

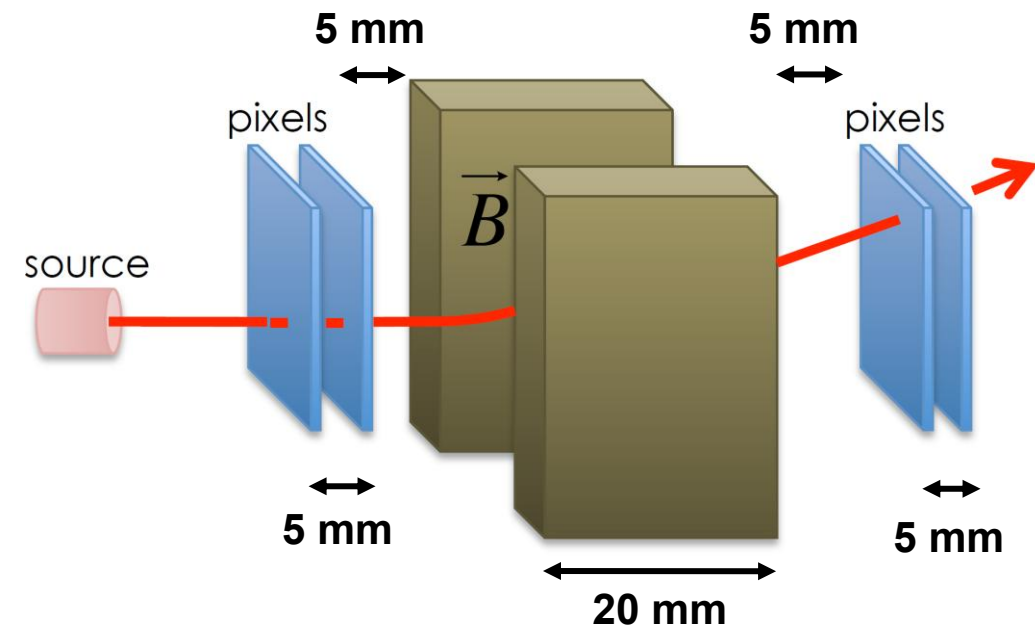
Silicon Tracker with International Education Objective

J. Baudot, Y. Enari

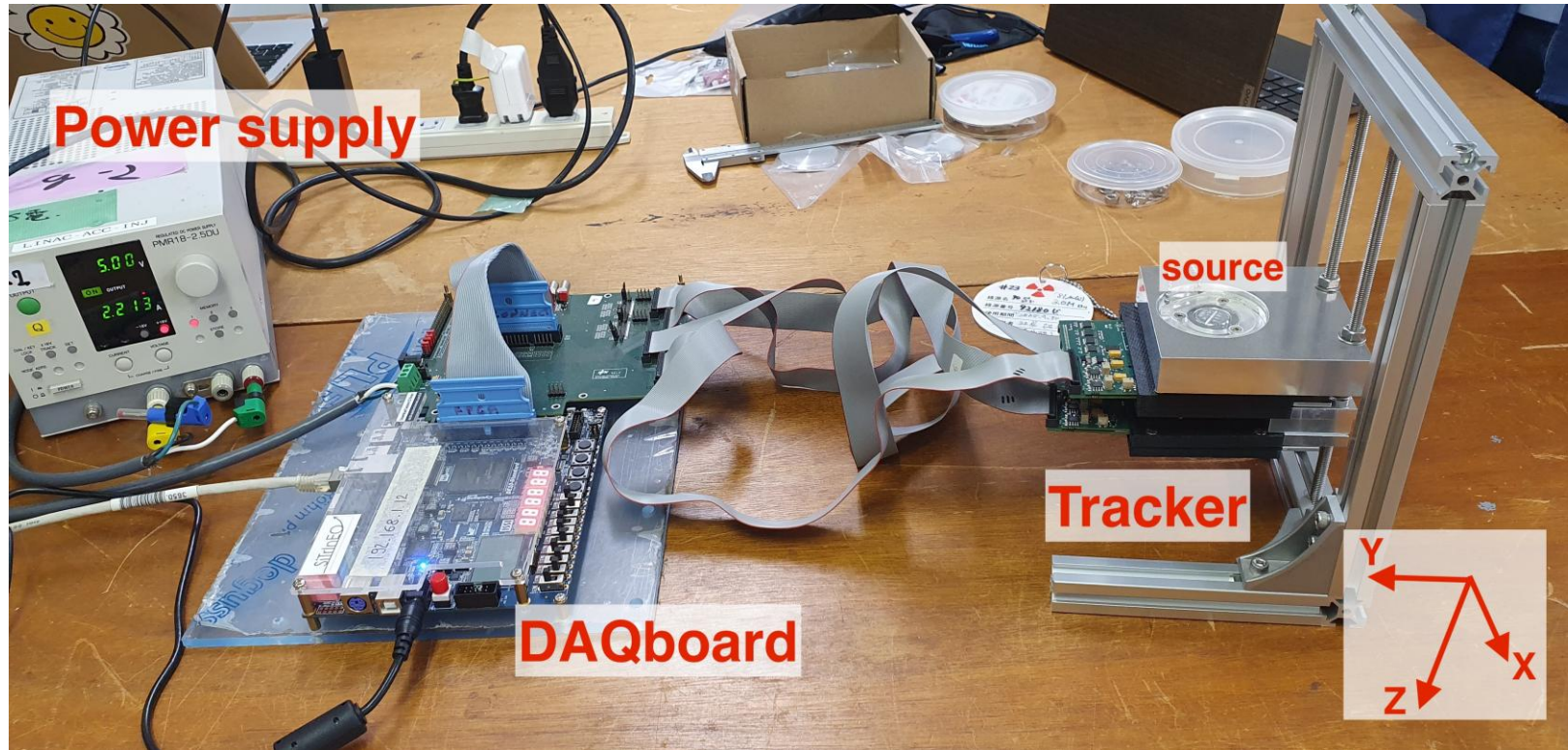
This presentation is a support
material of the document and
README file to operate system.

Introduction

- What is SiTrInEO?
 - Silicon Tracker with International Education Objective
 - Developed by IPHC(Strasbourg, France) and Kyungpook National University (Korea)
- Goal
 - Operate and calibrate the setup
 - Understand the track reconstruction
 - With and without magnetic field



SiTrInEO setup

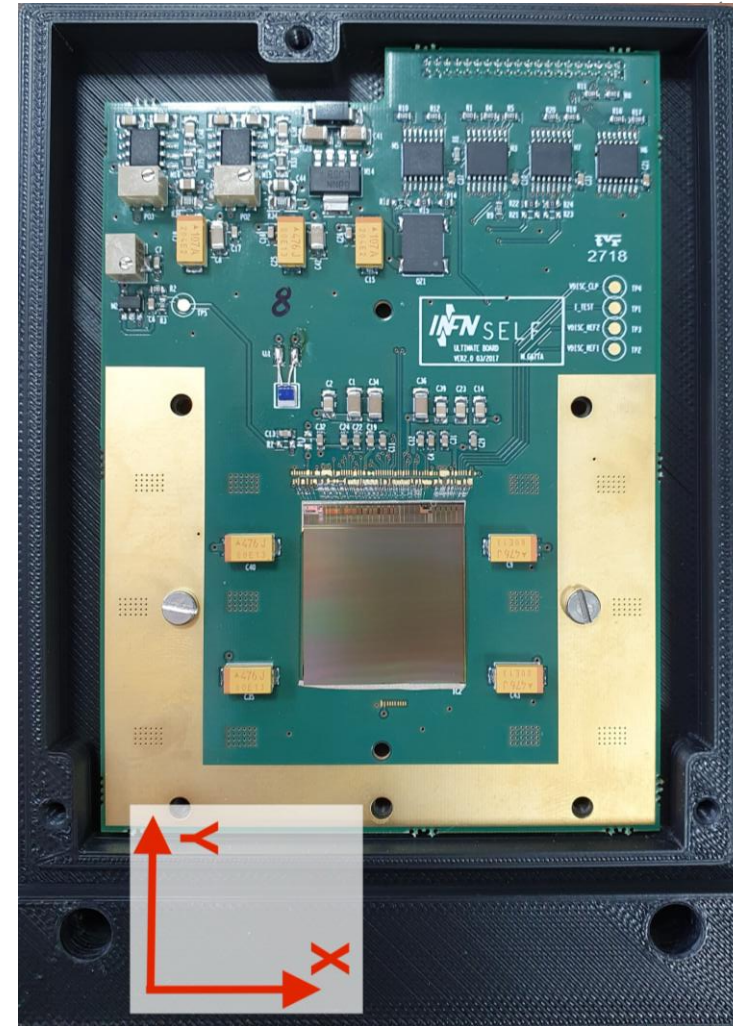


- The experimental setup consists of
 - Four Mimosa-28 sensors
 - Each with 3.8 cm² active area
 - A Halbach magnet ~0.1 T
 - between 2nd and 3rd sensor
- An FPGA board for data taking and powering the sensor
- A desktop PC with data analysis
- A radioactive beta ray source, ⁹⁰Sr

MIMOSA-28

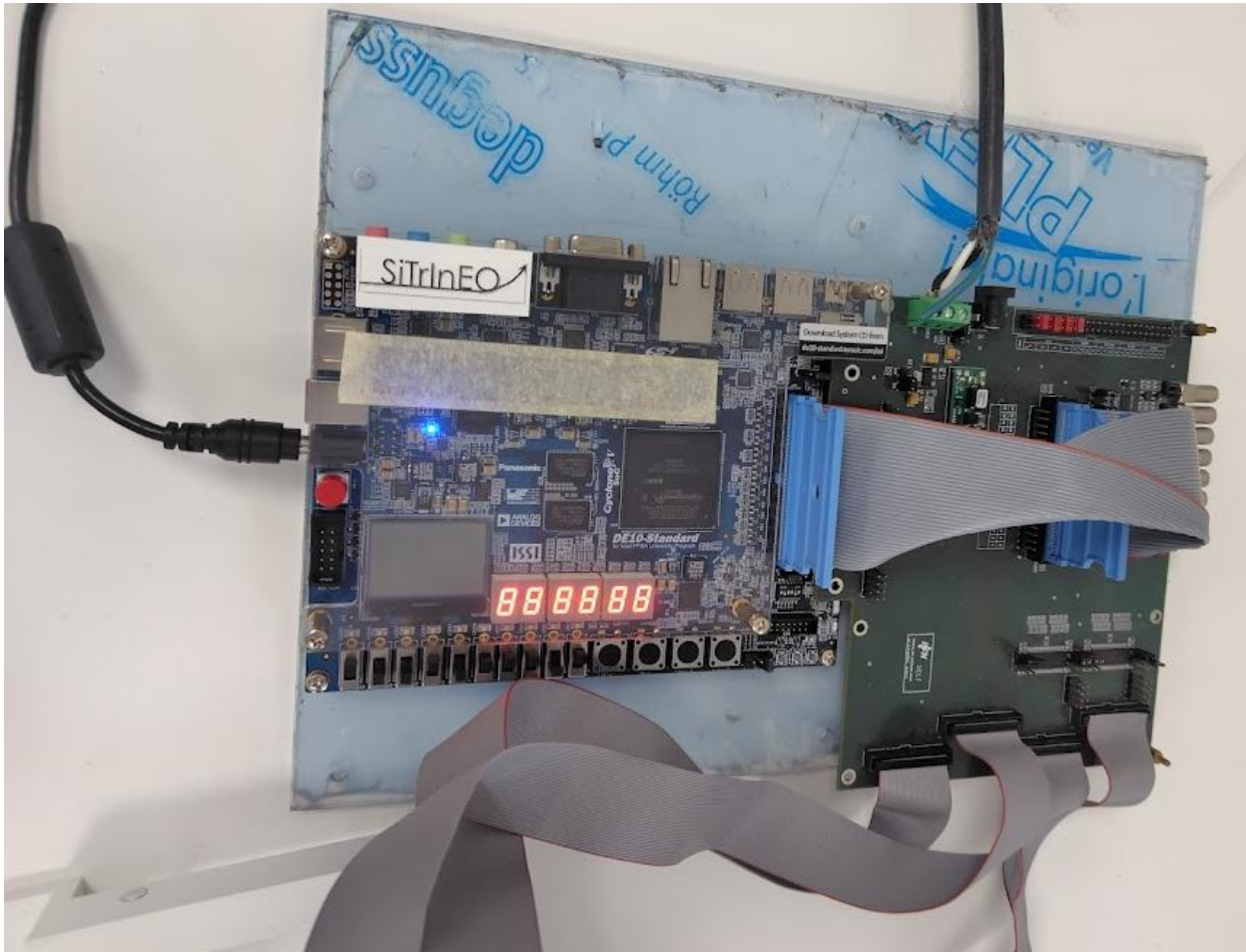
	Mimosa 28
Input & output Frequency	160 Mhz
Read out of 1 line	200 ns
Sensor dimension	20.2 * 22.7 mm
Matrix dimension	19.8 * 19.2 mm
Number of lines	928
Integration time	185.6 μ s
Number of Columns	960
Pitch	20.7 μ m
Number of pixel	890 k
Memory size	2 * 2048 w32
Max number of data transfert per frame	1850 w32 + 6 w32 (encapsulation)

- AMS 0.35 high-res process
 - epi. layer: 400 Ω .cm p-, 14 μ m thickness
- Rolling shutter read-out
 - triggerless



- Equivalent Noise Charge: ENC ~ 10 e-

Operate Mimosa28 via FPGA



Control MAPS

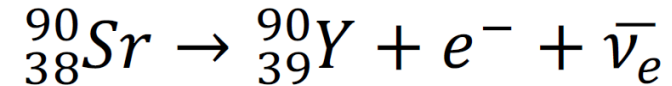
- FPAG is used for
- configuring parameters for MAPS
- Data readout
- handle up to four Mimosa28s

Case of SiTrinEO

- FPGA : ALTERA Cyclone V
- Linux OS is burned
- Access by ssh, issue commands.

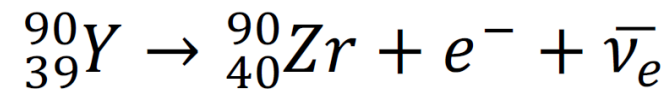
Beta source ^{90}Sr

- The radioactive source used was ^{90}Sr . It decays via β^- decay to ^{90}Y :



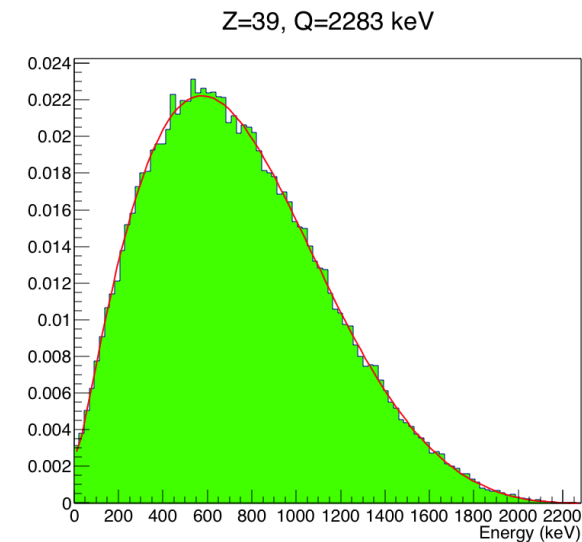
with $T_{1/2} = 28.8$ years and $Q = 0.546$ MeV

- The ^{90}Y then decays via β^- decay to ^{90}Zr

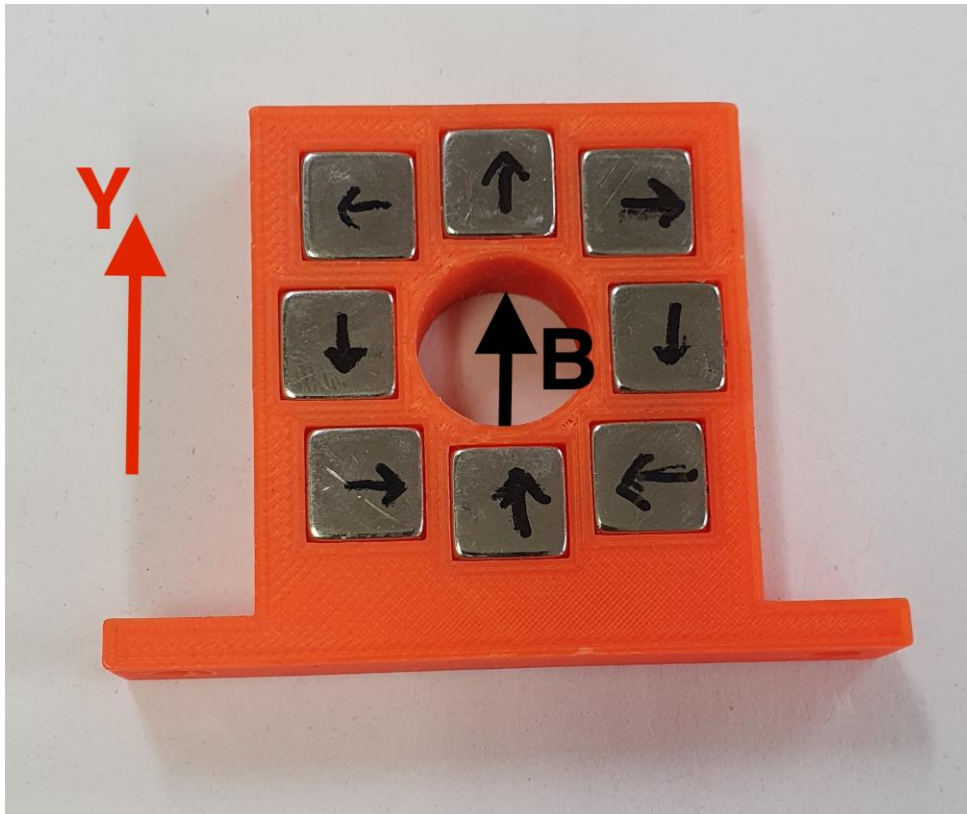


with $T_{1/2} = 64$ hours and $Q = 2.28$ MeV

- Detection of β^- particles of this process is mainly from the decay of ^{90}Y , not ^{90}Sr .

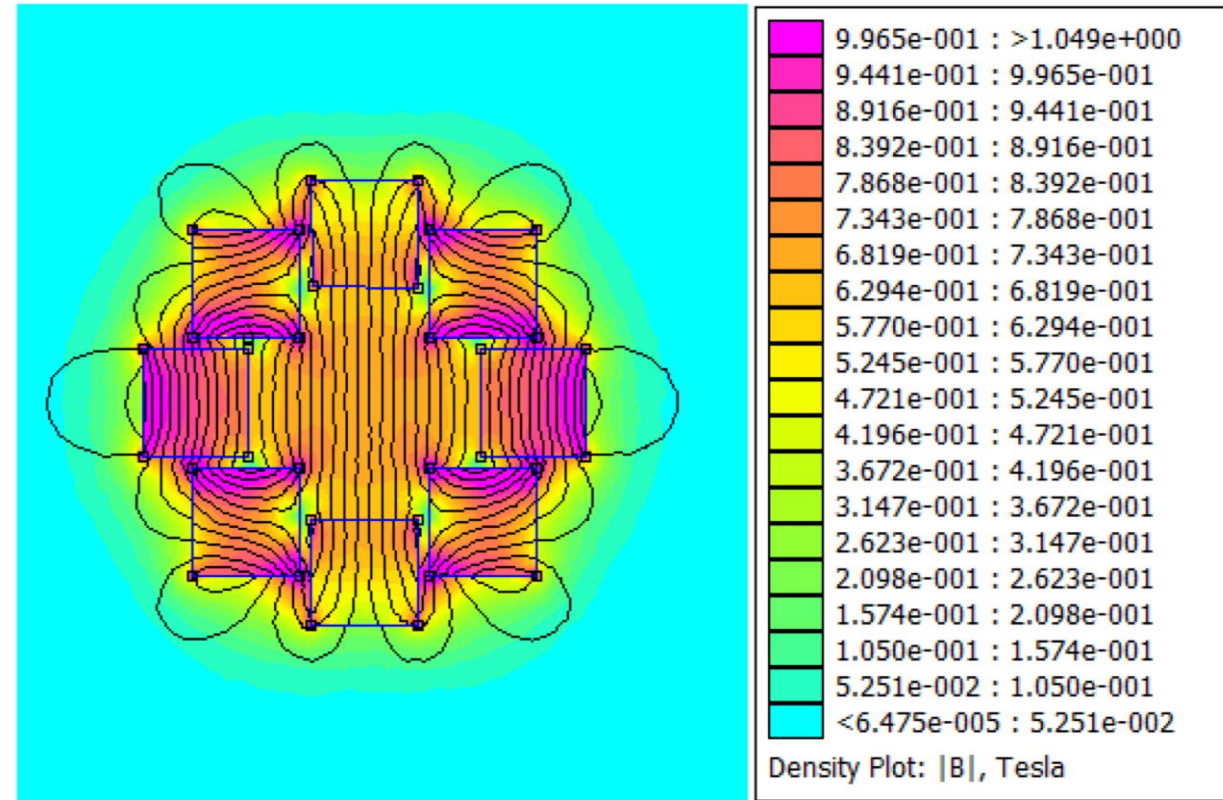


Halbach Magnet:



- Use several small magnets
- increase the field strength
 - improve field homogeneity

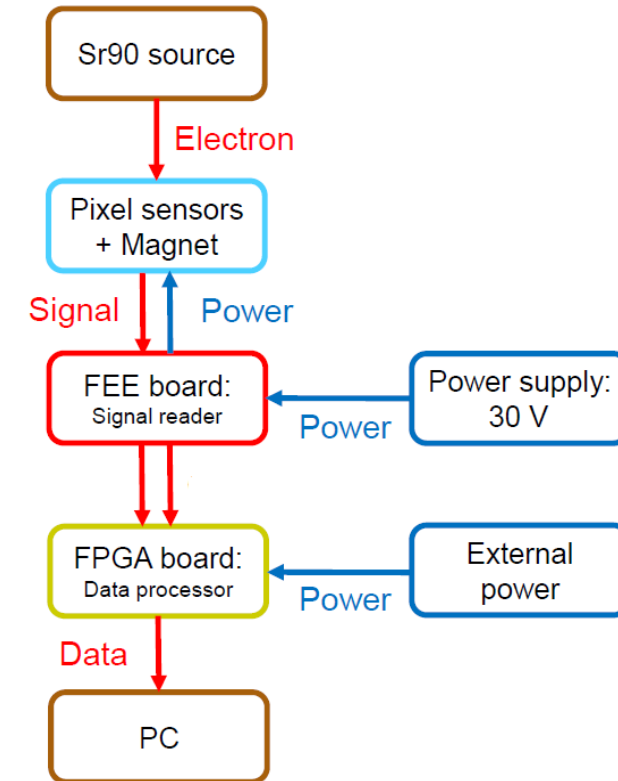
COMSOL simulation of ideal case



=> Magnetic field magnitude **in center is ~ 0.1 T**
(measured with magnetometer)

Data taking

- During each data run, the FPGA board saves the addresses of **all** the pixels that were fired in the form of a file readable by the data analysis software.
- The data files are then processed by the TAF, or Telescope Analysis Software package, which is based on the ROOT framework.



```
ssh root@192.168.1.110
```

1. sitrireset : reset system
 2. sitriconf : configure system
 3. sitristart : start clocking
 4. sitridaq : test DAQ
- all in one go: sitriall

4 steps

1. Fix thresholds of MIMOSA-28 sensors
2. Mask Noisy Pixels
3. Align Tracker
4. Build the source spectrum

Note: The initial values can not be trusted.

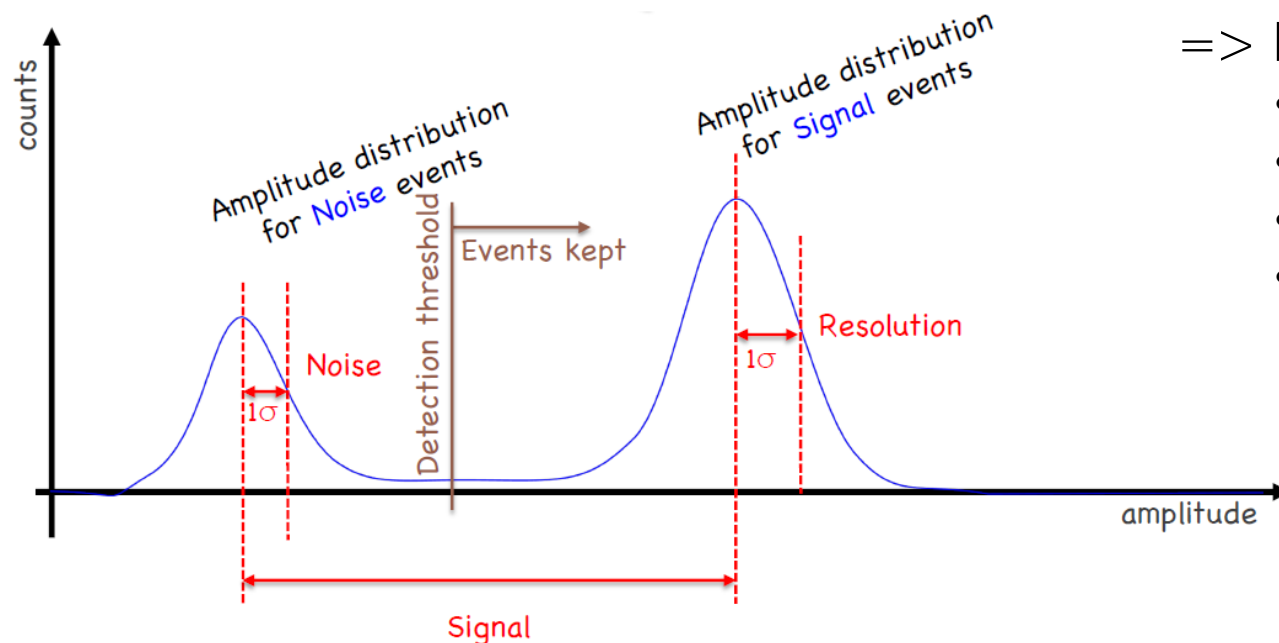
Do not rely on given values. Please confirm them by yourself.
Suggest to provide your findings to next group!

[Link to the shared log note](#)

[Link to the run list](#)

1. Fix sensor threshold

- Sensors have been calibrated in advance of the school
- Various **detection thresholds** files prepared
 - 8, 10, 12 x the std. deviation (i.e. the noise ~ 10 e-) + pedestal
- see README.txt to set the desired file



=> How large signal is expected for MIP particle?

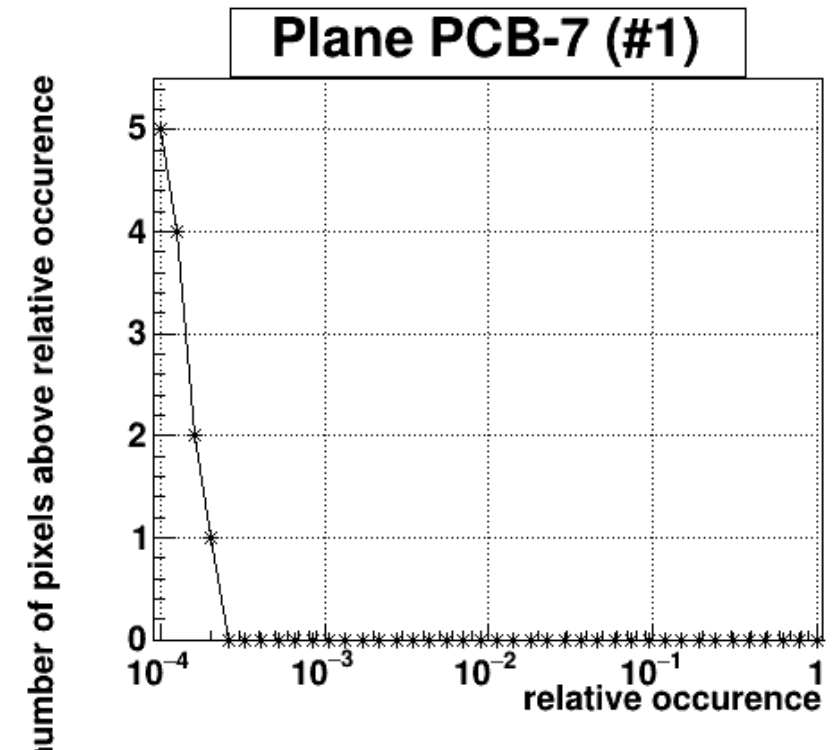
- Electrons from ^{90}Sr considered as MIP
- MIP generate ~ 70 e-/μm for thin sensors
- Sensitive layer ~ 14 μm
- Signal ~ 1000 e-

/opt/sitrineo/sitrineo/daq/copyThreshold1.sh [file]

2. Masking noisy pixels

events required $> 1/\text{minimal occurrence}$

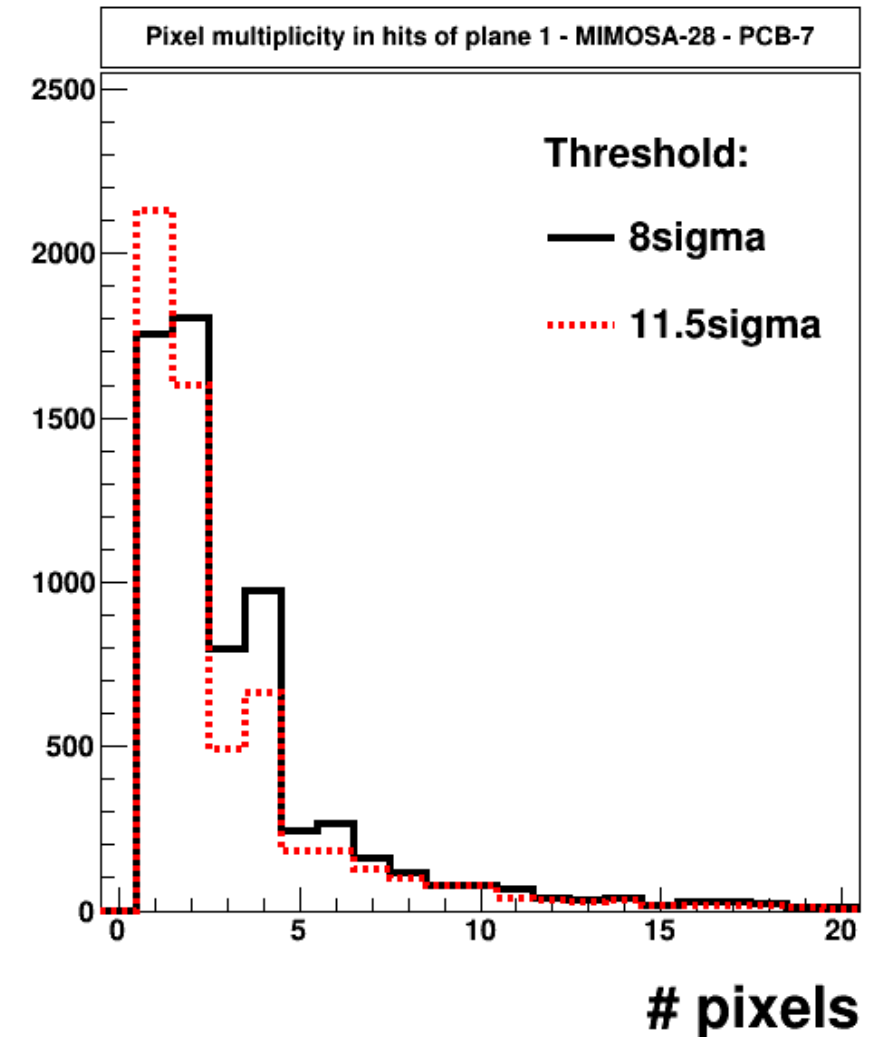
- Out of the $960 \times 928 = 890,880$ pixels in a sensor there exist a few faulty or “noisy” pixels
- TAF allows to remove these pixels by setting an **occurrence threshold**. Pixels with a higher occurrence are excluded from the analysis.
- Example of right plot:
 - 5 pixels above 10^{-4} fake rate, to be masked
- Instructions in README.txt file



=> What happens if a lower threshold level is used?

Sensor threshold cont.

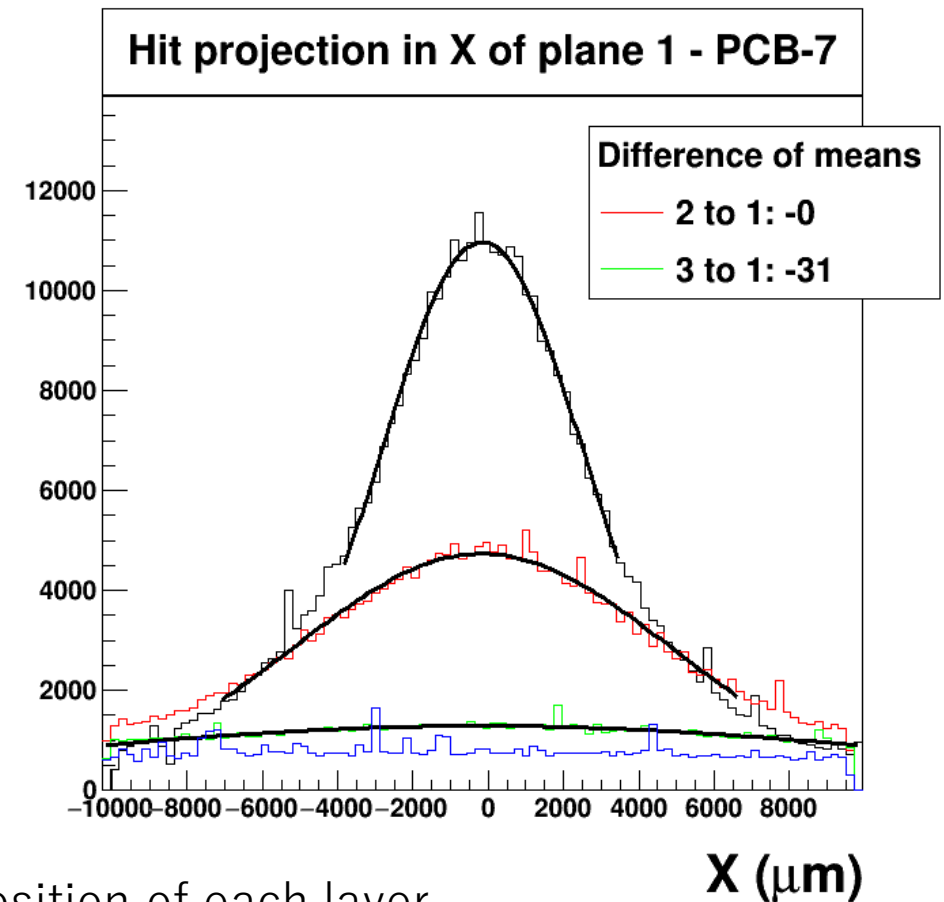
- After also taking data runs with the source, we settled on an 8σ threshold
- A threshold of 8σ means most of the noise is left out while most of the signal is kept – it's a **compromise**
- “Pixel multiplicity in hits”, or “Cluster size”, is also affected by the choice of threshold



3. Tracker Alignment procedure

REQUIRED: small collimator AND no magnetic field

- In order to make an accurate analysis of the hits in each detector plane, and thus find particle tracks, the planes have to be **aligned** with each other.
- These values are considered to be the physical distances in the XY plane, by which the secondary planes should be shifted to be aligned with the primary plane.

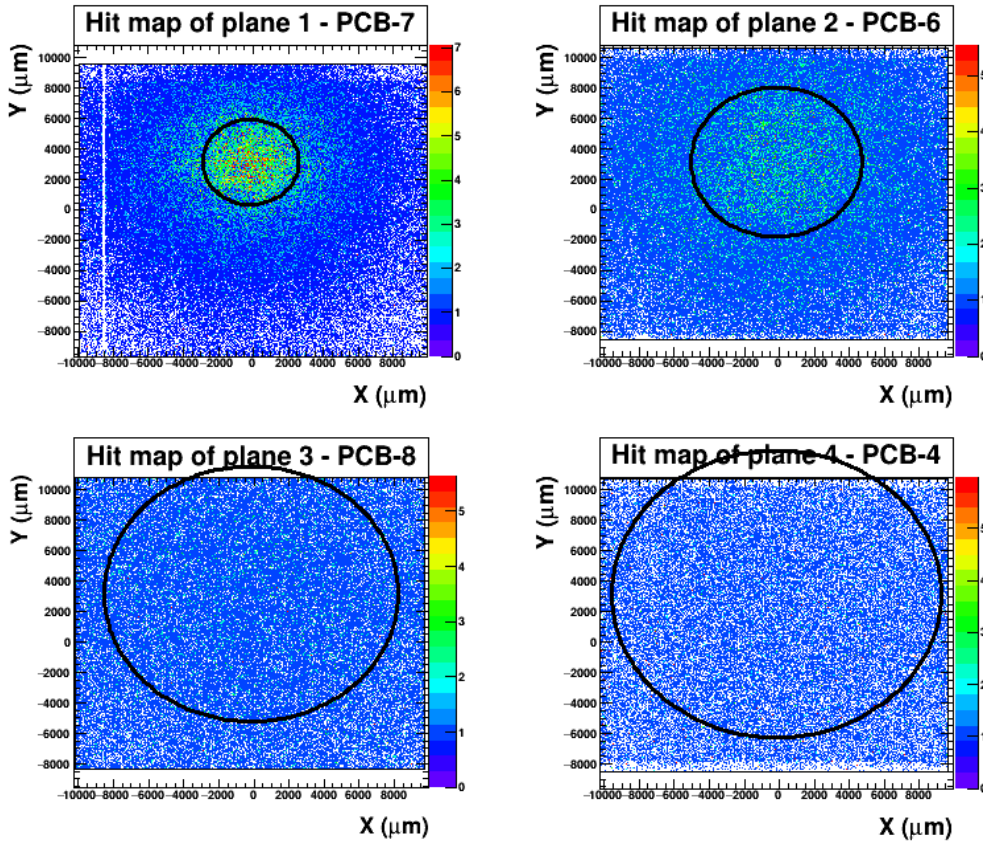


=> Let's measure sensor position. Set relative position of each layer.

Alignment Procedure

Without any magnetic field.

Run 3134, cumul over 200000 events

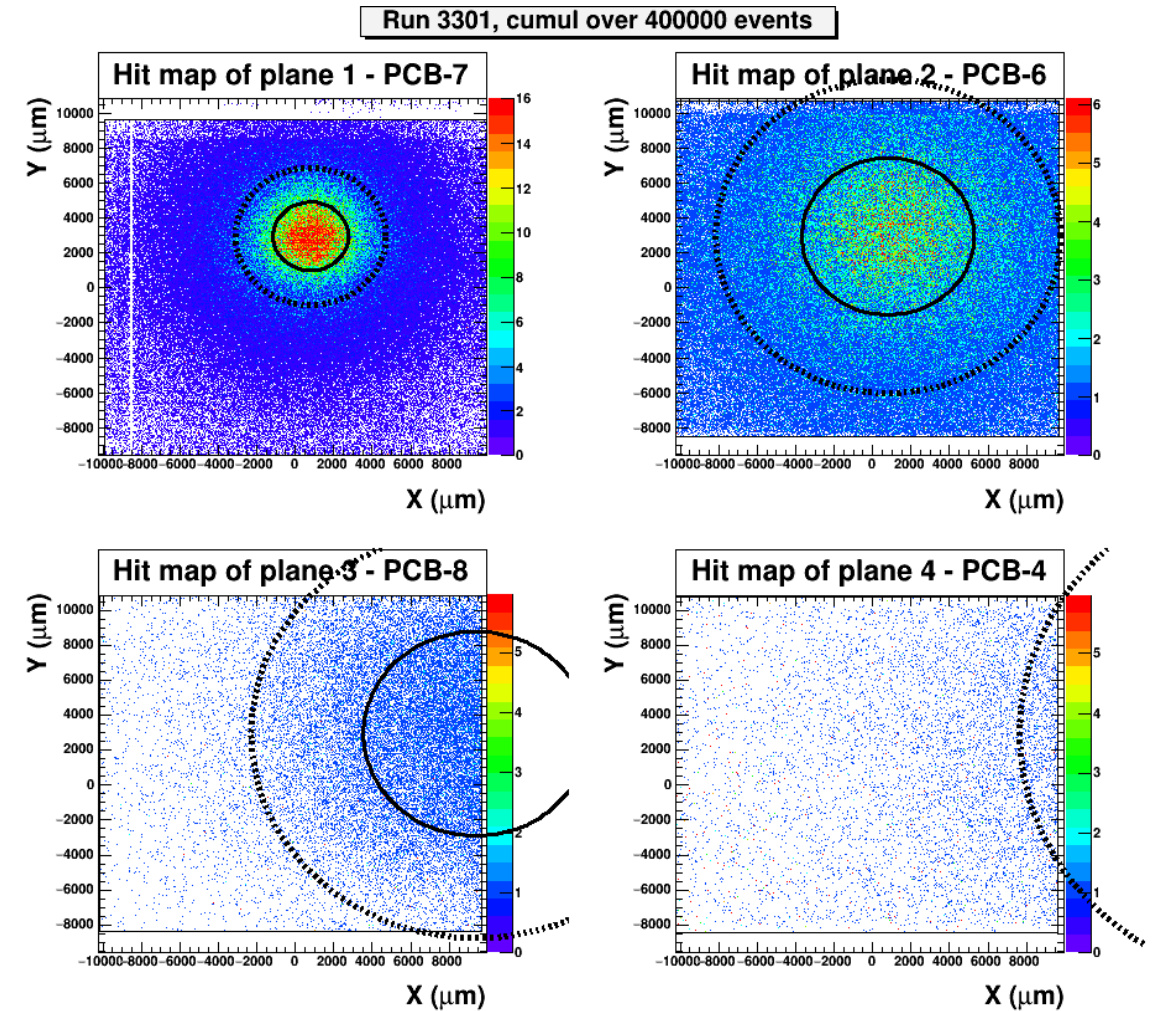


- In the same method, we also compute the expected spread due to multiple scattering in each plane
- Here the ellipses represent 1σ of spread in X and Y, due to multiple scattering
- It is clear that multiple scattering is dominant in the momentum regime that we work in (few MeV/c)

How the distribution would be changed if reduce layer?
How many scattering do you expect?

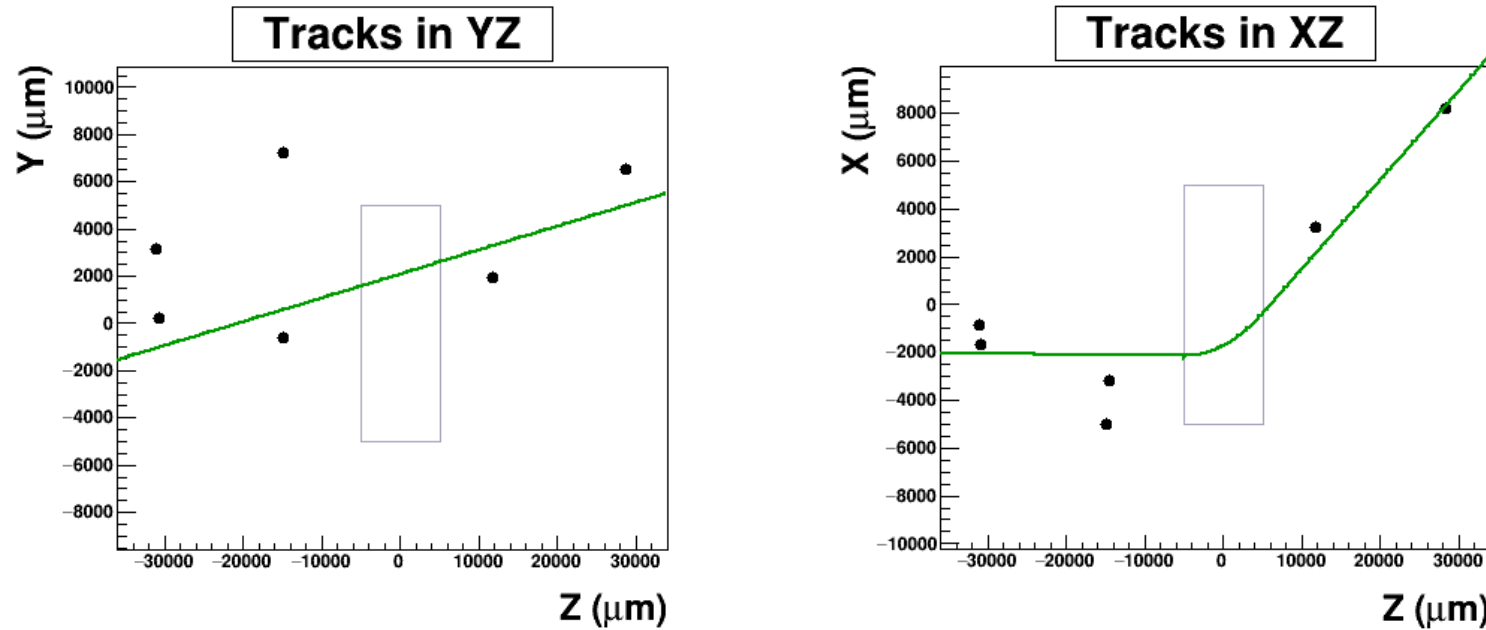
4. Track reconstruction with bending magnet

- The electrons are subjected to the magnetic force and deflected toward the positive X.
- The center of the ellipse in the fourth plane is shifted by ~ 2 cm.
- The observed beam spot is consistent with the prediction.



$$\frac{p \text{ (GeV /c)}}{q} = \frac{0.3 B(\text{T}) L(\text{m})}{\Delta\alpha}$$

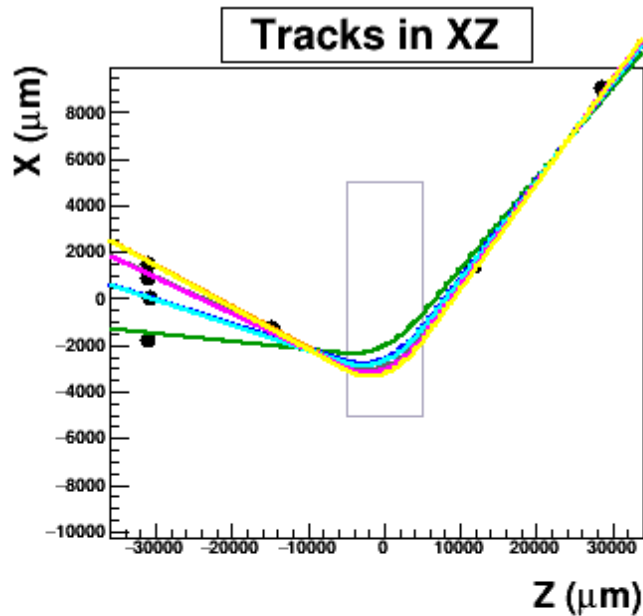
Fitting the hits assuming with a track



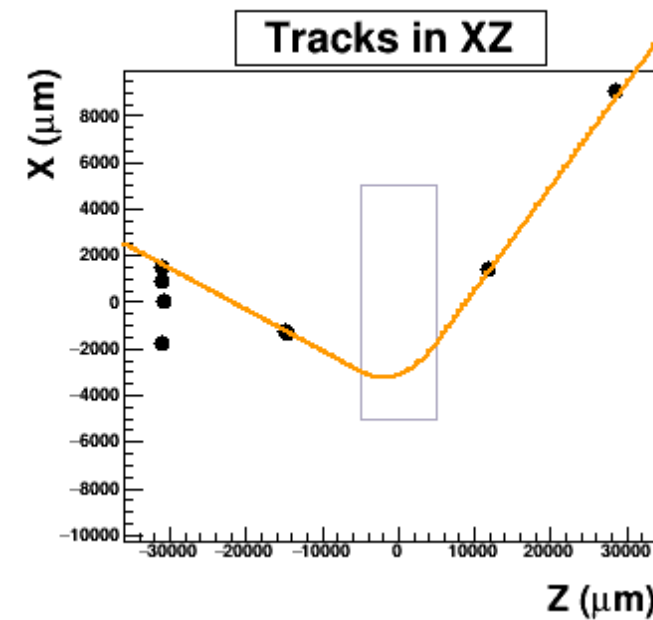
- Perform two chi-square fits for the YZ and XZ planes.

Track selection

- Track selection algorithm



Many track candidates can be constructed
One of them should be real track

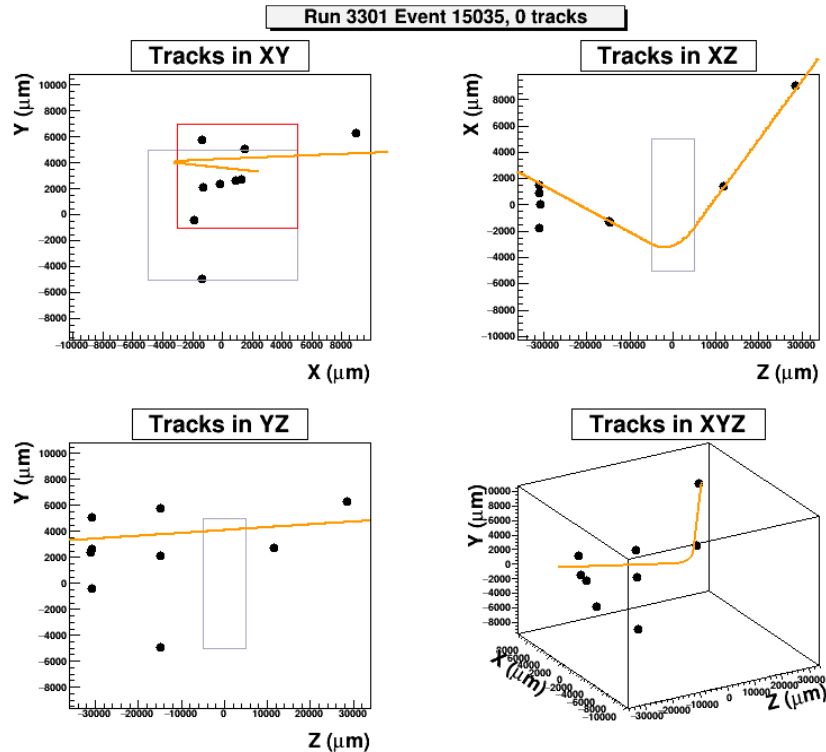


Selection of the best track
Based on chi-square in XZ plane.

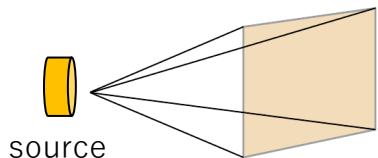
Is this best strategy?

**For a 2 million event run, 2955 tracks were removed
out of 4845 reconstructed tracks (~61%)**

Additional constrain could be introduced

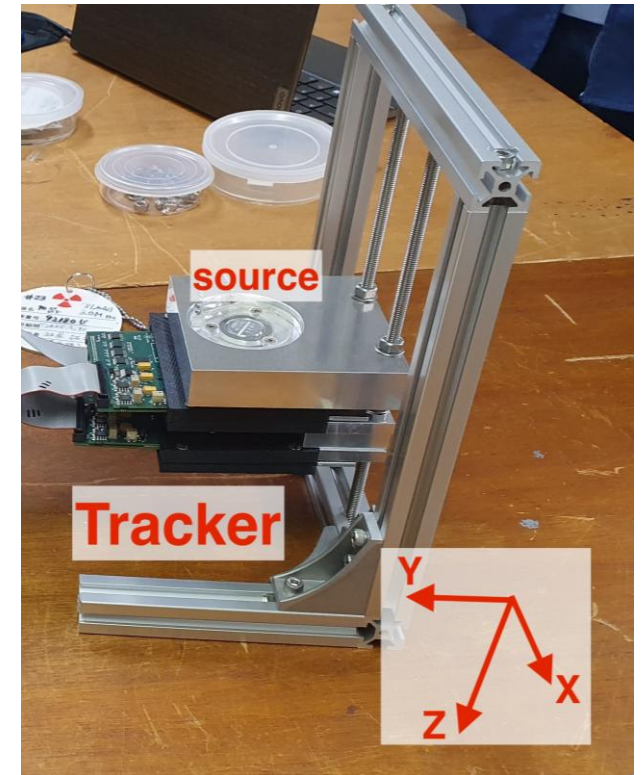


- Chi-square cuts
- Geometrical cut
 - Electron must originate from the source
 - The trajectory must go through the magnetic field
 - The initial angle with respect to the Z axis must be smaller than 30 degrees



Considering about the setup

- You can change position of each component:
 - Source
 - You can optimize z and x position
 - Upstream two layers
 - Magnet
 - Downstream two layers
- Items you need to consider:
 - Rate of electron from source
 - Hit position resolution
 - multiple scattering
 - How to extract / insert magnet?



Note: sensors and electronics are extremely fragile. Please handle with great care!

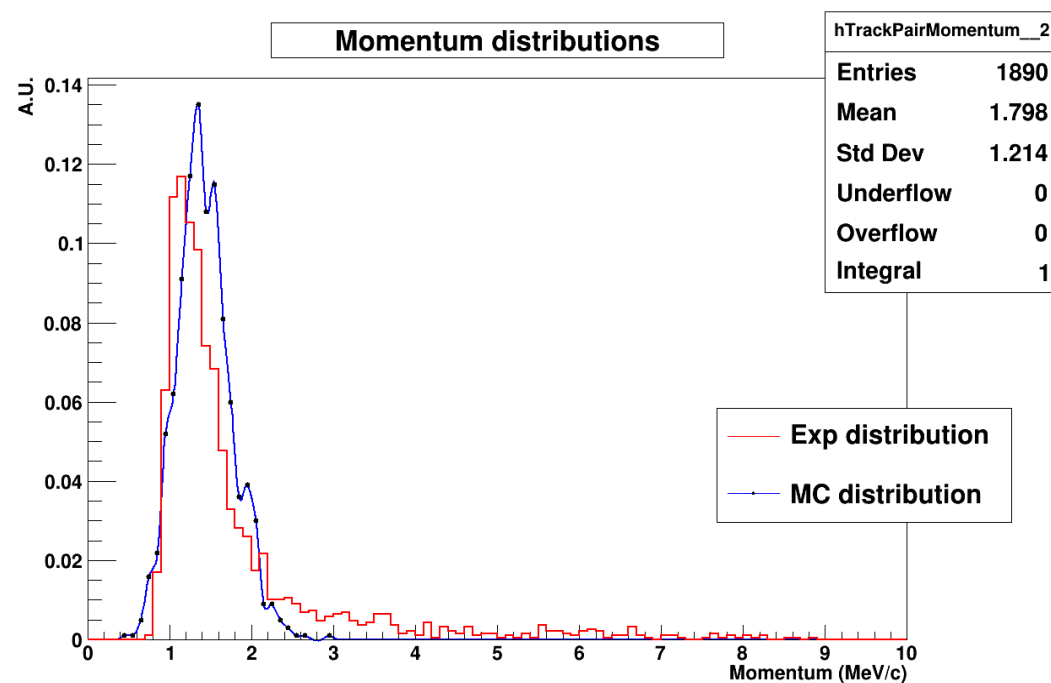
Share your experiences to next group

- [Link to the shared log note](#)
- [Link to the run list](#)

Note:

- The initial values can not be trusted.
- Do not rely on given values. Please confirm them by yourself.
- Suggest to provide your findings to next group!

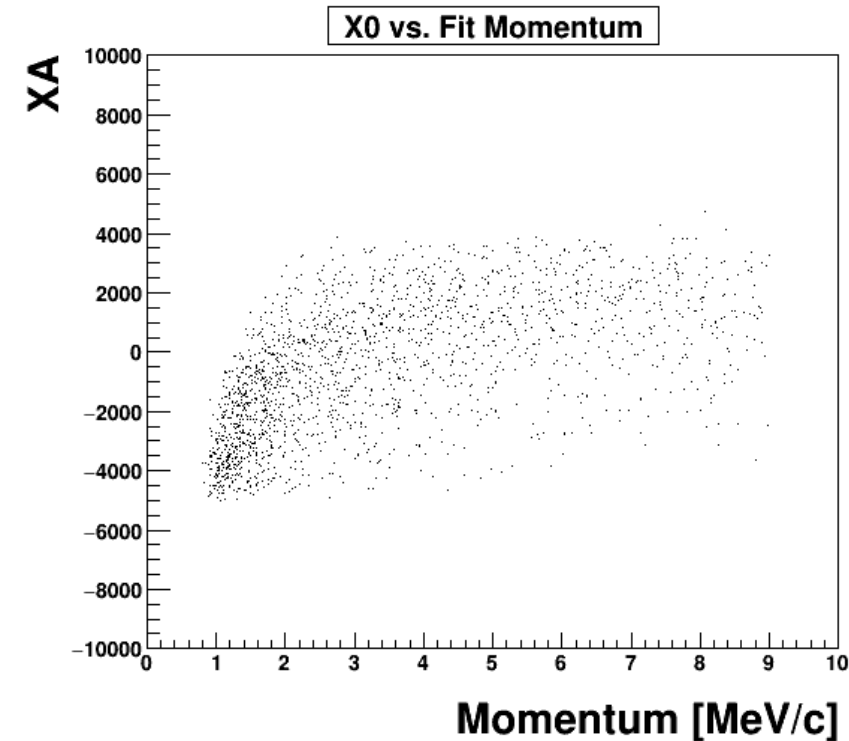
Data and MC comparison



Relatively good agreement
between data and simulation

- **Tail in the experimental distribution:**
 - Reconstruction of false tracks
- **Bias between the two**
 - Misalignment ?
- **Other differences:**
 - Problem in the initial assumptions (model of the uncertainties)

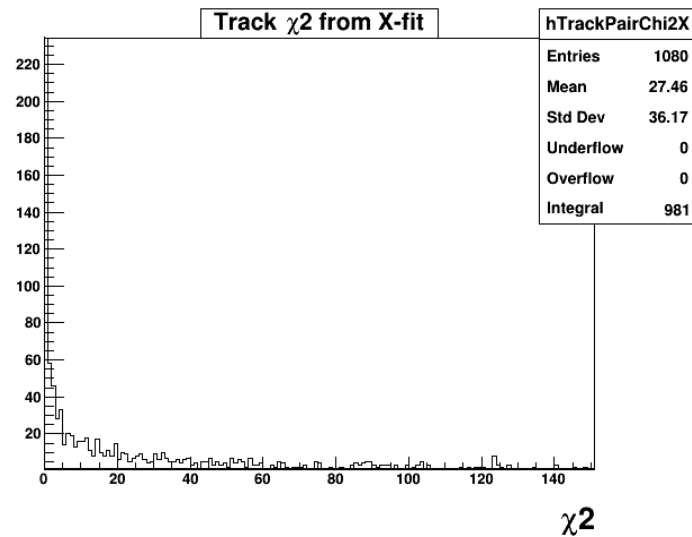
Effect of selection



- Check momentum dependence.
 - How the momentum distribution from reconstructed tracks?
 - Is it consistent with expectation?
- Should check possible bias due to applied selection

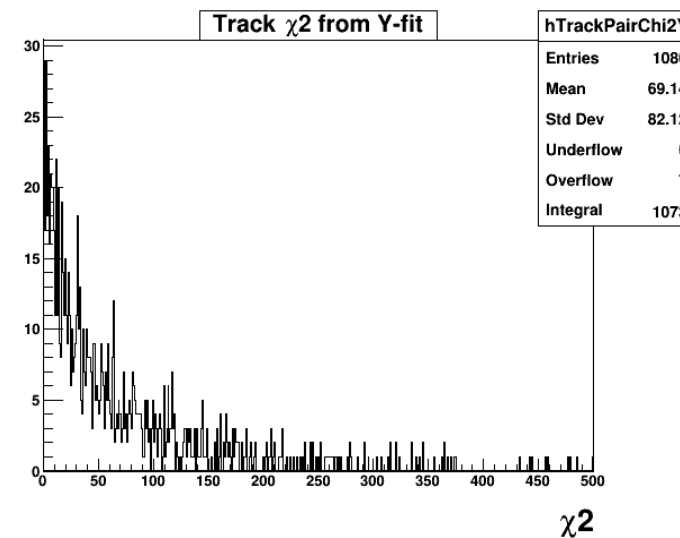
Result and discussion

- The chi-square (χ^2) fits



One degree of freedom

- 4 hits – momentum
 - Initial slope
 - Position in the magnetic field



2 degrees of freedom

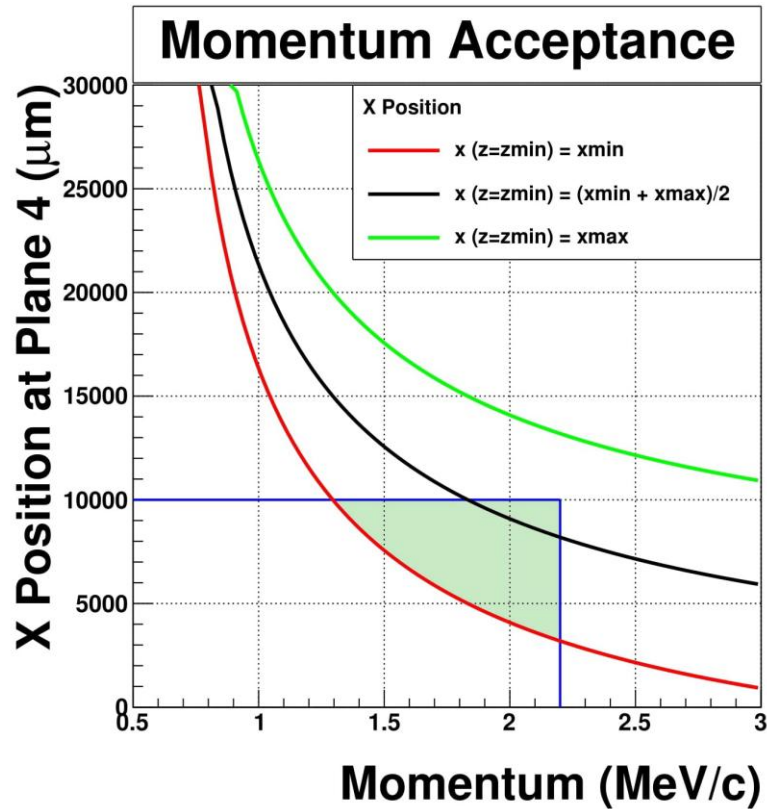
- 4 hits – Initial slope
 - Position in the magnetic field

In case you have time

- Hit pixels can be stored in a TTree
 - Use User Plot function.
 - You can reproduce the TAF is performing.
 - Data with with / without magnet
 - You can assign dimensions in your code.

Extra material

Monte carlo simulation



Simulated momentum distribution
= Fermi distribution x Gaussian

- We model the system uncertainty by a gaussian, introducing a relative uncertainty of 20 %.
- We cut the fermi distribution at 1.3 MeV, which is the lowest momentum accepted by the system.

MIMOSA-28 layout

