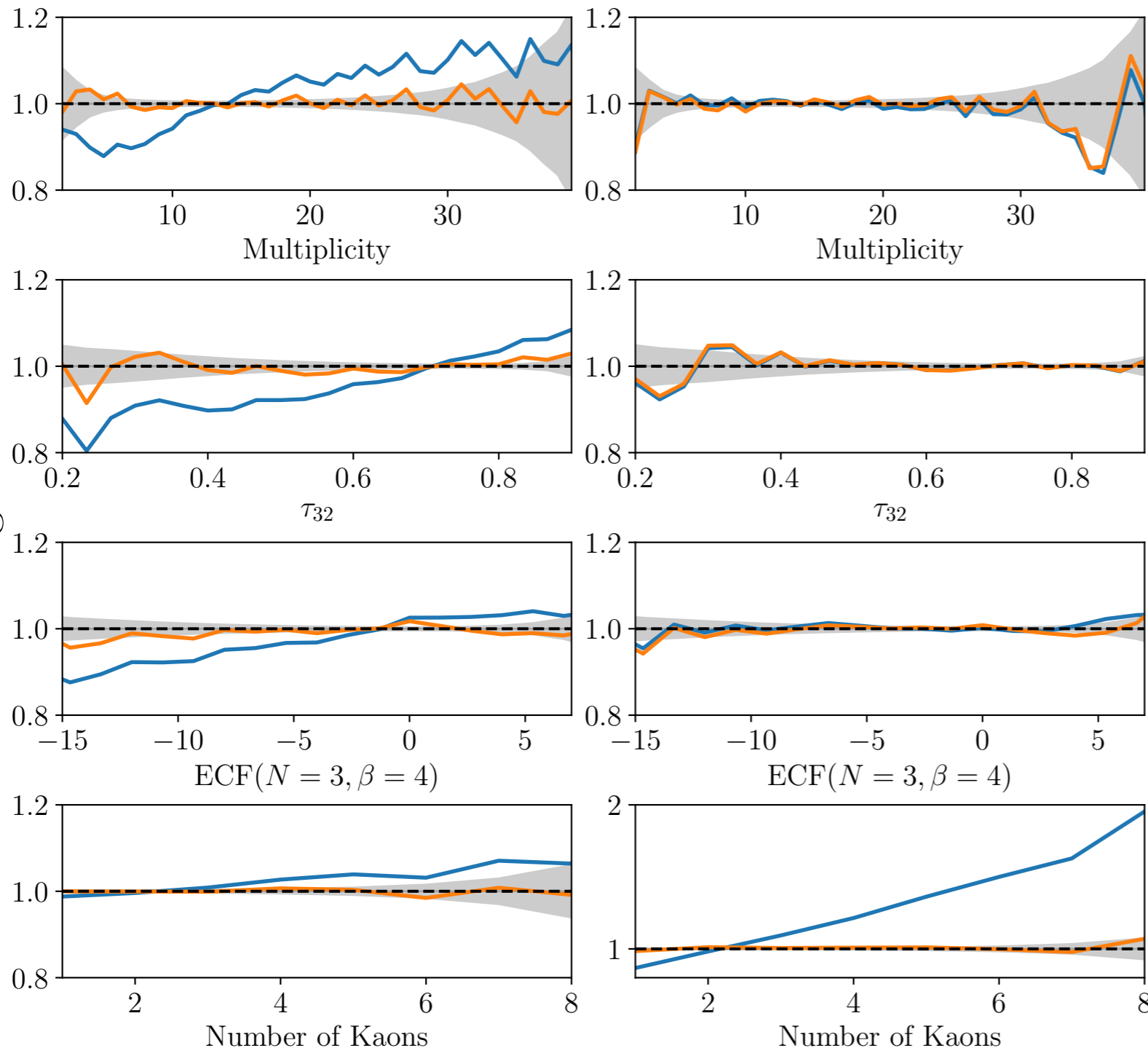
Achieving precision

156

StringZ:aLund

StringFlav:probStoUD

— Unweighted — Weighted



Works also when the differences between the two simulations are small (left) or localized (right).

These are histogram ratios for a series of one-dimensional observables

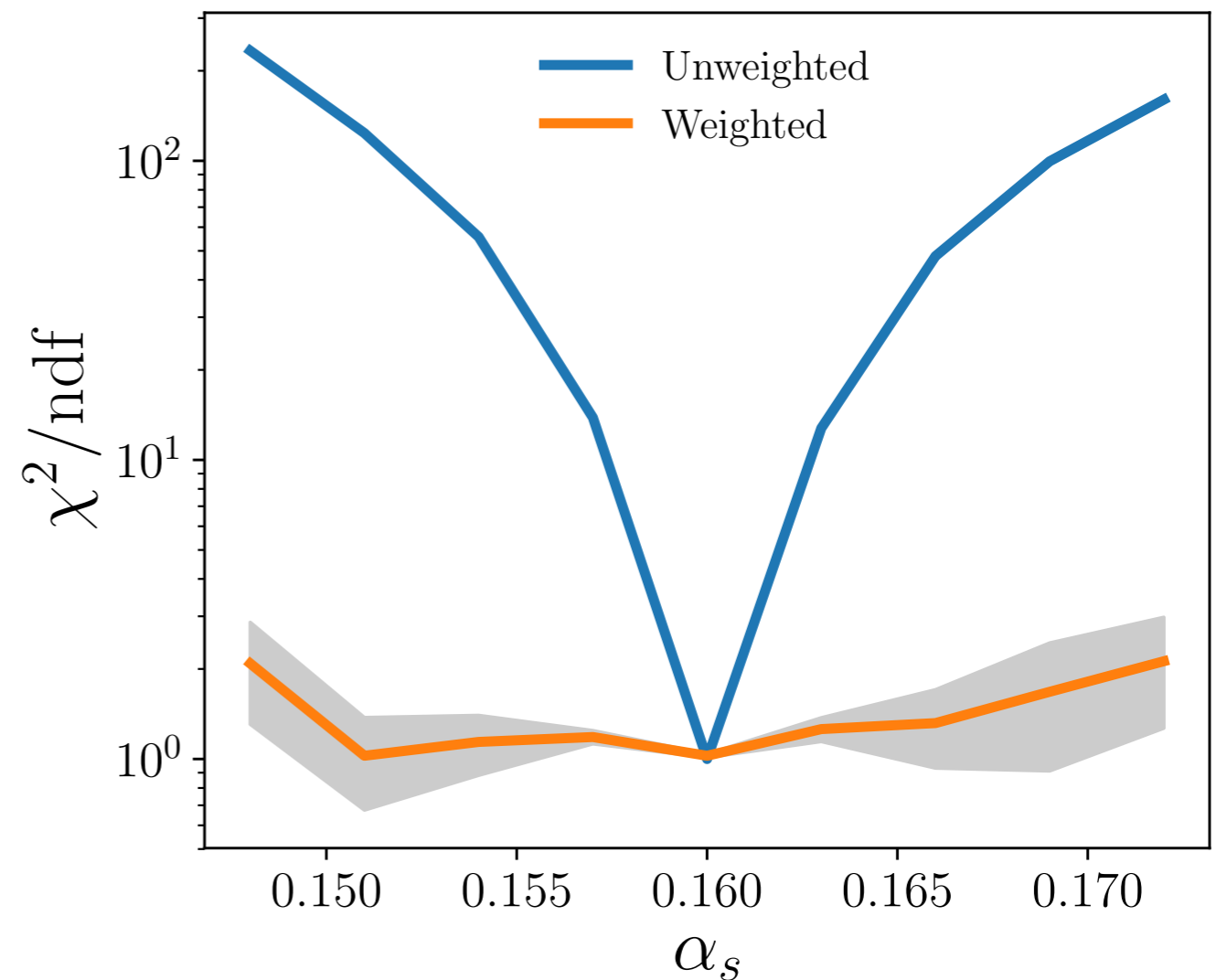
Parameterized reweighting

157

What if we have a new simulation with multiple continuous parameters θ ?

Easy - simply learn a parameterized classifier* !

...simply add the parameter as a feature to the network during training and let it learn to interpolate.



“fine structure constant”
of the strong force

*see Cranmer, Pavez, Louppe, 1506.02169


What if we want to reweight with **pre-detector particles**, but fit to **detector-level objects**?

$$\theta^* = \operatorname{argmax}_{\theta'} \min_g \sum_{i \in \theta_0} \log g(x_{D,i}) \quad [\text{data}]$$

[reweighted
simulation]

$$+ \sum_{i \in \theta} w(x_{T,i}, \theta) \log(1 - g(x_{D,i}))$$

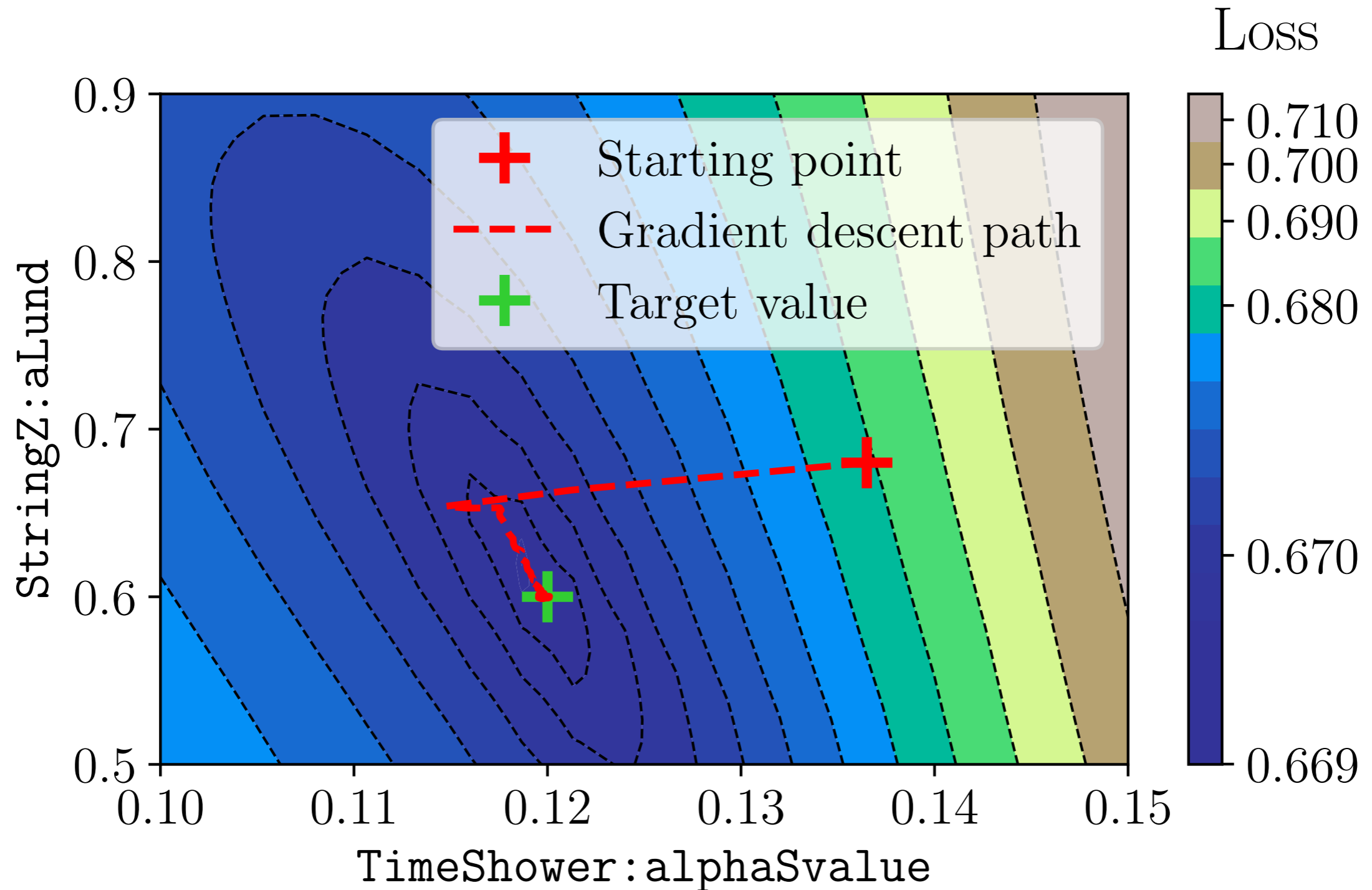
Intuition: reweight until you can't distinguish the data from the (reweighted) simulation!

$$\frac{f(x_T, \theta)}{1 - f(x_T, \theta)}$$


Parameter estimation

159

Fit 3 (2 shown) parameters using the full phase space!



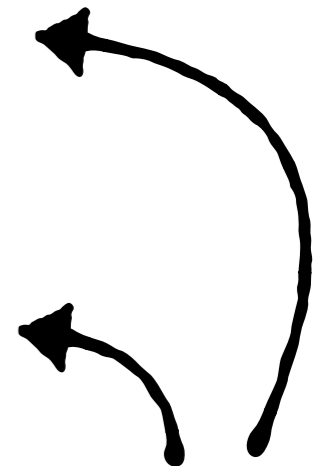
*a different method was used for this fit - it is not a minimax procedure but doesn't work at two levels ... ask later for details

Parameter estimation

160

Mean and standard deviation over 20 runs:

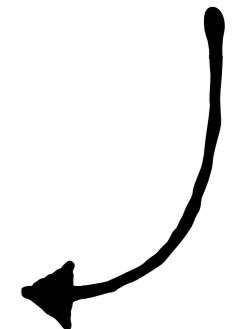
	Parameter	Target value	Fit value
Val.	TimeShower:alphaSvalue	0.1200	0.1195 ± 0.0022
	StringZ:aLund	0.6000	0.6276 ± 0.0373
	StringFlav:probStoUD	0.1200	0.1203 ± 0.0071
Blinded	TimeShower:alphaSvalue	0.1700	0.1707 ± 0.0022
	StringZ:aLund	0.7500	0.7425 ± 0.0453
	StringFlav:probStoUD	0.1400	0.1422 ± 0.0065



Similar spread

1D:

Parameter	Target value	Fit value
TimeShower:alphaSvalue	0.1600	0.1601 ± 0.0018
StringZ:aLund	0.8000	0.7980 ± 0.0257
StringFlav:probStoUD	0.2750	0.2754 ± 0.0065



The meaning of this “uncertainty” is discussed later.

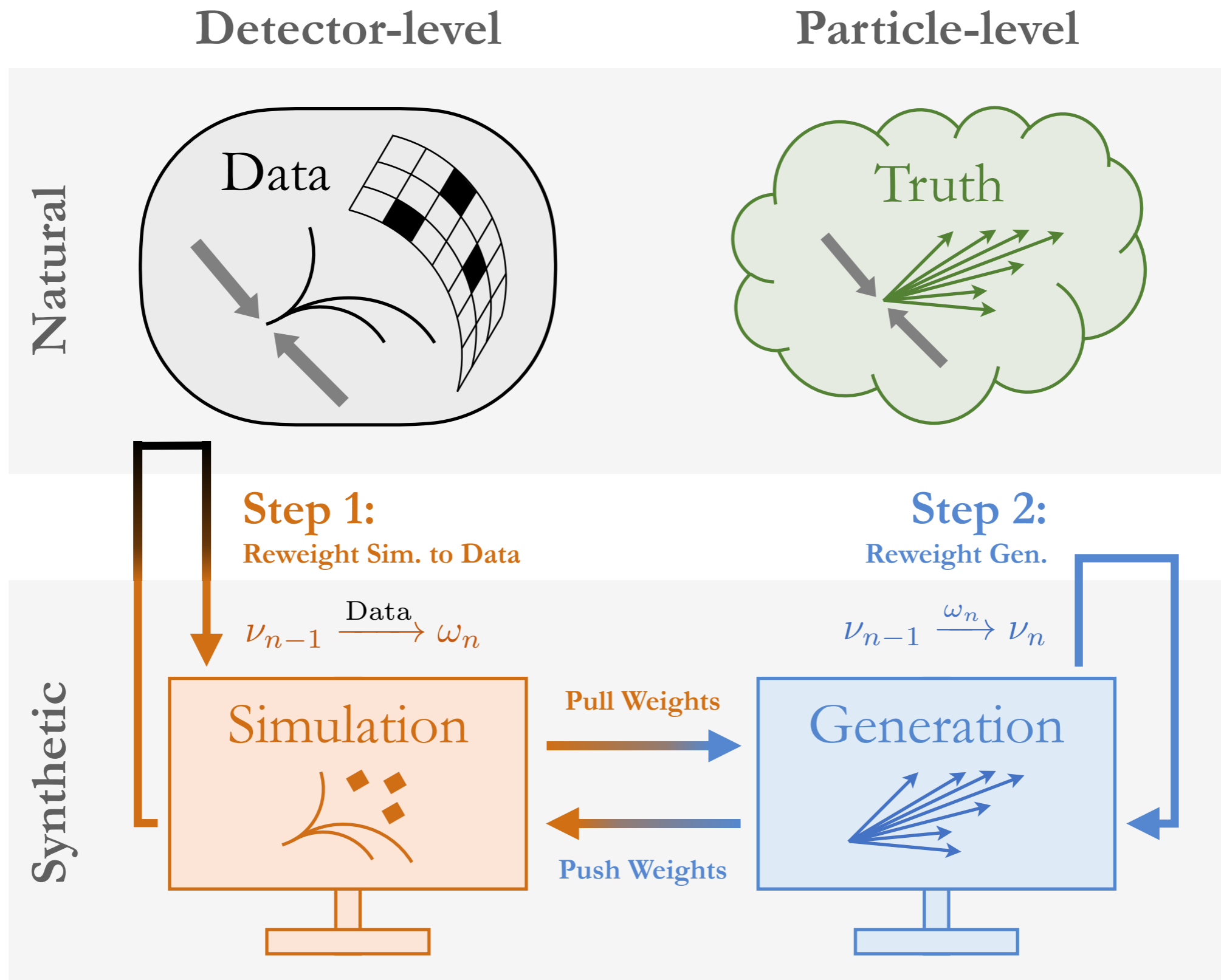
Emily Dickinson, #975

The Mountain sat upon the Plain
In his tremendous Chair –
His observation **omnifold**,
His inquest, everywhere –

The Seasons played around his knees
Like Children round a sire –
Grandfather of the Days is He
Of Dawn, the Ancestor –

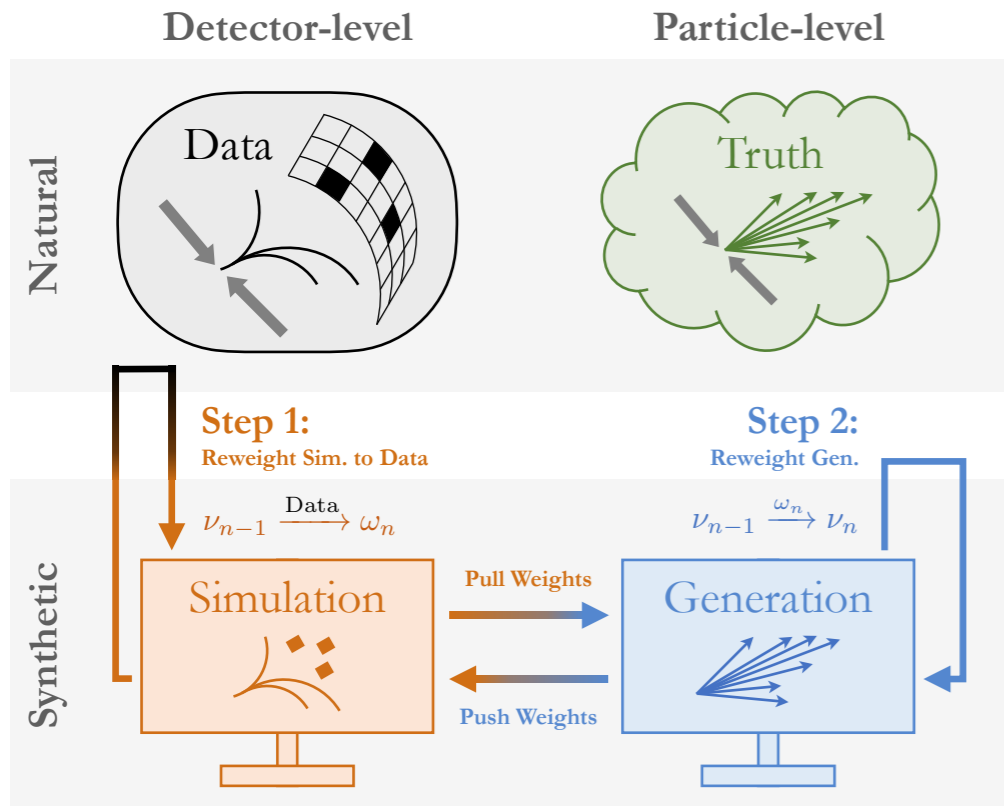


Full phase space unfolding: OmniFold



Full phase space unfolding: OmniFold

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Notation: m = measured, t = true

$$L[(w, X), (w', X')](x) = \frac{p_{(w, X)}(x)}{p_{(w', X')}(x)}$$

(accomplish with a classifier, as before)

$$\nu_0^{\text{push}}(m) = \nu_0(t) \quad \omega_n^{\text{pull}}(t) = \omega_n(m)$$

(these are not functions, since $t \rightarrow m$ is not 1:1)

Iterate:

1. $\omega_n(m) = \nu_{n-1}^{\text{push}}(m) L[(1, \text{Data}), (\nu_{n-1}^{\text{push}}, \text{Sim.})](m),$
2. $\nu_n(t) = \nu_{n-1}(t) L[(\omega_n^{\text{pull}}, \text{Gen.}), (\nu_{n-1}, \text{Gen.})](t).$

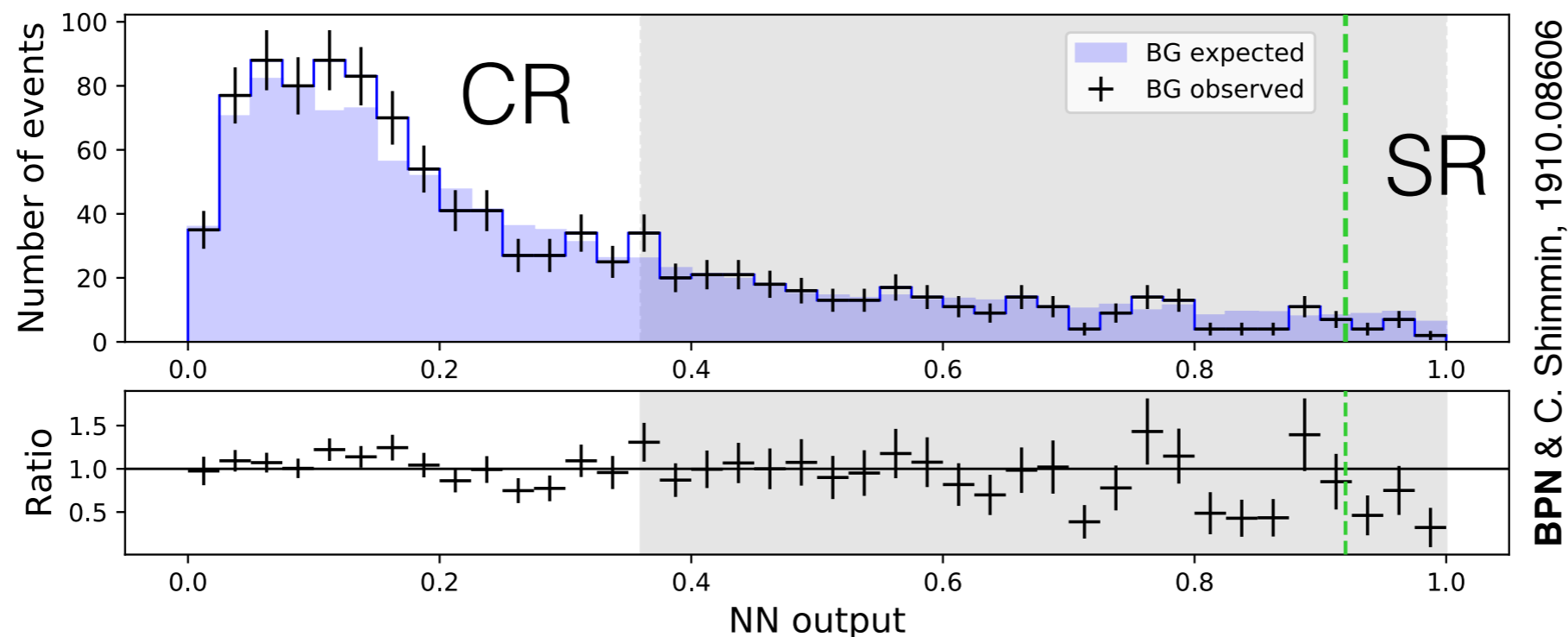
extreme example: $\text{measured}|\text{true} = \text{true} + X$

$$X \sim \mathcal{N}(\mu, \sigma)$$

If you control for X (=auxiliary feature), response is a delta-function!

To keep things simple, let's use the following common example:

1. Train a classifier (in sim.) for signal vs. background.
2. Define a control region and a signal region using (1).
3. Normalize simulation in CR.
4. Compare data and scaled simulation in SR.
5. Significantly different? go to Stockholm; else publish limits.



BPN & C. Shimmin, 1910.08606

Precision / Optimality

*Bad use of our data, time, money, etc. but **not wrong**.*

Accuracy / Bias

Precision / Optimality: $\text{NN}(\mathbf{x}) \neq \frac{p_{\text{true}}(x|S+B)}{p_{\text{true}}(x|B)}$

↑
Optimal by Neyman-Pearson

Accuracy / Bias

Note that this is not $p(x|S) / p(x|B)$, however the two are monotonically related to each other.

Precision / Optimality: $\text{NN}(x) \neq \frac{p_{\text{true}}(x|S+B)}{p_{\text{true}}(x|B)}$

Accuracy / Bias: $p_{\text{prediction}}(\text{NN}) \neq p_{\text{true}}(\text{NN})$

The distribution of the scaled sim. is not correct.

Uncertainties for a NN-based analysis

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Precision / Optimality: $\text{NN}(x) \neq \frac{p_{\text{true}}(x|S+B)}{p_{\text{true}}(x|B)}$

limited training statistics

$p_{\text{train}}(x) \neq p_{\text{true}}(x)$

inaccurate training data

$\text{NN}(x)|_{p_{\text{true}}=p_{\text{train}}} \neq \frac{p_{\text{true}}(x|S+B)}{p_{\text{true}}(x|B)}$

model/optimization flexibility

Statistical uncertainty

Systematic uncertainty

limited prediction statistics

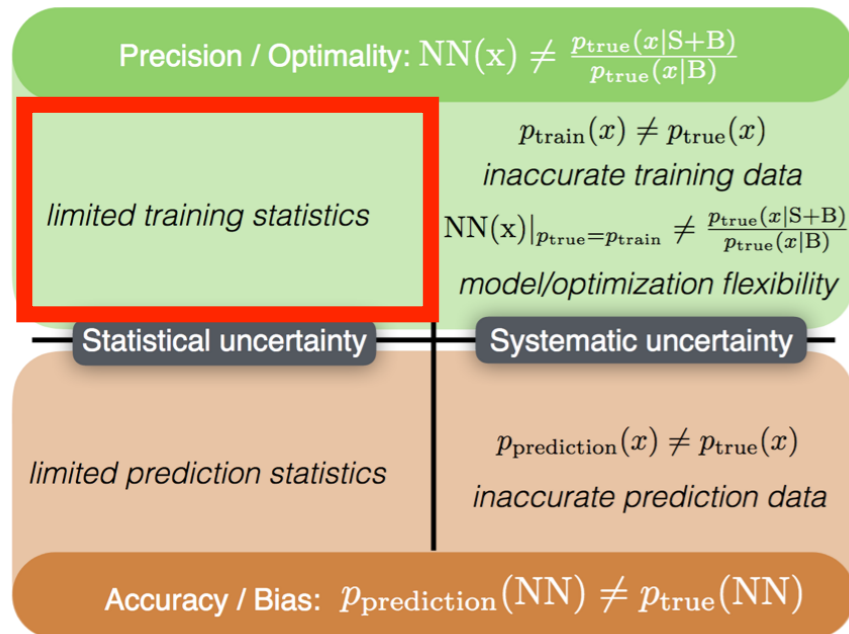
$p_{\text{prediction}}(x) \neq p_{\text{true}}(x)$

inaccurate prediction data

Accuracy / Bias: $p_{\text{prediction}}(\text{NN}) \neq p_{\text{true}}(\text{NN})$

How to estimate precision stat. uncerts.

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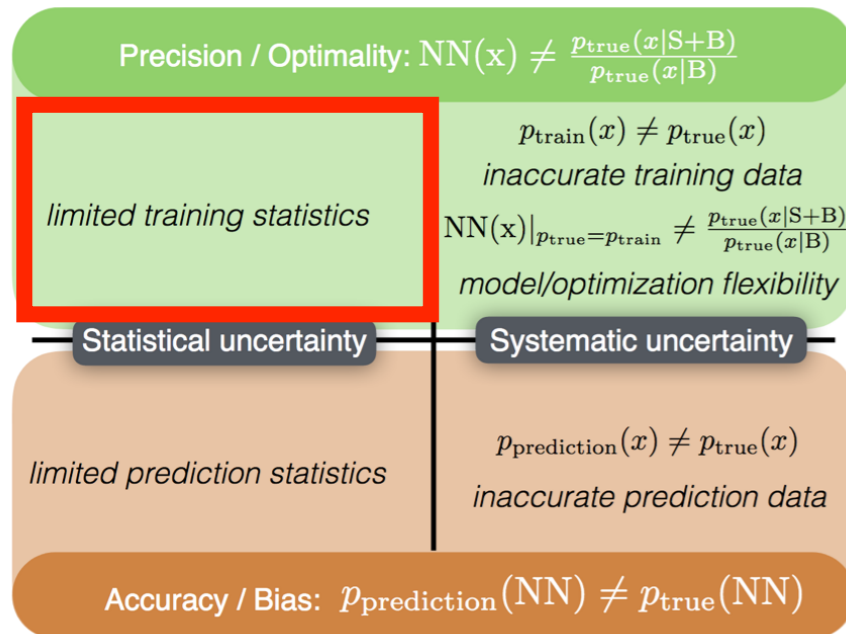
You can always accomplish this by bootstrapping: making pseudo-datasets from resampling and then retraining.

It is important to fix the NN initialization so that you are not also testing your sensitivity to that.

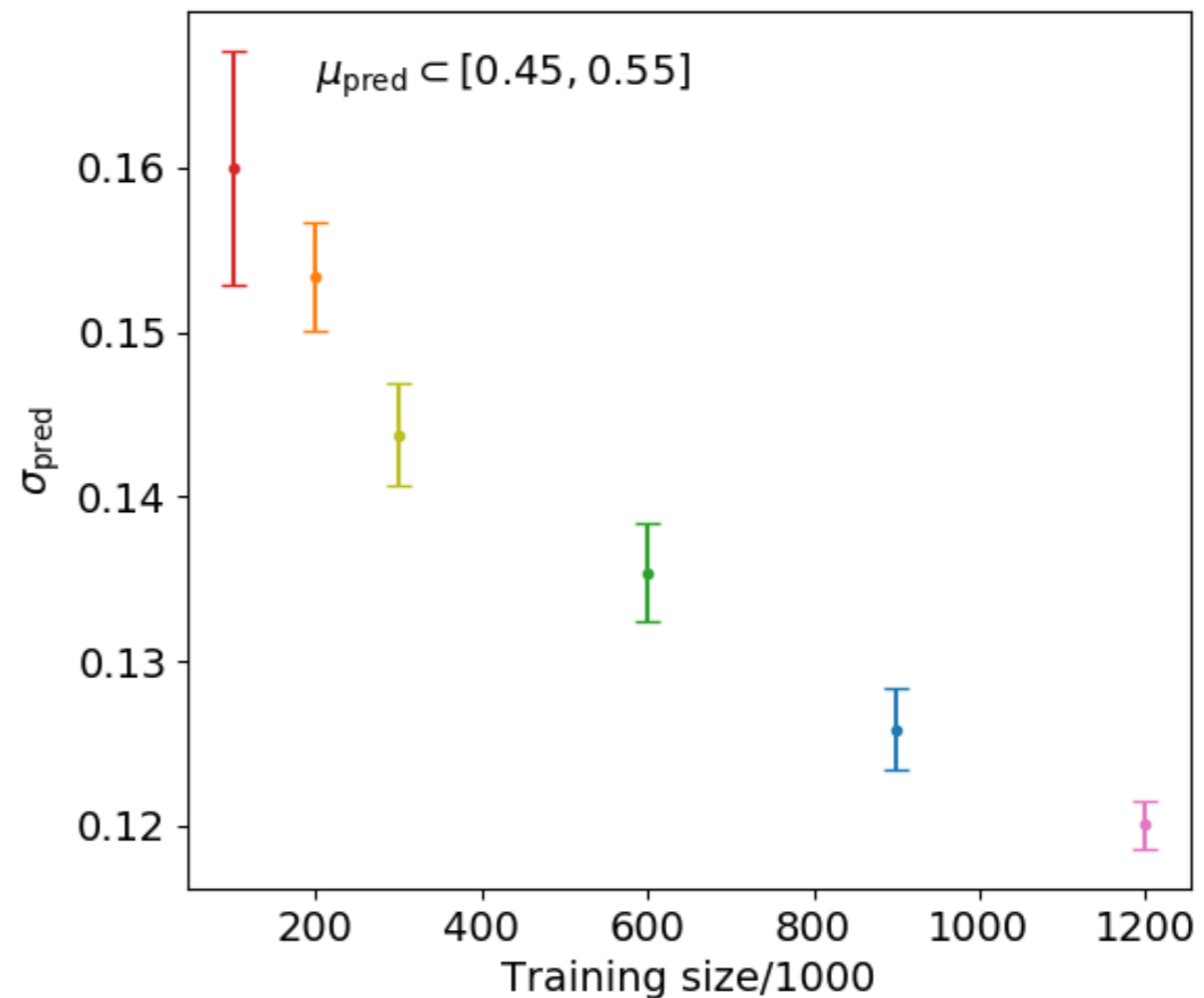
This can be painful because it requires retraining many NNs.

How to estimate precision stat. uncerts.

171



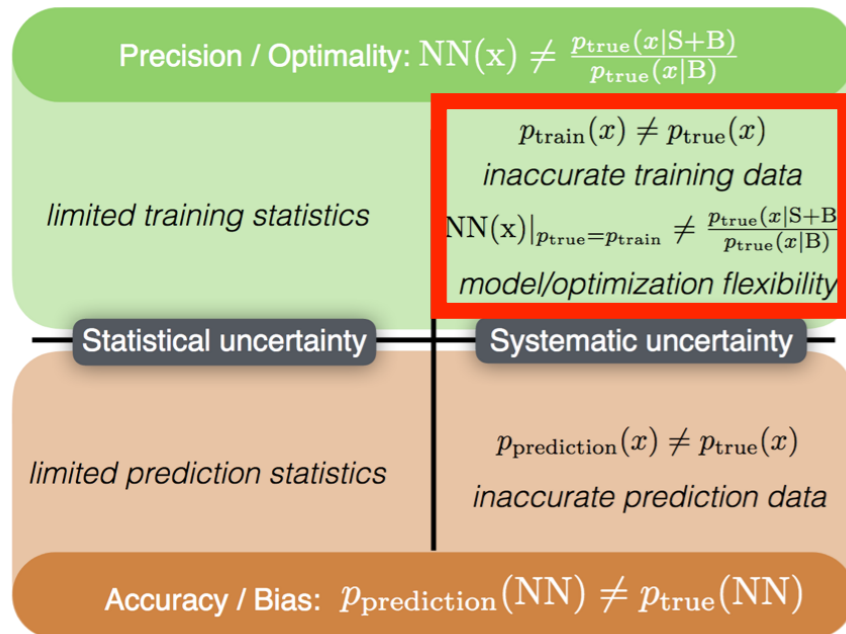
Alternative: train **one** Bayesian NN?!



S. Bollweg, M. Haußmann, G. Kasieczka, M. Luchmann, T. Plehn, J. Thompson, 1904.10004

How to estimate precision syst. uncerts.

172



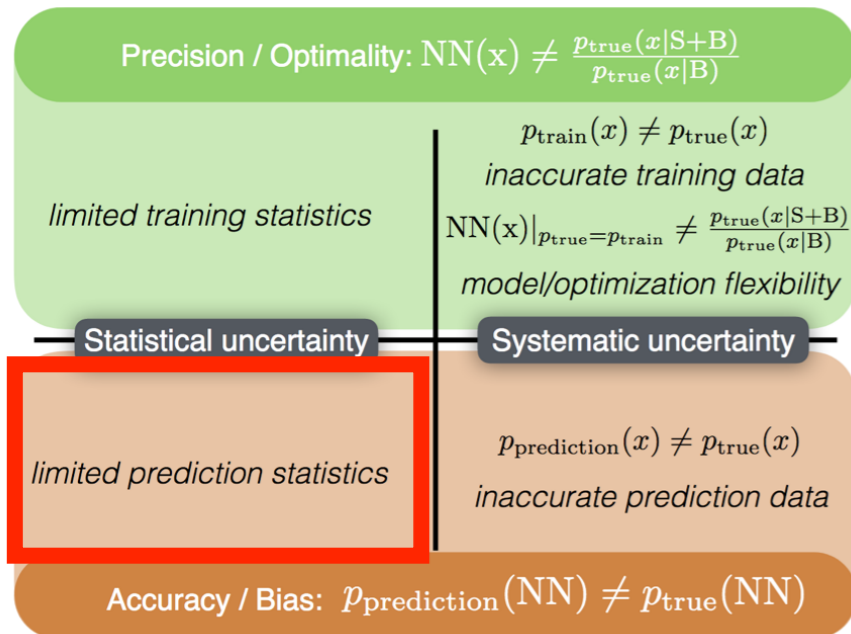
As with all systematic uncertainties, this is hard to quantify.

One component is due to the modeling of $p(x)$ - more on this later.

Testing the flexibility of the network requires checking the sensitivity to the architecture (#layers, nodes/layer, etc.), the initialization, the training procedure (#epochs, learning rate, etc.)

How to estimate bias stat. uncerts.

173

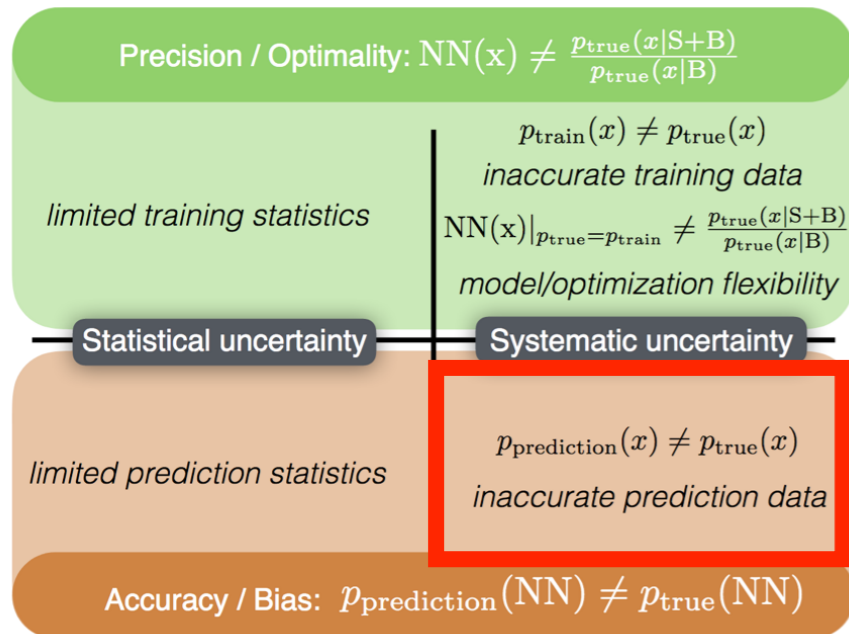


This uncertainty is post-training - Bayesian NNs unfortunately won't help.

Unfortunately, this is often not small given that we are now probing extreme final states and have a limited computing budget.

How to estimate bias syst. uncerts.

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This is the trickiest one...

...because we need the uncertainty on the modeling of x and x can be high-dimensional!

In many cases, the uncertainties factorize, e.g. the uncertainty on the jet energy is measured and evaluated per jet.

What about physics modeling uncertainties where we usually have a two-point comparison? (e.g. Pythia versus Herwig)

High-dimensional Bias Uncertainties

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One word of caution: current paradigm for uncertainties may be too naive for high-dimensional analysis!

(truly end-to-end)

e.g. for some uncertainties, we often compare two different models - one nuisance parameter.

How can we even see how sensitive we are to high-dimensional effects?

One word of caution: current paradigm for uncertainties may be too naive for high-dimensional analysis!

(truly end-to-end)

e.g. for some uncertainties, we often compare two different models - one nuisance parameter.

How can we even see how sensitive we are to high-dimensional effects?

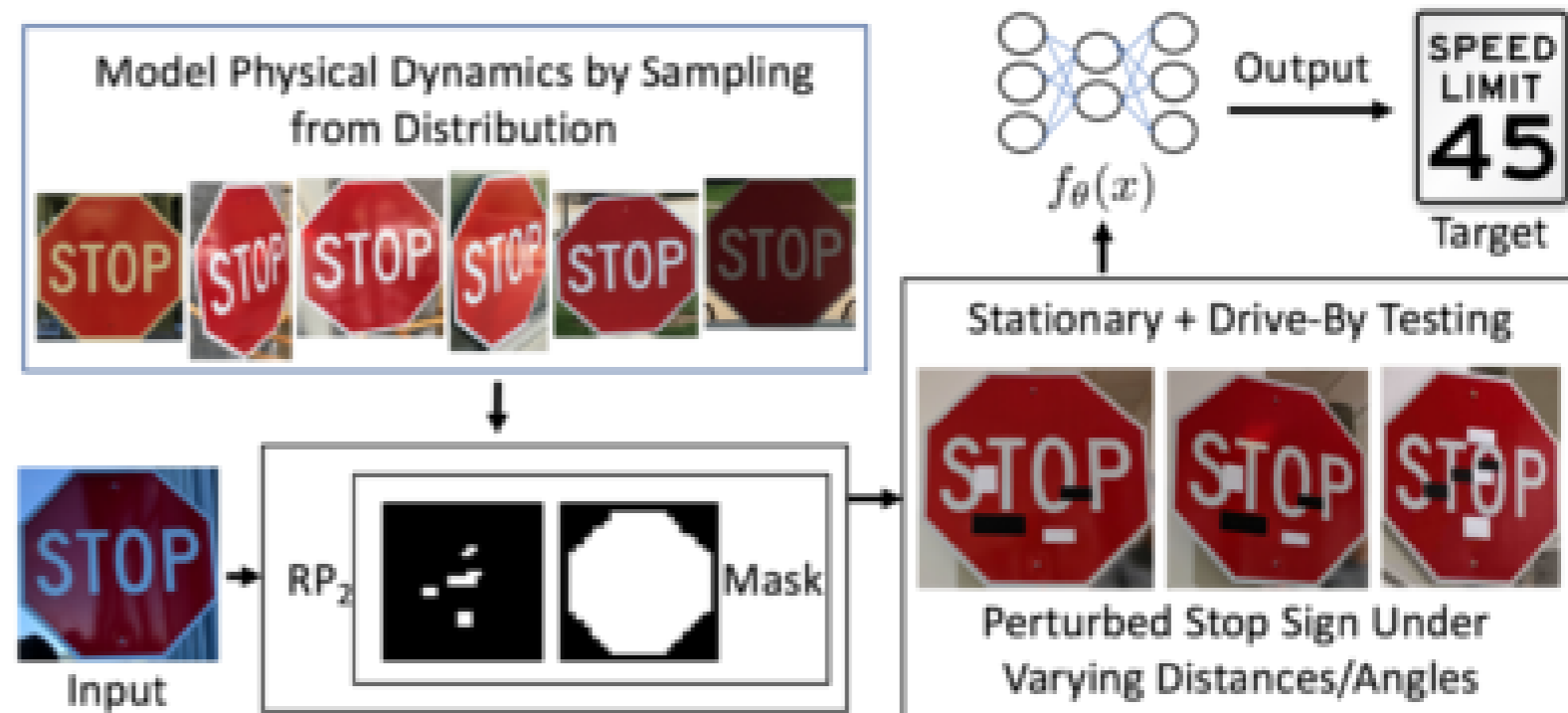
Answer: borrow tools from AI Safety



There is a vast literature on how easy it is to “attack” a NN.

They want to know: how subtle can an attack be and still significantly impact the output.

We know (hope?!) that nature is not evil, but these tools can help us probe the high-dimensional sensitivity of our NNs.



\mathbf{J} = jet (in all of its high-dimensional glory)

f = fixed classifier for signal vs. background

Loss

$$\mathcal{L}_{\text{sig}} = \log(1 - f(g(\mathbf{J}))),$$

$$\mathcal{L}_{\text{bg}} = \lambda_{\text{cls}} (f(\mathbf{J}) - f(g(\mathbf{J})))^2 + \sum_i \lambda_{\text{obs}}^{(i)} (\mathcal{O}^{(i)}(\mathbf{J}) - \mathcal{O}^{(i)}(g(\mathbf{J})))^2$$

g is a learned NN that maps \mathbf{J} to $\mathbf{J} + \delta\mathbf{J}$.

$\mathcal{O}(\mathbf{J})$ are observables that will be validated in the CR.

\mathbf{J} = jet (in all of its high-dim. uncertainty)

f = fixed classifier for signal

$$\mathcal{L}_{\text{sig}} = \log(1 - f(g(\mathbf{J})))$$
$$\mathcal{L}_{\text{bg}} = \lambda_{\text{cls}} (f(\mathbf{J}) - f(g(\mathbf{J})))$$
$$+ \sum_i \lambda_{\text{obs}}^{(i)} (\mathcal{O}^{(i)}(\mathbf{J}) - \mathcal{O}^{(i)}(g(\mathbf{J})))^2$$

Fun fact: this requires computing \mathbf{O} in the NN - now have GPU implementations of many standard observables!

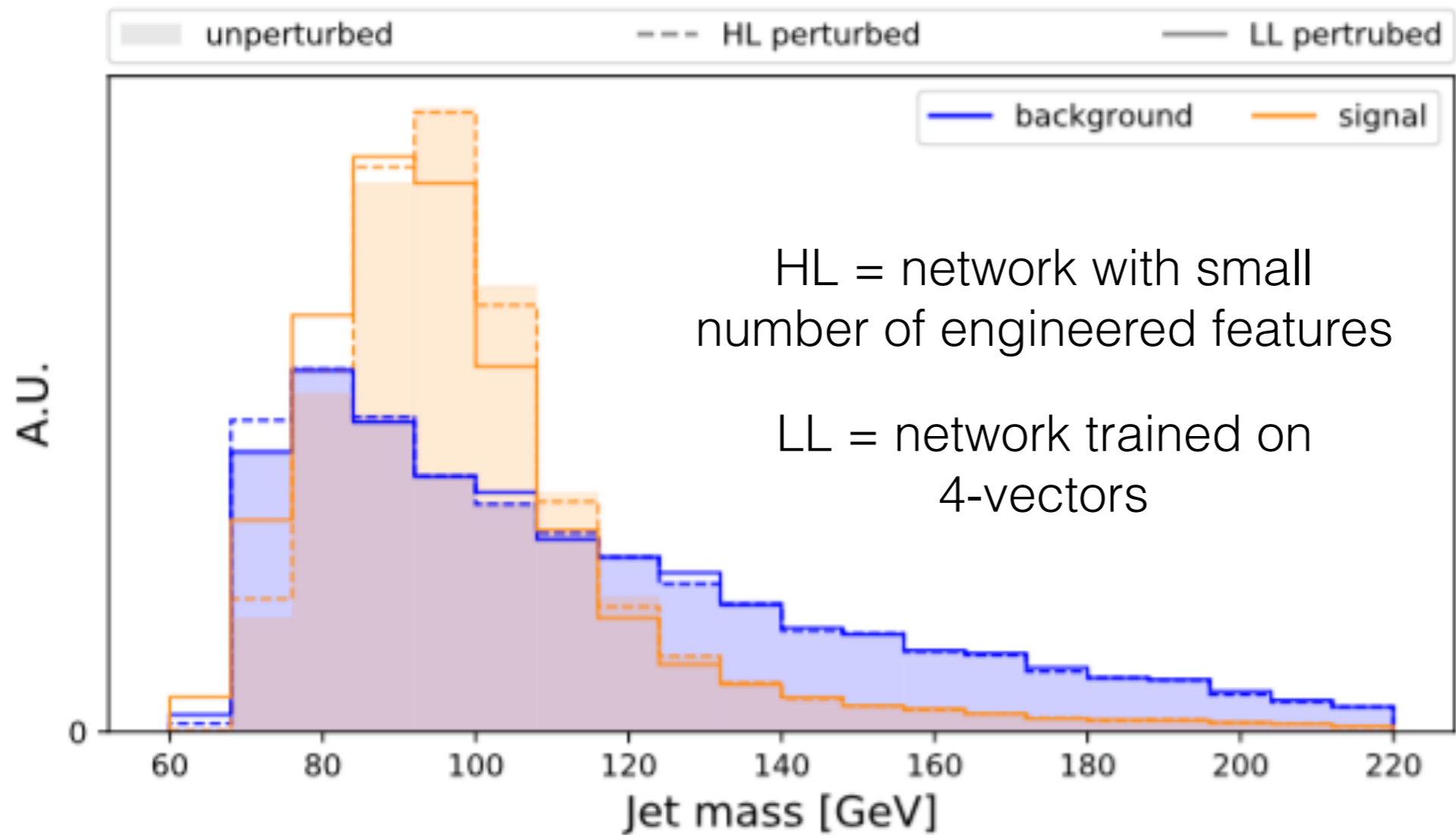
g is a learned NN that maps \mathbf{J} to $\mathbf{J} + \delta\mathbf{J}$.

$\mathbf{O}(\mathbf{J})$ are observables that will be validated in the CR.

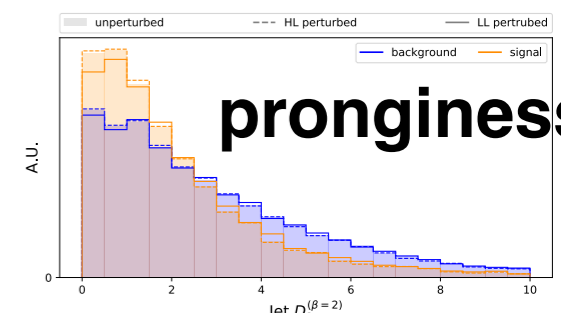
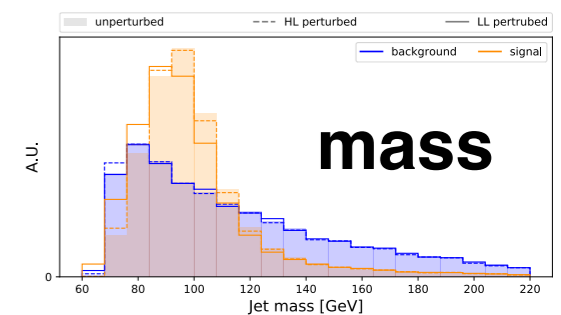
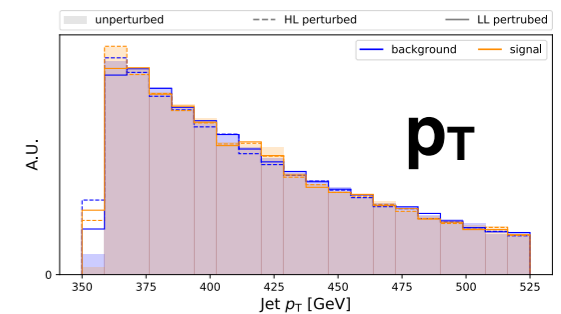
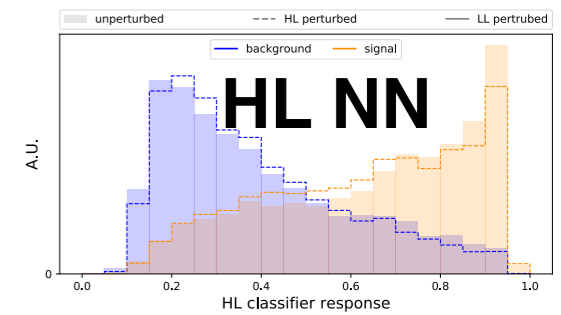
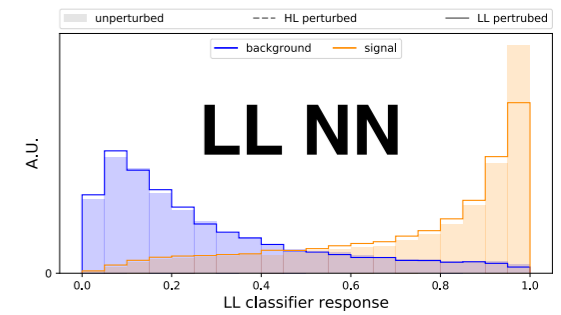
High-dimensional Uncertainty



Example case: Boosted Z's versus QCD

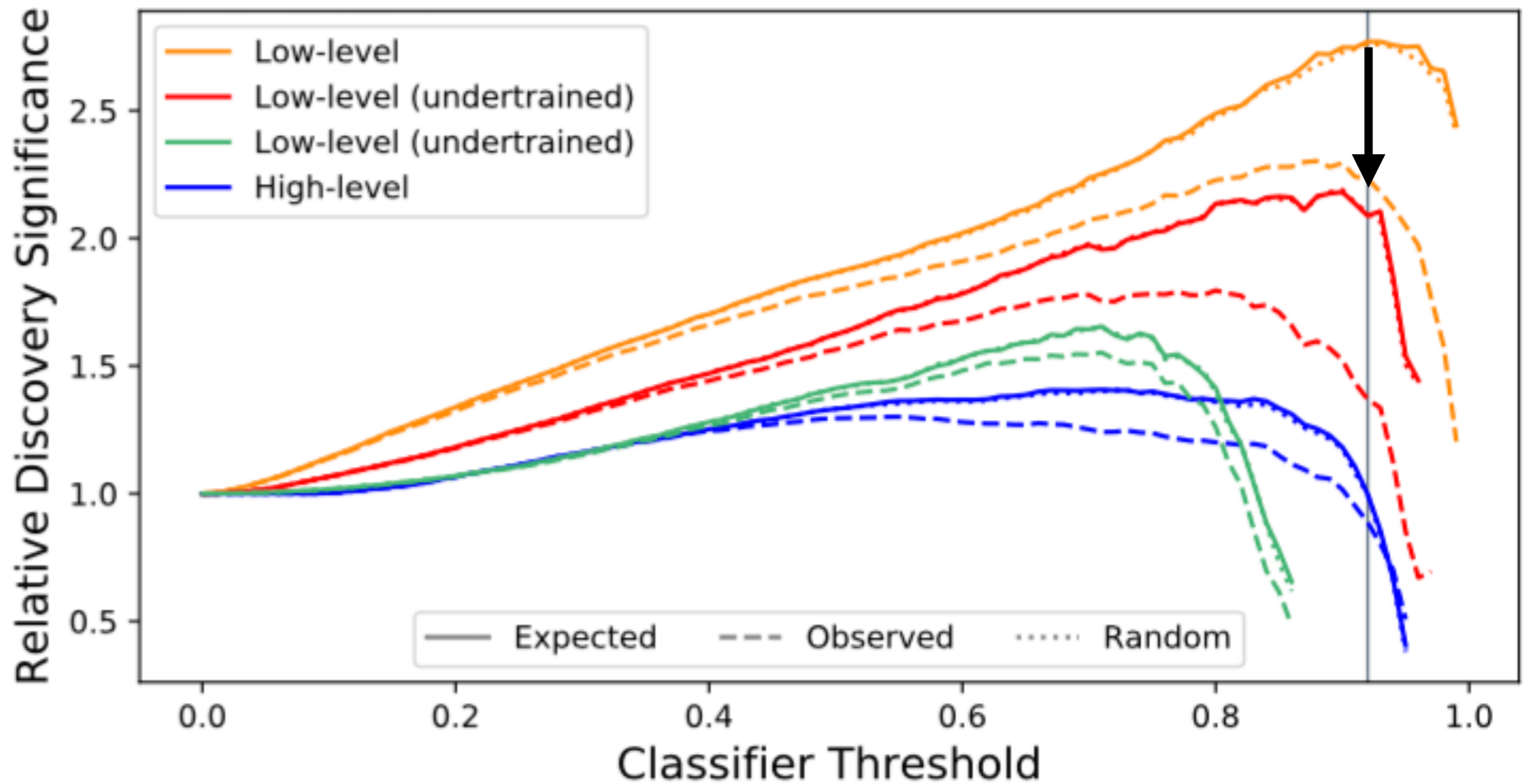


It is “easy” to preserve the blue and modify the orange.



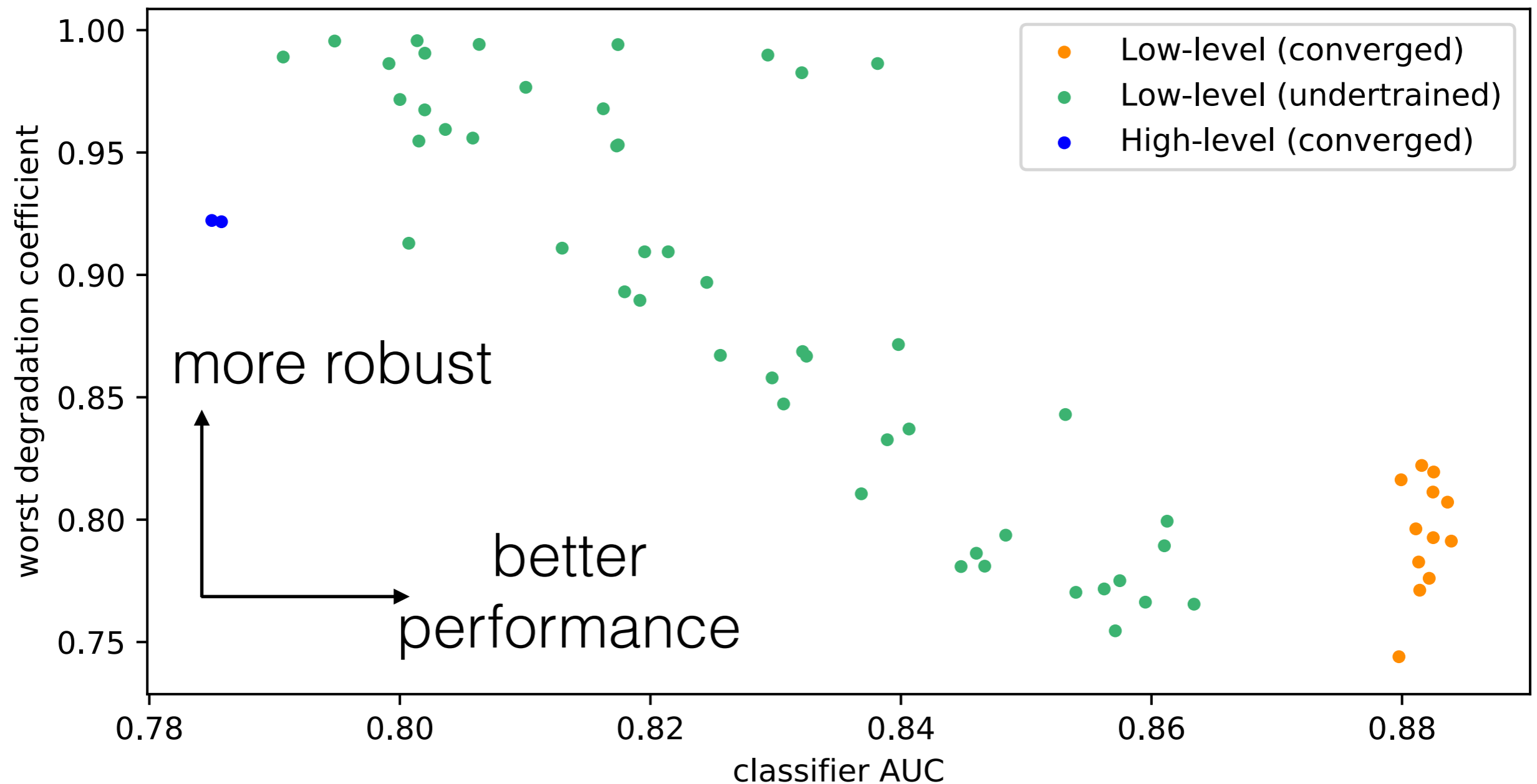
High-dimensional Uncertainty

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High-dimensional Uncertainty

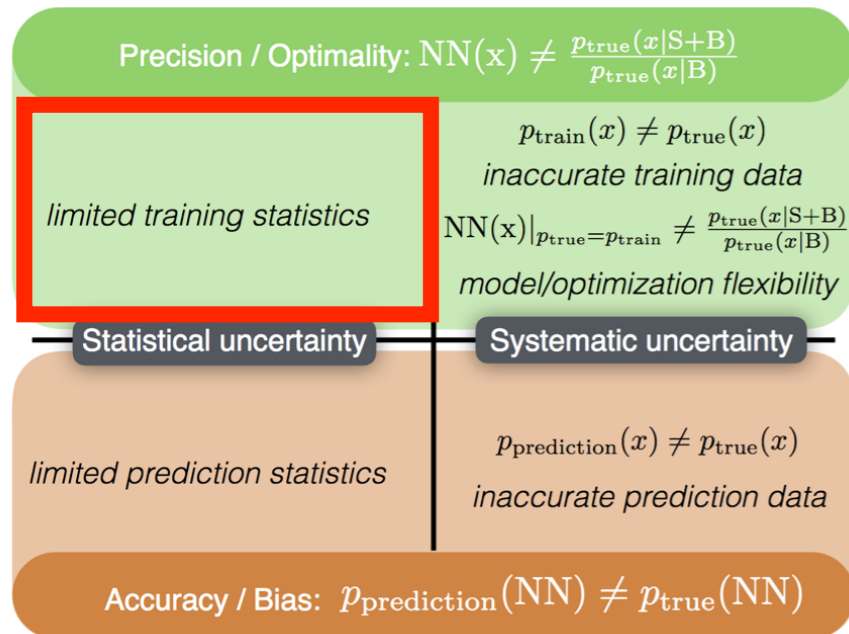
Under training may help with robustness:



Perturbed significance improvement / nom. sig. improvement

How to reduce precision stat. uncerts.

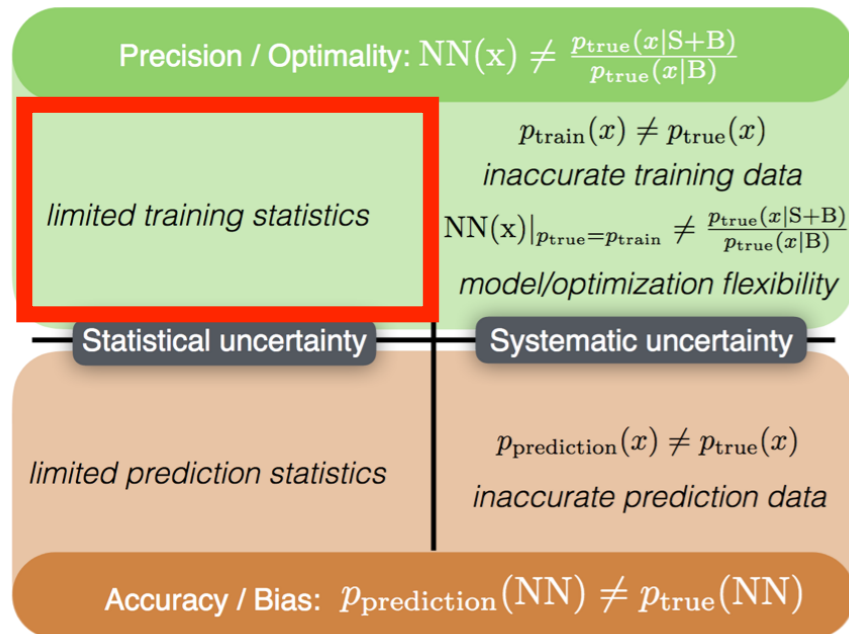
183



Train with more events!

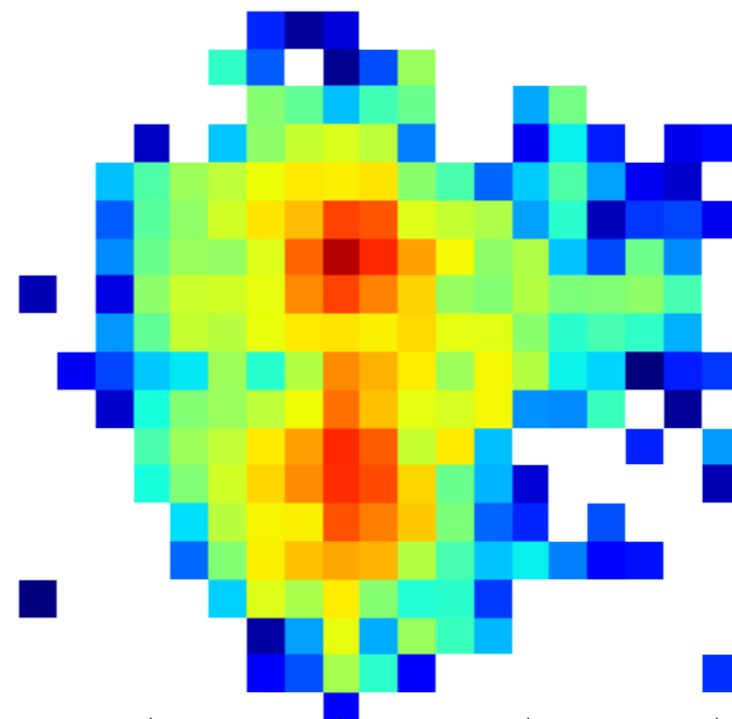
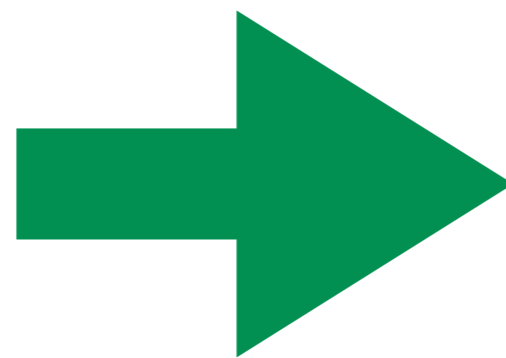
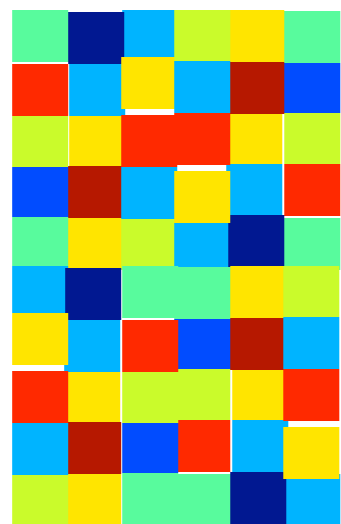
How to reduce precision stat. uncerts.

184



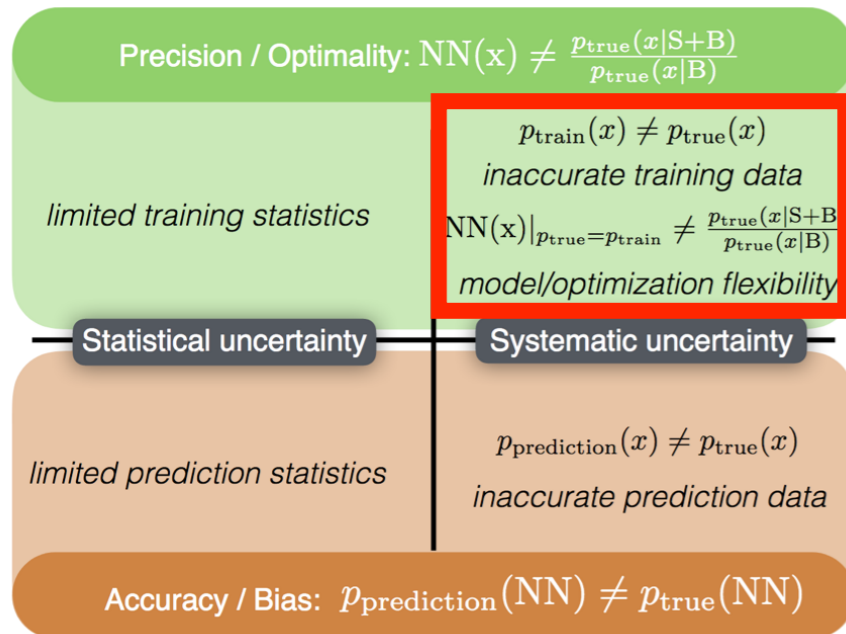
Train with more events!

...maybe use NN's to help with that



How to reduce precision syst. uncerts.

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You might be tempted to force the NN to not depend on some uncertain parameters.

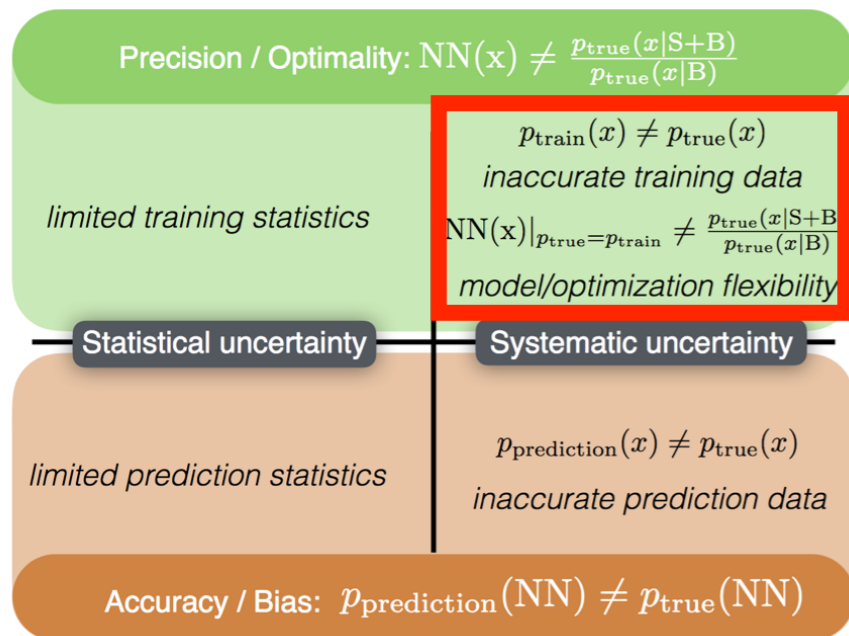
There are many ways to do this, e.g. adversarial techniques¹ or DisCo²

Unless this is needed to estimate the background³, this is usually suboptimal and may not even reduce the uncertainty.

1. G. Louppe, M. Kagan, K. Cranmer, 1611.01046
2. Gregor Kasieczka and D. Shih, 2001.05310
3. C. Shimmin et al. Phys. Rev. D 96, 074034 (2017), and many others including (2)

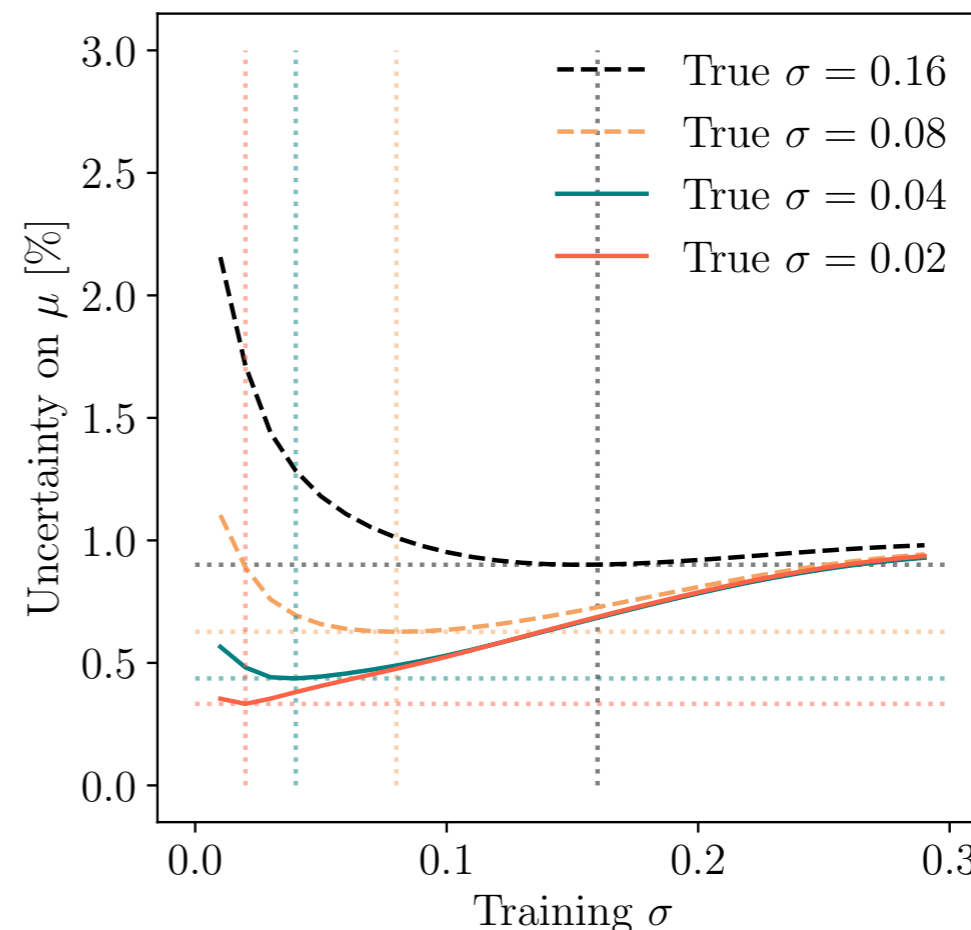
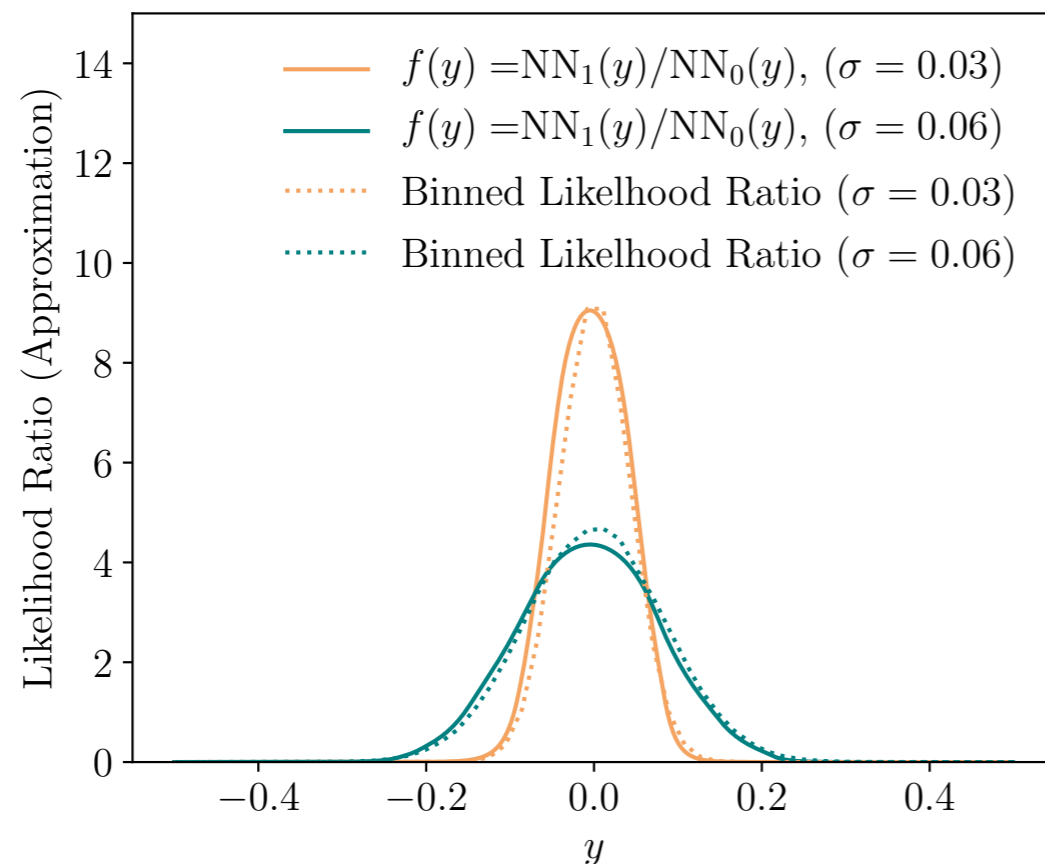
How to reduce precision syst. uncerts.

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Profiling instead of pivoting:

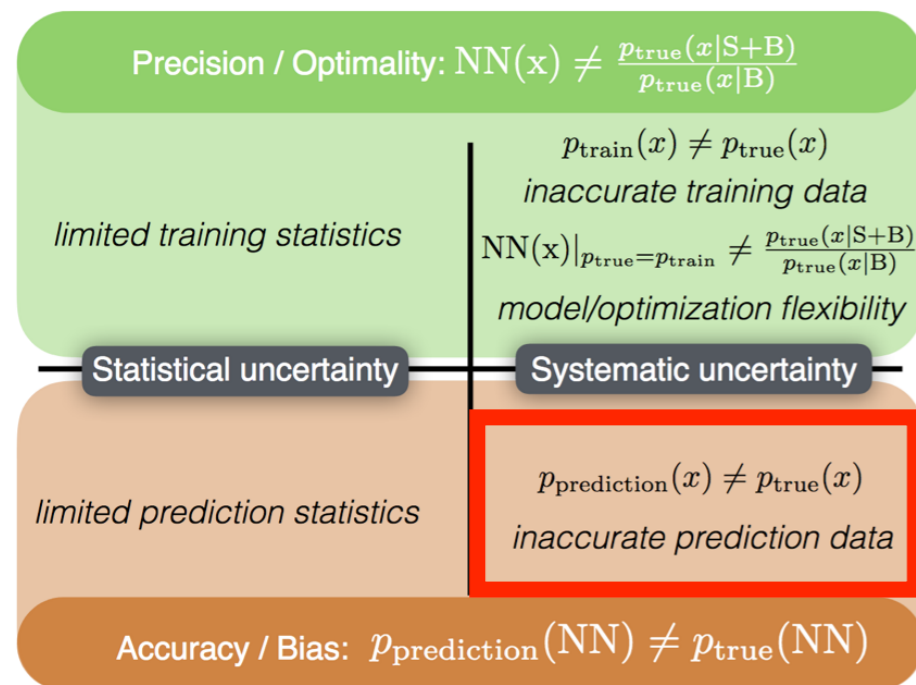
Better to do the opposite: let your NN **depend explicitly** on uncertainty quantities and then **profile them!**



How to get around high-D bias uncerts?

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Work hard to understand the true nuisance parameters in the hypervariate parameter space.



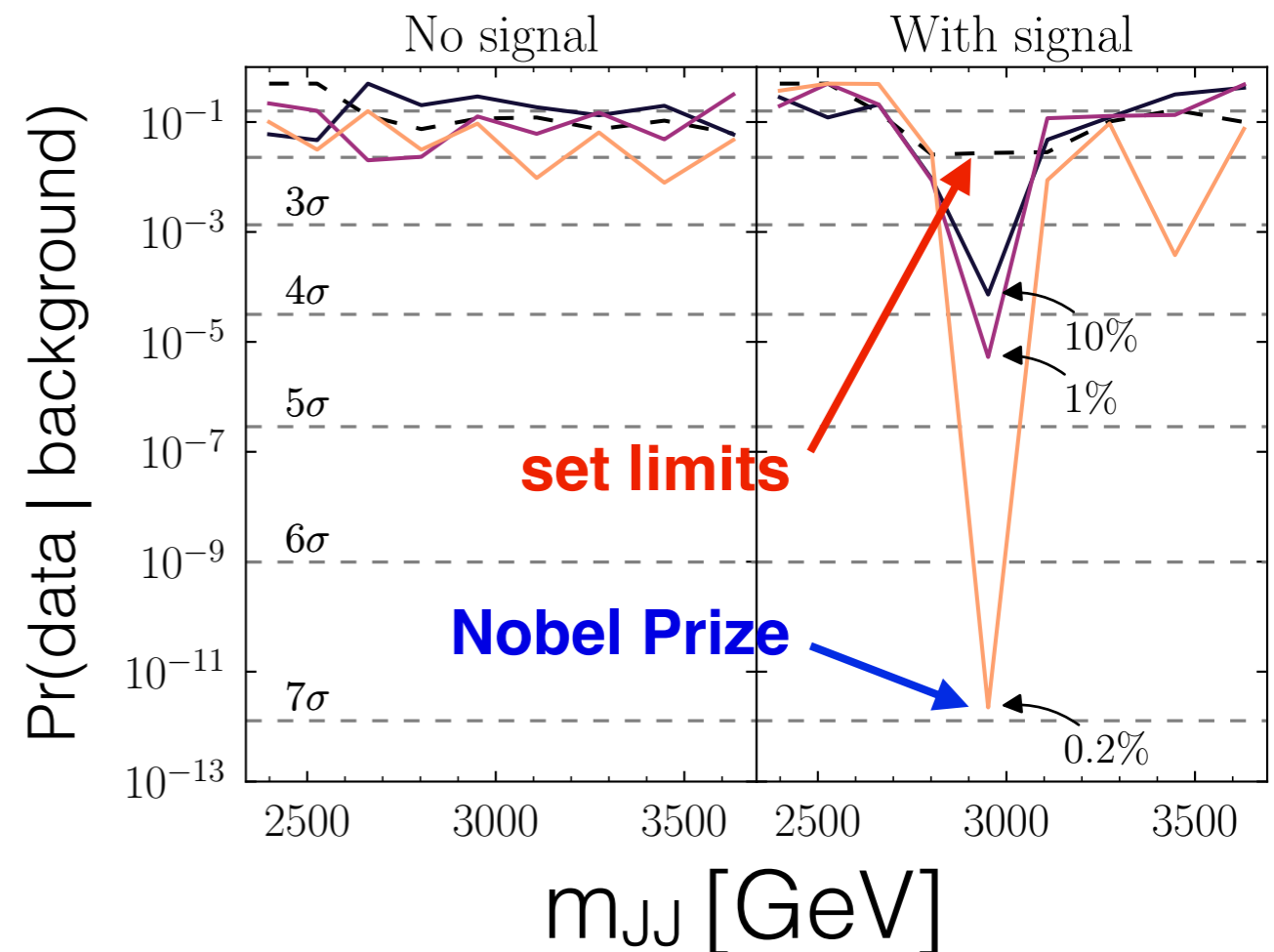
In my opinion, this is **THE** biggest challenge with deploying NN-based analyses ... solving it will require hard physics work.

How to get around high-D bias uncerts?

188

Work hard to understand the true nuisance parameters in the hypervariate parameter space.

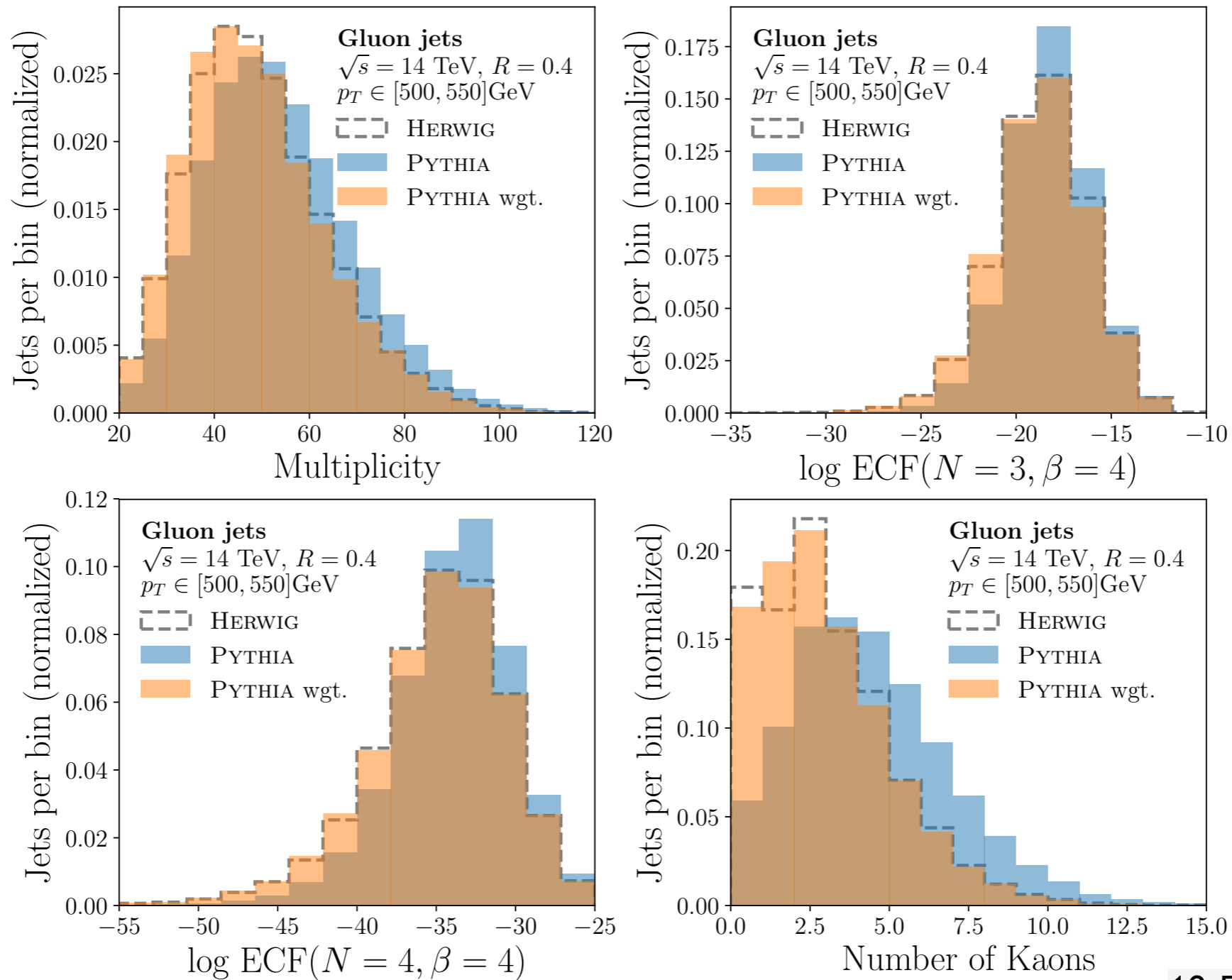
Don't use simulation!
(not always possible!)



Pythia versus Herwig



No hyper-parameter tuning - out of the box!

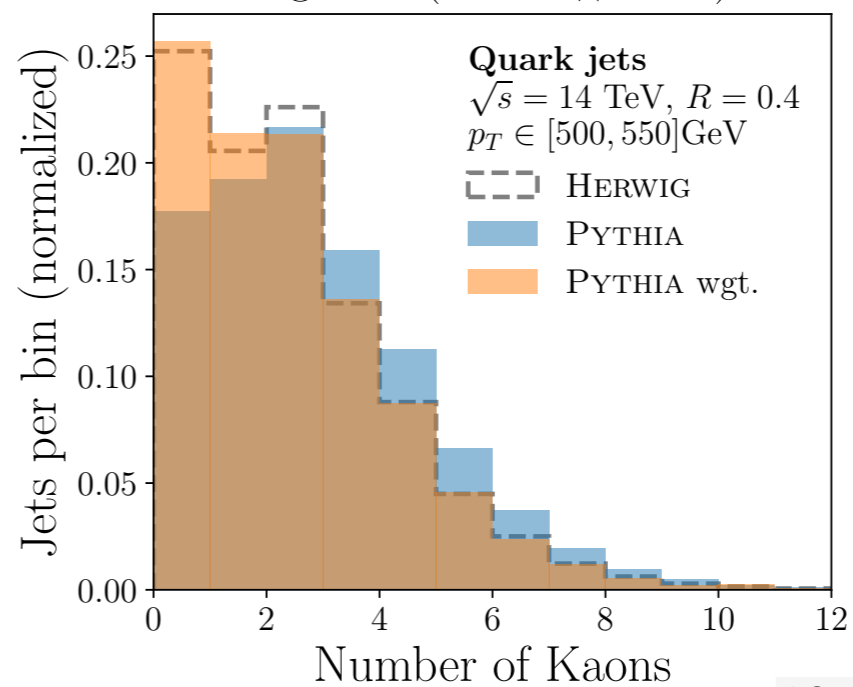
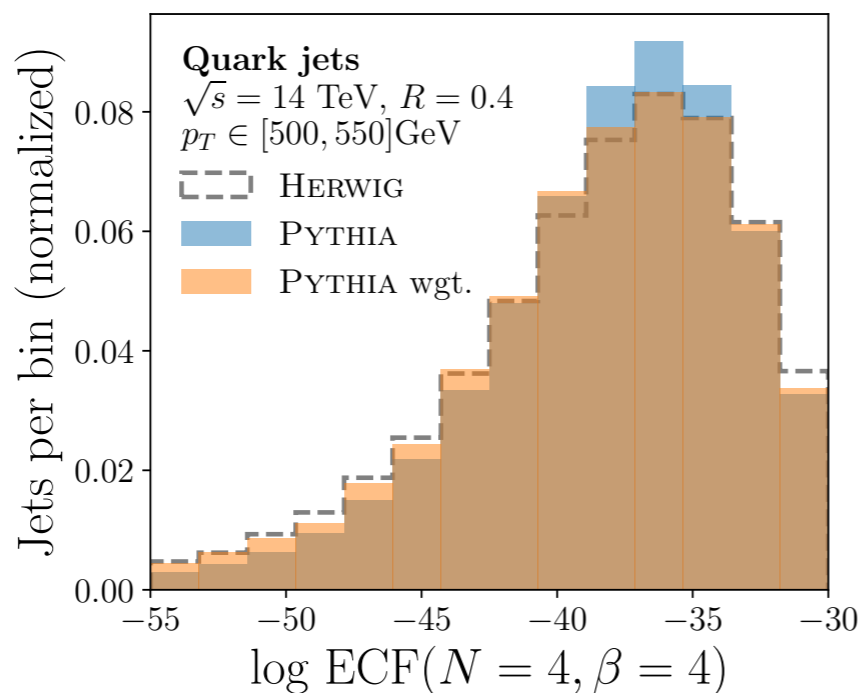
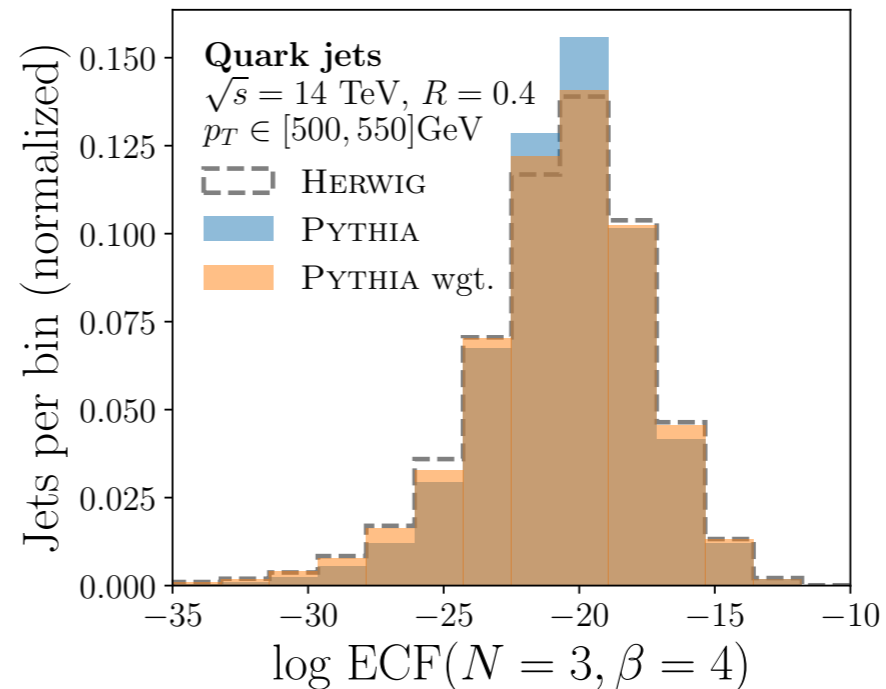
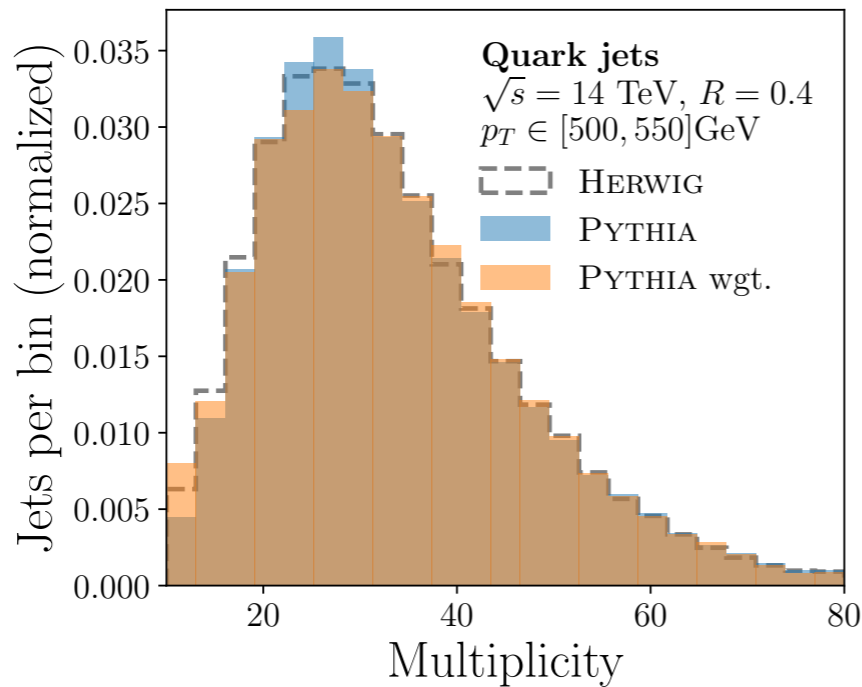


Samples from
[10.5281/zenodo.2658764](https://zenodo.org/record/2658764)
[10.5281/zenodo.3164691](https://zenodo.org/record/3164691)

Pythia versus Herwig



No hyper-parameter tuning - out of the box!



Samples from
[10.5281/zenodo.2658764](https://zenodo.org/record/2658764)
[10.5281/zenodo.3164691](https://zenodo.org/record/3164691)

More weak supervision: *Learn with proportions*

This is essentially a generalization of the template method.

Standard supervised learning

$$f_{\text{full}} = \operatorname{argmin}_{f': \mathbb{R}^n \rightarrow [0,1]} \sum_{i=1}^N \ell(f'(x_i) - t_i)$$

Weakly supervised learning

$$f_{\text{weak}} = \operatorname{argmin}_{f': \mathbb{R}^n \rightarrow [0,1]} \ell\left(\sum_{i=1}^N \frac{f'(x_i)}{N} - y\right)$$

Annotations for the full supervised learning equation:
- N : # of examples for training
- ℓ : loss fcn.
- t_i : labels
- $f'(x_i)$: neural network

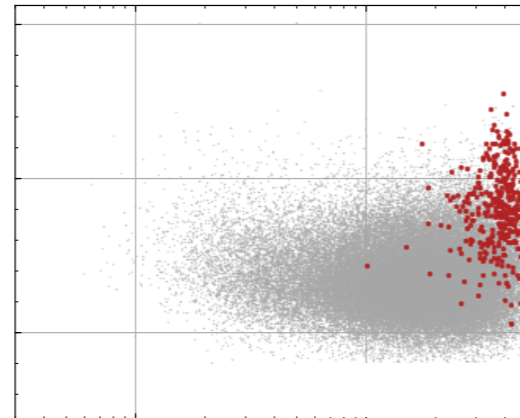
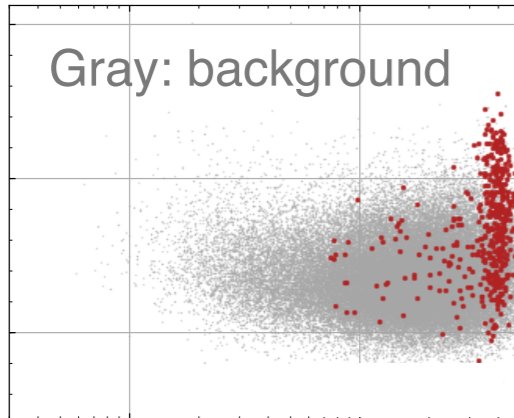
Annotation for the weakly supervised learning equation:
- y : proportions

What is the network learning?

Truth signal

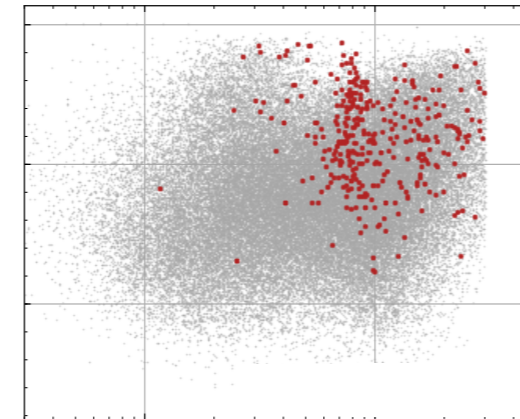
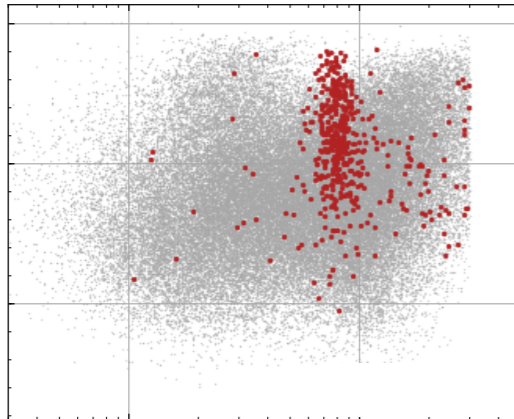
NN cut at 0.2%

Pr(4 prongs)



Heavier
Jet

Pr(2 prongs)

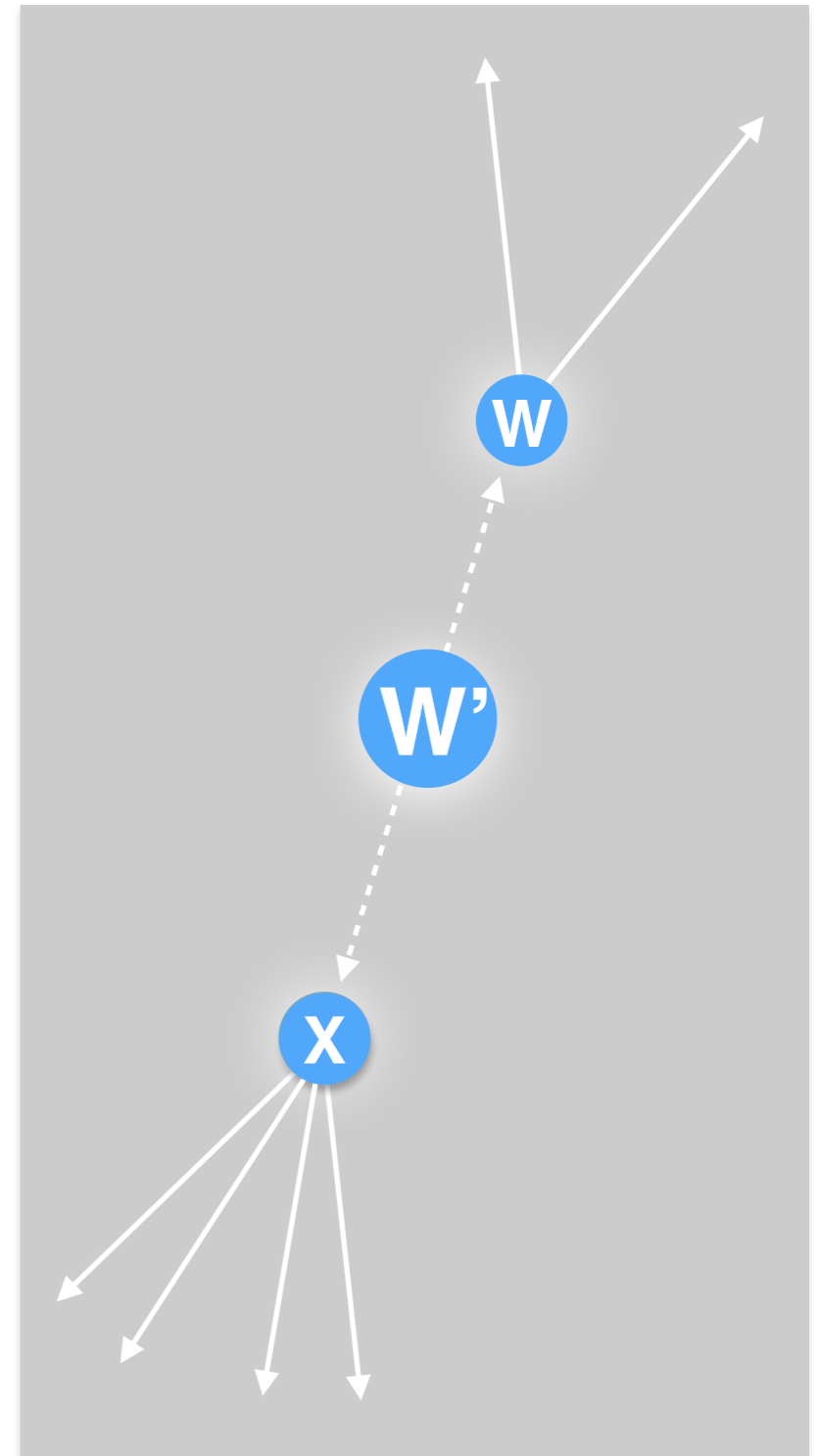


Lighter
Jet

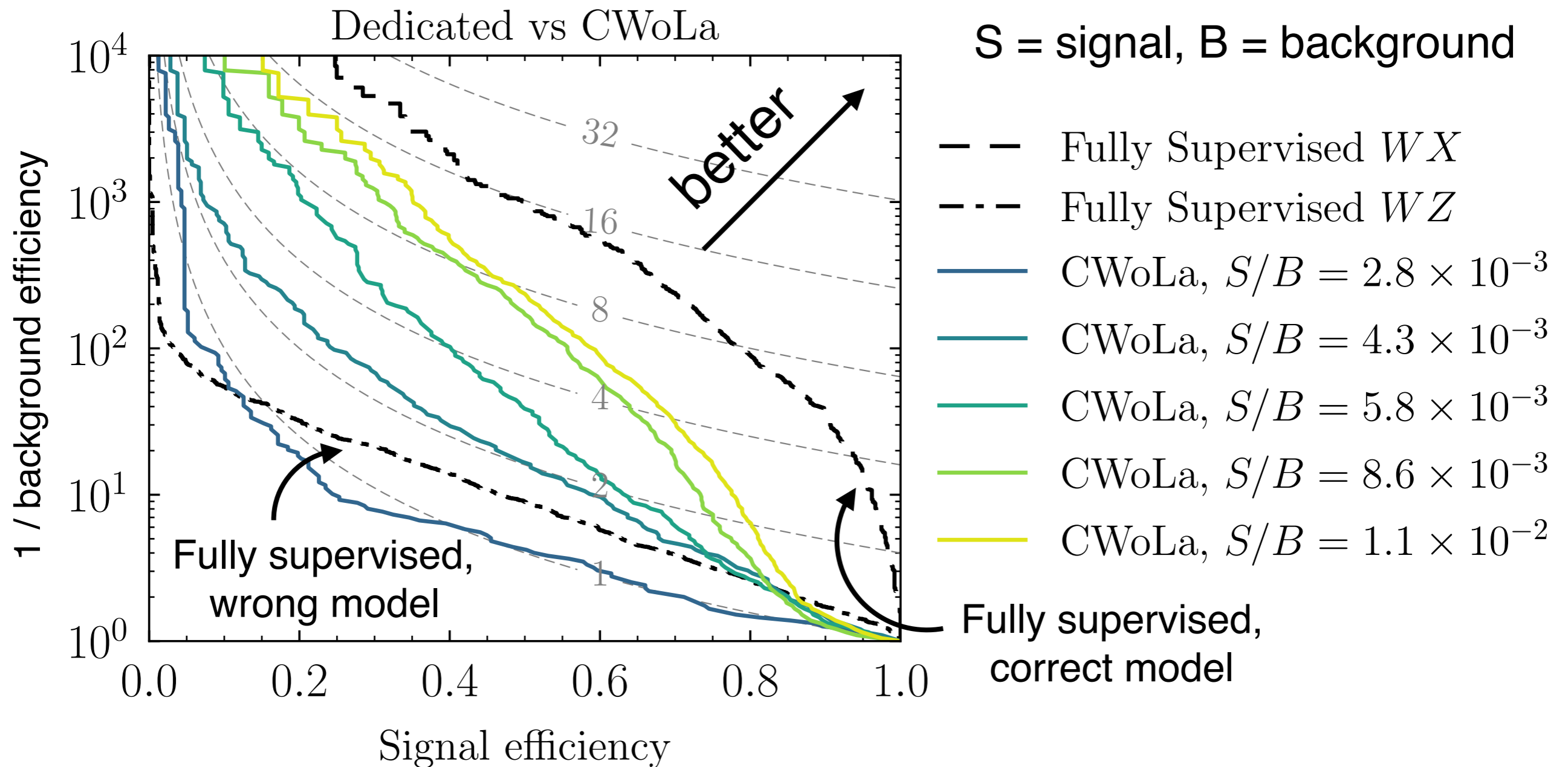
Mass

Mass

Learns to find the signal !



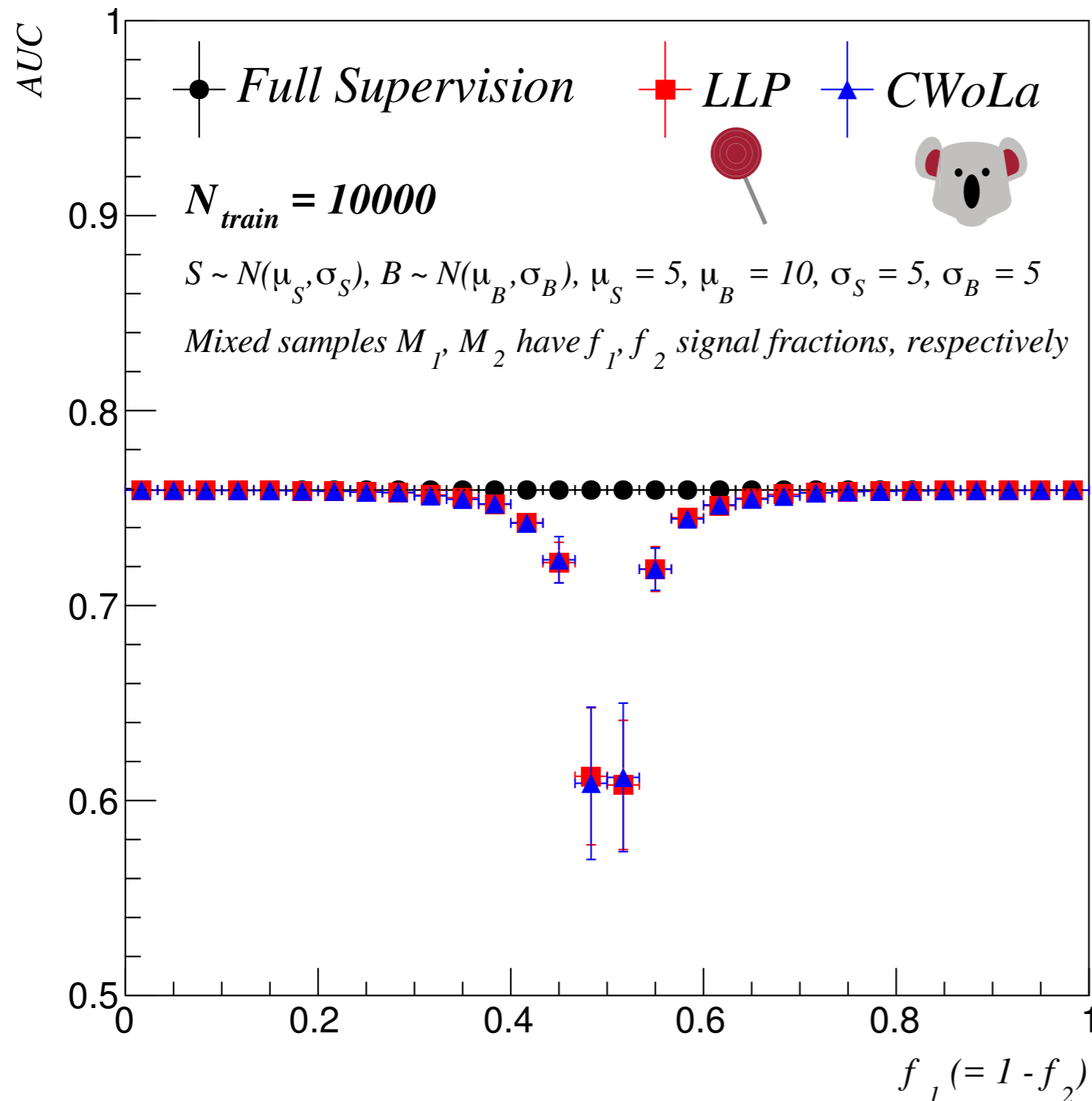
CWoLa hunting vs. Full Supervision



If you know what you are looking for, you should look for it. If you don't know, then CWoLa hunting may be able to catch it!

A note about training statistics

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Can't learn when the two proportions are the same.

The more similar they are, the worse the performance.
(lower effective statistics)

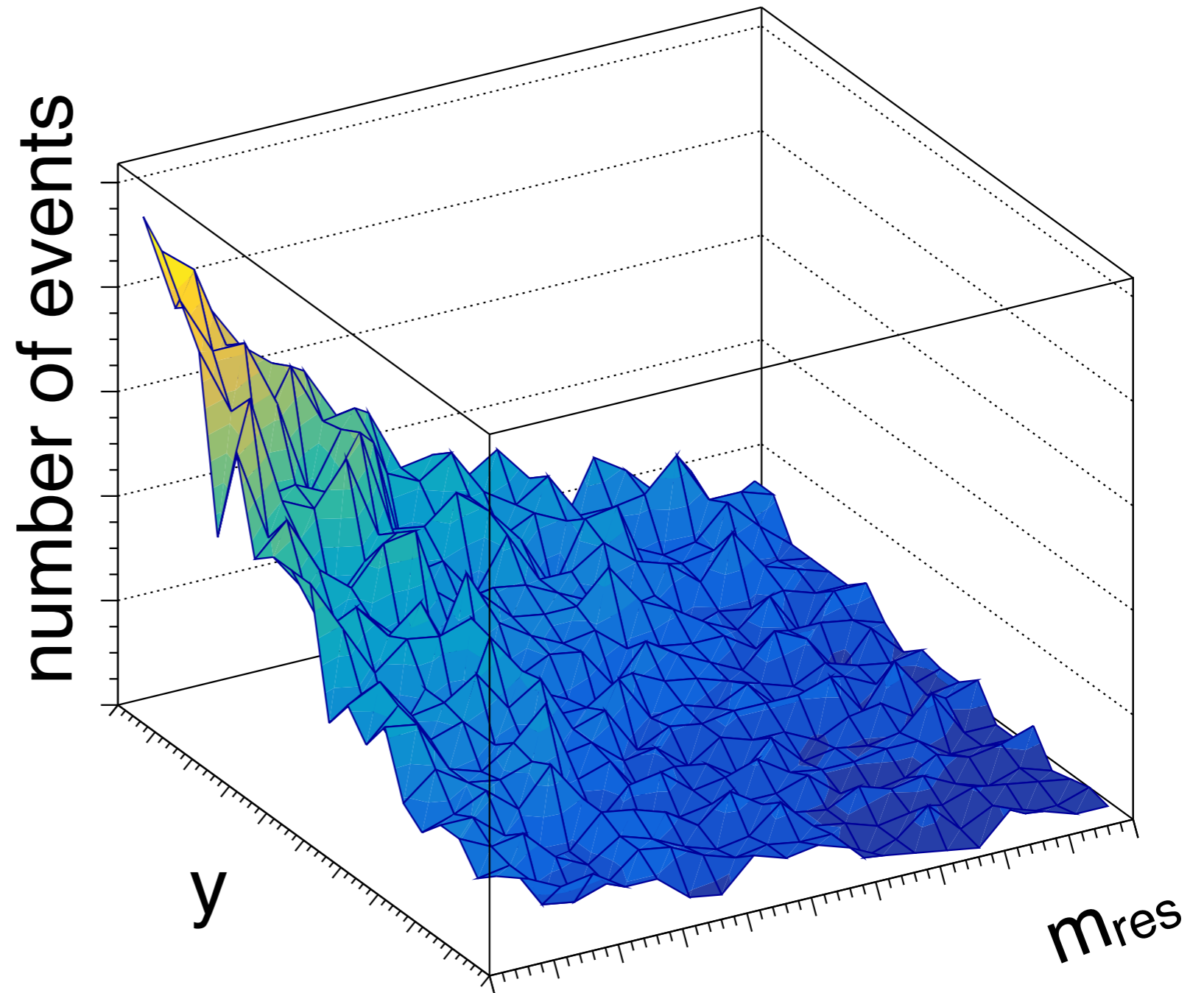
signal fraction of mixed sample 1

Overtraining & Look Elsewhere Effect*

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Naively, pay a huge penalty because y can be high-dimensional.

i.e. you will sculpt lots of bumps!



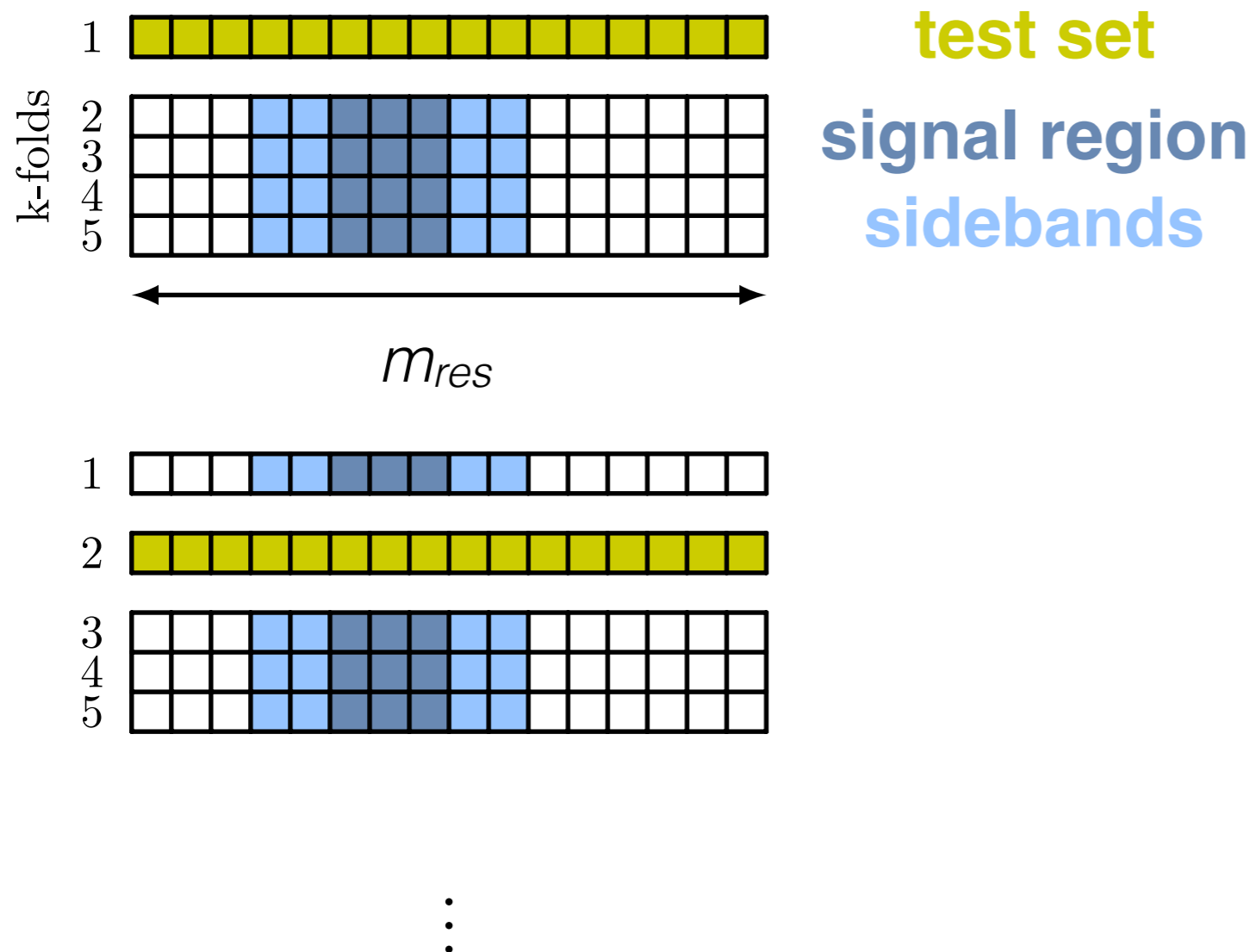
*you may know this as the multiple comparisons problem

Solution: **(nested) cross-training**

Nested cross-training

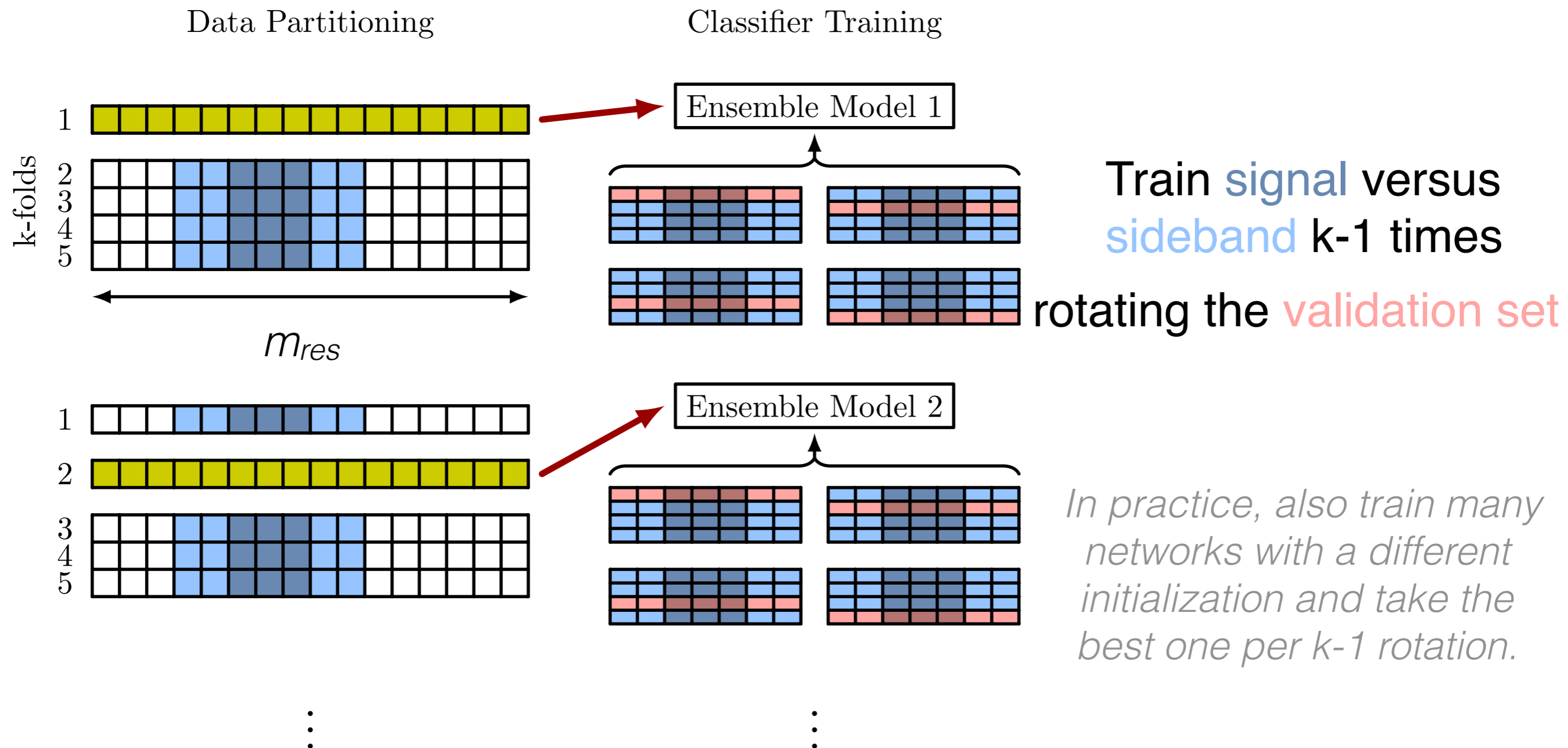
(1) Divide the entire dataset into k-folds.

Data Partitioning



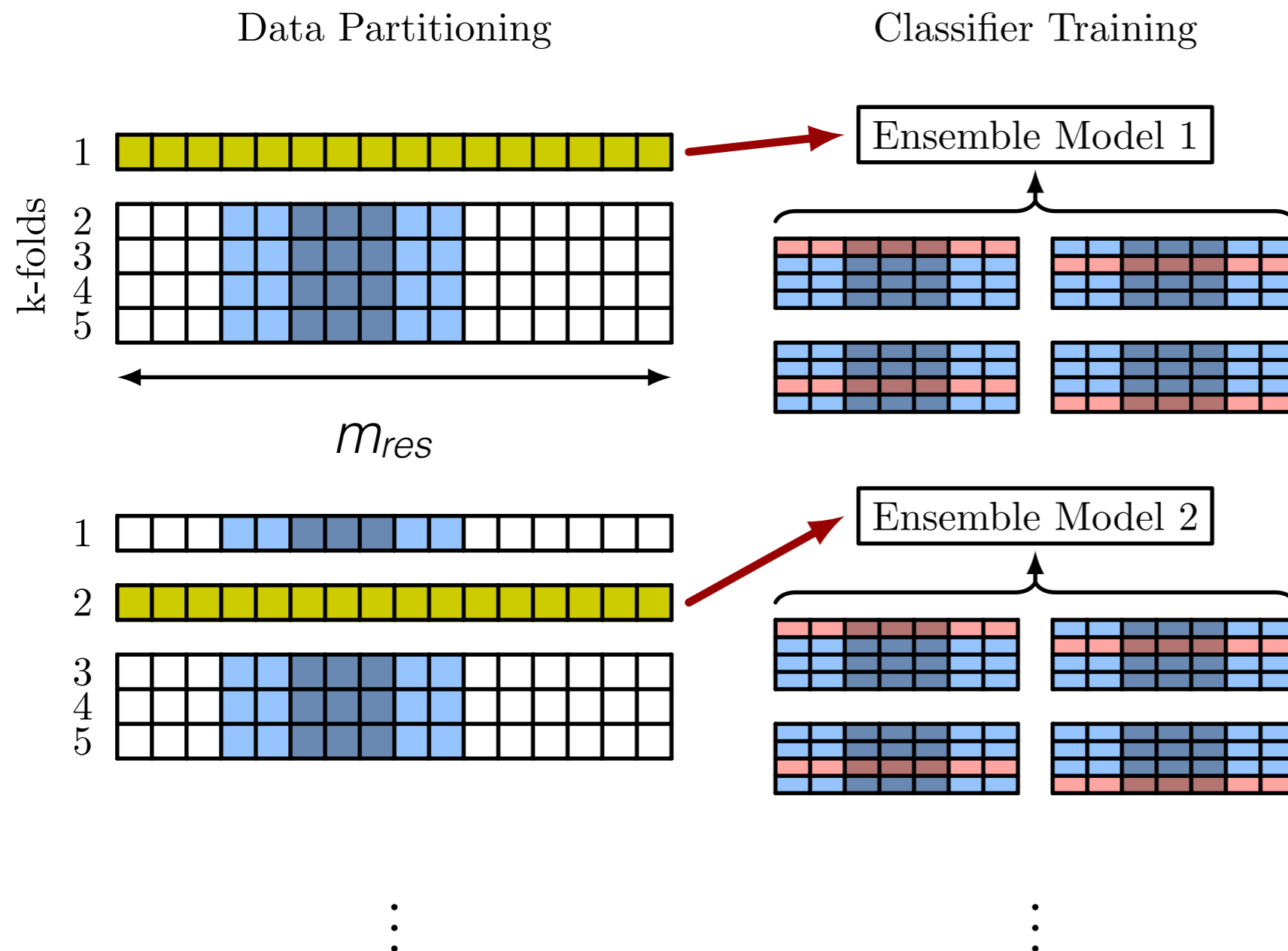
Nested cross-training

(2) Train CWoLa classifiers.



Nested cross-training

(2) Train CWoLa classifiers.

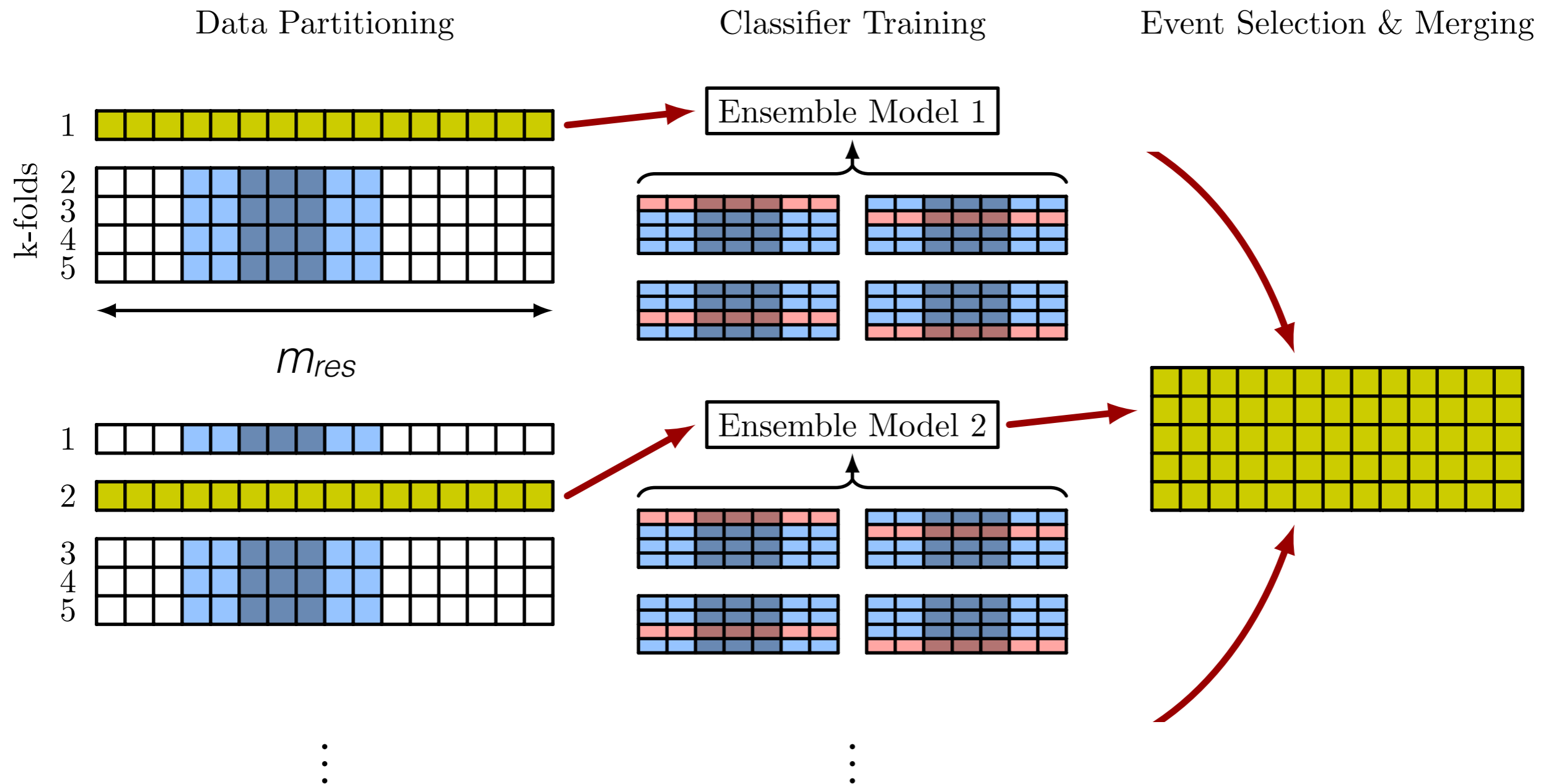


The **Ensemble Model** is just the average of the four networks.

Data fluctuations will cancel destructively while signal interferes constructively.

Nested cross-training

(3) Apply classifiers to holdout test sets and sum.

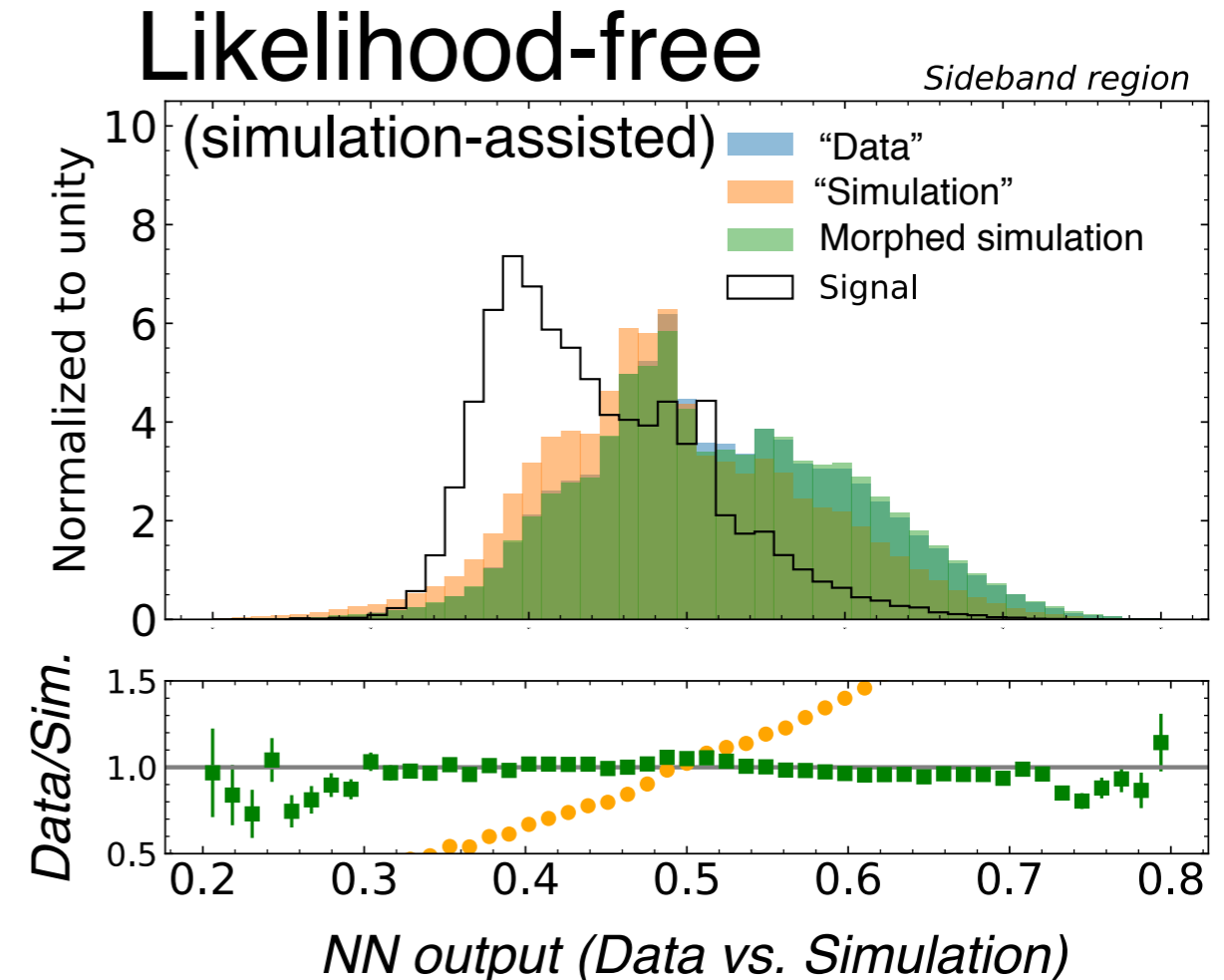
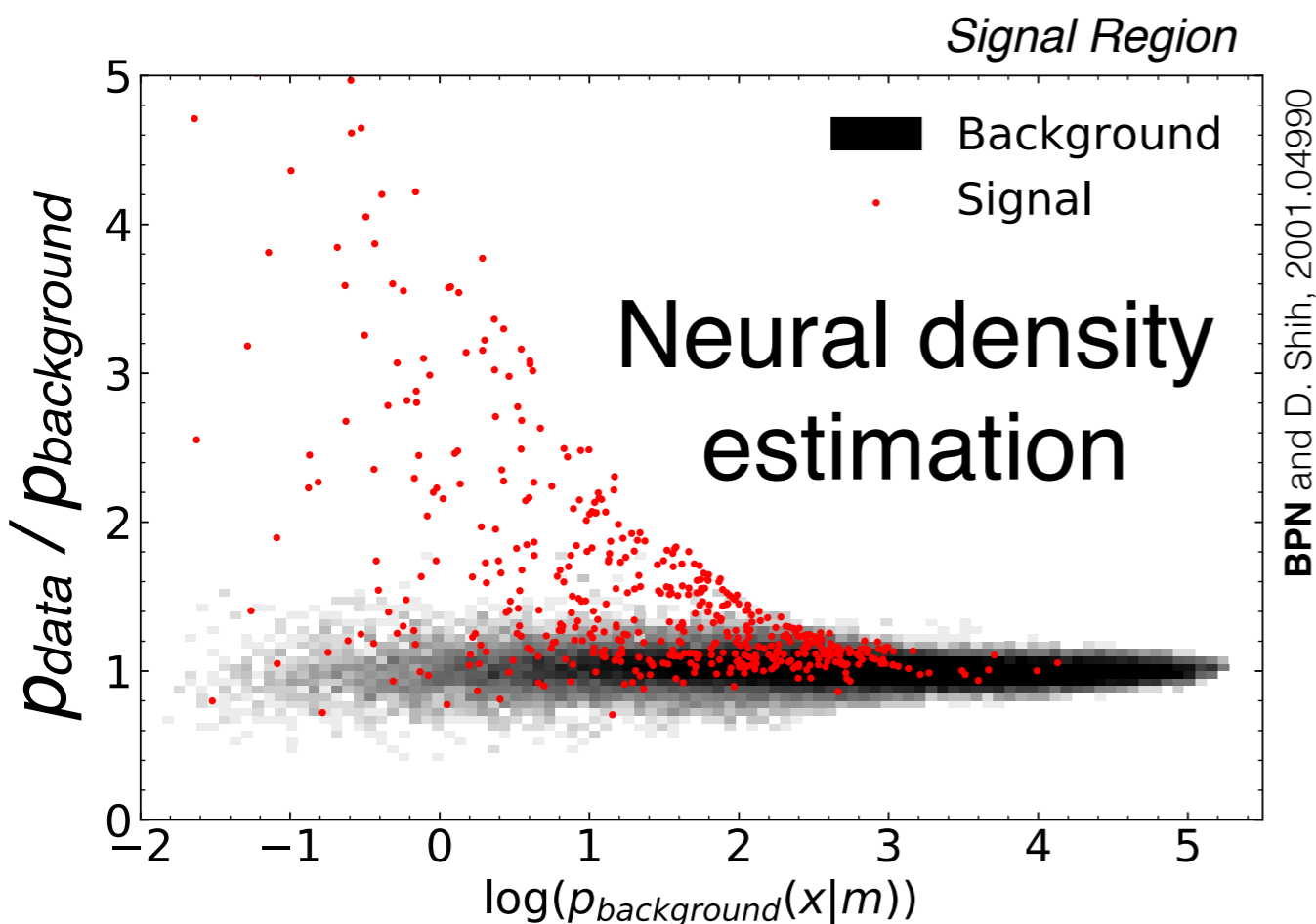


Extend techniques: Anomaly detection

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CWoLa hunting was the first of a growing number of new proposals.

e.g., CWoLa hunting doesn't work when there are strong correlations between y and m_{res} . New methods solve this!



New

Tying it all together: DCTR + anomalies

202

We want to reduce our dependence on simulation, but we also don't want to throw away our physics priors!

Tying it all together: DCTR + anomalies

We want to reduce our dependence on simulation, but we also don't want to throw away our physics priors!

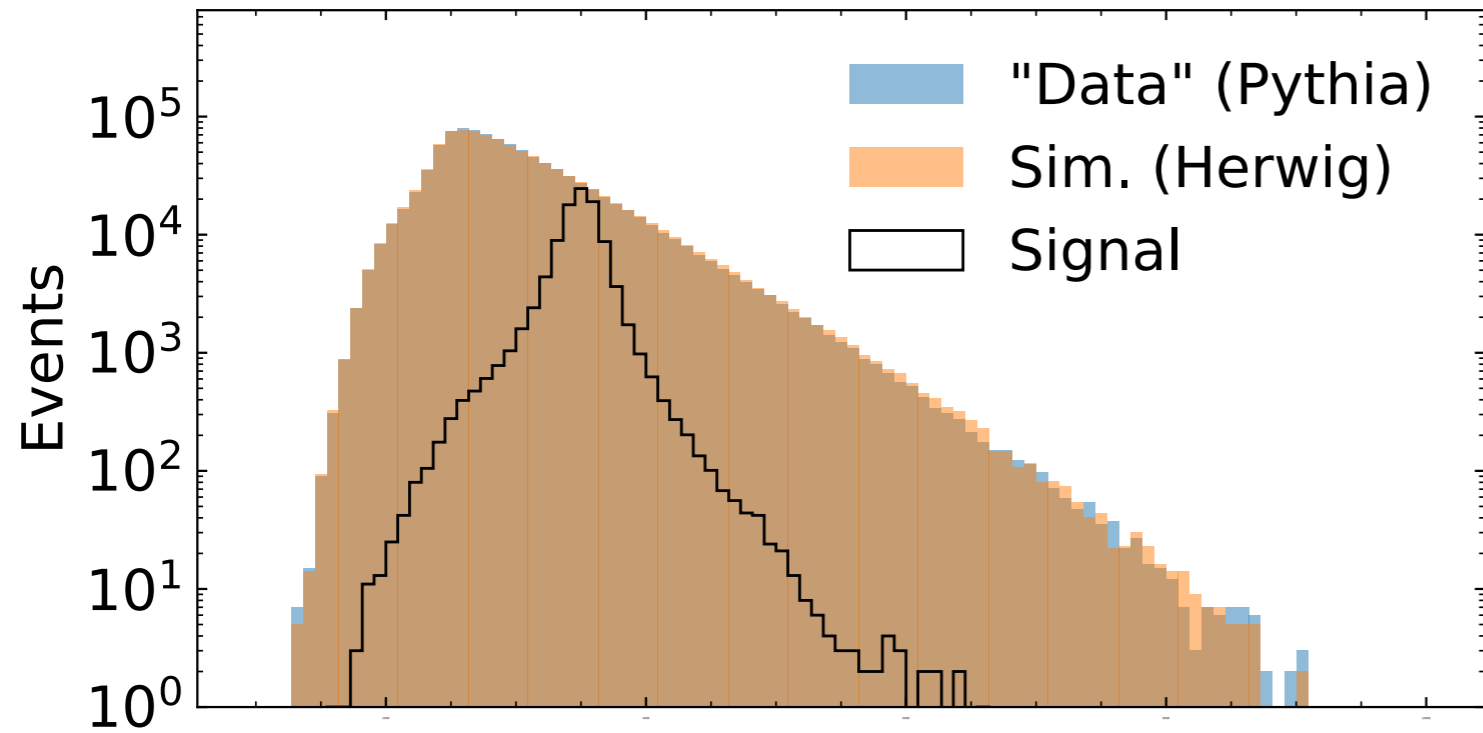
Can we use simulations in a way that is (nearly) simulation-independent?

We want to reduce our dependence on simulation, but we also don't want to throw away our physics priors!

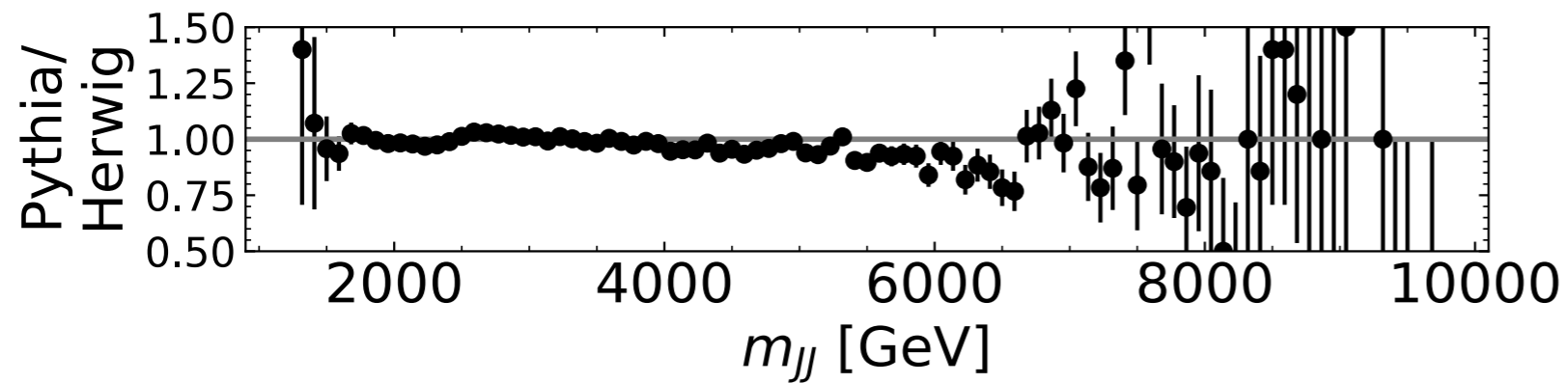
Can we use simulations in a way that is (nearly) simulation-independent?

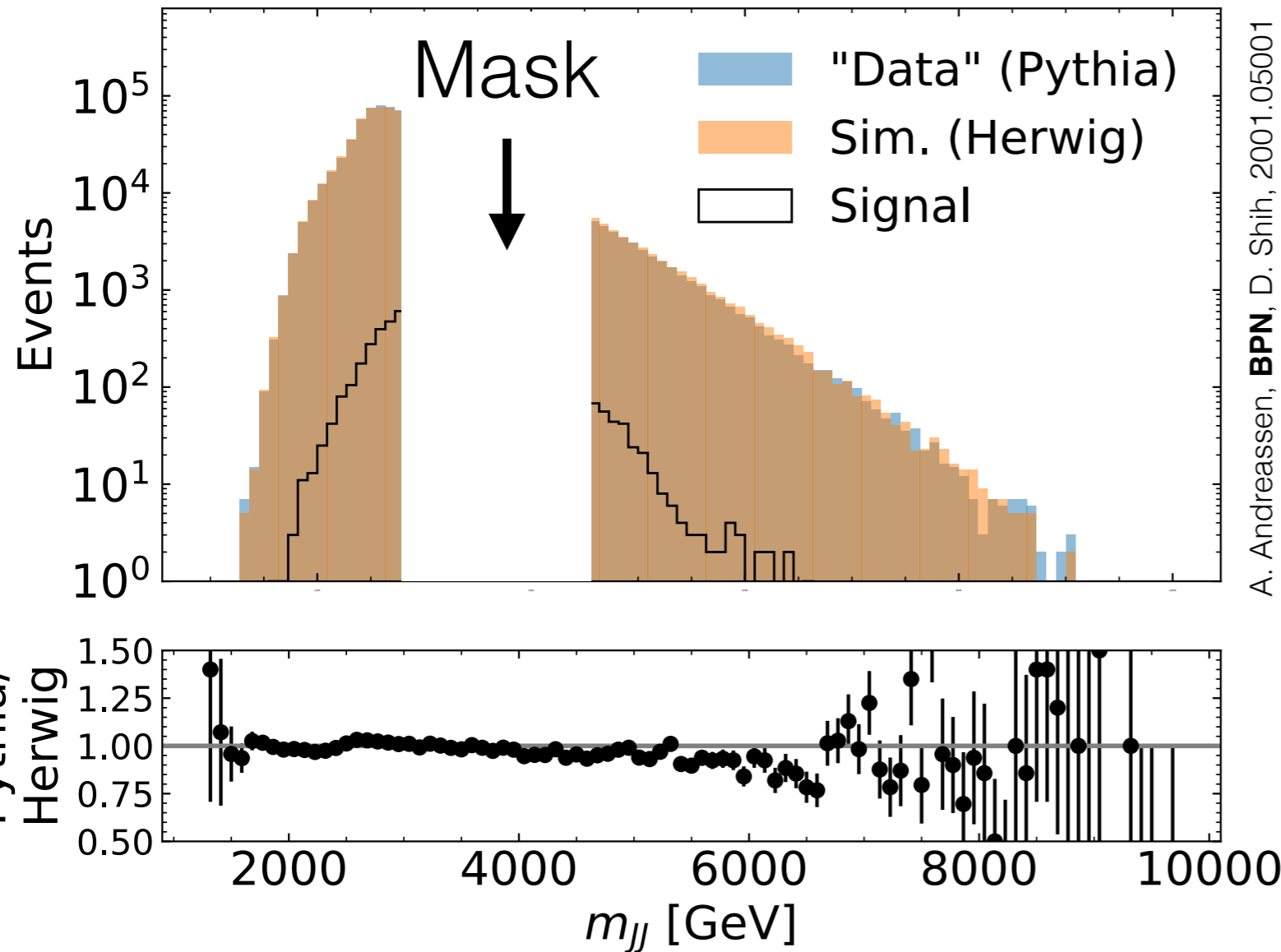
Answer:

Simulation Assisted Likelihood-free Anomaly Detection
(aka SALAD)



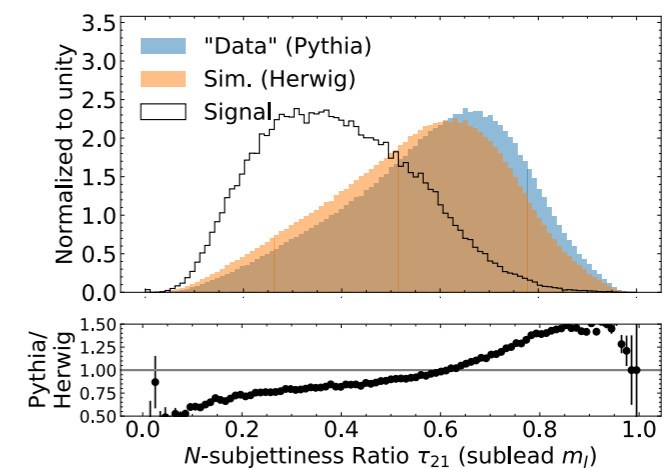
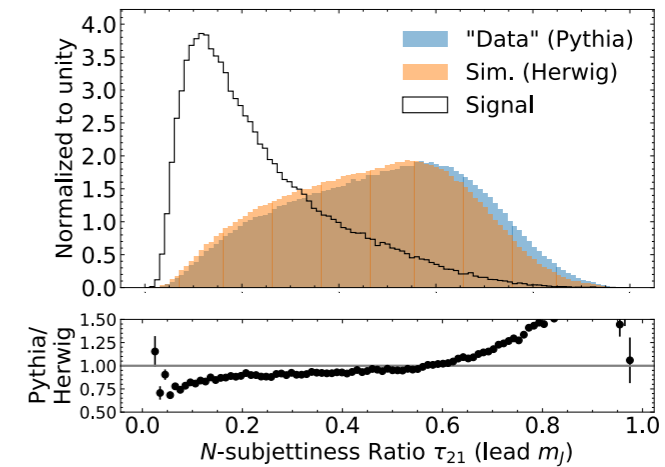
A. Andreassen, **BPN**, D. Shih, 2001.05001

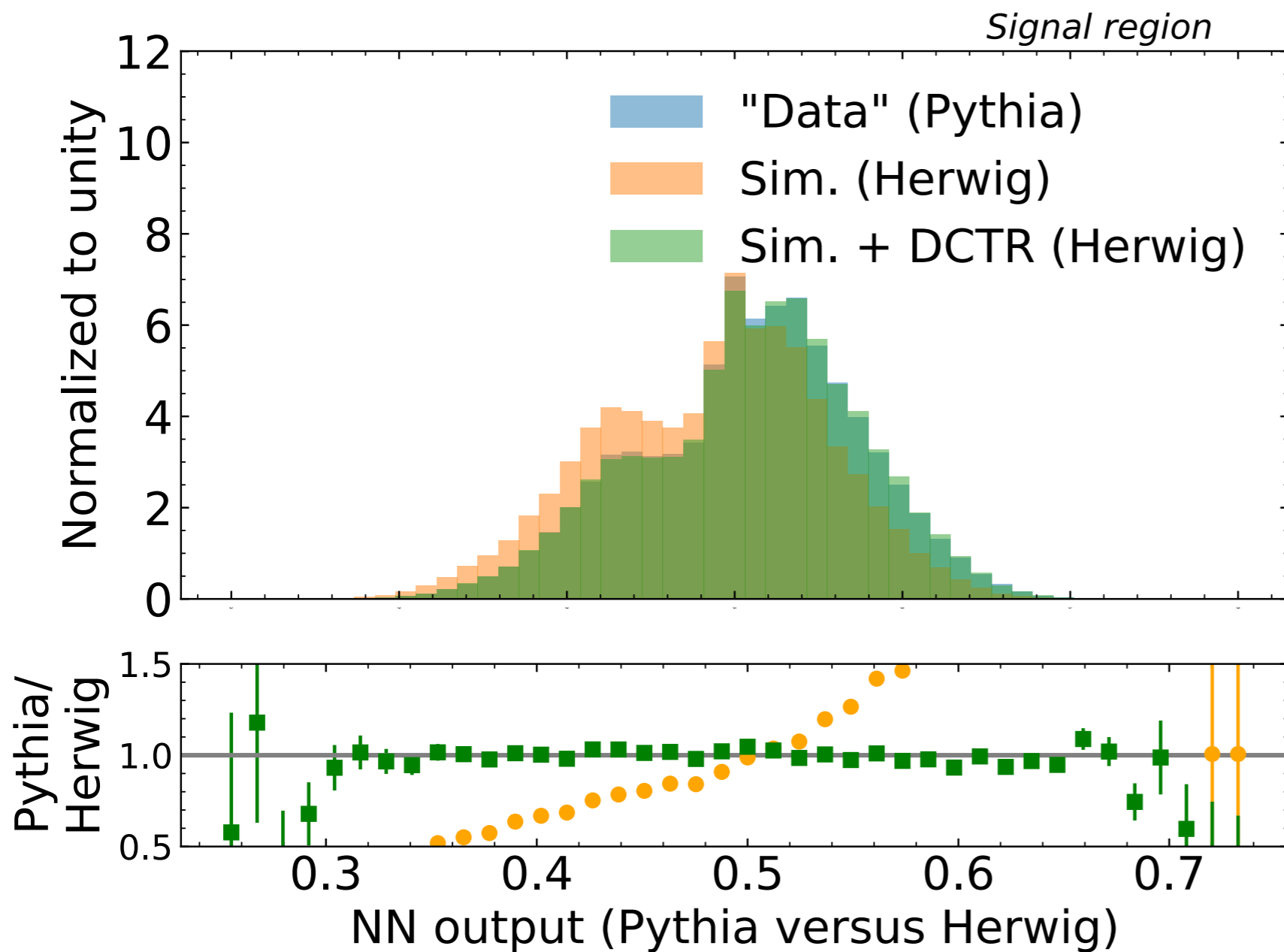




(1) Train DCTR in the sidebands to reweight MC to data

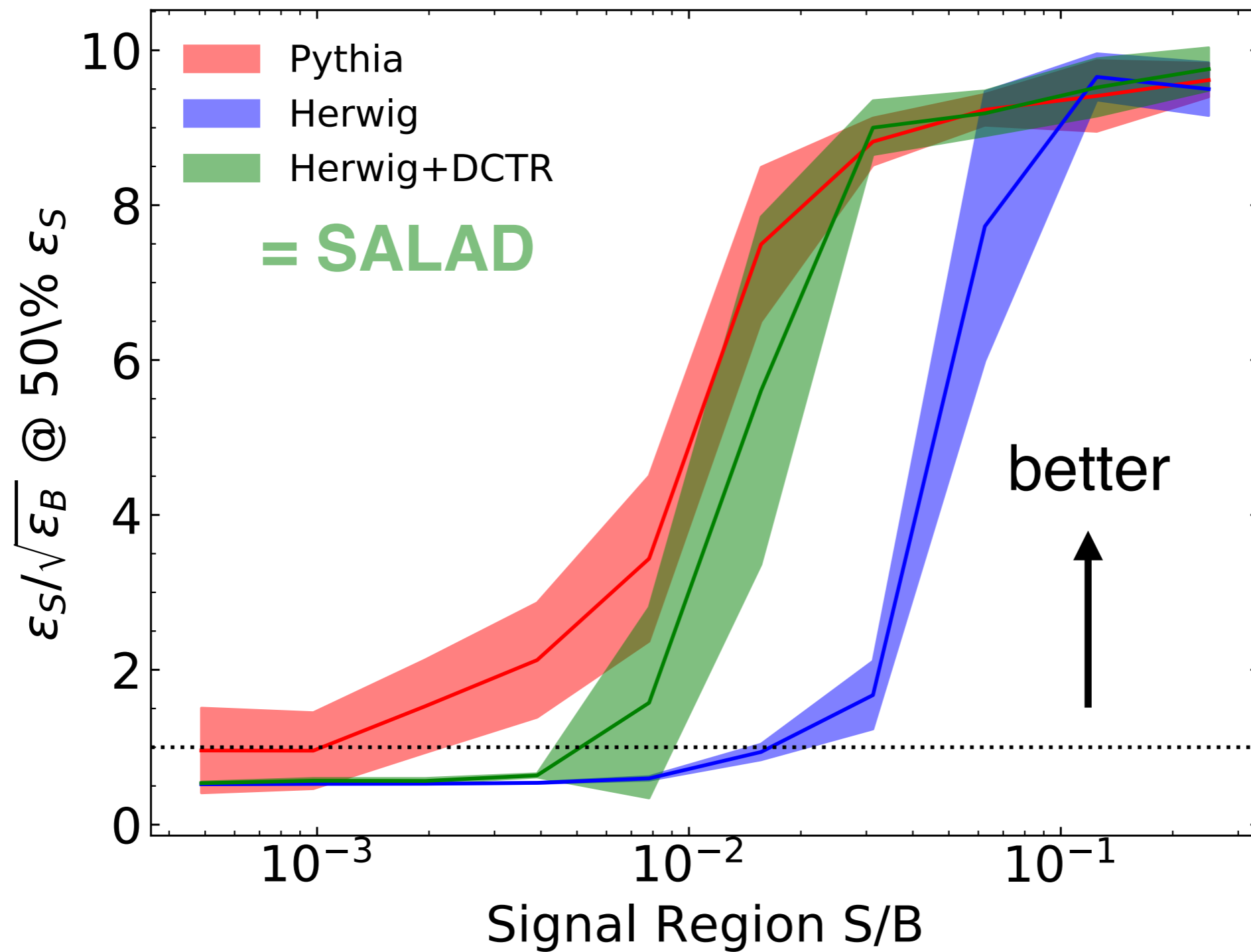
Features





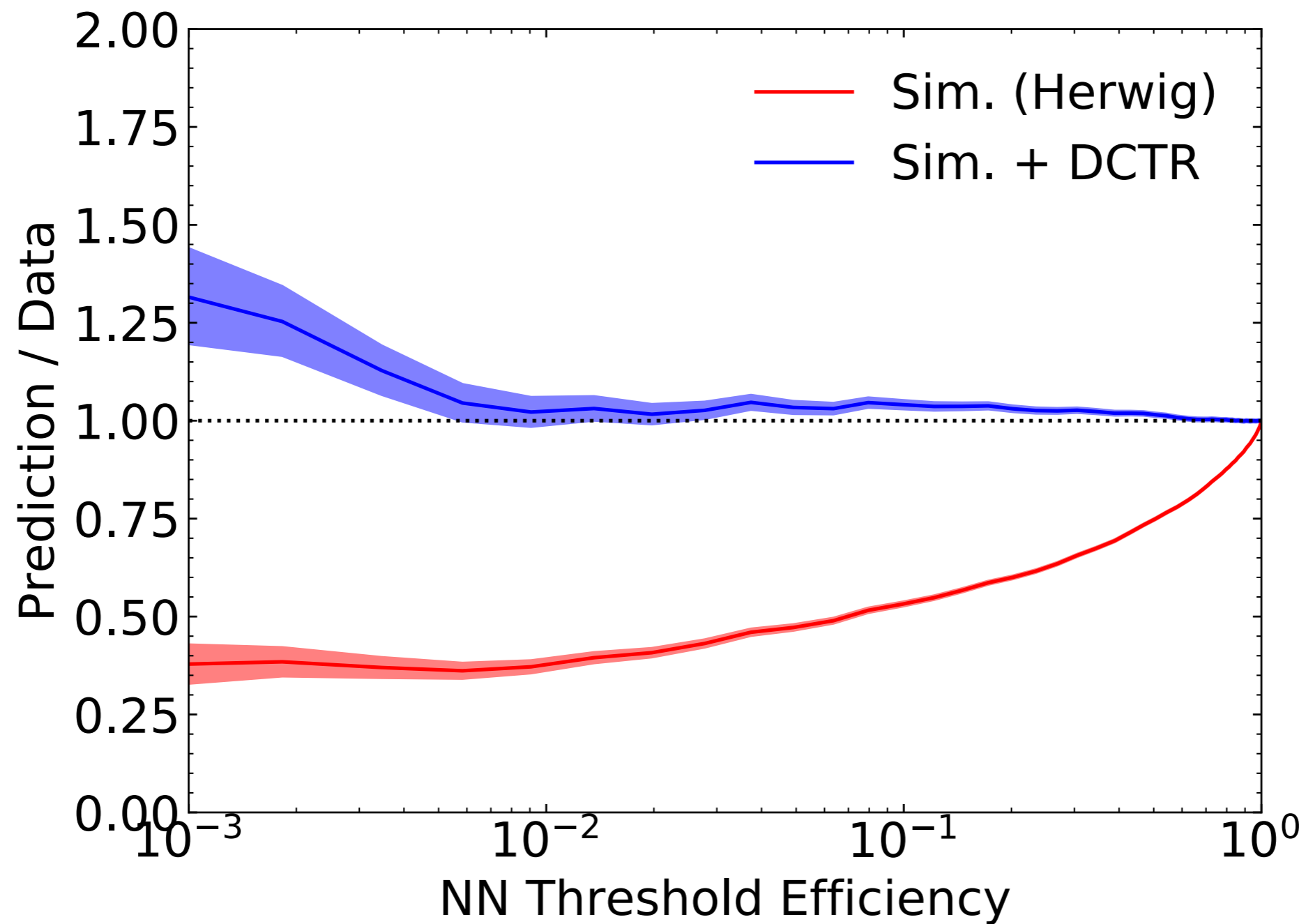
A. Andreassen, **BPN**, D. Shih, 2001.05001

- (2) Interpolate DCTR to signal region
- (3) Train classifier to distinguish reweighted MC from data



A. Andreassen, BPN, D. Shih, 2001.05001

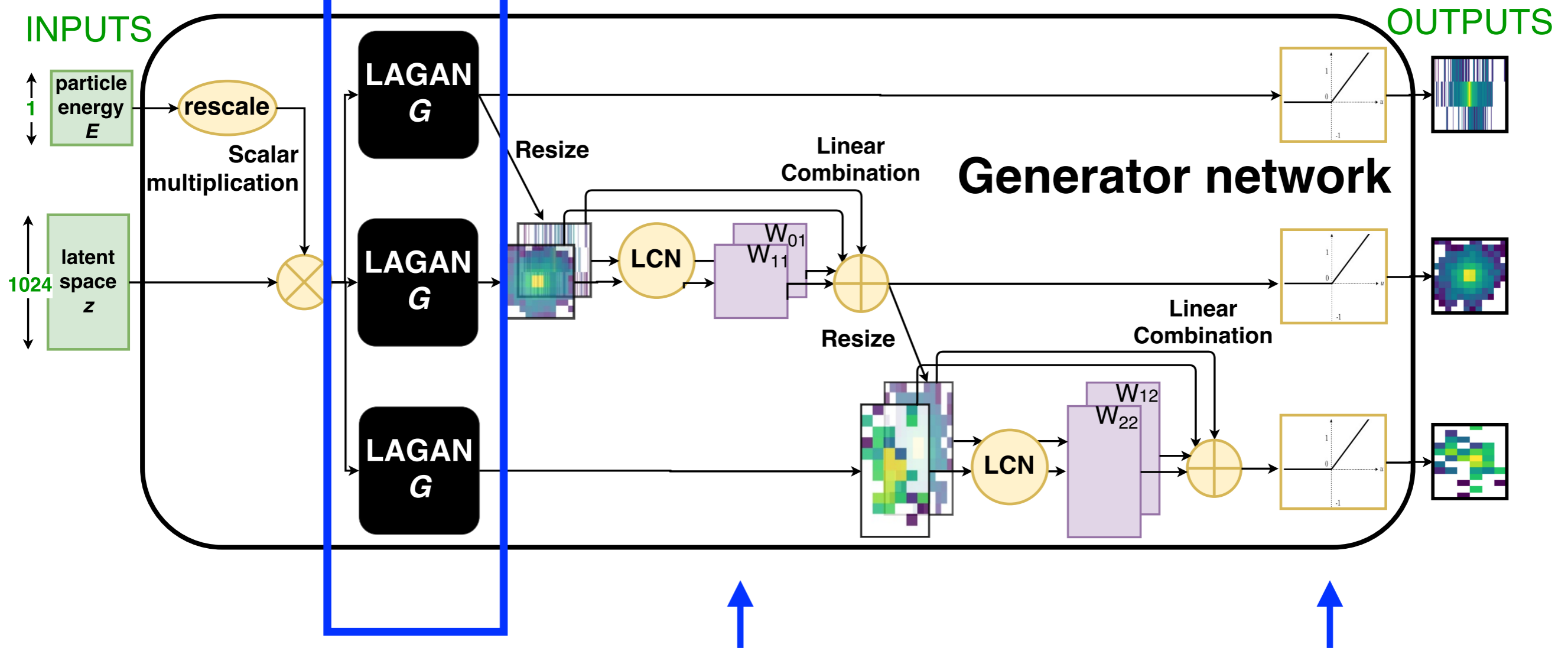
SALAD background



Introducing CaloGAN

One image per calo layer

One network per particle type; input particle energy



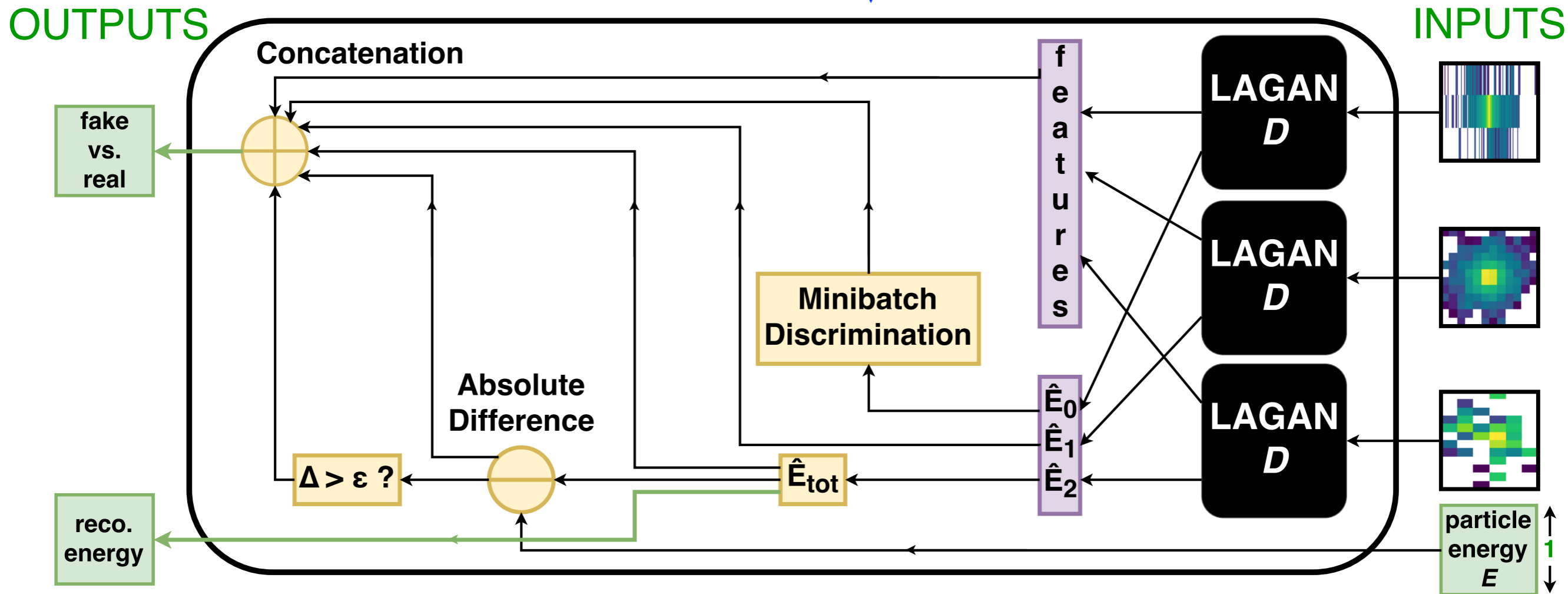
use layer i as input to layer $i+1$

ReLU to encourage sparsity

Introducing CaloGAN

Mode collapse: learns to generate one part of the distribution well, but leaves out other parts.

help avoid 'mode collapse'



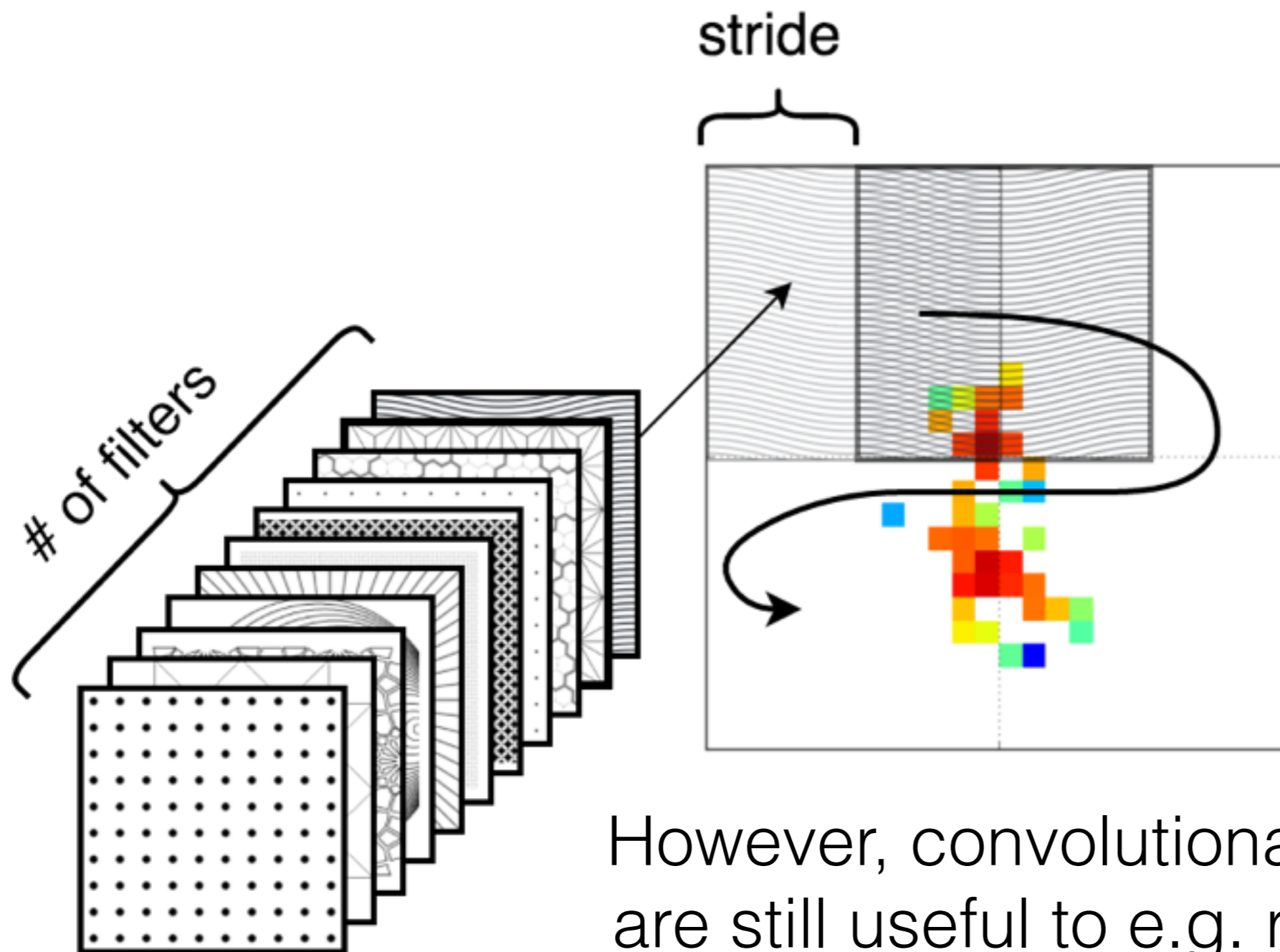
Discriminator network

Locally connected layers

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Due to the structure of the problem, we do not have translation invariance.

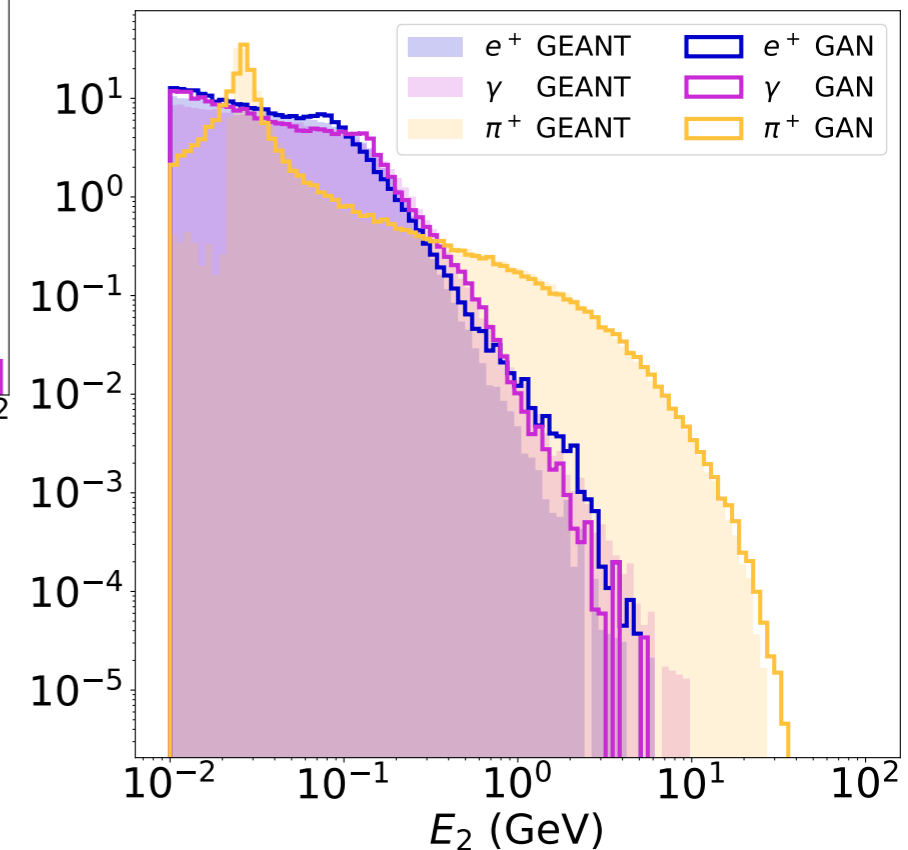
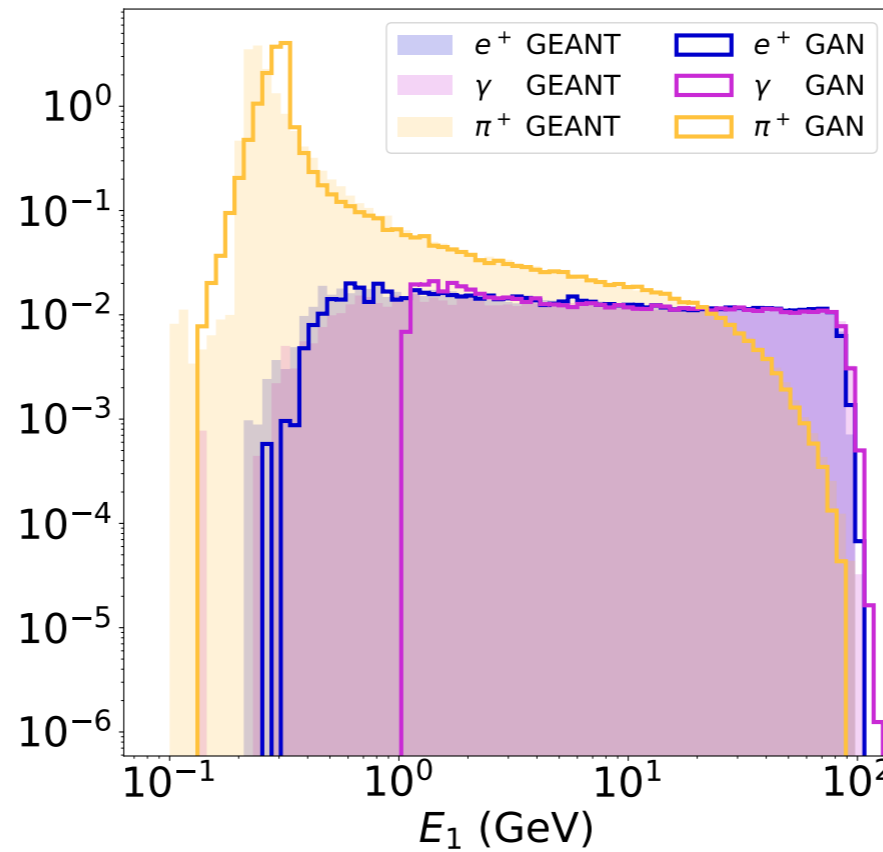
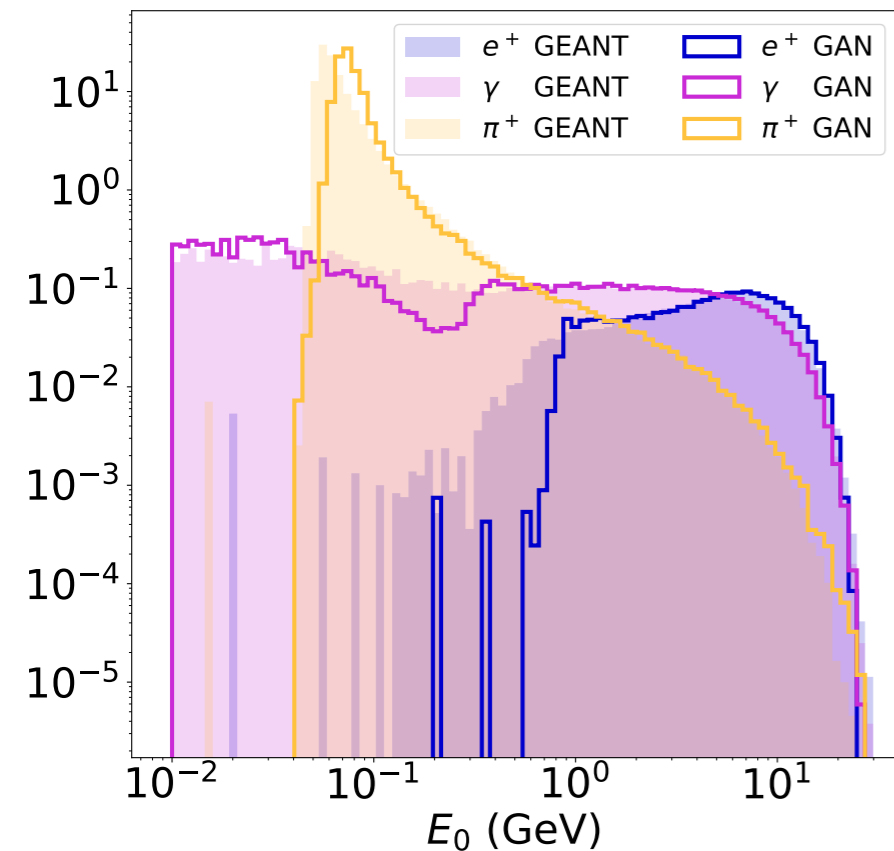
Classification studies found fully connected networks outperformed CNNs



However, convolutional-like architectures are still useful to e.g. reduce parameters

Energy per layer

Pions deposit much less energy in the first layers; leave the calorimeter with significant energy



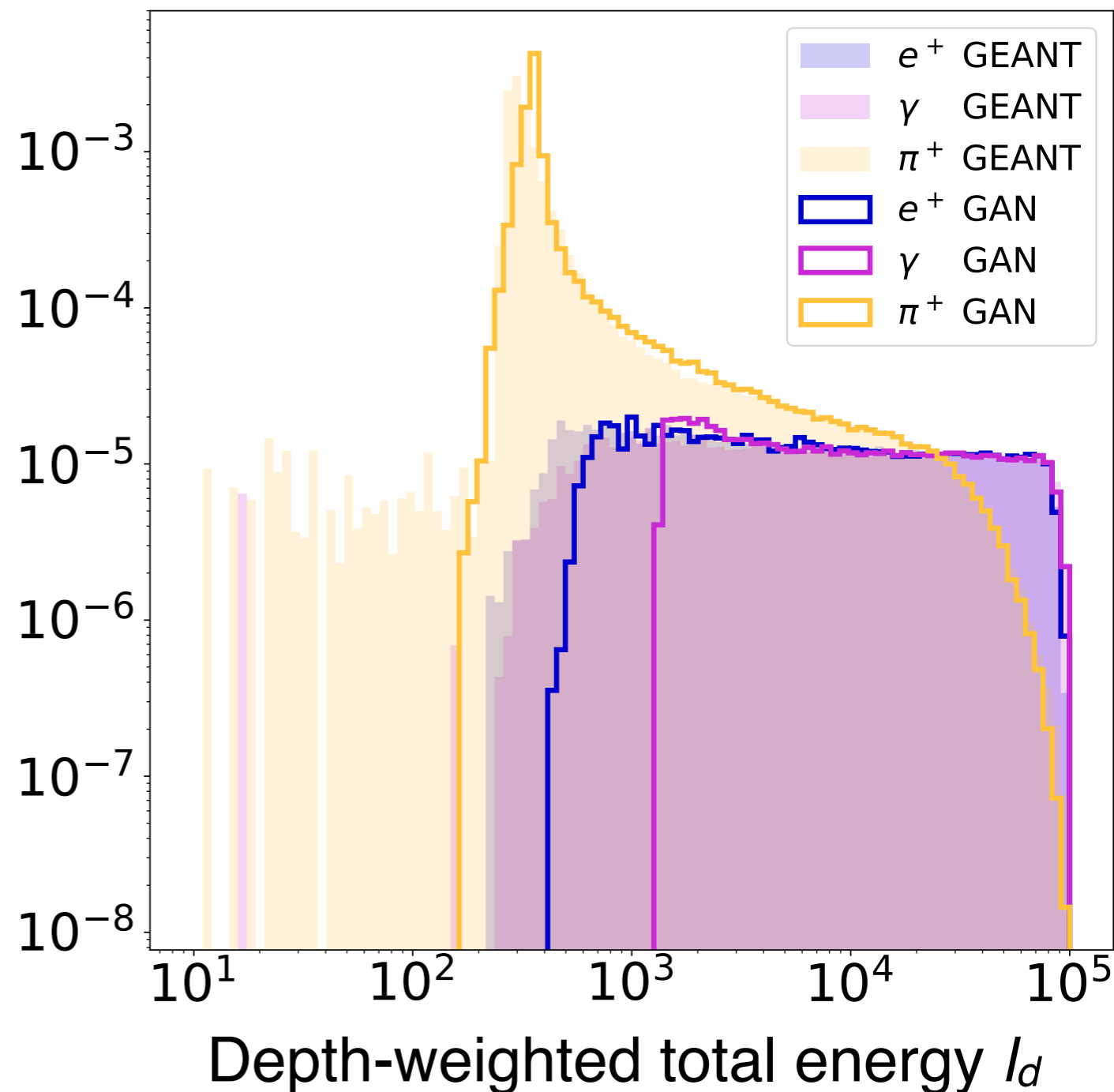
N.B. can always add these (and others) explicitly to the training

Warning: challenge with GANs

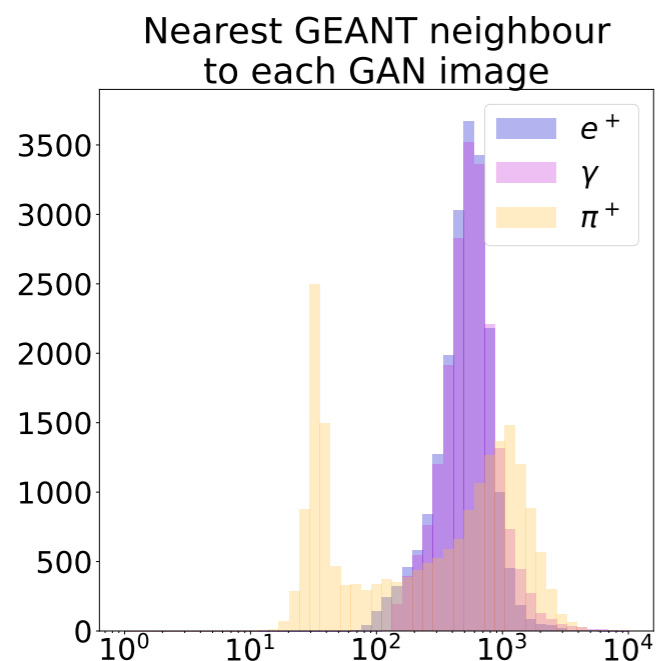
214

Unlike for classifiers, it is not easy to figure out which GAN is a good GAN - trying to learn a $O(1000)$ generative model and not a single likelihood ratio!

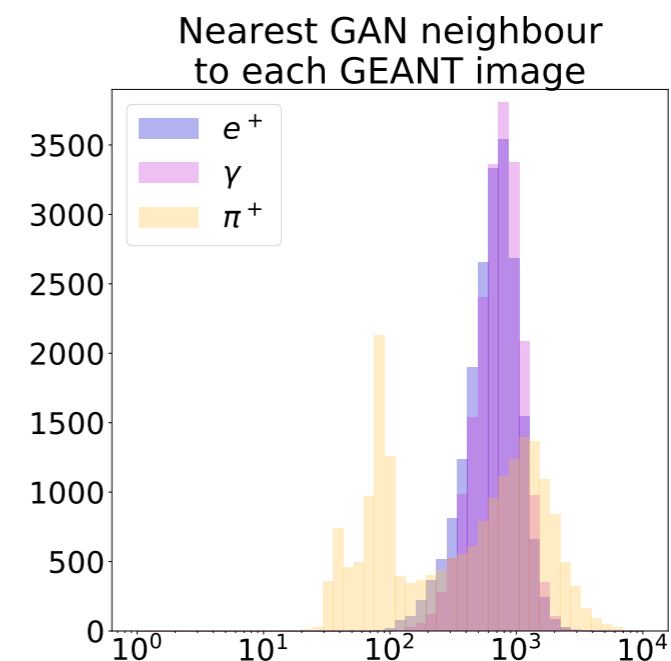
...this is a place where science applications can make a big impact on ML.



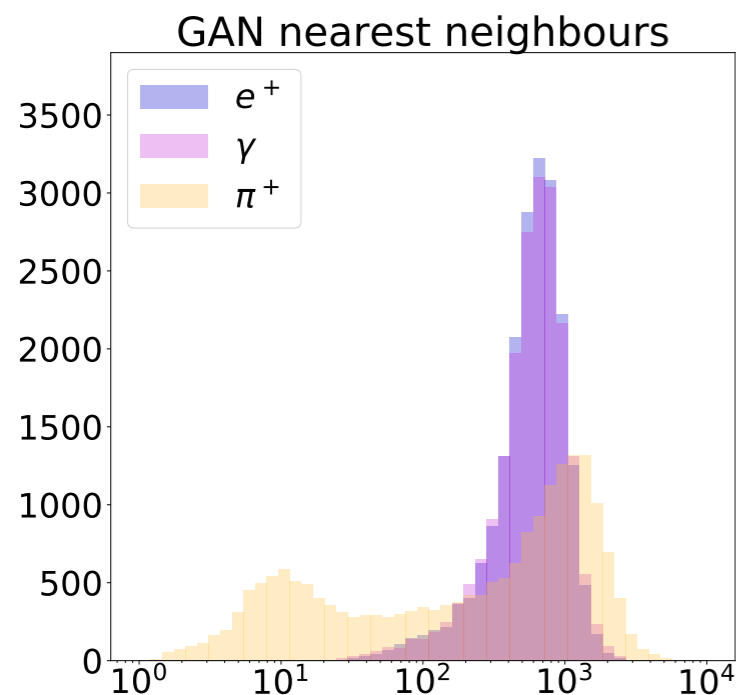
“Overtraining”



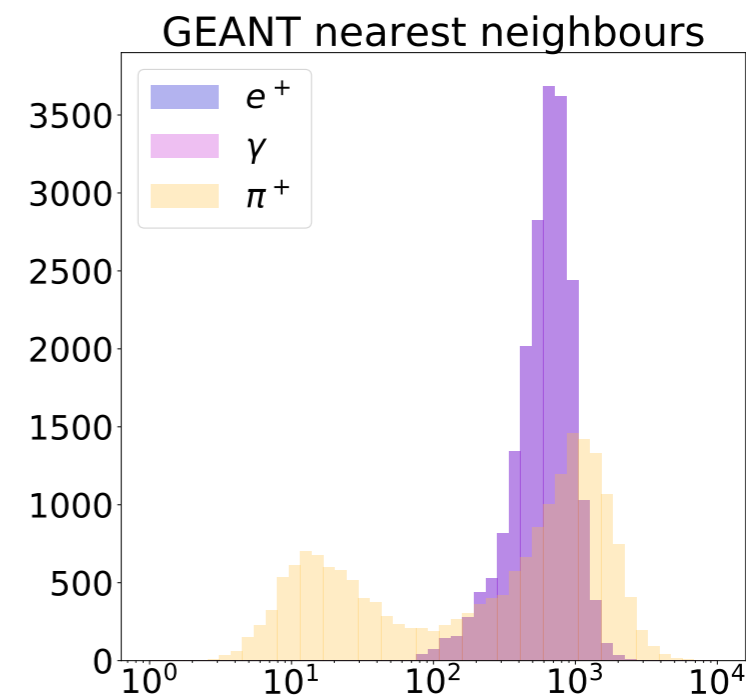
~not
memorizing



A key challenge in training GANs is the diversity of generated images. This does not seem to be a (big) problem for CaloGAN.

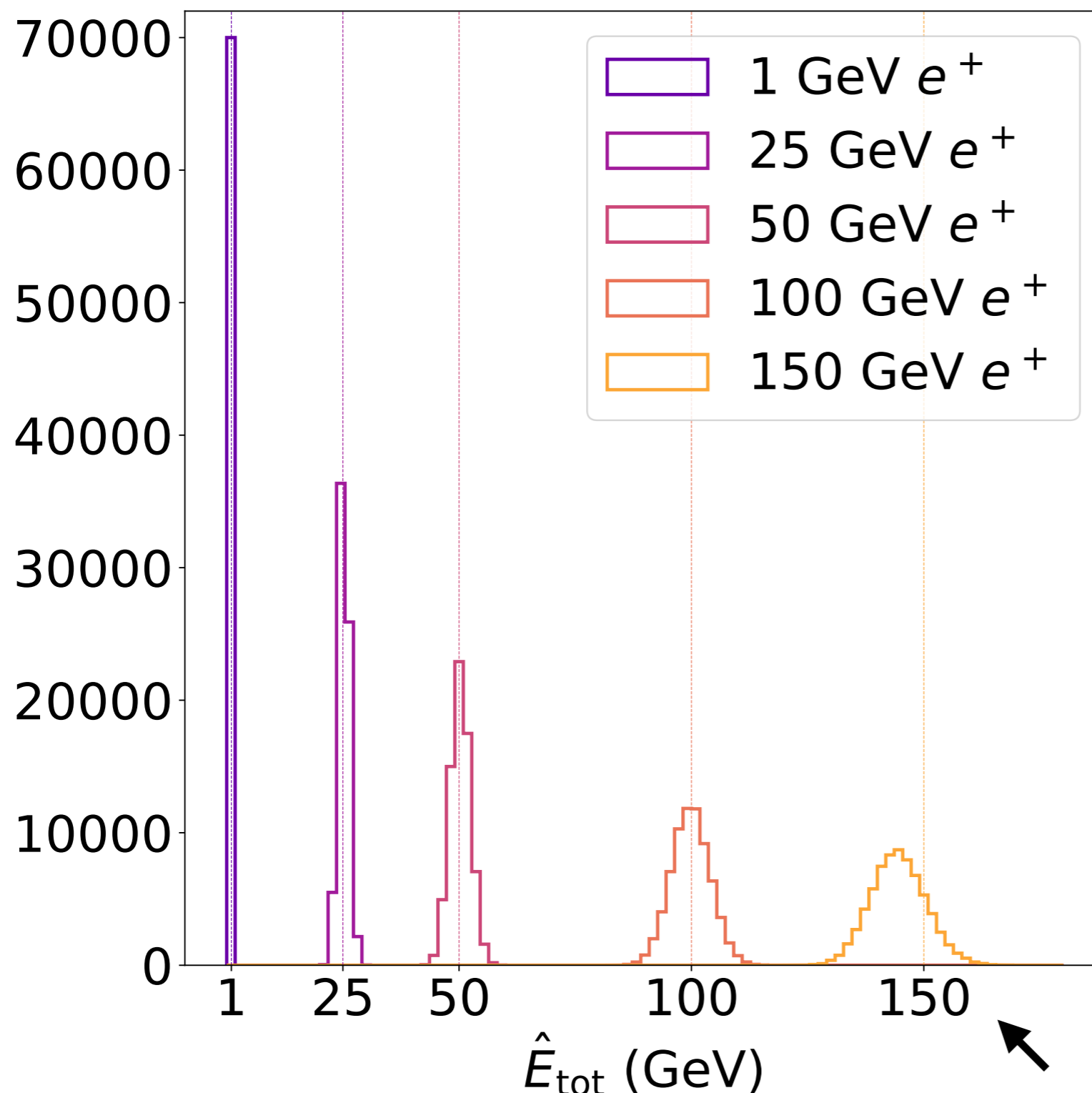


~no mode
collapse



Extrapolating

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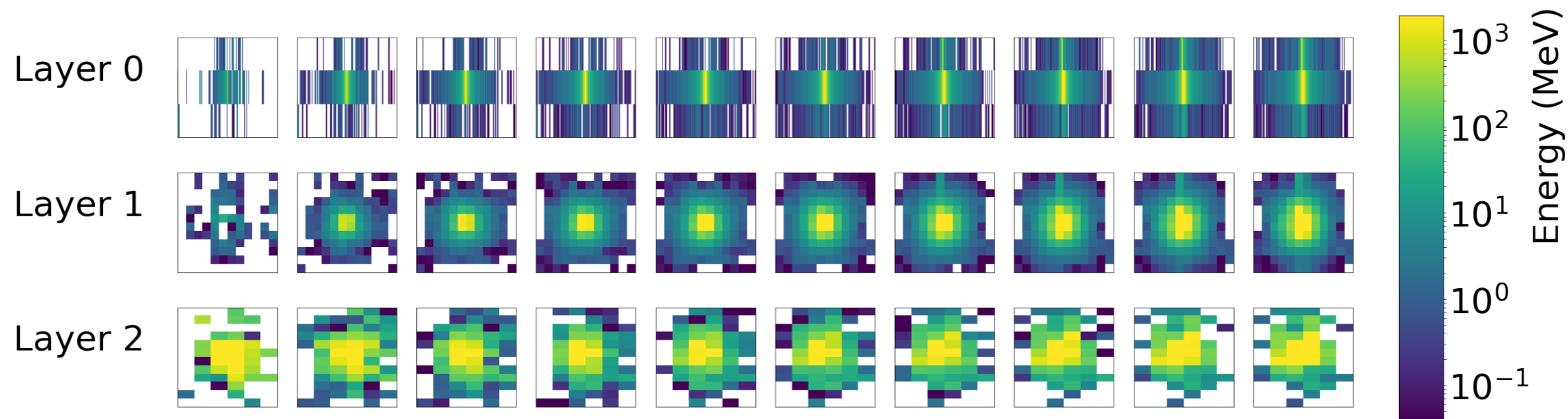
GANs are not designed to extrapolate, but in some cases, they can smoothly go on!

works here until there is no new physical principles which turn on at some energy

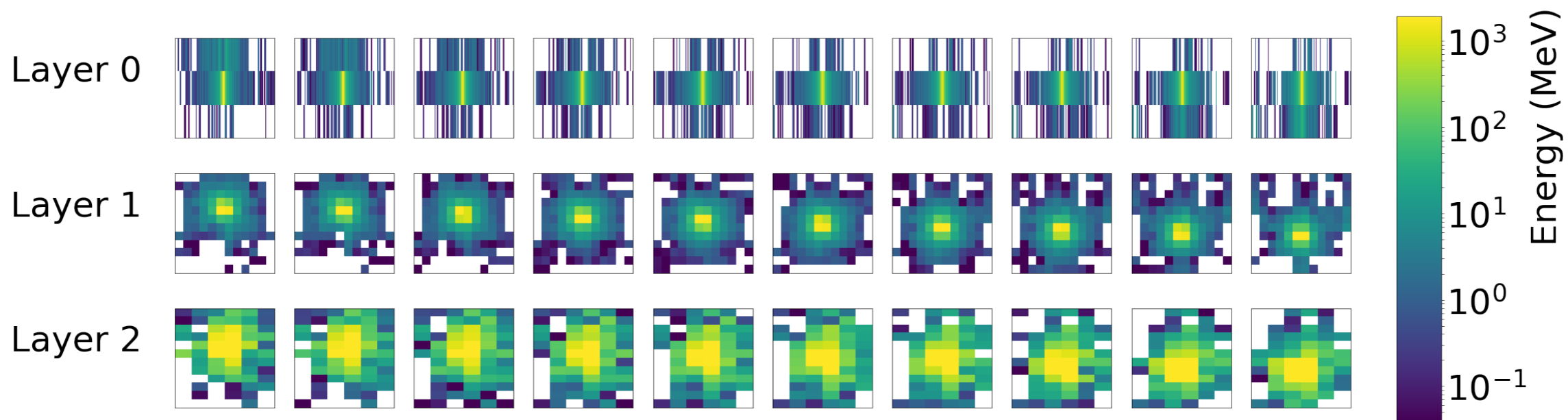
Beyond our training sample! →

Conditioning

Fix noise, scan latent variable corresponding to energy



Fix noise, scan latent variable corresponding to x-position



There is no consensus on architecture, but most efforts for universal quantum computing use superconductors.

I'm not going to talk about hardware, though it is an exciting topic.



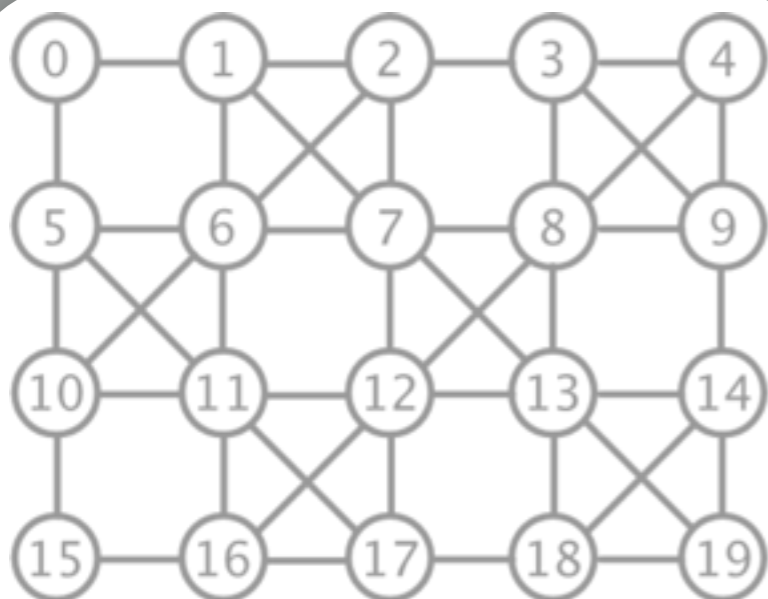
classical computing in the 1970's



quantum computing now

The best quantum computers have ~10-20 **qubits** with ~few connections per qubit and can stay coherent for $O(\text{hundreds})$ of operations.

A **qubit** is an abstract representation of a quantum system that can be in a superposition of two states (often thought of as a spin)

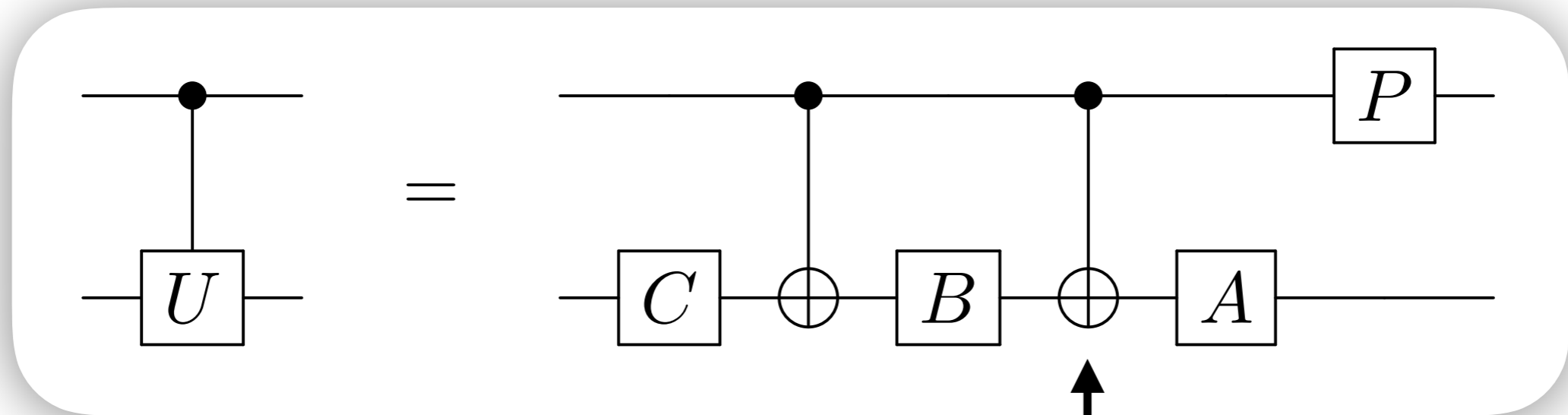


This is one of IBM's 20-qubit quantum computers. Lines represent connections.

Challenges with current computers

220

In practice: only controlled operation that is allowed is CNOT (swap if 1 otherwise do nothing) ... need to decompose.



CNOT “controlled not”

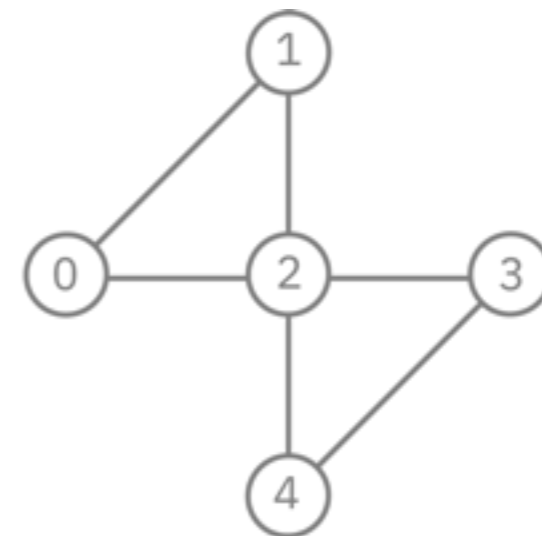
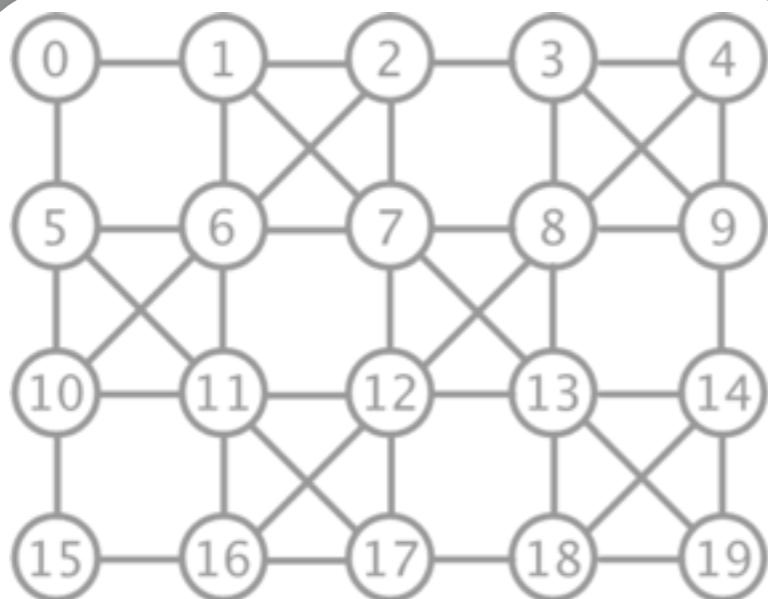
There is no compiler ... need to do circuit decomposition by hand (!)

Challenges with current computers

221

In practice: only controlled operation that is allowed is CNOT (swap if 1 otherwise do nothing) ... need to decompose.

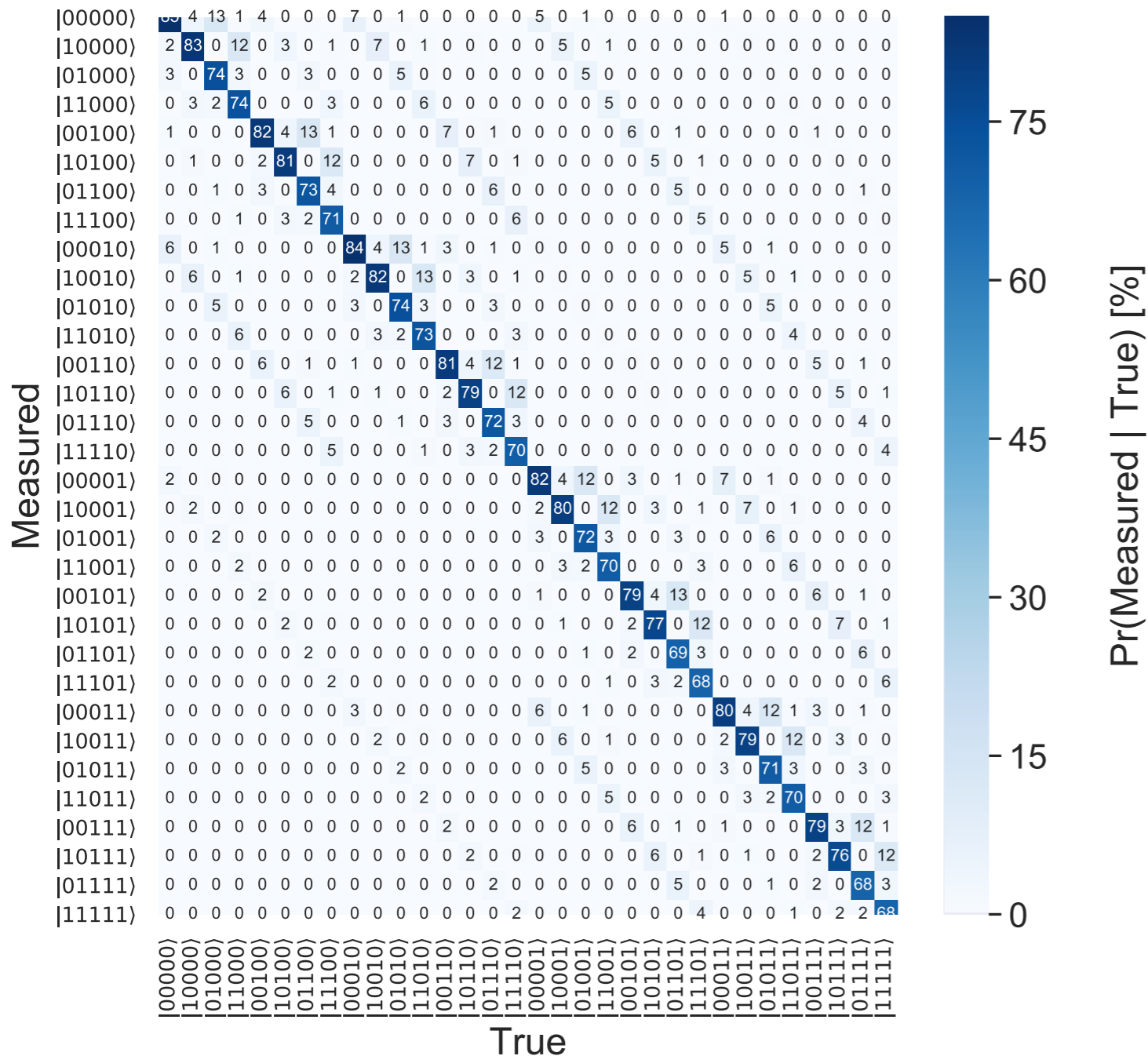
Circuit implementation is architecture-dependent
need to know what connections are available
(can swap, but CANNOT clone qubits!)



Readout error corrections



Qiskit Simulator
IBM Q Johannesburg Readout Errors



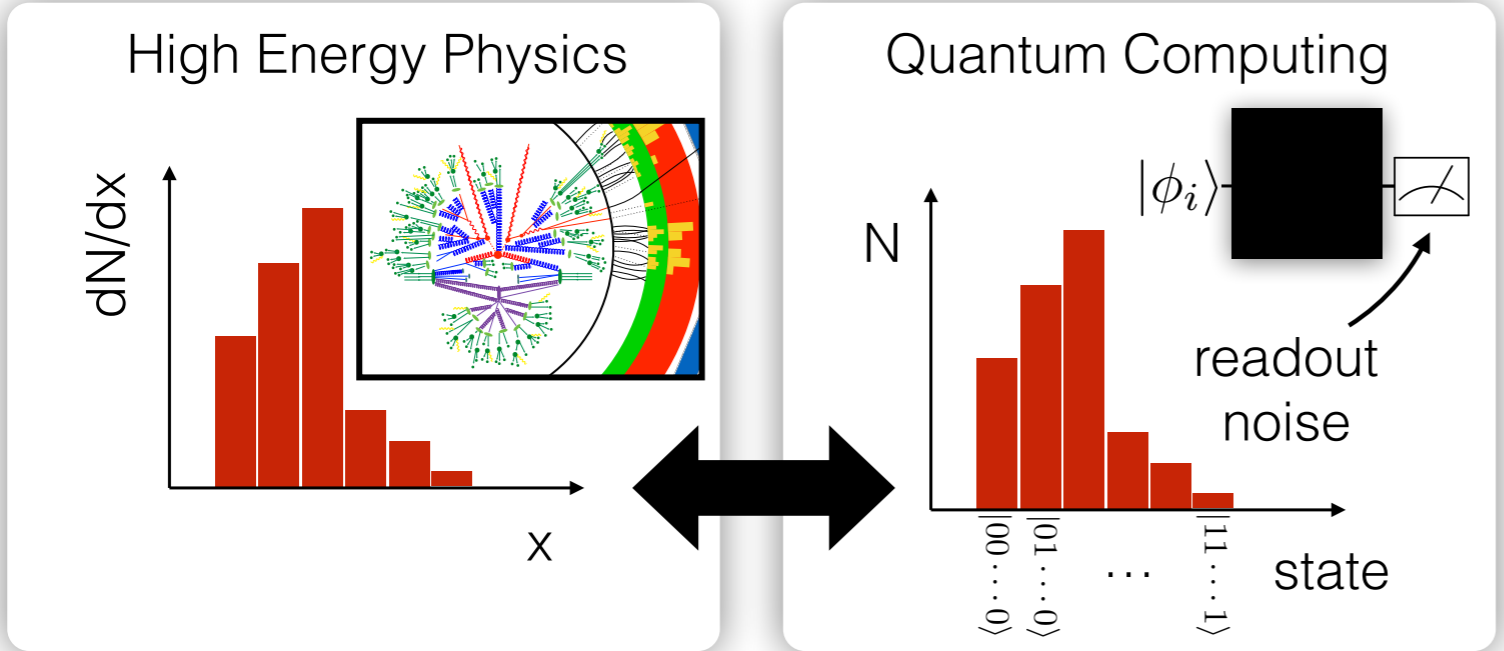
On a quantum computer, the state may be 1 but readout as a 0, etc.

For n qubits, there is a $2^n \times 2^n$ transition matrix.

HEP has proposed many solutions to this problem!

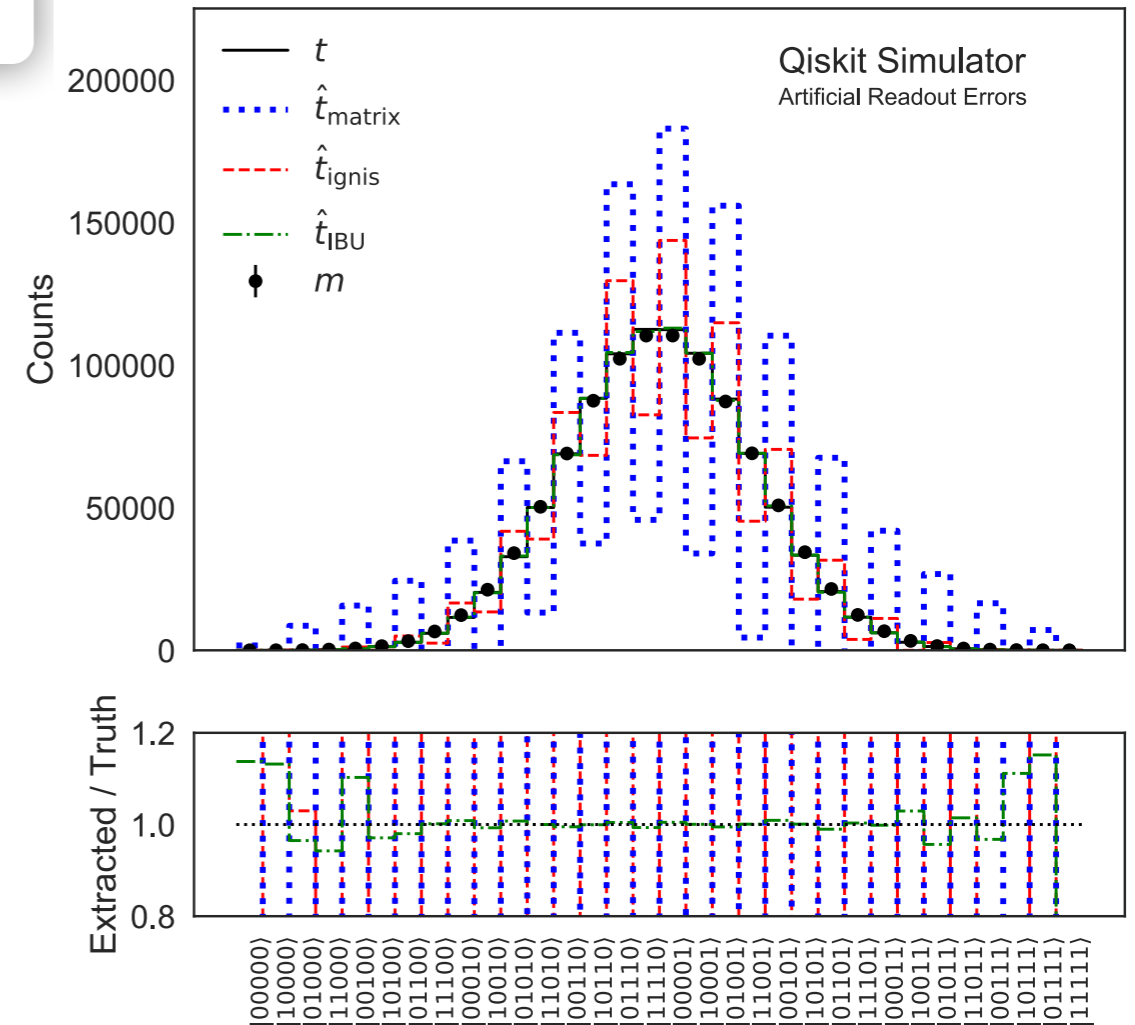
...and we call them **unfolding**

Readout error corrections



IBM standard
HEP standard

We have proposed to use HEP unfolding techniques to correct quantum computer readout errors.
...there are other connections we are exploring in this area - stay tuned!



Gate error corrections

